

RAYTHEON COMPANY
EQUIPMENT DIVISION



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RELIABILITY MODEL DERIVATION OF A
FAULT-TOLERANT, DUAL, SPARE-SWITCHING,
DIGITAL COMPUTER SYSTEM

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ABSTRACT

A computer based reliability projection aid, tailored specifically for application in the design of fault-tolerant computer systems, is described. Its more pronounced characteristics include the facility for modeling systems with two distinct operational modes, measuring the effect of both permanent and transient faults, and calculating conditional system coverage factors. The underlying conceptual principles, mathematical models and computer program implementation, are presented in considerable detail.

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TABLE OF CONTENTS

ABSTRACT	ii
LIST OF ILLUSTRATIONS	vi
LIST OF TABLES	vii
PART I	1
.1 - Overview	2
.2 - Dual Mode Model	4
.3 - Coverage Model	6
PART II	1-1
1 - INTRODUCTION	1-1
2 - CONCEPTUAL DEVELOPMENT	2-1
2.1 GROUNDRULES AND ASSUMPTIONS	2-2
2.1.1 Fault Simultaneity	2-2
2.1.2 Failure Rate	2-3
2.1.3 Coverage	2-3
2.1.4 Coverage Conditions	2-4
2.1.5 Systems Failure	2-5
2.1.6 Spares Reassignment	2-5
2.1.7 Spares Failure	2-6
2.1.8 Fault Classification	2-6
2.1.9 Fault Detection	2-7
2.1.10 Fault Isolation	2-9
2.1.11 Fault Recovery	2-9
2.1.12 D/I/R Mechanisms	2-11
2.1.13 Performance Characterization	2-12
2.1.14 DIET vs D/I/R Process Representation	2-14
2.2 SAMPLE FUNCTION SELECTIONS	2-15
2.2.1 Detection Function Rationale	2-19
2.2.2 Isolation Function Rationale	2-26
2.2.3 Fault Propagation Recovery Function Rationale	2-27
2.2.4 Time Lost Recovery Function Rationale	2-28
2.3 TERMINOLOGY DEFINITIONS	2-29

TABLE OF CONTENTS (Cont.)

3 - MATHEMATICAL MODELS	3-1
3.1 DUAL MODE RELIABILITY MODEL	3-1
3.1.1 G: Fortran DCG	3-2
3.1.2 R_u: Fortran DCRU	3-4
3.1.3 H: Fortran DCH	3-4
3.1.4 S: Fortran DCS	3-5
3.1.5 T: Fortran DCT	3-6
3.1.6 T₂: Fortran DCT2	3-7
3.1.7 R: Fortran DCR	3-7
3.2 COVERAGE MODEL	3-8
3.2.1 Subscripts and Simple Variables	3-10
3.2.2 C: Fortran COVAGE	3-10
3.2.3 C (i,s): Fortran COVAGE	3-11
3.2.4 g_i (τ): Fortran CVGS, CVG2 and CVG1	3-11
3.2.5 g'_i (τ): Fortran CVGP4 and CVGP3	3-14
3.3 PARAMETER DEFINITIONS AND APPLICABILITY	3-17
4 - SOFTWARE	4-1
4.1 PROGRAMMING CONSIDERATIONS	4-1
4.2 SUBPROGRAM DESCRIPTIONS	4-3
4.2.1 Altered Subprograms	4-7
4.2.2 New Utility Subprograms	4-11
4.2.3 Dual Mode Model Implementation Subprograms	4-13
4.2.4 Coverage Model Implementation Subprograms	4-14
4.3 MAJOR ARRAYS AND COVERAGE DATA BASE	4-26
4.3.1 Reliability Parameters	4-26
4.3.2 Reduced Field Length CARE2	4-27
5 - PROGRAM OPERATION	5-1
5.1 USER'S GUIDE	5-1
5.1.1 Processing Order	5-2
5.1.2 Use of the Input Algorithm	5-3
5.1.3 Specific Input Information	5-24
5.2 OPERATIONAL LIMITS	5-31

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6 - EXAMPLES AND TEST CASE DATA	6-1
6.1 JOB #1 - PRODUCT OF EQUATIONS 4 AND 2	6-2
6.2 JOB #2 - PRODUCT OF EQUATION 4 AND 2, WITH CALCULATED COVERAGE	6-2
6.3 JOB #3 - DUAL MODE MODEL (DUAL CHANNEL) WITH PRESET COVERAGE	6-3
6.4 JOB #4 - DUAL MODE MODEL (DUAL CHANNEL) WITH PRESET COVERAGE, MULTIPLE RUNS WITHIN RUNSET AND SPARES REASSIGNMENT	6-4
6.5 JOB #5 - DUAL MODE MODEL (DUAL CHANNEL) WITH CALCULATED COVERAGE AND MULTIPLE RUNSETS	6-5
6.6 JOB #6 - DUAL MODE MODEL (HYBRID CHANNEL) WITH CALCULATED COVERAGE AND MULTIPLE RUNSETS	6-5
6.7 JOB #7 - PRODUCT OF EQUATIONS 7, 4 AND 2	6-7
7 - SUMMARY AND CONCLUSIONS	7-1
APPENDIX A - FLOW DIAGRAMS	A-1
APPENDIX B - PROGRAM SOURCE LISTING	B-1

LIST OF ILLUSTRATIONS

FIGURES

2-1	DUAL CHANNEL SYSTEM RELIABILITY DIAGRAM	2-16
4-1	SAMPLE FUNCTION SELECTION CHART	4-17
5-1	INPUT ALGORITHM	5-5
6-1	JOB #1 INPUT/OUTPUT LISTINGS	6-8
6-2	JOB #2 INPUT/OUTPUT LISTINGS	6-19
6-3	JOB #3 INPUT/OUTPUT LISTINGS	6-30
6-4	JOB #4 INPUT/OUTPUT LISTINGS	6-34
6-5	JOB #5 INPUT/OUTPUT LISTINGS	6-40
6-6	JOB #6 INPUT/OUTPUT LISTINGS	6-51
6-7	JOB #7 INPUT/OUTPUT LISTINGS	6-63

LIST OF TABLES

2-1	SAMPLE COVERAGE MODEL SELECTIONS	2-18
3-1	PARAMETER/MODEL APPLICABILITY	3-18
3-2	PARAMETER DEFINITIONS	3-21
4-1	CROSS-REFERENCE LISTING OF CARE2 SUBPROGRAMS	4-4
4-2	PCW AND DEFAULTS	4-28
4-3	DIMENSION CHANGES FOR REDUCED FIELD LENGTH CARE2	4-30
5-1	DEFINITIONS OF LOGICAL AND CONTROL VARIABLES	5-15
5-2	CONTROL CARDS	5-17
5-3	INPUT FORMATS AND EXAMPLES	5-19
5-4	FUNCTION SPECIFICATIONS	5-25
5-5	FUNCTION SELECTIONS BY FAULT SUBCLASS	5-26
5-6	COVERAGE MODEL PARAMETERS	5-27
5-7	OPERATIONAL LIMITATIONS	5-32

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PART I

The task of predicting computer reliability, and in particular that of fault tolerant configurations, is unfortunately a rather complex one that, of necessity, is performed with ever increasing frequency. The complexity therein arises primarily as a consequence of the rather large set of interactive factors that must be contend-ed with if the prediction is to be meaningful. The quickening pace is the result of both increased application as, for example, in long life satellites and all digital flight control systems, as well as the general recognition that a multitude of reliability enhancement techniques are available and that the proper subset for a given application is best selected on a scientific rather than intuitive basis.

In recent years, a variety of computerized reliability models have been developed in order to minimize both the difficulty and the attendant inaccuracy long associated with such prediction. One or another of these gives proper recognition to such individual factors as coverage, multiple system operating modes, transient versus permanent failure, and so on. What is required, however, and not so readily available, is a unified model set incorporating the sum total of these, as well as a means of quantifying, rather than simply measuring the impact of, the most elusive of these, coverage. (This latter term represents the fact that the measure of reliability transcends hardware availability, and must in addition account for such issues as fault recognition, reconfiguration delay and applica-tion imposed time and accuracy constraints.)

The purpose of this report, then, is to describe the development and software implementation of a new series of mathematical models which are specifically designed to contend with these items. It thus portrays a reliability-assessment system that provides a unique capacity both for calculating coverage and for measuring re-liability as it relates to the totality of these factors. As such, hopefully, the system will serve as a moderate step forward in the

evolution of a scientific approach to fault tolerant computer analysis.

.1 OVERVIEW

The computer program itself, designated CARE2, is designed to run on a 60 bit CDC 6000 series computer system, using the RUN Fortran compiler, under either the KRONOS 2.1 or SCOPE 3.0 operating system. It is available in two versions, the first of which requires a field length of approximately 130K octal to load and execute and the second, approximately 100 K. The versions differ only with regard to their ability to provide output data in the form of reliability plots.

The program is based, in part, on an earlier version entitled CARE*. The latter is somewhat characteristic of its generation in that, although it calculates computer system reliability for a variety of possible configurations, it does not provide an accounting for the effects of transient faults, multiple system operating modes and most aspects of coverage.

The current program, with regard to its modelling capability, is comprised of three major and relatively independent portions. The first of these, designated "equations 1-6", is the collection of specialized reliability models included in original CARE. The second, referred to as either "equation 7" or the "dual mode model", is unique to CARE2, and provides the capability for assessing system reliability as it relates to the set of aforementioned factors. The third, known as the "coverage model", enables the calculation of this commodity under a variety of conditions, and thus serves as input for the dual mode model and, where applicable, equations 1-6.

*F.P. Mathur, "CARE Program (Computer-Aided Reliability Estimation)", Technical Memo No. 361-10, Jet Propulsion Laboratory, Pasadena, California, February 24, 1971

CARE2, like its predecessor, portrays a computer system as a series of one or more independent subsystems or stages, wherein system reliability, by definition, is equal to the product of stage reliabilities. In turn, a stage is comprised of a quantity of identical units, termed LRU's, a portion of which serve as active or on-line devices and the remainder, as standby spares. Each stage is then represented by a single equation (i.e., model), selected on the basis of its ability to adequately represent the required physical configuration.

By way of illustration, a typical computer system might be viewed as consisting of four stages representing, respectively, the input, central processing, memory and output functions. In turn, the input stage, for example, might itself consist of three units, whose outputs are majority voted, and a single standby spare. Given then certain simplifying assumptions, the stage can be characterized by equation 4, which represents a "hybrid/simplex" configuration as defined by Mathur*.

In addition, however, the current program also provides the means for analyzing a computer system (or portion thereof) in which the component stages are interdependent such that total reliability is not a simple product of stage reliabilities. This situation is typified by a multi-stage computer wherein, given insufficient LRU's to constitute a fully operational system, a portion of those that remain are switched off and a backup or degenerate mode of operation is entered (cf. Figure 2-1). In this instance, the failure of an LRU in one stage has a conditional effect on the quantity of on-line versus spare LRU's in a second and thus, given unequal failure rates in the two states, a reliability impact on the second stage.

This capability, as well as certain others, is unique to the dual mode model (equation 7). As a consequence of this, and the additional fact that the majority of equation 1-6 configurations

* op. cit.

are but specialized subsets of equation 7, the majority of systems can, in practice, be modelled without reliance on the original six. The following summary discussion thus centers solely on the dual mode and coverage models which, together, constitute both a complete evaluation system and the new modelling portion of CARE2.

.2 DUAL MODE MODEL

This model, which is appended to the original CARE program as the seventh of seven equations, to a large degree supplants the preceding six, and thus serves as the focal point for the majority of reliability evaluations performed within CARE2. The mathematical model which underlies it, though beyond the scope of this summary, is presented in detail in Section 3.1. The capabilities which the model provides, from the perspective of the user, are highlighted in the following paragraphs.

As noted previously, CARE2 represents a computer system as a series of stages, each corresponding to a single class of functional LRU's. The dual mode model, in terms of its software implementation, has a capacity for up to eight such stages, wherein each represents a grouping of like LRU's consisting of zero or more each of on-line and spare units.

The phrase dual mode is, itself, a reference to an ability to model a system comprised of two distinct quantities of on-line LRU's per stage, which correspond, respectively, to the number required for operation in each of two system modes. Thus, the object computer system is represented by two separately specified configurations which, in turn, characterize its hardware complement in both an initial and backup state.

This dual mode provision enables the representation of computer systems which, confronted with critical equipment failures, are designed to reconfigure into a second, and less demanding state. For example, in Figure 2-1, mode 1 is the preferred operating state as a consequence of its provision for rapidly discerning faults via the comparator. Given, however, a permanent failure in either the

comparator or all but one of the LRU's of a particular stage, operation can no longer continue in that state. At this point, the object computer system is designed to reconfigure into its mode 2 state wherein sufficient hardware, barring further critical failure, is available to maintain a "degenerate" form of operation.

In addition to stages and their component LRU's, the model also provides for the representation of two object system "single point failure mechanisms." The first of these corresponds to the class of switch and comparator/voter failures which, on occurrence, unconditionally cause degeneration from mode 1 to mode 2. The second represents the class of failures, termed catastrophic, which cause immediate and total loss of the system. Each is expressed, within the model, solely in terms of its corresponding permanent failure rate.

LRU's, on the other hand, are considered subject to both transient and permanent faults, wherein the rate of the latter is, in addition, conditioned by LRU status. As a consequence, the model provides for a separate LRU failure rate specification for each of three failure classifications i.e., transient, on-line permanent and standby permanent.

Given the occurrence of mode degeneration in a computer system, it is typically accompanied by a partial equipment shutdown in which one or more fully functional LRU's are released from active service. These units then, as a function of computer design specifics, either re-enter the spares pool or, conversely, are not re-assignable and thus, from a computer reliability viewpoint, are purged from the system. The model provides for either possibility, in accordance with a user controlled software switch setting.

In total then, the dual mode model has the capacity for representing a computer system with either one or two distinct hardware configurations, and consisting of one to eight functional stages. In practice, the system is defined in terms of these stages, wherein the user specifies, for each stage, the mode 1, mode 2 and spare LRU

count, as well as the applicable transient, on-line and standby failure rates. Additionally, the two single point failure rates and the spares reassignment method (on degeneration) are user specified at the system level.

.3 COVERAGE MODEL

For purposes of this study, coverage is defined as "the conditional probability, given a fault and sufficient hardware replacements to remedy it, that the system is returned to operational status in a form consistent with external time and accuracy needs." In other words, it is a measure of the reduction in system reliability due to issues other than those of hardware availability, and thus serves as an accounting for such factors as the inability to either detect, isolate and/or recover from, certain classes of faults. For example, given both a permanent fault in an on-line memory and a fully operational spare, the conditions of hardware success are, for the moment, met. Those of coverage, however, further dictate that the fault be correctly attributed to the memory, and that the replacement unit then be "reloaded" within certain time constraints.

It follows that coverage is not single valued for a given computer system. For instance, the ability to detect a fault is clearly a function of its location within that system. Further, the ability to recover, as from a memory fault, may depend on the presence of a second unit with identical storage contents, and this may be available in only one of the mode configurations.

From a system perspective then, coverage is readily seen to depend on fault subclass (location, as within an LRU), fault type (permanent or transient) and operating configuration (mode). In addition, it is related to at least two other factors; i.e., whether the fault results in a mode change (which may entail certain risk), and the status of spare LRU's (which are subject to prior failure, thus presenting a possible requirement for trial selection and testing in order to locate an operational unit).

The model provides for the calculation of a single conditional coverage value for each valid combination of these conditions. In turn, the set of computed values are then supplied to the appropriate reliability equation for inclusion in the system reliability assessment. Since, in practice, the original six equations are, at best, ill equipped to contend with coverage, the normal recipient is the dual mode model.

Since the same methodology is utilized to compute each of the conditional coverage values, the remainder of this discussion is addressed to the rationale underlying the modelling and calculation of a single value (i.e., for a fixed set of conditions). It should be specifically noted, however, that each of the parameters referenced therein has a potentially unique value for each set of conditions.

Given the occurrence of a fault, the object system is presumed to be equipped with more or less suitable defense mechanisms to contend with it. The coverage model is based on the assumption that, in all but the unprotected case, these consist of one or more fault detectors (e.g., memory parity and software selftest) as well as associated fault isolation and recovery techniques. In this sense, conditional coverage is but an overall performance measure of these, as a group, and as they pertain solely to the fixed conditions.

In addition, it is assumed that, given multiple fault detectors (within the fixed conditions set), they are best represented as statistically independent processes. (Conversely, members of separate sets are treated as mutually exclusive). As such, on occurrence of a fault, they can be viewed as competing with one another, though not necessarily with equal vigor. The "winner", if in fact there is one, then calls into play, in sequence, its associated isolation and recovery processes.

Given the detection of fault in the object computer system, the ability to identify the responsible detector can prove instrumental in constraining the isolation and recovery tasks which follow

(i.e., individual detectors have more or less unique properties with respect to the type of faults they detect and when they detect them). As a consequence, the coverage model is designed to provide for the calculation of the conditional detection probability associated with each of the competing detectors, given its presence in a competitive situation.

In turn, these values are highly dependent on the following factors:

- The stand-alone success probability of each fault detector (i.e., the percentage of faults it would discern if it were the only detector present).
- The corresponding stand-alone detection rate associated with each.
- The complete time base or scheduler interrelationship between each (i.e., individual repetition rates, where applicable, zero-offset delays, etc.).

Given this data as input, the model performs the calculations necessary (cf. Section 3.2) in order to establish the interrelationship that exists between the detectors, and thus provide the conditional detection probability and rate of each, when in competition with the others.

This information is then utilized, in conjunction with corresponding fault isolation and fault recovery time profiles, in order to produce the contribution to coverage (for the fixed condition set) associated with each of the individual detectors. Thus, their sum is the conditional coverage value associated with the set of conditions.

In this regard, the isolation profile is a rate (i.e., probability density) function which represents the performance characteristics of the isolation process corresponding to the particular detector. The referenced recovery profile is, in fact, two separate characterizations, both measured in terms probability (rather than probability density) versus time. The first of these, referred to

as the error propagation function, is indicative of the reduction in recovery probability due to the potentially unconstrained propagation of erroneous data, throughout the computer system, during the interval between fault occurrence and fault detection. The second, known as the time delay function, corresponds to the potential diminishment of recovery probability as a function of effective computer down time, and as measured from fault occurrence on through detection, isolation and, where required, trial selection and testing of spares, until such time as the true recovery process is initiated. (The time delay impact associated with the recovery process itself is handled implicitly in the recovery probability function.)

Again, it should be emphasized that the above discussion describes the coverage calculation process associated with a single subclass location, while operating in a particular mode, and when confronted by a specific type of fault. Also, it should be noted that each of the fault detectors has a unique description, both within and between condition sets, and further that the isolation and two recovery processes also have unique descriptions for each possible combination of detectors and condition sets.

In perspective, then, the repetition of this process, once for each of the possible condition sets, constitutes the process referred to as coverage calculation.

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PART II

SECTION I

INTRODUCTION

The purpose of this combined study and software development effort was to provide an advanced analytical tool for use in estimating the reliability of various fault-tolerant, dual, spare-switching digital computer systems. As such, it was to include a means of accounting not only for permanent (i.e., hard) faults, but also transient faults (i.e., faults which do not persist, but whose effects can) and coverage factor (i.e., the conditional probability of system recovery given that sufficient operational hardware is available).

As originally conceived, the phrase "dual system" was in reference to a configuration comprised of two identical computers, operating in parallel, and joined following their digital output stage by a comparator. Further, each computer was partitioned into four switchably replaceable units, and these in turn were backed up, at the system level, by a variable quantity of spares.

In the course of developing the accompanying mathematical models, an opportunity for increasing the problem solving capability rather significantly became apparent, but with it, a practical necessity that it be incorporated prior to any further software development. The resulting change, subsequently agreed to by both parties, amounted to substitution of the phrase "dual mode" for "dual system" in the original work statement. With it, however, came a revision of the mathematical models and software so as to include a capability for evaluating virtually any configuration involving sparing at the unit level, and accompanied by any kind of fault detection, isolation and recovery procedures, provided that only two system operating modes are required and that software based numeric limits are not exceeded. The resultant modeling capability thereby extends, for example, to the majority of both "N-modular-redundant" and "hybrid" systems.

The software phase of the effort was specified to be implemented as an addition to an existing statistical reliability prediction program entitled CARE*. This program was developed, by the Jet Propulsion Laboratory, to "serve as a computer aided reliability design tool to designers of ultra-reliable fault-tolerant systems, by facilitating reliability computation, data generation, and comparative evaluation".

CARE's rather singular emphasis on permanent faults and one mode system operation was seen, however, as a rather significant shortcoming with respect to the defined programmatic requirements, and thus indicative of the need either for a serious revision or a nearly stand-alone addition to the existing base.

As a practical matter the latter course was selected, and with it, the corollary development of a dichotomy between old and new halves of the program. This division, though most pronounced in the inner workings of the software, also evidences itself in both the input/output structure and the frequent overlapping of capabilities wherein a given system can be evaluated with either half, though with rather marked differences in terms of modeling depth.

The new portion of this program, at times supplemented by the old, can be used as a reasonably sophisticated analytical tool to assess the reliability of a wide variety of fault-tolerant computer configurations. In addition, it is particularly attuned to the needs of performing sensitivity analyses on variations of a single configuration including, for example, measuring the effect of changes in schedule on the usefulness of a software self-test routine.

* F.P. Mathur, "CARE Program (Computer-Aided Reliability Estimation)", Technical Memo No. 361-10, Jet Propulsion Laboratory, Pasadena, California, February 24, 1971

It should be specifically noted, however, that the necessary inputs to the program include a statistical specification of all significant fault detection, isolation, and recovery mechanisms within the system, i.e., it must be furnished data describing the properties of the various coverage features included in the object computer. The generation of this data is, in some cases, quite difficult, and the values obtained, often subjective. This is seen, however, not as a shortcoming of the study, but rather as an indication that reliability prediction is, itself, a difficult undertaking, and that much additional work remains before it can truly become a science.

The following sections describe the results of the subject effort, including development of the conceptual base, its implementation in terms of mathematical models and subsequently software, and instructions on its utilization in the form of a "users guide" for operation of the program.

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SECTION 2
CONCEPTUAL DEVELOPMENT

The achievement of fault tolerance in a reconfigurable computer system transcends the issue of hardware survivability; a second and equally essential prerequisite is that of fault awareness and the consequent ability to re-establish control successfully in a properly reconfigured system. This necessitates that the system include a methodology for detecting, isolating, and ultimately recovering from any of a necessarily large percentage of faults. Collectively, these methods are referred to herein as "fault tolerant features" (FTF's), and their integrated function is to provide "coverage".

At issue then, in a properly directed system design process, is the selection of an effective FTF set for a particular configuration, with the limiting constraint being that each provides a degree of coverage only at the expense of additional hardware and/or reduction in effective computational throughput. Up to a point therefore, the addition of FTF's enhances the probability of successful operation; beyond that, the ever decreasing gain in coverage (via overlap of faults covered) is quickly overshadowed by the failure mechanisms inherent in the FTF implementation hardware.

This study, which is itself the outgrowth of a current necessity for quantifying fault tolerant computer performance has, therefore, as its fundamental objective, the development of a computer based method for assessing system reliability as it relates to both hardware configuration and FTF's employed therein.

Of the three main tasks in this effort, deriving the mathematical reliability model for a dual mode system, providing for calculation of the coverage factor, and extending the existing CARE program accordingly, the second is undoubtedly the most complex, and necessarily the most open to question. Consequently, much of the following discussion centers on this particular aspect of the study.

2.1 GROUNDRULES AND ASSUMPTIONS

In order to place bounds on both the magnitude of the study and the execution time required for the resulting computer program, certain simplifying assumptions must necessarily be made. At the same time, however, it is of even greater importance that all governing performance factors be properly accounted for. What is called for, then, is a somewhat delicate balance between too much and too little. Unfortunately, as is often the case when developing models, the quantitative information most desired for the decision making process is available only as an output from, rather than input to, the modeling task. As a consequence, therefore, it is necessary to rely rather heavily on intuitive processes rather than known phenomena.

In this study, the following considerations were judged to be both necessary and sufficient in order to provide for a representative reliability assessment:

2.1.1 Fault Simultaneity

Independent and simultaneous, or near simultaneous, fault occurrences are assumed to be sufficiently improbable as to justify ignoring them, both for the purpose of system evaluation and for that of system design as well.

2.1.2 Failure Rate

Constant values are assumed throughout. In particular, three separately specified quantities are provided for each of a quantity of LRU (line replaceable unit) types:

- λ - the permanent-failure rate of on-line (i.e., active) LRU's
- μ - the permanent-failure rate of standby (i.e., spare) LRU's
- γ' - the transient-failure rate of on-line LRU's.

In addition, two single-valued system level rates are included:

- $\hat{\lambda}_2$ - the permanent-failure rate of system components whose loss forces an immediate degeneration in operating mode (e.g., certain non-catastrophic failures in an output voter or comparator)
- $\hat{\lambda}_3$ - the permanent-failure rate of system components whose loss is catastrophic (e.g., loss of all input power to the system).

2.1.3 Coverage

For purposes of this study, coverage is defined as "the conditional probability, given a fault and sufficient hardware replacements to remedy it, that the system is returned to operational status in a form consistent with external time and accuracy needs". In turn, its value is viewed as functionally dependent on three conditional probabilities:

- The probability, given a fault, that it is detected
- The probability, given a detected fault, that it is properly isolated

- The probability, given a properly isolated fault and sufficient spares to remedy it, that a satisfactory cure is effected.

2.1.4 Coverage Conditions

Though often discussed as though it were a single valued quantity for a given system operating in a given environment, coverage is more accurately a set of values, each of which corresponds to a specific situation. In particular, the degree of coverage offered is, at a minimum, dependent on the following conditions:

- operating mode - whether the system is fully operational (e.g., 2 out of 2 channels functioning) or degenerate (e.g., 1 out of 2 channels functioning)
- fault location - whether the fault lies, for example, in the system's input, CPU, memory bit plane, memory word electronics or output area
- fault type - whether the fault is permanent or transient
- spares status - whether initial replacement units, as selected from the spares pool to remedy a fault, are themselves operational or faulty
- degeneration requirements - whether or not it is necessary, as a function of spares status, to change operating mode (i.e., to undergo transition) in the event of a fault.

As a consequence, a unique coverage value exists for each combination of conditions, and must therefore be accounted for in the reliability assessment.

2.1.5 System Failure

It is assumed throughout this study that a coverage failure inevitably results in total system failure. Specifically, this includes:

- failure to detect a fault
- failure to correctly isolate a detected fault
- failure to recover from a correctly isolated fault.

(In addition, of course, lack of sufficient hardware to constitute an operational, degenerate system also leads to the same consequence.)

While this is in general a reasonable assumption, it is possible to conceive of reconfiguration strategies that recover from certain transients, which would otherwise be disabling, by changing to a degenerate mode of operation (e.g., by entering a simplex mode). Similarly, in certain situations, other forms of coverage failure could conceivably also lead to a degenerate mode rather than to system failure.

2.1.6 Spares Reassignment

Given a degenerative failure, a quantity of fully operational on-line LRU's are typically released from active service. Depending on system architecture specifics, those so released may or may not be available for use as spares in the event of subsequent failure. Since either situation may prevail, it is necessary that both be accounted for in the model, with the determination of which is most appropriate for representing a given configuration left to the discretion of the user.

2.1.7 Spares Failure

Since spare LRU's are themselves subject to failure (at rate μ), it is necessary to provide for situations in which the spare selected to replace a failed on-line LRU has itself failed, and must consequently be replaced by yet a second (or, in the general case, nth) spare. In the model, this is provided for in the form of a single delta coverage value per fault classification per operating mode, wherein the as calculated value is a measure of the reduction in recovery probability resulting from incurred downtime during the conditional trial and error replacement period. In calculating this, it is assumed that failed spares are purged from the system in bulk on the occurrence of mode degeneration, and as individuals following their selection as a replacement unit.

2.1.8 Fault Classification

The ability of a given detector to recognize a specific fault is, in most instances, highly dependent on the precise nature of the fault. For purposes of this study, it is assumed that two levels of classification are adequate for the purpose of so categorizing faults. The first of these, referred to as fault class, is the LRU type (e.g., CPU or memory) in which the fault occurs. The second, or fault subclass, is an arbitrarily selected portion of an LRU (e.g., arithmetic unit in a CPU).

Thus, by proper partitioning of the object system representation, first into LRU's or classes, and then into subclasses, the various faults can be categorized according to their specific detection characteristics.

2.1.9 Fault Detection

The representation of an object computer system as a series of fault subclasses underlies the approach to coverage measurement utilized in this study. Specifically, each subclass is by design a grouping of possible faults, so categorized solely on the basis of their common susceptibility to one or more fault detectors. In other words, the set of fault detectors associated with a particular subclass is, by definition of the subclass itself, comprised wholly of statistically independent members. In turn, such independence implies that each member detector has a finite probability of detecting any of the possible faults within the subclass, and that it therefore competes with all other members toward the objective of being first to detect a local fault.

This concept of competing fault detectors should not be construed to imply that a degree of equality need exist between them; on the contrary, the contest is of necessity as imbalanced as reality dictates.

For a moment perhaps, it is useful to look at the performance characteristics of a stand-alone detector i.e., one which has no competitors within the subclass. Given both singular occurrences of random faults and infinite time, the detector has an associated non-zero probability of detection. This value, as well as the corresponding detection rate profile, forms a substantial portion of the detectors' characterization.

In addition however, it is necessary to consider the occurrence rate of the detector itself i.e., the timing basis or schedule on which it executes. Two basic categories are apparent: periodic and aperiodic. The former is populated, in the main, by software based detectors (e.g., software selftest), whereas the

latter group consists primarily of hardware detectors (e.g., memory parity). (In both of these cases, it is assumed that the initial execution of the test, if unsuccessful in detecting a specific previous fault, precludes any possibility of later detection, i.e., the fault is transparent to the test.)

Returning then to a competitive situation, and given each detector characterized in terms of its stand-alone detection probability, detection rate and schedule, it would be a relatively simple task to compute an overall subclass detection probability and expected time, based on the interaction (i.e., competition) between detectors. It would not be sufficient, however, for the following reasons:

- knowledge of the specific test by which a fault is detected is frequently utilized, in the object computer, to constrain the isolation process
- individual detectors vary in their ability to either prevent or minimize fault propagation (i.e., contamination of correct information via improper processing). Since this can have major influence on the probability of recovery, knowledge of the specific detector involved must be made available.

It is necessary, therefore, that a conditional detection probability and rate be computed for each subclass member, as the values relate to the totality of competitive detectors.

2.1.10 Fault Isolation

Unlike fault detection, the isolation of faults is assumed to be a single-threaded process in which a lone isolator seeks out the source of difficulty. Since the object system, in all probability however, incorporates multiple isolators (each tailored to a specific task), it is necessary to provide accordingly in the model.

In particular, it is assumed that each detection process is uniquely linked to an isolator such that, given detection of a fault by it, the corresponding isolator is unconditionally brought into play. In turn the isolator, by virtue of its tailored design, inherently capitalizes on whatever unique characteristics the detector may possess in order to constrain the bounds of the search.

By way of example, the isolation process associated with detection by memory parity is clearly minimal (if in fact it exists at all), whereas detection by an external voter implies nothing in the way of fault location, thus mandating a far-ranging and potentially time-consuming search.

As in the case of fault detectors, fault isolators are seldom, if ever, perfect, and thus have both a non-unity success probability and a finite process rate. For analogous reasons then, this must be accounted for in the impending fault recovery process.

2.1.11 Fault Recovery

The hardware aspects of fault recovery are reasonably well disciplined. Either a spare hardware unit and the needed switching apparatus are available, in which case that portion of the cure can be effected, or they are not, in which case the system either degrades or fails completely (barring the use of techniques such as those of "graceful degradation" in the event of partial memory loss, etc.).

The coverage portion of fault recovery, on the other hand, must contend with all issues save those of hardware availability, and is thus confronted with a rather unwieldly grouping of considerations which, in turn, are considerably more difficult to deal with, both in the object system itself and, consequently, in the model as well.

In particular, it is felt that each of the following are of sufficient importance as to necessitate inclusion in the model:

- the subclass in which the fault is located (for reason of its potential influence on recovery difficulty)
- the time delay between fault occurrence and fault recovery, as it relates to the issue of system downtime. (Of necessity, this incorporates any time devoted to spares checkout including repetitions, where required, to locate a functional spare)
- the degree and location(s) to which fault propagation was contained, and the corresponding time interval during which it was unconstrained. (The model assumes here, as a first order approximation, that this interval starts on occurrence of the fault and ends on its detection. Compensatory adjustments, where called for, can be achieved by modifying the degree of sensitivity)
- the detector responsible for finding the fault, as it relates both to the degree of fault propagation and the time required for detection
- the system operating mode at the time of fault occurrence
- the type of fault involved (permanent or transient)
- the need, or lack of it, for mode degeneration.

In addition, successful recovery is assumed to be conditioned by the following:

- successful detection of the fault
- successful isolation of the fault
- in the case of a permanent fault, availability of a spare LRU or, barring that, sufficient on-line LRU's to maintain operation in a degenerate mode
- in the case of a permanent fault, successful detection of any failure present in a selected spare LRU.

2.1.12 D/I/R Mechanisms

Since each of the object system fault detection (D), isolation (I) and recovery (R) processes has the potential for reacting differently to a fault as a function of its location (subclass), the type of fault (permanent or transient), the system operating mode (fully operational or degenerate) and any requirement for degeneration (given certain hardware losses in a fully operational system), it is necessary to provide a means for modeling each possible reaction separately. The total set of system reaction descriptions corresponding to detection by a particular detector is then referred to as a D/I/R mechanism.

By way of illustration, take the case of a CPU selftest fault detector. As its name implies, it is most proficient at detecting fault which occur in the CPU; nonetheless, it exhibits a finite capacity to detect those in other subclasses as well. For instance, given that the test executes out of memory, it follows

that certain faults located therein will cause it to misexecute, thus resulting in an eventual fault indication (albeit for the wrong reason). Similarly, though the test is reasonably adept at detecting permanent CPU faults, its capacity in the presence of transients is, at best, marginal.

It follows then, in the general case, that a detectors' performance may be expected to vary as a function of all the aforementioned environmental conditions. In analogous fashion, the isolation and recovery processes associated with that detector may likewise be expected to exhibit similar dependencies.

In context, then, a D/I/R mechanism is the total set of performance descriptors pertaining to a particular fault detector. As such, it consists of separate detection, isolation and recovery performance characterizations, one each for every meaningful combination of conditions.

2.1.13 Performance Characterization

As noted, each of the object system fault detectors, together with its associated fault isolation and fault recovery techniques, is represented in the model as a D/I/R mechanism. Each mechanism is then represented by a set of performance characterizations, one each for all combinations of detection, isolation and recovery processes across a spectrum of conditions.

In turn, each of the individual performance characterizations is expressed in terms of a function specification and a referenced

function model. The latter are parametrically expressed probability and probability density functions which serve as a representative form or pattern for the characterization, and the former provide specific numeric details to round out the characterization. The end object of these (i.e., a fully described process representation) is then referred to as a function.

In particular, the following set of function models is viewed as sufficient to enable adequate characterization of the majority of known processes:

- Impulse - a burst of zero duration with finite integral, representing an instantaneous process
- Constant - a pulse with finite duration, representing a constant process
- Finite Pulse String - a series of equally spaced pulses, representing a discontinuous process
- Exponential - a decaying exponential, representing a continuous, but ever decreasing, process.

In practice (i.e., in the software implementation of the model), each function specification is identified, for reason of user convenience, by means of a unique function number. As a consequence, like process characterizations, once defined, can be elicited repeatedly via their identifying number.

Viewed as a whole, D/I/R mechanisms are utilized, on a one for one basis, to describe the totality of performance characteristics associated with each fault detector. In turn, mechanisms are defined in terms of function numbers, one each for all combinations of conditions and processes. Each function number corresponds directly to a function specification which, in turn, contains both quantitative data and a reference to a particular function model. The latter then is a parametric expression which describes the general form of the performance characterization.

2.1.14 DIET vs. D/I/R Process Representation

In previous sections, frequent reference has been made to the detection, isolation and recovery process representations which constitute a D/I/R mechanism. In particular, the requirements for modeling each were developed in sections 2.1.9, 10 and 11 respectively, their relation to a D/I/R mechanism presented in section 2.1.12, and the general method utilized to specify them described in section 2.1.13.

As a final note, however, it should be recognized first, that given both a particular detector and set of environmental conditions, there exists a singular set of process representations which describe the corresponding detection/isolation/recovery sequence and second, that the set consists of four representations, one each describing the detection (D), isolation (I), error-propagation-recovery (E) and time-lost-recovery (T) facets of the

corresponding mechanism. The latter subdivision (of recovery into components I and E) is a direct consequence of the rationale presented on page 2-10, second and third items respectively.

2.2 SAMPLE FUNCTION SELECTIONS

Although the objective of this study is to develop a relatively general-purpose system reliability prediction tool, an underlying goal is its application to a specific fault tolerant computer configuration; a dual channel system consisting of input, CPU, memory and output LRU's, plus an external comparator (cf. figure 2-1).

To this end, D/I/R mechanism definitions and performance characterizations have been made for a set of fault detectors, each member of which has potential application in the subject system. Table 2-1 summarizes these, wherein the reader's leftmost column is a list of the detectors (and equivalently, the D/I/R mechanisms). The double row to the right of each detector defines the mechanism as it relates to varying environmental conditions, the latter consisting of combinations of fault subclass (Input vs. CPU etc., across the top heading row), fault type (Permanent vs. Transient, across the second heading row), and system operating mode (2 channel vs. 1 channel, down the second column from the left). In turn, each rectangle (representing a single mechanisms performance under specific conditions) contains either a zero (representing a null

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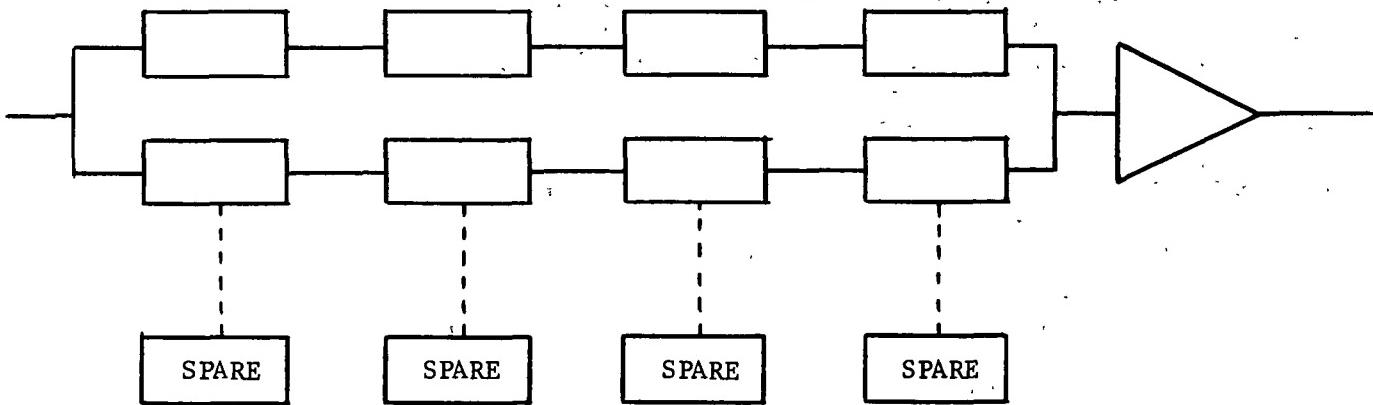
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LRU TYPE

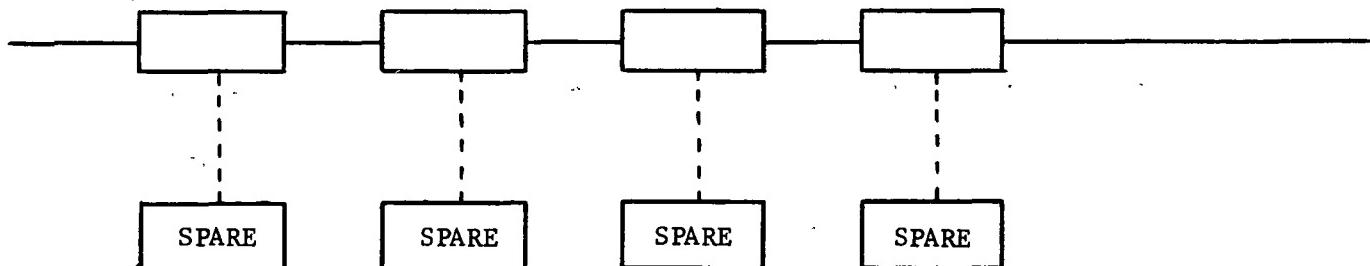
INPUT CPU MEMORY OUTPUT (COMPARATOR)

FAULT SUBCLASS

INPUT CPU BIT PLANE WORD ELECT. OUTPUT



MODE 1 CONFIGURATION (FULLY OPERATIONAL)



MODE 2 CONFIGURATION (DEGENERATE)

FIGURE 2-1
DUAL CHANNEL SYSTEM
RELIABILITY DIAGRAM

response) or a series of four numbers. In the latter case, the four correspond to detection (D), isolation (I), error-propagation-recovery (E) and time-lost-recovery (T) function numbers, respectively, as indicated by the third heading row.

The function numbers referred in Table 2-1 are defined, in Table 5-4, in terms not yet presented. The rationale leading to their specification and selection, however, is discussed at length in the remainder of this section. Prior to initiating this, though, the following points should be noted:

- individual detectors have been purposely interpreted, in terms of their scope, in a somewhat restrictive fashion. For example, software selftest can be viewed as including some form of memory addressing scheme check; in terms of this study, however, each has been interpreted to be a separate and distinct test, and categorized accordingly.

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		INPUT	CPU	MEMORY	WORD SELECT	PERM.	TRANS.	PERM.	TRANS.	OUTPUT
		D I E T	D I E T	D I E T	D I E T	D I E T	D I E T	D I E T	D I E T	D I E T
MEMORY CODE	2 ch.	o	o	o	o	1 1 1 1	1 1 1 1	o	o	o
	1 ch.	o	o	o	o	1 1 1 2	1 1 1 2	o	o	o
OUTPUT	2 ch.	9 2 1 2	9 3 1 2	9 2 1 2	9 3 1 2	9 2 1 2	9 3 1 2	9 2 1 2	9 3 1 2	o
COMPARE/VOTE	1 ch.	o	o	o	o	o	o	o	o	o
I/O WRAP-AROUND	2 ch.	11 1 1 1	o	12 2 1 1	o	12 2 1 1	o	13 2 1 1	o	11 1 1 1
	1 ch.	11 1 2 2	o	12 2 2 2	o	12 2 2 2	o	13 2 2 2	o	11 1 2 2
CPU SOFTWARE	2 ch.	o	o	10 1 1 1	o	14 2 1 1	o	15 2 1 1	o	o
SELFTEST	1 ch.	o	o	10 1 2 2	o	14 2 2 2	o	15 2 2 2	o	o
REASONABLENESS TESTS	2 ch.	2 1 1 1	2 1 1 1	16 2 1 1	16 3 1 1	16 2 1 1	16 3 1 1	16 2 1 1	16 3 1 1	o
	1 ch.	2 1 1 2	2 1 1 2	16 2 1 2	16 3 1 2	16 2 1 2	16 3 1 2	16 2 1 2	16 3 1 2	o
TIMEOUT	2 ch.	3 1 1 1	3 1 1 1	17 2 1 1	17 3 1 1	o	o	3 1 1 1	3 1 1 1	3 1 1 1
COUNTERS	1 ch.	3 1 1 2	3 1 1 2	17 2 2 2	17 3 2 2	o	o	3 1 1 2	3 1 1 2	3 1 1 2
CPU CODE	2 ch.	o	o	2 1 1 1	2 1 1 1	o	o	o	o	o
	1 ch.	o	o	2 1 1 2	2 1 1 2	o	o	o	o	o
MEMORY SUMCHECK	2 ch.	o	o	4 2 1 1	o	18 1 1 1	18 3 1 1	19 1 1 1	o	o
	1 ch.	o	o	4 2 2 2	o	18 1 2 2	18 3 2 2	19 1 2 2	o	o
INVALID INST	2 ch.	o	o	5 1 1 1	5 3 1 1	5 1 1 1	5 3 1 1	5 1 1 1	5 3 1 1	o
	1 ch.	o	o	5 1 1 2	5 3 1 2	5 1 1 2	5 3 1 2	5 1 1 2	5 3 1 2	o
READ/WRITE PROTECT	2 ch.	o	o	5 1 1 1	5 3 1 1	5 1 1 1	5 3 1 1	5 1 1 1	5 3 1 1	o
	1 ch.	o	o	5 1 1 2	5 3 1 2	5 1 1 2	5 3 1 2	5 1 1 2	5 3 1 2	o
ADDRESS FEEDBACK	2 ch.	o	o	o	o	o	o	6 1 1 1	6 1 1 1	o
	1 ch.	o	o	o	o	o	o	6 1 1 2	6 1 1 2	o
ADDRESSING SCHEME CHECK	2 ch.	o	o	7 2 1 1	o	7 2 1 1	o	8 1 1 1	o	o
	1 ch.	o	o	7 2 2 2	o	7 2 2 2	o	8 1 2 2	o	o

 TABLE 2-1
 SAMPLE COVERAGE MODEL SELECTIONS

- certain detectors, in the process of searching out faults in a particular unit, have an inherent capacity to detect faults in others as well. This capacity, though perhaps beyond the intended scope of the test is, in many cases, significant enough to warrant inclusion in the model set.
- in many instances, the ability of a detector to find faults in a particular unit, though possibly non-zero, is of insufficient magnitude to warrant consideration in the study.
- the time at which a fault actually occurs is viewed as immaterial and, in its place, emphasis is placed on the time at which it can first affect other processes.

2.2.1 Detection Function Rationale

The following subsections describe the reasoning behind the detection function selections shown in Table 2-1:

2.2.1.1 Memory Code

Any such code, for example, Hamming or simple parity, offers the same form albeit not the same degree of protection. This can be characterized by noting that:

- in a typical implementation, only memory bit plane (i.e., data) faults are protected
- the degree of protection offered is independent of the quantity of channels operating and independent of whether the fault is permanent or transient
- to the extent that a given faulty bit pattern is covered, the fault will be detected on reading the cell and, thus,

given a reasonable computer and software design, mission computation will cease prior to any consequent incorrect processing.

The latter gives rise to a belief that any such code can be modeled via an impulse. Further, since error propagation is precluded, the effective delay time between fault occurrence and fault detection is zero.

2.2.1.2 Output Compare/Vote

The technique requires the presence of at least two operating and fully synchronized channels and is, therefore, inoperative in all one-channel situations. Given two or more, it is capable of detecting all faults save those in the output unit, on their passage from channel to comparator (cf. Figure 2-1).

On the assumption that the comparator/voter receives all digital output commands, but no others, its detection rate can be characterized as a decaying exponential training off eventually to zero. (The presumption here is that all meaningful faults ultimately result in the output of erroneous values, and that the probability as to when is highest immediately following fault occurrence and ever diminishing thereafter.)

Since detection is presumed to occur on output, external, but not internal, faults are precluded from propagating.

2.2.1.3 I/O Wraparound

Test performance is independent of the quantity of channels operating. In effect, only permanent faults are detected in that transients can be observed only in the situation where they occur during performance of the test case. Such faults affect only test data.

The test, by design, checks out portions of the input and output units; indirectly, however, it affords some detection of faults in the remaining units by virtue of its dependence on them for operation of its software-based implementation.

The detection rate can be characterized as a pulse (i.e., a constant detection rate over its operating interval) in that the test consists primarily of the sequential checkout of multiple channels, each with equal likelihood of having failed. Because it is a periodic (i.e., scheduled) test, it affords little protection against fault propagation. Similarly, the delay time between fault occurrence and fault detection is dependent on when the fault occurs with respect to the scheduled test time.

2.2.1.4 CPU Software Selftest

The expression software selftest often implies a medley of assorted tests. For purposes of clarity, all but one of these, CPU test, have been broken out and categorized separately.

The residual test is seen as offering no protection against meaningful transient faults and no protection against input or output faults. By design, it detects the majority of CPU faults, with the rate function seen as a truncated decaying exponential. In this sense, the cutoff portion represents those faults which are not detected, and the non-zero duration of the truncated exponential corresponds to the run time of the test. The decaying exponential form represents a belief that the majority of faults (for reason both of test design and hardware requirements to run the test) are detected near the beginning of the test and that, from there on, it is a fight against ever-diminishing returns up through test end.

The test, by nature of its being a scheduled event, precludes

little in the way of fault propagation and, for the same reason, varies in its detect time as a function of the relationship between fault occurrence time and test run time.

Since the test operates out of memory, it offers a degree of fault detection with respect to memory-based faults.

2.2.1.5 Reasonableness Tests

The tests are interpreted to be a series of short duration checks, primarily on the validity of recently calculated data, which are performed throughout the epoch cycle. As such, their performance is unaffected by the quantity of channels operating, as well as by whether the fault is permanent or transient. By reason of inaccessibility to internal processes, output faults cannot be detected.

The use of a zero delay impulse model to characterize its detection rate function for input faults, is based on the inherent capacity of the test to preclude certain faults from entering the system. This in turn is seen as equivalent to a zero detection time.

On the other hand, CPU and memory are provided with unscheduled pulse rate functions, as warranted by their aperiodic characteristics (with respect to fault occurrence) and the consequent variant time interval prior to detection.

2.2.1.6 Timeout Counters

Such counters can be incorporated in any or all channel sub-units, though incorporation in memory is viewed as offering word select protection only. In all cases, other than CPU, the tests can be adequately characterized by means of an unscheduled zero-delay impulse, due to their essentially instantaneous service. The CPU counter, on the other hand, is presumably a watchdog timer and, thus,

has a delay time measured in milliseconds. Since the time of detection is independent of when the fault occurs (within the timeout interval), the test appears as an unscheduled pulse. Consequently, little protection against fault propagation is offered.

All forms of the test are relatively insensitive to whether the fault is permanent or transient, and totally insensitive to the quantity of operating channels.

2.2.1.7 CPU Codes

Though other forms are possible, this class of test is typically implemented as a residue or product code applied to the ALU, data path and register portions of a CPU. As such, it offers singular protection against a large subclass of CPU faults, and does so independent of whether the fault is permanent or transient. The quantity of computers operating has no impact.

Since faults are detected on occurrence, all forms of fault propagation are precluded, and, thus, the proper model is an unscheduled impulse of zero delay.

(Note that the existence of fault partitions within the CPU (from the view of this particular test) suggests rather strongly that the CPU might better have been treated as two subclasses for coverage computation purposes (i.e., one containing the ALU and the other, the control unit.))

2.2.1.8 Memory Sumcheck

The technique, which consists of occasional exclusive-or sum-checks on the contents of invariant subportions of memory, offers a significant degree of memory bit plane and word select fault detection. In the case of bit plane faults, the protection afforded is unaffected

by whether the perturbation was transient or permanent, whereas in the word select case, only permanent faults (in any meaningful sense) are detected. In both cases, the quantity of computers operating has no impact.

Since the test, by virtue of its rather excessive run time, is typically partitioned into a series of N subtests, each operating on a portion of memory, it can be characterized by a string of N impulses, typically extending beyond a single epoch cycle. Due to the scheduled nature of the test, detection time is aperiodic with respect to fault occurrence, and little protection is offered against either form of fault propagation.

As a consequence of the test being implemented in software, a small degree of protection is offered against CPU faults.

2.2.1.9 Invalid Instruction

This test, in many respects, serves more as an indicator of software errors than hardware faults. For completeness it is, however, included.

To the degree that faults are in fact detected, the protection is independent of both the quantity of operating computers, and whether the fault is permanent or transient. No protection against input and output faults is offered. The detection of CPU and memory faults, though severely limited in scope, is instantaneous and independent of the time of fault occurrence.

2.2.1.10 Read/Write Protect

The test, assumed to be implemented in hardware, serves primarily as a software error detector. It does, however, have limited hardware fault detection capabilities, and is, therefore, included.

No protection is offered in the case of input and output faults. CPU and memory faults are in select cases detectable and, to this extent, the protection is independent of the quantity of computers operating and also independent of whether the fault is permanent or transient.

Detection, when it occurs, is instantaneous and, thus, the appropriate model is the zero delay impulse.

The following, severely limited, classes of faults are detectable by this technique:

- CPU - limited instances of incorrect memory address computation
- Memory bit plane - situations where the address portion of an instruction stored in memory is, on access, incorrect to the extent of crossing a protection boundary
- Memory word select - instances where an instruction fetch is performed on an incorrect memory cell, which itself contains an out-of-range address.

In these situations, fault propagation is precluded.

2.2.1.11 Address Feedback

The technique, though seldom discussed, offers a significant degree of singular protection against memory word select faults. Implementation techniques vary, with one of the more straightforward methods consisting of the encoding of address and data, rather than merely data, on storage of a word into memory. Given then a reasonably strong code, for example, six-bit Hamming, a high percentage of addressing faults can be detected on readout via the decoding process.

Protection is instantaneous, and independent of fault occurrence time, quantity of operating computers, and whether the fault is permanent or transient. Fault propagation is precluded.

2.2.1.12 Addressing Scheme Check

Given either a 2½D or 3D memory addressing scheme (preferably the latter), this technique offers a reasonable form of memory word select verification. Its methodology, which is based on the use of coincidence for word selection, enables the bulk of the memory addressing circuitry to be verified (the exception being that fraction which is unique to the variable portion of storage).

The technique, which relies on the exclusive or sumcheck testing of a specific small subset of memory locations, detects addressing faults by virtue of the implication that correct sumcheck signifies correct addressing. The test is implemented in software and, thus, also offers a small degree of CPU and memory bit plane checkout. The latter is supplanted, to a minor extent, via the sumcheck process itself which verifies the contents of the memory subset.

Because of its software basis, the test is necessarily periodic and, therefore, incapable of precluding fault propagation. Similarly, the time required to detect is dependent on the relationship between fault occurrence time and test run time. The test is not dependent on the quantity of computers running. Little or no practical protection is offered against transient faults.

2.2.2 Isolation Function Rationale

Three functions have been selected to represent the isolation process for this particular implementation of the four LRU, dual-channel system (cf. Table 5-4).

2.2.2.1 Primary Isolation Processes

This isolator, represented as a slightly delayed impulse with unity coefficient, typifies the situation in which the fault location implied by the initiating detector was, in fact, the actual location. For example, in the case of CPU selftest, the implied location is the CPU itself and, as a consequence, the first area searched in the isolation process.

Given that the implication is correct, the corresponding determination of this fact is made after a short delay (as measured from the end of the detection process) which itself represents the duration of the isolation function.

2.2.2.2 Secondary Isolation Processes

In the situation where the fault location lies other than in the detector implied LRU, the search is both misguided (initially) and, of necessity, quite extensive in domain. Correspondingly, it is best modeled as a pulse of long duration which, in turn, represents a process with constant isolation probability throughout the total interval.

2.2.2.3 Tertiary Isolation Processes

The isolation process is most complex, and least likely prone to success, in situations where either a transient fault has occurred, or where the fault is totally unlocalized (as with detection by a comparator external to the channel). Consequently, an impulse model, with long initial delay, has been selected as reasonably representative.

2.2.3 Fault Propagation Recovery Function Rationale

Two functions have been selected to represent the fault propa-

gation aspect of the recovery process. The first of these is a pulse of long duration, and represents a situation in which the recovery probability is undiminished, from this effect, up through the end point of the pulse. It corresponds to either of two situations:

- the associated fault detector precludes any appreciable form of fault propagation
- fault propagation is of little consequence, due to the presence of an operational second channel which can be utilized for update purposes

The second function corresponds to the opposite situation, in which fault propagation is of considerable potential effect, and the function is, thus, provided in the form of a decaying exponential, whose diminishment with time represents a like decrease in recovery probability. It is utilized primarily in the combined situation of degenerate system operation and the presence of fault propagation.

2.2.4 Time Lost Recovery Function Rationale

The time lost aspect of fault recovery contends with the effect, on external-to-the-system operational requirements, of channel loss during a "fault-present" interval. In the situation where both channels were operative prior to the fault, one channel normally continues servicing external needs, and, thus, the overall effect is minimal. A long duration pulse is applied in this case.

In the situation either of previous degenerate operation or fault detection by the comparator, however, the total system is temporarily out of service, and, thus, no external processing requirements are met. (Detection by the comparator is assumed to require that both channels cease normal operation and enter into the

isolation phase concurrently.) The function selected to represent this situation is a decaying exponential with cutoff in the region of mission critical time.

2.3 TERMINOLOGY DEFINITIONS

Batch Run - The total data processing task performed at one time. It may consist of one or more run-sets.

Category 1 Switch Failure - A failure, typically of spares-switching hardware, such as to prevent proper operation of a single unit. This possibility must be accounted for in estimating the failure rate of the unit.

Category 2 Switch Failure - A failure, typically of spares-switching hardware, such as to force degeneration of the system from mode M to mode M+1.

Category 3 Switch Failure - A failure, typically of comparator or voter hardware, such as to disable the entire system.

Channel - The minimum complement of operational hardware required to perform the system computational task.

Coverage - The conditional probability, given both an on-line unit failure and sufficient spare hardware to maintain computational processes, that the failure is detected and operation is successfully re-established, consistent with application imposed time constraints.

Coverage Model - A set of equations for evaluating the ability of a system to recover from permanent or transient hardware faults in a spares-switching environment. Also, the implementation of this model in CARE2.

Degenerative Failure - Any condition which necessitates reconfiguration of the system, from Mode M to Mode M+1, in order to regain full processing capabilities.

D/I/R Mechanism - (Detection/Isolation/Recovery Mechanism) - A coverage model representation of the conditional performance characteristics of all detection, isolation and recovery processes associated with a particular fault detector. In turn, the conditions are comprised of valid combinations of fault subclass, mode, fault type and potential requirement for mode degeneration.

Dual Mode Reliability Model - A set of equations for evaluating the reliability of a system, given that the system has no more than two distinct and relevant operating modes. Also, the implementation of this model in CARE2.

Fault - An event which perturbs computational processes within the computer system and, as a consequence, requires remedial action, in the form of detection, isolation and recovery, in order to preclude an operational anomaly.

Fault Class - The total set of possible faults associated with a single stage of a computer system.

Fault Detector - A hardware or software process whose function is to recognize the occurrence of certain classes or subclasses of faults within a system.

Fault Isolator - A hardware or software process whose function is to isolate a detected fault to the responsible LRU.

Fault Recovery Process - A hardware or software process whose function is to minimize or eliminate the potentially harmful effects of a fault, given that it is properly isolated, by means of appropriate remedial actions.

Fault Subclass - A fractional portion of a fault class, distinguished from other subclasses within the stage by either its unique susceptibility, or lack thereof, to recognition and treatment by one or more fault detection, isolation and/or recovery processes.

FTF - (Fault Tolerant Feature) - A hardware or software based process included in the system for the purpose of detecting, isolating or recovering from certain classes or subclasses of faults.

Hybrid Channel - A fault tolerant computer system in which the component stages contain unequal quantities of on-line LRU's, thereby precluding division of the system into discrete channels.

LRU - (Least Replaceable Unit) - The smallest system component which may be switchably replaced by an equivalent spare, in the event of its failure.

Major Cycle - The time interval between repetitions of the total set of scheduled detectors (i.e., the time after which the total set is repeated).

Note: In CARE2, this value is calculated internally.

Minor Cycle - The time interval between repetitions of the most frequent scheduled detector.

Note: In CARE2, all scheduled detector periods must be integer multiples of the minor cycle.

Mode - One of the possible hardware configurations in which the system can operate. In general, mode M requires more on-line units than mode M+1, and is the preferred operating configuration.

Operational Anomaly - The consequence of a fault which for reason of non-detection, incorrect isolation or unsuccessful recovery, is not remedied and therefore manifests itself in the issuance of improper control signals from the computer system.

Parameter - A variable, either defaulted, input, or precalculated, which is meaningful in either the reliability or coverage model description.

Note: In CARE2, certain parameters, such as the inverse dormancy factor K, cannot be directly input by the user.

Parameter Vector - A one dimensional Fortran array which contains the values of a single parameter for all stages in the system.

Permanent Fault - A fault which, because of its permanent nature, requires either the use of a spare LRU or degeneration in the process of recovering from its effects.

Run - The process of computing system reliability, versus time, for a given list of equation numbers (models) and a fixed set of model parameters.

Run-set - One or more runs, with possible variation of one reliability parameter type (for all stages), through the use of array PARAM. (Coverage parameters may not be varied in this way, for reason of the data base format structure.) Data base management operations take place between run-sets.

Scheduled Detector - A fault detector, usually software, which is initiated at regular periodic intervals.

Spare LRU - A single LRU contained in the spares pool. Equivalent to the term 'standby spare'.

Spares Checkout - The process of testing a standby spare, for proper operation, during the interval between occurrence of a permanent fault and commitment of the particular spare as the replacement.

Spares Pool - The total set of standby LRU's available for substitution in the event of permanent failure in one of the on-line LRU's. Note that substitution is conditioned by a requirement that both the failed LRU and its replacement be contained in the same stage.

Spares Reassignment - The process of releasing the operational LRU's in a defunct channel to the spares pool. Given that the specific computer system design allows for reassignment, the process takes place at the time of degeneration from Mode M to Mode M+1.

Stage - The total set of identical LRU's, including both on-line and standby devices, contained in the system (cf. page 4-2).

Standby Spare - A single LRU contained in the spares pool. Equivalent to the term 'spare LRU'.

System - The full complement of hardware and software comprising a fault tolerant computer configuration. In CARE2, the complex of coverage and hardware reliability data associated with a single execution run defines the current system.

TMR - (Triple Modular Redundancy) - A fault tolerant computer system consisting, initially, of three parallel and active channels in series with a majority voting element. In the event of a singular channel failure, the voter maintains correct system outputs.

Transient Fault - A fault which, because of its temporary nature, requires neither the use of a spare LRU nor degeneration in the process of recovering from its effects.

Transition - The process of switching the computer system operating mode (from Mode M to Mode M+1).

Unit Time - An arbitrary time interval, as for example seconds or hours, used in conjunction with failure rates, detection rates, reliability, etc.. Although consistent units must be utilized within a model (i.e., Reliability or Coverage), there is no need to use common units in separate models.

Unscheduled Detector - A fault detector, usually hardware, in which the detection process is triggered either directly, or effectively in outward appearance, by the occurrence of a fault.

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SECTION 3

MATHEMATICAL MODELS

The total system reliability of a redundant computer configuration can be expressed mathematically in a number of ways. These expressions all tend to be rather cumbersome, however, and therefore one of the objectives of this study was to devise formulations that can be evaluated efficiently by computer. A second, and equally important goal, was that the formulations be of a sufficiently general nature as to provide considerable design flexibility to the user. The following sections present both the end result of these efforts and, as an interpretation aid, a listing and definition of all parameters.

3.1 DUAL MODE RELIABILITY MODEL

The Dual Mode Reliability Model subprogram, with respect to initial plans, has been extended in scope significantly such that it now includes not only dual channel capability, but a variety of others as well. These include both N channel (where N is a user specified integer) and Hybrid configuration (where the quantity of active units differs between stages).

The reliability equations utilized in encoding the model, as well as a functional description of each, are presented in this section. Subscripts and other simple variables used therein are as follows:

- x - Refers to the set of LRU's which constitute a particular stage of the reliability model
- y - Refers to the operating mode
- t - Either the independent time variable or a dummy time variable (made clear by context)
- r - A dummy time variable for integration or function referencing
- i,j,l - Dummy integer variables for counting or function referencing.

3.1.1 G: Fortran DCG(IUN,MD,I,T) - "The probability of using exactly i spares by time t."

$$G(x,y,i,t) = \begin{cases} e^{-(\gamma_{x,y})t} * (\delta_{x,y})^i * \left(\frac{(K_x)(Q_{x,y})(C_{x,y})(\delta_{x,y})^{-1+i-1}}{i!} \right)^* \\ (1-e^{-(\mu_x)t})^i * e^{-(Q_{x,y})(\lambda_x)t} \\ \text{for } K < \infty \\ e^{-(\gamma_{x,y})t} * \left(\frac{(Q_{x,y})(C_{x,y})(\lambda_x)t}{i!} \right)^i * e^{-(Q_{x,y})(\lambda_x)t}, \\ \text{for } K = \infty \end{cases}$$

This function expresses the probability of using exactly i of the available spares by time t under the following assumptions:

- $Q_{x,y}$ LRU's are required, with standby and active LRU's having the constant failure rates μ_x and $\lambda_x = K_x \mu_x$, respectively.
- The coverage factor, given that the ℓ th spare tested following a detected failure is the first operational spare, is $C_{x,y} \delta_{x,y}^{\ell-1}$. (Note: coverage is defined here as the conditional probability of successful recovery given that an error occurs and sufficient hardware is available. If recovery is possible, the system operational mode is determined solely by the remaining available hardware.)
- Non-recoverable transients occur at the rate $\gamma_{x,y} = \gamma'_{x,y} * (1-P_{r_{x,y}})$ per second. In the case of recoverable transients, the system resumes operation in the same mode as was in effect prior to the transient.

The first term in the above expression, then, is the probability that no non-recoverable transients occur by time t . The product of the remaining terms is the probability that exactly i LRU's sustain failures by time t , either while operating or prior to the time they are needed. (Notice that a failure in a spare LRU is not counted here until that spare would have been used following a failure in an operating LRU.) To verify this, we observe that the reliability of an r -on- m configuration (r spares on m operating elements) having active and standby failure rates λ and μ , respectively, is equivalent to that of an r on $\lambda m / \mu$ configuration having a constant failure rate μ for both active and standby elements.* Further, since with probability $C_{x,y} / \delta_{x,y}$, the system can recover from a failure on the condition that it can also find and successfully activate a standby spare, the rate of such recovered failures is $\lambda C_{x,y} / \delta_{x,y}$, and hence the effective number of active elements is $K Q_{x,y} C_{x,y} / \delta_{x,y} \stackrel{\Delta}{=} M$. The probability that exactly i spares are used by time t is thus the product of the probability

$$\binom{M+i-1}{i} (1 - e^{-\mu_x t})^i e^{-(M-1)\mu_x t}$$

that exactly i recoverable failures occur in the first $M+i-1$ LRU's, the probability $e^{-\mu_x t}$ that the i^{th} spare is operational, the probability $\delta_{x,y}^i$ that i spares are successfully tested, and the probability

$\exp \left[-Q_{x,y} \left(1 - C_{x,y} / \delta_{x,y} \right) \lambda_{x,y} t \right]$ that no non-recoverable failures occur during this period.

* C.F. J. J. Stiffler, "On the Efficacy of R-on-M Redundancy", IEEE Trans. on Reliability, (to appear).

3.1.2 R_u : Fortran DCRU(IUN,MD,L,TAU) - "The probability of using at most ℓ spares by time τ ."

$$R_u(x, y, \ell, \tau) = \sum_{i=0}^{\ell} G(x, y, i, \tau)$$

The probability of using at most ℓ spares is clearly the sum of the mutually exclusive probabilities that exactly i spares are used, for $i = 0, 1, \dots, \ell$.

3.1.3 H: Fortran DCH(IUN,TAU) - "The probability density of a degenerative failure in stage x at time τ ."

$$H(x, \tau) = \begin{cases} Q_{x,1} \lambda_x \sum_{i=0}^{(S_x)} \left\{ G(x, y=1, [(S_x)-i], \tau) * (C'_x)(\delta'_x)^i * (1-e^{-(\mu'_x)\tau})^i \right\}, \\ \text{for } K < \infty \\ \lambda_x Q_{x,1} (C'_x) * G(x, y=1, (S_x), \tau), \\ \text{for } K = \infty \end{cases}$$

The conditional probability density of a degenerative failure at time τ , given exactly $S_x - i$ prior failures, is equal to the product of the probability density $Q_{x,1} \lambda_x$ of a failure in an operational unit and the probability $(1-e^{-(\mu'_x)\tau})^i$ that the i remaining spares have failed by time τ , times the probability $C'_x(\delta'_x)^i$ that it is possible to recover from this event. The product of this conditional probability density with the probability that exactly $S_x - i$ failures have occurred by time τ , summed over all $i = 0, 1, \dots, S_x$, is thus the desired probability density.

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3.1.4 S: Fortran DCS(IUN,T,TAU) - "The conditional probability that the set of units in stage x can remain operational in mode y = 2, from time τ to time t, given that the mode changed from 1 to 2 at exactly time τ ."

$$S(x, t, \tau) = \left\{ \begin{array}{l} \sum_{\ell=0}^{(S_x)} \left[\sum_{j=0}^{(S_x)-\ell} \left\{ \binom{(S_x)-\ell}{j} * (1-e^{-(\mu_x)\tau})^{(S_x)-\ell-j} * e^{-j(\mu_x)\tau} * G(x, y=1, \ell, \tau) * R_u(x, y=2, j', (t-\tau)) \right\} \right] \\ \text{for } K < \infty \\ \sum_{\ell=0}^{(S_x)} \left[G(x, y=1, \ell, \tau) * R_u(x, y=2, [(S_x)-\ell], (t-\tau)) \right] \\ \text{for } K = \infty \end{array} \right.$$

where $j' = \begin{cases} j, & \text{no spares reassignment} \\ j + Q_{x,y=1} - Q_{x,y=2}, & \text{reassignment allowed} \end{cases}$

$$[(S_x)-\ell]' = \begin{cases} [(S_x)-\ell], & \text{no spares reassignment} \\ [(S_x)-\ell] + Q_{x,1} - Q_{x,2}, & \text{reassignment allowed} \end{cases}$$

The product of the first three terms in the summand is the probability that exactly j of the $S_x - \ell$ unused spares are still operational at time τ . The fourth term is the probability that exactly ℓ spares have been used in mode 1 by time τ , and the fifth term the probability that the remaining j' spares are sufficient to keep the unit operating in mode 2 for the next $(t-\tau)$ seconds. The sum over all $\ell = 0, 1, \dots, S_x$ and $j = 0, 1, \dots, S_x - \ell$ is thus the probability of the event described.

3.1.5 T: Fortran DCT(IUN,J) - "The probability that the system will survive until time t , and that a failure in the set of units in stage x will have forced degeneration from mode $y = 1$ to mode $y = 2$."

$$T(x,t) = \begin{cases} \int_0^t \left[\prod_{x \neq x} \left\{ S(\bar{x}, t, \tau) \right\} * R_u(x, y=2, \tau, (t-\tau)) * H(x, \tau) * e^{-(\hat{\lambda}_2)^2 \tau} \right] d\tau, & \text{for } Q(x,1) > Q(x,2) \\ 0, & \text{for } Q(x,1) \leq Q(x,2) \end{cases}$$

The integrand is the product of the probability density of a failure in unit x at time τ (3rd term), the probability that the unit functions successfully for the next $t-\tau$ seconds in mode 2 (2nd term), the probability that all other units remain in operation until time τ in mode 1 and from time τ to time t in mode 2 (1st term), and the probability that no category-two failures occur during this time (4th term). Since a degenerative failure can occur any time during the interval $0 < \tau < t$, $T(x,t)$ is the integral of this density function over that interval.

3.1.6 T_2 : Fortran DCT2(J) - "The probability that the system will survive until time t , and that a category 2 switch failure will have forced degeneration from mode $y = 1$ to mode $y = 2$."

$$T_2(t) = (\hat{\lambda}_2)(C_2) \int_0^t \left[\left\{ S(x, t, \tau) \right\} * e^{-(\hat{\lambda}_2)\tau} \right] d\tau$$

Here the 1st term in the integral is the probability that all units function successfully in mode 1 until time τ and in mode 2 from time τ to time t . The product $\hat{\lambda}_2 C_2 e^{-\hat{\lambda}_2 \tau}$ is the probability density of a category-two failure at time τ times the conditional probability C_2 that recovery from such a failure is successful. The integral of this quantity over all τ , $0 < \tau < t$, is therefore the result sought.

3.1.7 R: Fortran DCR(J, UNITR, RELM1, RSYS) - "The system reliability at time t ."

$$R(t) = \left[\prod_x \left\{ R_u(x, y=1, S_x, t) \right\} * e^{-(\hat{\lambda}_2)t} + T_2(t) + \sum_x \left\{ T(x, t) \right\} \right] e^{-(\hat{\lambda}_3)t}$$

The first term here is the product of the probability that each of the units function until time t in mode 1 and that no category-two failures occur during that time. The remaining two terms represent the probabilities that the system successfully survives until time t , with a degeneration occurring sometime during that interval because of a category-two switch failure, and because of a degenerative failure in one of the units,

respectively. The sum of these three terms multiplied by the probability that no category-three failures occur during the period in question is thus the probability that the system operates successfully over the entire t-second interval.

The function also computes system and stage reliabilities, assuming mode 1 operation alone, and returns the values as RELM1 and array UNITR, respectively. The expressions for these values are subsets of the above equation:

$$R(t, y=1) = \left[\prod_x R_u(x, y=1, S_x, t) \right] e^{-(\hat{\lambda}_2 + \hat{\lambda}_3)t}$$

$$R_x(t, y=1) = R_u(x, y=1, S_x, t)$$

3.2 COVERAGE MODEL

The function subprogram COVAGE, in concert with certain other routines, is utilized to calculate coverage for application in both the dual mode reliability model and original CARE equations 2 and 3. This section presents the equations utilized therein, as well as corresponding functional descriptions.

The basic coverage calculation described herein returns a single value C(s) corresponding to a specific system operating mode, fault type (permanent or transient), quantity of spares tested, and fault subclass. The calculative process is then iterated, via separate calls to COVAGE, for each combinatorial set of conditions.

Since the ensuing reliability model accepts coverage values at the stage rather than subclass level, it is necessary to preprocess the above according to the relation

$$C(I) = \sum_{\sigma, L_\sigma=I} (d_\sigma C_\sigma)$$

where C(I) is a coverage factor

of stage I*, and is computed as an average of the C_σ factors returned, as $C(s)$, by COVAGE (cf. section 3.2.2), weighted by the fractional fault occurrence rate d_σ for each fault subclass σ associated with the stage. The association of stage and fault subclass is specified by the user when selecting input values for the linkage variable L_σ (IFSC), and the relative fault rate d_σ (FRAC), for each subclass used.

In turn, the required delta coverage inputs (representing the diminished recovery probability arising from trial repair with a previously failed spare), are computed in accordance with the expression

$$\delta(I) = C(I, s=2) / C(I, s=1)$$

where s is the quantity of spare LRU's which must be trial tested during the recovery process (i.e., $s-1$ having failed the test).

In perspective then, it should be noted that the following coverage and delta coverage values are computed, and delivered to the reliability model, for each stage of the object computer system:

- Coverage - $C(I)$
 - $C_{x,y=1}$ - permanent fault, continued Mode 1 operation
 - $C_{x,y=2}$ - permanent fault, continued Mode 2 operation
 - C'_x - permanent fault, transitional from Mode 1 to 2
 - P_r - transient fault, continued Mode 1 operation
 - $P_{r,x,y=1}$ - transient fault, continued Mode 2 operation
 - $P_{r,x,y=2}$ - transient fault, transitional from Mode 1 to 2
- Delta Coverage - $\delta(I)$
 - $\delta_{x,y=1}$ - permanent fault, continued Mode 1 operation
 - $\delta_{x,y=2}$ - permanent fault, continued Mode 2 operation
 - δ'_x - permanent fault, transitional from Mode 1 to 2

* Note that, in the reliability model, x was used to denote a stage.

3.2.1 Subscripts and Simple Variables

t, τ, α, v, η - dummy variables for integration, summation and substitution.

i, j, k, l - detector number. The choice of variable is determined as:

i - general-purpose detector symbol (used on either side of an equation)

j - scheduled detector symbol (right side of equation only)

k - non-scheduled detector symbol (right side of equation only)

l - non-scheduled impulse detector symbol (right side of equation only). Specifically, l_1, l_2, \dots, l_{m_i} comprises the set of non-scheduled impulse detectors, excluding the i^{th} , which have the same delay (t_{d_i}) as detector i , given m_i such detectors.

3.2.2 C: Fortran COVAGE - "The sum of coverage contributions of all competing D/I/R mechanisms given that s spares must be checked prior to recovery."

$$C(s) = \sum_i C(i,s)$$

The coverage value $C(s)$ associated with a single fault subclass under given spares status and computer system operating conditions is clearly the summation of individual D/I/R mechanism contributions ($C(i,s)$) over all i .

3.2.3 C(i,s): Fortran COVAGE - "The coverage contribution of the D/I/R mechanism associated with detector i, when all competing detectors are accounted for and when s spares must be checked during the recovery process."

$$C(i,s) = p_i p'_i p_s^s \int_0^\infty g_i(\tau') r'_i(\tau') \int_0^\infty h_i(\tau'' - s\tau_s) r''(\tau' + \tau'') d\tau'' d\tau'$$

The detection probability density function for the i^{th} detector is $p_i g_i(\tau')$ and the associated isolation density function is, by definition, $p'_i h_i(\tau'')$. If s spares must be checked in order to recover successfully from a fault, the overall recovery probability is decreased by the factor p_s^s (with p_s the probability of successfully checking out a spare) and the isolation delay is effectively increased by the factor $s\tau_s$. The term $C(i,s)$ is thus equal to the conditional probability that the system can still recover given a τ' -second detection delay times the detection probability density function, multiplied by the conditional probability that the system can recover given that it has survived a τ' -second detection delay and must in addition undergo a total of $(\tau' + \tau'')$ seconds down-time, times the corresponding isolation density function, the whole thing integrated over all τ' and τ'' , and multiplied by p_s^s .

3.2.4 $g_i(\tau)$: Fortran CVGS, CVG2 and CVG1 - "The conditional detection rate of the i^{th} detector when in competition with all other detectors."

The function $g_i(\tau)$ represents the i^{th} detectors' conditional detection rate when competitive processes are taken into account. In turn, the corresponding detection probability density function

is then expressed as $p_i g_i(\tau)$. The rate itself is determined by using one of three equations depending on the nature of the i^{th} detection process, i.e., whether it is scheduled or unscheduled and, in the latter case, whether it is a finite or impulse detector.

- Scheduled $g_i(\tau)$: Fortran CVGS

$$g_i(\tau) = \begin{cases} \prod_k [1 - p_k F_k(\tau - t_{d_k})] g'_i(\tau), & \text{for } 0 \leq \tau \leq n_i T_{mr} \\ 0, & \text{otherwise} \end{cases}$$

The product over k represents the probability that none of the non-scheduled detectors has detected the fault by time τ (note that $F_k(t) = 0$ for all $t < 0$). The function $g'_i(\tau)$ is the conditional detection rate of the i^{th} scheduled detector when competing with the other operative scheduled detectors only (see Section 3.3.4).

- Finite Non-Scheduled $g_i(\tau)$: Fortran CVG2

$$g_i(\tau) = \prod_{k \neq i} [1 - p_k F_k(\tau - t_{d_k})] * \left[1 - \sum_j p_j \int_0^\tau g'_j(\eta) d\eta \right] * f_i(\tau - t_{d_i})$$

The product over k is the probability that none of the other non-scheduled detectors has sensed the fault by time τ . Similarly, the second term is the probability that none of the scheduled detectors has succeeded by time τ . The last term is, of course, the detection rate of the detector in question in the absence of any competition.

- Non-Scheduled Impulse $g_i(\tau)$: Fortran CVG1

$$g_i(\tau) = \left[1 - \sum_{v=1}^{m_i} \frac{(-1)^{v+1}}{v+1} \sum_{\ell_1 < \ell_2 < \dots < \ell_v} p_{\ell_1} p_{\ell_2} \dots p_{\ell_v} \right] *$$

$$\prod_{\substack{k \neq i \\ k \neq \ell_1, \ell_2, \dots, \ell_{m_i}}} \left[1 - p_k F_k(t_{d_i} - t_{d_k}) \right] * \left[1 - \sum_j p_j \int_0^{t_{d_i}} g_j'(\eta) d\eta \right] * \mu_0(\tau - \tau_{d_i}),$$

$$\text{for } f_i(\tau) = \mu_0(\tau - \tau_{d_i})$$

where $\mu_0(x)$ is a unit impulse at $x = 0$

This expression has the same interpretation as the previous one except that the $f_i(\tau)$ is an impulse function. The first term assumes a different form here, reflecting the fact that if v impulse detectors having simultaneous delays τ_d all detect the same fault, only one of them is declared the winner. In this event, it is assumed that each of the successful detectors has the probability $1/v$ of being declared the victor. The first term in this expression, then, is the conditional probability that the impulse detector in question is declared the winner over its simultaneously occurring impulse competitors, given that it is, in fact, successful in detecting the error. The second term is the probability that none of the other non-scheduled detectors finds the error prior to time τ_{d_i} . The remaining terms are as previously defined.

3.2.5 $g'_i(\tau)$: Fortran CVGP4 and CVGP3 - "The conditional detection rate of the i^{th} scheduled detector when in competition with all other scheduled detectors."

The function $g'_i(\tau)$ represents the i^{th} scheduled detectors' conditional detection rate when competitive scheduled processes only are taken into account. It is determined using either of two equations depending on the nature of the i^{th} detection process, i.e., whether it is a finite or impulse detector.

- Finite $g'_i(\tau)$: Fortran CVGP4

$$g'_i(\tau) = \begin{cases} \frac{1-F_i(\tau)}{n_i T_{mr}} + \frac{n_i}{n_c} \sum_{\ell=1}^{n_c/n_i} \frac{1}{n_i T_{mr}} \int_0^\tau \prod_{j \neq i} [1-p_j F_j^{-\ell} (\eta-\tau+n_i T_{mr}+t_{d_i}-t_j^\ell)] * f_i(\eta) d\eta \\ \text{for } 0 \leq \tau \leq \Delta t_i \\ \frac{n_i}{n_c} \sum_{\ell=1}^{n_c/n_i} \frac{1}{n_i T_{mr}} \int_0^{\Delta t_i} \prod_{j \neq i} [1-p_j F_j^{-\ell} (\eta-\tau+n_i T_{mr}+t_{d_i}-t_j^\ell)] * f_i(\eta) d\eta \\ \text{for } \Delta t_i < \tau \leq n_i T_{mr} \\ 0, \text{ otherwise} \end{cases}$$

The first term in the expression for $g'_i(\tau)$ when $0 \leq \tau \leq \Delta t_i$ represents the conditional detection rate of the i^{th} scheduled detector given that the error occurs sometime during the period during which that detector is active (e.g., while the associated diagnostic program is running).

Note: It is assumed here, and throughout this discussion, that the probability that an error is detected by a given detector during a given interval is equal to the integral of its probability density function over that interval. Furthermore, each portion of a scheduled test is assumed to have a probability of detecting a particular fault only during its first exposure to that fault. Thus, for example, if a fault occurs when a given scheduled program of T_0 seconds duration is in progress and has t_0 seconds left to run, and if the fault is not detected during those t_0 seconds, the fault has a chance of being detected only during the first $T_0 - t_0$ seconds of that program when it is next run, and if it is not detected then, it will not be detected by that program during any subsequent runs.

The l^{th} term in the summation in both expressions for $g_i'(\tau)$ (i.e., for $0 \leq \tau \leq \Delta t_i$ and for $\Delta t_i < \tau \leq n_i T_{\text{mr}}$) is the conditional detection rate of the i^{th} scheduled detector, given that the fault occurs either during or following the l^{th} scheduling of that detector, but is not detected during that scheduled run. Accordingly, the product denotes the probability that none of the other scheduled detectors exposed to the fault during the τ seconds prior to its detection is successful in detecting it. This product, multiplied by the detection rate function $f_i(\eta)$ associated with the i^{th} detector and averaged over all η gives the desired result. Summing these conditional detection rates over a major cycle then yields the desired detection rate for the i^{th} scheduled detector when competing only with other scheduled detectors. Note that there are exactly n_c/n_i repetitions of the i^{th} detector during one major cycle. (A major cycle is defined as the overall period of the combined scheduled tests.)

- Impulse $g'_i(\tau)$: Fortran CVGP3

$$g'_i(\tau) = \begin{cases} \frac{n_i}{n_c} \sum_{\ell=1}^{n_c/n_i} \frac{1}{n_i T_{mr}} \prod_{j \neq i} \left[1 - p_j F_j^{-\ell} \left(-\tau + n_i T_{mr} + t_{d_i} - t_j^{\ell} \right) \right] \\ \text{for } 0 \leq \tau \leq n_i T_{mr} \text{ and } f_i(\tau) = \mu_0 t_{d_i} \\ 0, \text{ otherwise} \end{cases}$$

This expression is simply a specialization of the previous expression for the case in which $f_i(\tau)$ represents a scheduled impulse detector (i.e., $f_i(\tau)$ is an impulse function).

3.3 PARAMETER DEFINITIONS AND APPLICABILITY

The quantity of parameters contained in CARE2, with reference to the original CARE program, has of necessity increased rather significantly. In particular, the total set now consists of:

- CARE/CARE2 compatible parameters - Variables retained from the original CARE program for use in CARE2
- Dual Mode Reliability Model parameters - Variables which were introduced to allow implementation of Equation #7
- Coverage Model parameters- Variables which were introduced to allow calculation of coverage.

Table 3-1 lists the major parameters currently utilized in both the models and their Fortran implementation, and denotes their applicability with respect to both coverage and each of the seven basic reliability forms (i.e., equations 1-6 of original CARE and equation 7 as added in CARE2). In addition, it provides a categorization of each with respect either to its source or its use as a model output.

These same parameters are then defined, in Table 3-2, in the form a, A(N), alpha, where:

- a - is the symbol used in analytic expressions
- A(N) - is the Fortran mnemonic, with subscripts where applicable
- alpha - is the parameter name.

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TABLE 3-1
PARAMETER/MODEL APPLICABILITY

Parameter	Coverage Model	Reliability Model/ Equation Number						
		1	2	3	4	5	6	
C	R	-	I*	I*	-	-	-	I*
C'	R	-	-	-	-	-	-	I*
C ₂	-	-	-	-	-	-	-	I
C _σ	C	-	-	-	-	-	-	Note 1
d _σ	I	-	I	I	-	-	-	I Note 1
δ	R	-	-	-	-	-	-	I*
δ'	R	-	-	-	-	-	-	I*
F _i (η)	C	-	-	-	-	-	-	-
$\bar{F}_i^l(\eta)$	C	-	-	-	-	-	-	-
F _j ^l (η, i)	C	-	-	-	-	-	-	-
f _i (τ)	I	-	-	-	-	-	-	-
g _i (τ)	C	-	-	-	-	-	-	-
g' _i (τ)	C	-	-	-	-	-	-	-
h _i (τ)	I	-	-	-	-	-	-	-
γ	-	-	-	-	-	-	-	C
γ'	-	-	-	-	-	-	-	I
IET	S	-	-	-	-	-	-	-
IGENC	I	-	-	-	-	-	-	-
IGENP	I	-	-	-	-	-	-	-
K	-	C	C	C	C	-	-	C
L _σ	I	-	I	I	-	-	-	I Note 1
γ	-	I	I	I	I	I	I	I
Σλ	-	-	-	-	-	-	-	C

cf. continuation sheet 2 of this table for explanatory symbols and notes.

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TABLE 3-1 (Cont.)

<u>Parameter</u>	<u>Coverage Model</u>	<u>Reliability Model/ Equation Number</u>						
		<u>1</u>	<u>2</u>	<u>3</u>	<u>4</u>	<u>5</u>	<u>6</u>	<u>7</u>
$\hat{\lambda}_2$	-	-	-	-	-	-	-	I
$\hat{\lambda}_3$	-	-	-	-	-	-	-	I
MD	S	-	-	-	-	-	-	S
μ	-	I	I	I	I	-	-	I
N	-	I	-	-	-	-	-	-
n_c	C	-	-	-	-	-	-	-
n_i	I	-	-	-	-	-	-	-
P	-	-	-	-	-	I	-	-
p_i	I	-	-	-	-	-	-	-
p'_i	I	-	-	-	-	-	-	-
$p_i f_i(\tau)$	C	-	-	-	-	-	-	-
$p'_i h_i(\tau)$	C	-	-	-	-	-	-	-
p_r	R	-	-	-	-	-	-	I*
p_s	I	-	-	-	-	-	-	-
Q	-	-	I	I	-	-	-	I
R	-	R	R	R	R	R	R	R
$r_i(\tau', \tau'')$	C	-	-	-	-	-	-	-
$r'_i(\tau')$	I	-	-	-	-	-	-	-
$r''_i(\tau' + \tau'')$	I	-	-	-	-	-	-	-
RSGN	-	-	-	-	-	-	-	I
RV	-	I	I	I	I	I	-	-
S or r	-	I	I	I	I	-	-	I

TABLE 3-1 (Cont.-2)

<u>Parameter</u>	<u>Coverage Model</u>	<u>Reliability Model/ Equation Number</u>					
		<u>1</u>	<u>2</u>	<u>3</u>	<u>4</u>	<u>5</u>	<u>6</u>
s	S	-	-	-	-	-	-
σ	S	-	-	-	-	-	-
t_{d_i}	I	-	-	-	-	-	-
Δt_i	I	-	-	-	-	-	-
$t_{d_i} + \Delta t_i$	C	-	-	-	-	-	-
T_i	C	-	-	-	-	-	-
$t_j^f(i)$	C	-	-	-	-	-	-
T_{mr}	I	-	-	-	-	-	-
τ_s	I	-	-	-	-	-	-
W	-	I	I	I	I	I	-
Z	-	I	I	I	I	I	-

C - computed by program

I - input by user or default table

I* - input by user, default table, or coverage model

R - result (i.e., output) of model

S - subscript used for summation, selection, etc.

-- not applicable

Note 1: These parameters are used to specify the relationship between coverage subclasses and reliability stages for equations 2, 3 and 7. They are included in the table for reason of completeness although, as a consequence, the relationship to column headings is somewhat strained.

TABLE 3-2
PARAMETER DEFINITIONS

<u>Symbol</u>	<u>Fortran Mnemonic</u>	<u>Name</u>	<u>Definition</u>
C	C1(I), C2(I)	Coverage factor	The conditional probability, for mode equals 1, 2 respectively, that the system can recover from a permanent hardware failure in an LRU of stage I, given that sufficient spare hardware is available.
C'	CTR(I)	Transitional coverage factor	The conditional probability that the system can recover from a permanent failure in an LRU of Stage I, given that no spares are available and hence that the system must degenerate from Mode M to Mode M+1.
C ₂	CCSF	Switch failure coverage factor	The coverage factor associated with recovery via degeneration, due to a category 2 switch failure.
C _σ	COVAGE	COVAGE returned valve	The coverage factor for fault subclass σ under a given set of conditions i.e., given values of MD, IET and JS in the COVAGE argument list.
d _σ	FRAC	-	The fraction of class (i.e., stage) faults which are attributed to member subclass σ .
δ	CD1(I), CD2(I)	Delta coverage factor	A term defined by the equation $C_i = C \delta^i$, with C_i the conditional probability, for Mode equals 1, 2 respectively, that the system can recover given that the first i of $i+1$ or more spares has failed in the idle state, that the next has not, and that recovery is initially attempted utilizing the i failed spares.

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<u>Symbol</u>	<u>Fortran</u> <u>Mnemonic</u>	<u>Name</u>	<u>Definition</u>
δ'	CDTR(I)	Delta transitional coverage factor	A term, defined by the equation $C_i' = C(\delta)^i$, with C_i the conditional probability of recovery given that all i of the remaining spares have failed and that all i are tested to ascertain this prior to degeneration.
$F_i(\eta)$	--	Cumulative detection probability function	The integral of the function $f_i(\tau)$, i.e., the probability that an ideal detector will detect an error within $\eta + \tau_{d_i}$ time units after its occurrence. Note: It is recommended that the user formulate the integrals for any general function models created, and provide these as associated integral models.
$\bar{F}_i^l(\eta) =$ $(1 - F_i^l(\eta))$	--	--	Probability of non-detection (with $F_i^l(\eta) \stackrel{\Delta}{=} F_i(\eta)$).
$F_j^l(\eta, i)$	--	--	The probability that an ideal scheduled detector (with a detection rate identical to that of detector j) will detect a fault within η time units after the initial delay, when detector j is scheduled to begin $t_j^l(i)$ time units after the occurrence of a fault.
$f_i(\tau)$	--	--	The user specified conditional detection rate of detector i in the absence of any competitive detection processes.
$g_i(\tau)$	CVGS, CVG1, CVG2	--	The conditional detection rate of the i th detector when in competition with all other detectors.

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<u>Symbol</u>	<u>Fortran</u> <u>Mnemonic</u>	<u>Name</u>	<u>Definition</u>
$g_i'(\tau)$	CVGP3, CVGP4	--	The conditional detection rate of the i^{th} scheduled detector when in competition with all other scheduled detectors.
$h_i(\tau)$	-	Isolation rate function	The user specified isolation rate of isolator i .
γ	GM1(I), GM2(I)	System transient failure rate	The product $\gamma' \cdot (1 - P_f)$ for a unit of stage I, and for mode equals 1,2 respectively.
γ'	GMP(I)	Transient failure rate	The rate at which transient hardware errors take place in on-line units of stage I. Expressed in failures per unit time.
--	IET	Fault type code	A code which specifies the "duration" of a fault. Equal to: - 1 for permanent faults - 2 for transient faults.
--	IGENC(I)	Coverage calculation flag	An integer variable which conditionally specifies the source of permanent fault coverage factors for stage I: - for $IGENC < 0$, coverage is calculated prior to each run-set - for $IGENC = 0$, coverage is not calculated (i.e., either input or defaulted) - for $IGENC > 0$, coverage is calculated prior to the first run-set only. Note: A negative coverage value input by the user serves as a higher precedence command, and forces calculation of a "replacement" value, given only that coverage itself is applicable to the corresponding reliability model.

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<u>Symbol</u>	<u>Fortran</u> <u>Mnemonic</u>	<u>Name</u>	<u>Definition</u>
--	IGENP(I)	Transient recovery calculation flag	An integer variable similar to IGENC, except that transient fault recovery probabilities (P_r) are the candidates for calculation.
K	K(I)	Inverse dormancy factor	The ratio of λ / μ for LRU's of stage I.
L_σ	IFSC	Fault class indicator	A pointer or linkage to fault subclass σ , wherein the subclass accounts for a fractional portion (d_σ) of the faults which occur in stage L_σ of the system.
λ	LAM(I)	On-line failure rate	The rate at which permanent hardware failures take place in on-line units of stage I. Expressed in failures per unit time.
$\Sigma \lambda$	SUMLAM	Simplex on-line failure rate	The sum of on-line failure rates over units of all stages, for the purpose of calculating simplex reliability.
$\hat{\lambda}_2$	SLH2	Category 2 switch failure rate	The occurrence rate of permanent hardware failures which cause degeneration from mode M to mode M+1. Expressed in failures per unit time.
$\hat{\lambda}_3$	SLH3	Category 3 switch failure rate	The occurrence rate of permanent hardware failures which cause total system failure. Expressed in failures per unit time.
--	MD	Mode	The computer system operating mode. In the Dual Mode model, modes are distinguished by the quota of on-line units for each stage. In the Coverage model, D/I/R

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<u>Symbol</u>	<u>Fortran</u> <u>Mnemonic</u>	<u>Name</u>	<u>Definition</u>
			processes are defined separately for modes 1 and 2, as well as dummy mode 0. MD is equal to: <ul style="list-style-type: none">- 1 for full up- 2 for degenerate- 0 for transitional (coverage only, during transition from MD=1 to MD=2).
μ	MU(I)	Stand-by failure rate	The rate at which permanent hardware failures take place in stand-by LRU's (spares) of stage I. Expressed in failures per unit time.
N	N(I)	Modular redundancy factor	The number of identical active units in a fully operational NMR system.
n_c	LCM	--	The least common multiple of the n_i 's where n_i is the repetition factor (where applicable) of the i^{th} detector, in terms of minor cycles.
n_i	IREP(I)	Repetition factor	The integer ratio of the repetition period of the i^{th} scheduled detector to the minor cycle duration, i.e., $T_i = n_i T_{mr}$.
P	P(I)	--	The probability of stage I failing with a logical zero output.
p_i	--	--	The conditional probability that the i^{th} detector will detect an arbitrary fault, given infinite time and no competitive detection processes.
p'_i	---	--	The probability that the i^{th} isolator is able to isolate a fault.

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<u>Symbol</u>	<u>Fortran</u> <u>Mnemonic</u>	<u>Name</u>	<u>Definition</u>
$p_i f_i(\tau)$	--	--	The detection probability density function of detector i in a non-competitive environment (i.e., when no other detectors are operative). The value of p_i and the function $f_i(\tau)$ are defined explicitly, as is the initial detection delay t_{d_i} . The "rate function" $f_i(\tau)$, then, represents the rate of detection for an ideal detector, i.e., one which guarantees detection, given an adequate amount of time. Since τ_{d_i} is explicit, $f_i(\tau)$ must be defined so that $f_i(0^+) \neq 0$. The duration of the function is defined as the value of τ after which detection cannot occur.
$p_i h_i(\tau)$	--	--	The isolation probability density function of the process associated with detector i . Note also $h_i(\tau)$ is a rate function defined similarly to $f_i(\tau)$.
P_r	PRC1(I), PRC2(I)	Transient recovery probability	The probability, for mode equals 1, 2 respectively, that the system can recover from a transient fault occurring in an LRU of stage I.

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<u>Symbol</u>	<u>Fortran</u> <u>Mnemonic</u>	<u>Name</u>	<u>Definition</u>
p_s	PFDS (ISU)	--	Probability of detecting a failure in a failed spare during checkout. Note that this has the effect of directly reducing the final coverage result, since no provision is made for subsequent recovery from undetected failures in spares. The value selected must therefore account for all secondary recovery capabilities of the computer system. Note also that the value is, for reason of its inclusion in the coverage model, assigned to a fault subclass rather than an LRU.
Q	Q1(I), Q2(I)	Quota	The number of on-line LRU's required in stage I for system operation in mode equals 1, 2 respectively.
R(t)	R	Reliability	The probability that the system is operational at time t given that it was operational at time 0.
$r_i(\tau', \tau'')$	--	Recovery probability function	The conditional probability of system recovery, given detection and isolation delays of τ' and τ'' , respectively. $r_i(\tau', \tau'') \equiv r_i(\tau') \cdot r_i(\tau' + \tau'')$
$r_i^*(\tau')$	--	Fault propagation recovery function	The conditional probability of system recovery, given detection time τ' for the i^{th} detector at the end of which, fault propagation ceases.

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<u>Symbol</u>	<u>Fortran</u> <u>Mnemonic</u>	<u>Name</u>	<u>Definition</u>
$r_i^{''(r'+r'')}$	--	Time lost recovery function	The conditional probability of system recovery, given total detection and isolation delay of $(r'+r'')$ for the i^{th} detector, isolator pair at the end of which, fault recovery is initiated.
--	RSGN	Reassignment flag	A logical variable which for RSGN =.TRUE., enables operational LRU's in a failed channel to be reassigned i.e., released to the spares pool =.FALSE., precludes reassignment (Note: RSGN must be set true if the quota in mode $M+1$ is greater than in mode M).
RV	RV(I)	Restoring organ reliability	An overall limiting probability of success applied to stage I.
S or r	S(I)	Spares	The number of spare LRU's available in stage I at time $t = 0$.
s	JS	--	The quantity of spare LRU's which must be checked out before recovery can proceed. (normally 0 or 1).
o	ISU	Fault subclass	An integer subscript ($0 < ISU \leq 8$) which identifies a set of competitive D/I/R processes (i.e., a fault subclass). One or more such sets may be assigned to a single stage of the reliability model.

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EQUIPMENT DIVISION



<u>Symbol</u>	<u>Fortran</u> <u>Mnemonic</u>	<u>Name</u>	<u>Definition</u>
t_{d_i}	TDEL	Delay time	The delay time associated with initiation of detection process i. For scheduled detectors, it is measured relative to the beginning of a major cycle; for non-scheduled detectors, it is the interval between occurrence of a fault and the instant it can first be detected.
Δt_i	TDUR	Duration time	The time interval during which a detection function is non-zero.
$t_{d_i} + \Delta t_i$	--	--	Finishing time for detector i, i.e., the time relative to the start of a major cycle (scheduled detectors) or the occurrence of a fault (non-scheduled detectors) after which detector i is not effective. Note: $\int_0^{\infty} f_i(\tau) d\tau = \int_0^{\Delta t_i} f_i(\tau) d\tau \equiv 1.0$ (delay is external to function)
T_i	--	--	The repetition period of the i^{th} scheduled detector.
$t_j^{\ell(i)}$	CYTJL(J,L,I)	--	Largest solution t to the equation $t = t_j + \nu T_j - (\ell-1) T_i, \nu = 0, 1, 2, \dots, \text{in the range } (t_i, t_i + T_i). \text{ (If there is no}$

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<u>Symbol</u>	<u>Fortran</u> <u>Mnemonic</u>	<u>Name</u>	<u>Definition</u>
			solution in this range, $F_j^{\ell}(\eta)$ = 1.) Thus, t_j^{ℓ} represents the starting time of the last occurrence of the j^{th} scheduled test in the interval $(t_i + (\ell-1)T_i, t_i + \ell T_i)$.
T_{mr}	TMINOR	Minor Cycle	The minor cycle duration, i.e., the greatest common divisor of the repetition period T_i .
τ_s	TFDS (ISU)	Checkout Time	The average on-line time re- quired to test a single spare, given an accompanying test success probability of p_s . Note that the value is, for reason of its inclusion in the coverage model, assigned to a fault subclass rather than an LRU.
W	W(I)	Division factor	The number of identical sub- units which comprise one unit in stage I. The sub-unit failure rate λ_s thus relates to the unit failure rate λ as $\lambda_s = \lambda / W$.
Z	Z(I)	Iteration factor	The number of identical units operating in series which comprise stage I. The reli- ability of the stage is thus the product of the reliabili- ties of the Z sub-stages.

SECTION 4

SOFTWARE

CARE2 was developed using the CDC RUN76 compiler, under the KRONOS 2.1 Operating System, on the CDC 6700 Time-sharing Computer at Raytheon MSD, Bedford, Massachusetts. The program is essentially ANSI Fortran IV, with the exception that, like original CARE, it is designed for execution on a 60 bit CDC computer. The field length required for the complete program version is less than 130K (octal), and for the reduced version (without plotting options) less than 100K.

Program modules added were designed to be of comparable scope with existing modules as far as programming efficiency and run time considerations would permit. The statistical, mathematical or implementation significance of each revised or added subprogram is described in this section.

4.1 PROGRAMMING CONSIDERATIONS

The task of including both a dual mode reliability model and a model for the calculation of coverage factors, was originally expected to entail additions to CARE only. Ideally, the former would replace dummy subprogram NEQ7, and the latter would require one additional CALL statement in the main program, plus the implementing code. However, the relatively complex method of passing statistical parameters to the reliability models, combined with the need for communication between stages of the dual mode model, disallowed this ideal. Simply stated, the CARE program requires 1) that an equation use at most one parameter of each type, and 2) that individual systems be evaluated serially. Thus major revisions of the data base structure were undertaken. The possibility of expanding the existing structure to accommodate a large number of additional parameters was rejected in favor of a simpler format.

In CARE2, a computer system is represented as a series of one or more stages, each of which is comprised of identical subunits including one or more optional spares. Each invocation of equations 1-6 corresponds to the definition of a single such stage, whereas equation 7 has internal provision for representing up to eight stages.

For the group of up to 10 stages which can be modelled at one time, there exists a base run vector (i.e., an array of dimension 10) for each parameter type. In addition, any one of 19 parameter types may be selected for variation (cf. sheet 2 of Table 4-2), which is accomplished internally by alternately refreshing the selected run vector from a single 10 x 16 iteration array and evaluating the system. (The latter process, consisting of up to 16 evaluations or runs, is termed a run-set.) Optionally, run-sets may also be repeated, following user changes to run vectors, iteration data and iteration parameter.

Coverage factors are treated the same as other parameters when input directly by the user. Conversely, however, they can be computed, for equations to which they apply, provided that separate coverage input data is supplied. These inputs, because of their relative diversity, cannot be varied as described above. Most, with the exception of the flags which request calculation and the linkage table which unites the two halves of the program data base, can be changed at the run-set level.

In structuring the input algorithms for CARE2, it was apparent that both the size of the data base and the assumption that the program would be used for sensitivity analyses, indicated an "inputs only for changes" rule should apply throughout. Thus program defaults, where provided, are initiated prior to user inputs (except in unaltered portions of READIN). The default values themselves, in the case of basic reliability model parameters, may optionally be input early in the batch run. In addition, by setting LSTCH to true (cf. Table 5-1), the

inputs required for parameter variation can often be minimized. In this case, non-default inputs to the iteration array PARAM will be extended upward along the iteration dimension, replacing only default values.

The development of CARE2 was performed using MODIFY, a system level program on the Bedford 6700. MODIFY facilitates the manipulation of source code by representing the original and subsequent versions as card deck images stored in disk files. Cards and decks are inserted, moved or deleted, by introducing directives in groups which are also represented as card decks, and are saved with the source for future reference.

The identifying names seen in columns 73-80 of the CARE2 source code refer to the origin of the card. Thus cards bearing the subprogram name, in the case of original CARE subprograms, were in fact in the original program. The modification set name, where it appears, in general refers to the reason for the card's replacement or addition.

For example, CAREFIX cards arose from early modifications which were required to enable the CARE program to operate properly on the Bedford computer. MAINLOG cards indicate basic logic modifications, and PARMOD cards refer to the restructured parameter data base.

4.2 SUBPROGRAM DESCRIPTIONS

This section describes, in paragraph form, each of the new and altered subprograms, as they exist in the "complete" version of the CARE2 program. Each is also described in flow diagram form (cf. Appendix A) as well as in the source listing itself (cf. Appendix B). Table 4-1 is provided in order to aid in their location.

TABLE 4-1

CROSS-REFERENCE LISTING OF CARE2 SUBPROGRAMS

Subprogram Name	Source Listing S/R Order #	Paragraph #	Flowchart #	Comments
BISECT	2	-	-	Original
*CARE2	1	4.2.1.1	A-1	Modified CARE main program
COVAGE	47	4.2.4.1	A-18	Added
COVGEN	37	4.2.2.3	A-8	Added
CVGPI	54	4.2.4.8	A-25	Added
CVGP3	51	4.2.4.5	A-22	Added
CVGP4	52	4.2.4.6	A-23	Added
CVGS	50	4.2.4.4	A-21	Added
CVG1	48	4.2.4.2	A-19	Added
CVG2	49	4.2.4.3	A-20	Added
CVTJL	53	4.2.4.7	A-24	Added
DCG	45	4.2.3.7	A-16	Added
DCH	43	4.2.3.5	A-14	Added
DCOMB	46	4.2.3.8	A-17	Added
DCR	39	4.2.3.1	A-10	Added
DCRU	44	4.2.3.6	A-15	Added
DCS	42	4.2.3.4	A-13	Added
DCT	41	4.2.3.3	A-12	Added
DCT2	40	4.2.3.2	A-11	Added
*EQUAL	3	-	-	Original
FEVAL	56	4.2.4.10	A-27	Added
FFAC	4	-	-	Original
FINTEG	57	4.2.4.11	A-28	Added
FNCK	5	-	-	Original

*Affected by array dimension modifications, as required for optional reduced field length execution.

TABLE 4-1 (cont.)

Subprogram Name	Source Listing S/R Order #	Paragraph #	Flowchart #	Comments
FN1	61	4.2.4.15	A-32	Added
FN1I	62	4.2.4.16	A-33	Added
FN2	63	4.2.4.17	A-34	Added
FN2I	64	4.2.4.18	A-35	Added
FN3	65	4.2.4.19	A-36	Added
FN3I	66	4.2.4.20	A-37	Added
FN4	67	4.2.4.21	-	Added (dummy routine)
FN4I	68	4.2.4.22	-	Added (dummy routine)
FN5	69	4.2.4.23	-	Added (dummy routine)
FN5I	70	4.2.4.24	-	Added (dummy routine)
FN6	71	4.2.4.25	-	Added (dummy routine)
FN6I	72	4.2.4.26	-	Added (dummy routine)
IGET	58	4.2.4.12	A-29	Added
INTEGR	6	-	-	Original
IPUT	59	4.2.4.13	A-30	Added
ISHIFT	60	4.2.4.14	A-31	Added
MOVC	26	4.2.1.4	A-4	Modified to use ISHIFT
NEQ1A	9	4.2.1.2	A-2	Corrected logic error
NEQ1B	10	-	-	Original
NEQ2A	7	-	-	Original
NEQ2B	8	-	-	Original
NEQ3	11	-	-	Original
NEQ4A	12	-	-	Original
NEQ4B	13	-	-	Original
NEQ5	14	-	-	Original
NEQ6	15	-	-	Original

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TABLE 4-1 (cont.-2)

<u>Subprogram Name</u>	<u>Source Listing S/R Order #</u>	<u>Paragraph #</u>	<u>Flowchart #</u>	<u>Comments</u>
*NEQ7	16	4.2.1.3	A-3	Replaced dummy
PARAR1	17	-	-	Original
PGET	38	4.2.2.4	A-9	Added
PLOTN	24	-	-	Original
*PLOTR	22	-	-	Original
*PLOTRV	18	-	-	Original
*PLOTT	23	-	-	Original
PROD	20	-	-	Original
PROD1	21	-	-	Original
RCOMB	19	-	-	Original
*READIN	34	4.2.1.5	A-5	Modified
READIN2	35	4.2.2.1	A-6	Added
REDUC	27	-	-	Original
RELATE	28.5	-	-	Deleted
RELEQS	30	-	-	Original
*RIFDIF	29	-	-	Original
RITE	30.5	-	-	Deleted
ROMBD	28	-	-	Original
ROWPLT	31	-	-	Original
SCAN	33.5	-	-	Deleted
SEARCH	31.5	-	-	Deleted
SIMPLE	33	-	-	Original
SIMPRI	32	-	-	Original
SPECIT	55	4.2.4.9	A-26	Added
TRANSFR	36	4.2.2.2	A-7	Added
WRNR	25	-	-	Original

*Affected by array dimension modifications, as required for optional reduced field length execution.

4.2.1 Altered Subprograms

4.2.1.1 CARE2 (Main subprogram)

The basic order of processing is the same as that of CARE. All output options which were allowed in CARE exist unchanged in CARE2, with the exception of simultaneously varying more than one parameter type and automatically obtaining all possible combinations. The current ability to repetitively input changes to both parameter and coverage data provides an equivalent capability and, in addition, allows for direct user selection of the combinations to be evaluated. The restrictions on plotting options which applied to evaluations of a product of reliabilities now apply, analogously, to evaluation of a dual mode system (Eq. 7) with more than one stage.

A dual mode system of up to 8 stages can be modelled in series with other computer models, by declaring array PROD as a like quantity of 7's, followed by the numbers of the other desired equations.

As in CARE, the invariant data for a batch run is specified via READIN. The additional data now contained in this category, as included in Figure 5-1 and Table 3-1, consists of:

- flags which enable the calculation of coverage and the display of intermediate coverage results
- a flag enabling the display of mode 1 reliability of the dual mode system model and its individual stages
- a flag enabling display of the reliability model parametric inputs, iteration array and dual mode system special data (defaulted to .TRUE.).

- linkage data to allow calculated coverage values to be applied to reliability models
- a flag to specify the method used to fill the iteration array
- a debug flag (see below).

Following READIN, the variant data is input via READIN2.

(The data following READIN, is termed variant because the call to this subprogram is the beginning of a main subprogram loop which may be continued indefinitely.) All inputs to READIN2 are made via control cards, which determine the data to be input as well as the format to be used. This data includes both parameters for the reliability models and inputs to the coverage model.

After all data has been processed, the coverage driver, COVGEN, is called to effect all requested coverage calculations and transfer their result to the run vectors, using the linkage algorithm. The iteration array, PARAM, is then adjusted as required, and the prepared inputs to the reliability models are (optionally) displayed.

If the DEBUG flag has been set, control passes directly back to READIN2, and no reliability model evaluation occurs. This is useful 1) for checking data cards for validity, and 2) when coverage analyses only are desired.

If DEBUG is not set, reliability equations are evaluated sequentially, and reliability versus the independent variable, followed by the selected computational and plot options, are printed. In the case of dual mode system, the independent variable must be time and must begin at zero, due to the use of structured numerical integration.

An additional, more specific, overview of CARE2 is provided in Appendix A (cf. flow diagram A-1).

4.2.1.2 NEQ1A

A simple correction was made to this routine during the initial investigation of CARE. Specifically, a card sequence error was found in the algorithms' source listing which in turn caused the summation on L (or LX) to be set equal to its last term. (cf. flow diagram A-2)

4.2.1.3 NEQ7

As mentioned in Section 4.1, the data available to this sub-routine via its argument list is inadequate for evaluation of the dual mode model. The model is thus referenced separately by the main program, with parameters held in common blocks.

NEQ7 is capable of interpolating the results stored in array R(121,25), when referenced via RELEQS by subprograms which perform secondary calculations (e.g., MTF). It uses a 2nd order (parabolic) integration technique. (cf. flow diagram A-3)

4.2.1.4 MOVC

This routine, which transfers six-bit characters between words of memory, originally required a Langley installation routine called SETBIT. It now uses ISHIFT, which is written in COMPASS and included in the source code. (cf. flow diagram A-4)

4.2.1.5 READIN

The basic input package provided by READIN remains unaltered with the exception that the reliability model parameters (Q, N, LAM, etc.) have been removed from namelist \$VAR. As in CARE, READIN is referenced once by CARE2, and thus data processed by it cannot be changed during later execution.

Since CARE inputs were originally based on a time-sharing question and answer format, they are rather awkward for use in batch mode, and for clarity require the use of either a standardized procedure or analysis of subprogram READIN. The substantial number of new inputs now required to accommodate the dual mode and coverage models complicate this matter further. In an attempt to clarify the issue somewhat, the current input algorithm is shown in Figure 5-1, in flowchart form.

The essential differences between CARE and CARE2 in this context are:

- A number of logical variables have been added to Name-list \$OPTION, including DEFCHNG and COVPRC.
- Two additional Namelists, \$DEFAULT and \$COVCAL, are read following \$VAR, conditional on their respective flags, DEFCHNG and COVPRC, being set .TRUE.
- As in CARE, the inputs to READIN are invariant for the entire batch run. The addition of subprogram READIN2 allows most parametric data to be altered between run-sets
- The basic reliability model parameters (Q, S, LAM, etc.) have been moved from Namelist \$VAR in READIN to Namelist \$PARVEC in READIN2.

More detailed information on the current complement of variables and flags, as well as an overview of the revised READIN flow and the context of how it is used in CARE2, is provided in Sections 2.3, 4.2.1.1 and 5.1.2 and flow diagram A-5.

4.2.2 New Utility Subprograms

4.2.2.1 READIN2 (NRS, DMFLG, IRES, LVARY, DVAL, DEBUG)

This subroutine is called by CARE2 directly after READIN, and again after completing evaluation of the reliability models and secondary calculations. It is thus possible to continue altering the parametric and/or coverage data base, and in turn re-evaluating the models, indefinitely.

Due to the "inputs only for changes" rule, extensive use is made of the Namelist feature of Fortran. Also, for this reason, all input processing is carried out in direct response to control cards. The routine continuously reads these cards, using a standard format, and processes them along with other indicated data, such as namelist inputs, until such time as a return to model evaluation is specifically requested.

The control cards contain an identifying code in columns 1-3 which indicates one or more of the following:

- a reference to a particular Namelist follows in the input stream
- the control card contains specific information in a fixed format
- the subroutine is to perform a specific processing task.

A code which begins with "I" requests the reading of a Namelist, and those beginning with "P" cause the immediate printing of a portion of the data base. A general description of each of the 12 control codes is contained in table 5-2. (cf. flow diagram A-6)

4.2.2.2 TRANSFR(X,I)

This subroutine conditionally prints a line of parametric input data starting at the address of X. I is the element of array PCW(22), which contains applicability information concerning the parameter vector to be printed. Only those values pertaining to the applicable reliability model are printed. (cf. flow diagram A-7)

4.2.2.3 COVGEN

If one or more of the coverage factors are to be calculated, this routine is called by CARE2 directly after return from READIN2. COVGEN responds to requests for coverage calculation from both the IGENC(10) and IGENP(10) flags (which correspond to stages of the reliability models) and to individual requests initiated by setting coverage parameters to negative values. For each request, the routine determines applicability by testing the proper element of PCW(22).

Since delta coverage is computed using corresponding basic coverage, the order of calculation is by parameter type, with subclass linkage tests secondary. A fault subclass is linked to a stage if the corresponding element in IFSC(8) is the stage number. The corresponding fractional fault rate in FRAC(8) is then applied. (cf. flow diagram A-8)

4.2.2.4 PGET(IR,I,NPROD)

PGET refreshes the run vector of the parameter to be varied with NPROD values from row I of the iteration array PARAM (16,10). IR indicates the parameter of interest. (cf. flow diagram A-9)

4.2.3 Dual Mode Model Implementation Subprograms

4.2.3.1 DCR(J,UNITR,RELM1,RSYS)

This subroutine, driven by the time step counter J, computes the dual mode system (eq. 7) reliability RSYS at the point in time $t = \text{STEP}*(J-1)$. It also evaluates the system and individual stage reliabilities as they apply to mode 1 operation alone (RELM1,UNITR(8)). (cf. section 3.1.7 and flow diagram A-10)

4.2.3.2 DCT2(J)

This function computes the probability that the system will have survived to time $t=\text{STEP}*(J-1)$, having degraded due to a category 2 switch failure. (cf. section 3.1.6 and flow diagram A-11)

4.2.3.3 DCT(IUN,J)

This function computes the probability that the system will have survived to time $t=\text{STEP}*(J-1)$, having degraded due to a failure in stage IUN. (cf. section 3.1.5 and flow diagram A-12)

4.2.3.4 DCS(IUN,T,TAU)

This function computes the conditional probability that stage IUN can survive in mode 2 from time TAU to time T,

given that a degenerative failure occurred in the stage at time TAU. (cf. section 3.1.4 and flow diagram A-13)

4.2.3.5 DCH(IUN,TAU)

This function computes the probability density of a degenerative failure in stage IUN of the system at time TAU. (cf. section 3.1.3 and flow diagram A-14)

4.2.3.6 DCRU(IUN,MD,L,TAU)

This function computes the probability of using at most L spare units in stage IUN by time TAU, given the system is operating in mode MD. (cf. section 3.1.2 and flow diagram A-15)

4.2.3.7 DCG(IUN,MD,I,T)

This function computes the probability of using exactly I spare units in stage IUN by time T, given the system is operating in mode MD. (cf. section 3.1.1 and flow diagram A-16)

4.2.3.8 DCOMB(TOP,K)

This function computes the binomial coefficient of the expression:

$$\binom{\text{TOP}}{K}$$

It is equivalent to the RCOMB function except for the case when K=0. (cf. flow diagram A-17)

4.2.4 Coverage Model Implementation Subprograms

4.2.4.1 COVAGE (ISU, MD, IET, JS)

This function returns a single value, either a coverage factor or transient recovery probability, for each reference. (Since little sharing of intermediate variables is possible in

coverage calculations, efficiency is not lost by the single value format.) The routine is driven by COVGEN, which provides the proper arguments for the type of coverage value required for the reliability models.

The Fortran statement for referencing COVAGE is:

CVAL = COVAGE(ISU,MD,IET,JS)

where

- ISU is the fault class or subclass
- MD is the computer system operational mode
- IET is the major fault type, either a permanent or transient failure
- JS is the number of spare units which must be checked out during the recovery process.

With reference to the definition of coverage (cf. section 2.3) as a conditional probability, the arguments MD and IET can be taken as the "given" conditions, i.e., coverage input data may be entirely different for differing values of these variables. In addition, a coverage factor is computed independently for each class or subclass of faults, where a class is defined as those faults occurring in a specific stage of the computer model. Within the fault class, faults may arbitrarily be divided into subclasses, provided that a decimal fraction, specifying the relative rate of fault occurrence, is assigned to each subclass. A subclass may be those faults occurring in a specific part, or subunit of an LRU, or those having a certain characteristic, such as "easy to find", etc.. The coverage factor applied to a computer stage is the average of the factors calculated for the applicable subclasses, weighted by the rela-

tive rates of occurrence assigned by the user.

Each call to the COVAGE sub-program results in a calculation of the systems' conditional ability to detect, isolate (to a specific LRU) and recover from the specified subclass of faults (ISU), under given conditions of mode, fault type and quantity of spares checked (as defined by MD, IET and JS respectively). To accomplish this, it is necessary that the components of the recovery system (i.e., the FTF's) be described, as input to the model, in terms of their stand-alone capacity to contribute. The model evaluation then combines the effects of these by statistically accounting for the competitive nature of the detectors, and the conditional isolation and recovery success probability associated with each.

The quantity of the data required by the model, due to its flexibility, is necessarily large. The user can, however, do much to simplify the corresponding data specification task by approaching it systematically. A convenient (although not necessary) starting point for this is to first list the names of all hardware and software fault detection devices available in the computer system. If there are 20 or less, a unique number is then assigned to each name which, in turn, represents the D/I/R mechanism corresponding to that detector. (If there are more than 20, sharing of numbers is required.)

Figure 4-1, by way of example, represents the processes (for all valid combinations of mode and fault type) which deal with faults of subclass 3. Each row therein represents the portion of a D/I/R mechanism corresponding to a single detector and each column, the set of coexistent processes which compete for detection of (and subsequent recovery from) faults of a particular type and occurring during a particular mode of operation. The four numbers

Mechanism Number	Detector Name	Fault type/mode		TRANS/1	TRANS/2	PERM/O
		PERM/1	PERM/2			
1	6 BIT MEMORY CODE (Hamming)	1, 1, 1, 1	1, 1, 1, 2	1, 1, 1, 1	1, 1, 1, 2	1, 1, 1, 1
2	OUTPUT COMPARATOR	9, 2, 1, 2	Not Applicable	9, 3, 1, 2	N/A	9, 2, 1, 2
3	I/O WRAPAROUND	12, 2, 1, 1	12, 2, 2, 2	N/A	N/A	12, 2, 1, 1
4	CPU SELFTEST	14, 2, 1, 1	14, 2, 2, 2	N/A	N/A	14, 2, 1, 1
20	unused					

FIGURE 4-1

SAMPLE FUNCTION SELECTION CHART

contained in each intersect, designated function numbers, specify the detection, isolation, and 2 recovery characteristic functions selected to represent the components of the corresponding mechanism. Each such number designates a fully specified time function whose parameters are contained in one of four specification arrays, corresponding respectively to detection (D), isolation (I), error-propagation-recovery (E) and time-delay-recovery (T) functions (cf. Table 5-4). Each array has sufficient room for a number of specification lists which, in turn, are common to the entire model.

Looking again at figure 4-1, it should be noted that the only restrictions placed on the selection of function numbers is that a non-zero (i.e., enabled) detector be accompanied by non-zero function numbers for isolation and recovery, and that all 4 functions be properly defined.

In order to generate a characteristic curve versus time (or its integral), the coverage model uses an evaluation sub-program which applies the specifications of the selected function number to one of several common function models. Each model, in turn, is a Fortran sub-program, in the form of a generalized equation with one independent variable and up to 3 fixed parameters, as for example:

$$f(t) = a(e^{-bt} + c).$$

The user generates specifications at run time, in part, by linking each function number to a particular function model, and

in part, by selecting appropriate values for a, b and c. He may also alter, or add to, the set of function models, recompiling only the corresponding model sub-programs. Once specification lists have been input, the D/I/R sequences (i.e., mechanism portions corresponding to specific conditions) can be defined, one at a time or in groups, by selecting 4 function numbers for each.

It should be noted that the functions selected are characteristic curves which describe detection, isolation and recovery capabilities under a given set of conditions. A software detection device which is good at finding permanent failures in a CPU register may perform poorly when the register simply "drops a bit." The characteristic curves, and thus the functions (numbers) selected, will be different even though the same detector is used.

The 4 processes comprising a D/I/R sequence must be clearly understood, from a statistical point of view, before a realistic recovery system can be modelled. Up to this point, these functions have not been given a physical significance in order to avoid confusion. Although the 4 functions are implemented in the same manner, the detection and isolation functions have units of probability density, whereas the 2 recovery functions have units of probability. More specifically, the detection and isolation functions are rate functions, which for the present purposes means that the shape and coefficient of each detection and isolation function is provided and utilized separately. These rate functions (exclusive of the coefficient) are required by the model to have an integral of 1.0, with the co-

efficient then lying between 0.0 and 1.0. A normalization routine is provided in READIN2 to assure that the rate functions are correct.

The error-propagation-recovery and time-delay-recovery functions give the probability of successful recovery versus the time 1) that errors are allowed to propagate through the system and 2) that is required for detection plus isolation of a fault. The model treats these probabilities as conditional upon each other, such that the success probability for a given detection time and a given isolation time is the product of the two recovery functions.

Other data items which affect coverage are the probability of recognizing a failure in a spare LRU, as selected to replace a failed active unit, and the time required to test such a spare, whether or not it has failed. (cf. section 3 and flow diagram A-18)

4.2.4.2 CVG1(I,T)

This function computes the coefficient of the function for unscheduled impulse detector I, at time T units after the occurrence of a fault. The g function is an impulse in this case, and its coefficient indicates the competitive effectiveness of the detector. (cf. section 3.2.4 and flow diagram A-19)

4.2.4.3 CVG2(I,T)

This function computes the value of the g function for unscheduled finite detector I, at time T units after the occurrence of a fault. The g function is a measure of the competitive effectiveness of the detector. (cf. section 3.2.4 and flow diagram A-20)

4.2.4.4 CVGS(I,T)

This function computes the value of the g function for scheduled detector I, at time T units into the period of the test (detector). The detector may be either an impulse or finite function, and the calculation is based in part on the sample g' values saved in array GPAR(20,101). The g function is a measure of the competitive effectiveness of the detector. (cf. section 3.2.4 and flow diagram A-21)

4.2.4.5 CVGP3(I)

This subroutine computes and stores N+1 samples of the g' function for scheduled impulse detector I, over its period (i.e., the time between successive runnings of the test). The assumption is made that no detection can be made after one such period, measured from the occurrence of a fault. The g' function is a measure of the effectiveness of the test, in competition with other scheduled detectors. (cf. section 3.2.5 and flow diagram A-22)

4.2.4.6 CVGP4(I)

This subroutine computes and stores N+1 samples of the g' function for scheduled finite detector I, over its period (i.e., the time between successive runnings of the test). The

assumption is made that no detection can be made after one such period, measured from the occurrence of a fault. The g' function is a measure of the effectiveness of the test, in competition with other scheduled detectors. (cf. section 3.2.5 and flow diagram A-23)

4.2.4.7 CVTJL(J,L,I)

This function returns the time difference value $t_j^l(i)$ for use by CVGP3 and CVGP4 in evaluating the competition between scheduled detectors, i.e., the effect of detector J on detector of interest I. (cf. flow diagram A-24)

4.2.4.8 CVGPI(I,T)

This function interpolates the sample g' values (for detector I) which have been saved in array GPAR(20,101) by CVGP3 and CVGP4. The result is used by CVGS in determining the effectiveness of scheduled detectors in competition. (cf. flow diagram A-25)

4.2.4.9 SPECIT(FLIST,NUM,IGFT,ISCH,IREP,INTF,COEF,TDEL,P1,P2, P3,TDUR)

This subroutine sets up a specification list (in one of four arrays) which defines a characteristic curve (function) versus time for either a detection, isolation, error-propagation-recovery or time-lost-recovery process. The respective specification arrays which receive this data are FDET(7,200), FISO(7,50), FEPR(7,25), or FTLR(7,25). FLIST is the address of one of these arrays, and NUM the column position within it where the data will be stored. The remaining arguments are the function specifications:

IGFT The identification number of the function model to be employed in evaluating the curve

ISCH The scheduling indicator. Equal to 0 for unscheduled, or 1 for scheduled detectors. Does not apply to other processes

IREP The repetition factor of scheduled detectors only, i.e., the number of minor cycles in the detector period

INTF The integral-defined indicator. Equal to 0 if the integral model corresponding to IGFT above does not exist, and 1 if it does

COEF The explicit coefficient of the function. For detection and isolation, it is also the infinite-time success probability

TDEL The delay time associated with a detector or isolator. For detectors, it is measured either from the occurrence of a fault (unscheduled), or from the beginning of the test period (scheduled)

P1,P2,P3 Arbitrary parameters which are passed to function model number IGFT via COMMON block CVB4, and used for the evaluation of the process characteristic. If normalization is to be performed using the routine in READIN2, P1 must be an internal coefficient in the function model selected to represent either a detection or isolation rate function

- TDUR The duration of any finite process, including recovery. This is used to determine upper limits for numerical integrations, and for reasonableness sampling when requested.

(cf. flow diagram A-26)

4.2.4.10 FEVAL(FLIST,NUM,T)

This function evaluates the characteristic function representing a detection, isolation, error-propagation-recovery, or time-lost-recovery process. The function specifications are retrieved from the array position indicated by FLIST (which may stand for FDET, FISO, FEPR, or FTLR) and NUM (the column position within the array). The independent variable T is passed to the function model. (cf. flow diagram A-27)

4.2.4.11 FINTEG(FLIST,NUM,T)

This function evaluates the time integral of the characteristic function representing detection (although it could be used for another process). The function specifications are retrieved as in FEVAL, and the integral-defined indicator is tested. If it is greater than 0, the independent variable is passed to the proper integral model. Otherwise, a numerical integration (Simpson 3 point) is performed using N+1 samples of the function, which are returned by FEVAL. N is a local variable which may be altered by the user, via a recompilation of FINTEG alone. (cf. flow diagram A-28)

4.2.4.12 IGET(IWORD,INDEX)

This function returns the INDEX'ed 12 bit field of IWORD (one of 5 in the 60 bit word), as a right justified integer. (cf. flow diagram A-29)

4.2.4.13 INPUT(IWORD,INDEX,ICODE)

This subroutine packs the rightmost 12 bits of ICODE into the INDEX'ed 12 bit field of IWORD, after first clearing the field. (cf. flow diagram A-30)

4.2.4.14 ISHIFT(IWORD,NBITS)

This COMPASS function returns, as an integer, the result of performing a left circular shift of NBITS on IWORD. (cf. flow diagram A-31)

4.2.4.15-16 FN1(T) and FN1I(T)

This function model and corresponding integral model represent the characteristics of a "single pulse" or constant amplitude function. General parameter P1 is the amplitude, and the only parameter used in this case. It is important to note that the model does not incorporate a cutoff of its own, but is defined simply as FN1=P1. The coverage model applies the TDEL and TDUR values in its evaluation, in such a way as to properly service the numerical integral routines. (cf. flow diagrams A-32 and A-33)

4.2.4.17-18 FN2(T) and FN2I(T)

This function model and corresponding integral model represent the characteristics of a "pulse train" function, with amplitude P1, pulse width P2, and pulse repetition period P3.

Due to the discontinuities inherent in this function, it is not recommended for general use, except on an experimental basis.
(cf. flow diagrams A-34 and A-35)

4.2.4.19-20 FN3(T) and FN3I(T)

This function model and corresponding integral model represent the characteristics of an exponential function. The equation is:

$$FN3(T) = P1(e^{-P2*T} + P3)$$

(cf. flow diagrams A-36 and A-37)

4.2.4.21-26 FN4(T), FN4I(T), FN5(T), FN5I(T), FN6(T) and FN6I(T)

These dummy functions are provided to allow the user to expand the inventory of models, as more complex systems for coverage modelling are evolved.

4.3 MAJOR ARRAYS AND COVERAGE DATA BASE

The following sections describe both the new format of the reliability model parameter arrays, and the changes in dimension needed to run the reduced field length version of CARE2.

4.3.1 Reliability Parameters

As mentioned previously, the original 16X10 parameter arrays proved too cumbersome for use with the dual mode model, due to the complex method employed for extracting individual elements. The new version of this data base consists of a set of 19 independent and 3 dependent parameter vectors, of dimension 10. Each vector holds the inputs, for up to 10 computer stages, for one parameter (e.g., Q, LAM etc.).

A parameter control array, PCW(22), contains applicability and other information in packed format, with one element of the array corresponding to each parameter. The first part of table 4-2 shows the fields within a word, and the second part of the table gives the parameter order and association of parameters with default variables.

4.3.2 Reduced Field Length CARE2

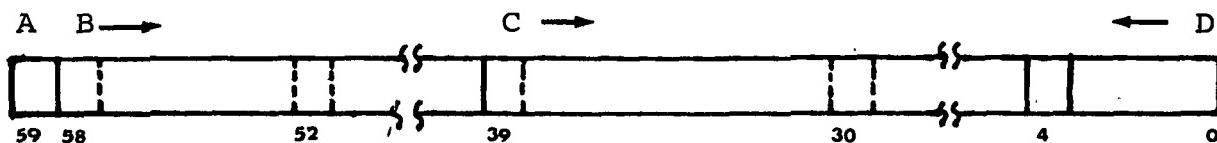
In the course of debugging the program with the new models included, the dimensions of certain of the plotting arrays not required for reliability computation, were temporarily reduced in size. The result was a 30K (octal) savings in required field length for execution. The user who wishes to obtain only tables of reliability can convert the complete program version by making the changes shown in table 4-3.

TABLE 4-2

PCW AND DEFAULTS

-ARRAY PCW (22)-

PCW contains packed information pertaining to the type and usage of each parameter in the reliability model. The fields within each word (one per parameter) are as follows:



<u>Field</u>	<u>Meaning if bit position is equal to one</u>
A	Parameter is represented in real format (as is default), otherwise it is in integer format
B _i	Parameter is used in the i th reliability equation, and B _i is located at (59-i)
C _i	Parameter is used in the reliability equation associated with the i th stage, and C _i is located at (40-i). (These bits are set by READIN for use by COVGEN & RITE2)
D	5 bit right justified integer giving the subscript of the default value in either INTDFS(4) or RLDFS(10), depending on field A (bit 59).

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TABLE 4-2 (Cont.)

-Parameter Names, Defaults and Usage-

PCW <u>SUBSCRIPT</u>	<u>NAME</u>	<u>DEFAULT</u>	<u>ARRAY POSITION</u>	<u>DEFAULT VALUE</u>	EQUATION						
					1	2	3	4	5	6	7
1	Q=Q1	Q1DEFr	RLDFS(1)	2.0		X	X				X
2	Q2	Q2DEFr	RLDFS(2)	1.0							X
3	N	NDEFi	INTDFS(1)	3		X					
4	S	SDEFi	INTDFS(2)	0		X	X	X	X		X
5	W	WDEFi	INTDFS(3)	1		X	X	X	X	X	X
6	Z	ZDEFi	INTDFS(4)	1		X	X	X	X	X	X
7	LAM	LAMDEFr	RLDFS(3)	10^{-6}		X	X	X	X	X	X
8	MU	MUDEFr	RLDFS(4)	10^{-6}		X	X	X	X		X
9	GMP	GMPDEFr	RLDFS(5)	10^{-6}							X
10	C=CI	CDEFr	FLDFS(6)	1.0		X	X				X
11	CD1	CDEFr	RLDFS(6)	1.0							X
12	C2	"	"	"							X
13	CD2	"	"	"							X
14	CTR	CTRDEFr	RLDFS(7)	"							X
15	CDTR	"	"	"							X
16	PRC1	PRCDEFr	RLDFS(8)	"							X
17	PRC2	"	"	"							X
18	RV	RVDEFr	RLDFS(9)	"		X	X	X	X	X	
19	P	PDEFr	RLDFS(10)	0.5							X
20	K		"	N/A		X	X	X	X		X
21	GM1		"	N/A							X
22	GM2		"	N/A							X

Note:

- other parameters (scalars) are printed when DCFLG = .TRUE.
- internal representation is denoted by subscript r for real and i for integer.

TABLE 4-3

DIMENSION CHANGES FOR REDUCED FIELD LENGTH CARE2

Subroutines affected:

- * CARE2 (main subprogram)
- * EQUAL
- * NEQ7
- * PLOTR
- * PLOTRV
- * PLOTT
- * READIN
- * RIFDIF

Arrays affected:

Complete version	Reduced version
R(121,25)	R(121,10)
DIFF(121,15)	DIFF(1,1)
RIF(121,15)	RIF(1,1)
GAIN(121,15)	GAIN(1,1)
ABSC(121,3)	ABSC(1,1)
G(121,16)	G(1,1)
XY(121,19)	XY(1,4)
RLRV(210,17)	RLRV(1,2)
FDUM(3233)	FDUM(1)

SECTION 5

PROGRAM OPERATION

CARE2 is designed to run on a 60 bit CDC 6000 Series computer system, using the RUN Fortran compiler in batch mode, under either the KRONOS 2.1 or SCOPE 3.0 operating system. Source and data input are nominally provided on punched cards, and output is nominally produced on a line printer. However, both operating systems allow reassignment of input/output devices with little effort.

In modifying and adding to the Fortran source code, care was taken to avoid using features of extended Fortran versions which were not used in the original CARE program. Reliance on library routines was also held to a minimum. The SETBIT routine is no longer required, and the ISHIFT function is included in the source as a Fortran callable COMPASS program. Other library references are to long-time standards such as AMIN1, OR, etc..

In comparison with CARE, which requires about 110K octal field length to load and execute, CARE2 runs in slightly under 130K (the precise figures depend somewhat on the compiler and operating system used). The reduced version of CARE2 runs in about 100K.

5.1 USER'S GUIDE

This section, although intended for those familiar with the operation of CARE, provides the information required for compiling all the input data to model computer systems and coverage systems with CARE2. An input algorithm, in flowchart form, is included to simplify usage. The use of the Fortran Name-

list feature and control cards on input facilitates sensitivity analyses, which is an expected mode of operation.

5.1.1 Processing Order

The general processing order of the program as a whole is as follows:

- 1) Input the computer configuration to be modelled, using one or more equation numbers to represent stages in series or, in the case of the dual mode model, a number of 7's to represent the stages within that model.
- 2) Input the upper limit of the independent variable and the step size to be used to generate reliability tables.
- 3) Input data to specify the desired computational and plotting options, changes to defaults (optional), and linkage data for the subsequent transfer of calculated coverage values to the reliability model date base.
- 4) Input non-default values for parameter base run vectors, coverage function selection and specification data, and special dual mode and coverage model variable data, as required.
- 5) Input iteration data, if any. (Enables the re-running of computer model evaluations with variations in a single parameter).
- 6) Print out selected parts of the coverage data base, if requested.

- 7) Compute any requested (and applicable) coverage factors, optionally displaying intermediate results (conditional D/I/R mechanism contributions).
- 8) Optionally print out parametric data to be used in reliability model evaluations, including calculated coverage and special variables.
- 9) Compute and print tables of reliability versus the selected independent variable, sequentially for each equation in the configuration list. If the dual mode model (equation 7) is evaluated, optionally print the mode 1 system and stage reliabilities versus time (ahead of the standard reliability table).
- 10) Compute product, MTF and other selected options, including plots.
- 11) Repeate steps 4 through 10, changing only the desired variant data. (Note that the iteration parameter and data will remain the same if not actively altered or defeated.)

5.1.2 Use of the Input Algorithm

Figure 5-1 is a working guide for the creation of an input deck. The requirements are unusually complex, partly due to the volume and variety of data, and partly since the input routine was originally written in a question-and-answer format for use in a time-sharing environment.

Each input record must of course contain the proper information in the proper format. Thus the algorithm, in flow chart form, covers all possible inputs in both READIN (invariant data) and READIN2 (variant data). It is not intended as a complete

flow diagram for either of these subroutines.

In following the diagram, note that a decision block contains either the name of a logical variable or shows some test of a variable. Input blocks which refer to Namelist names (designated by \$) have comments showing the names and dimensions of its contained variables.

Table 5-1 describes many of these variables in operational terms. The 12 possible control cards which initiate processing tasks in READIN2 are described in Table 5-2. Input blocks which show fixed format cards refer to format entries in Table 5-3.

FIGURE 5-1

INPUT ALGORITHM

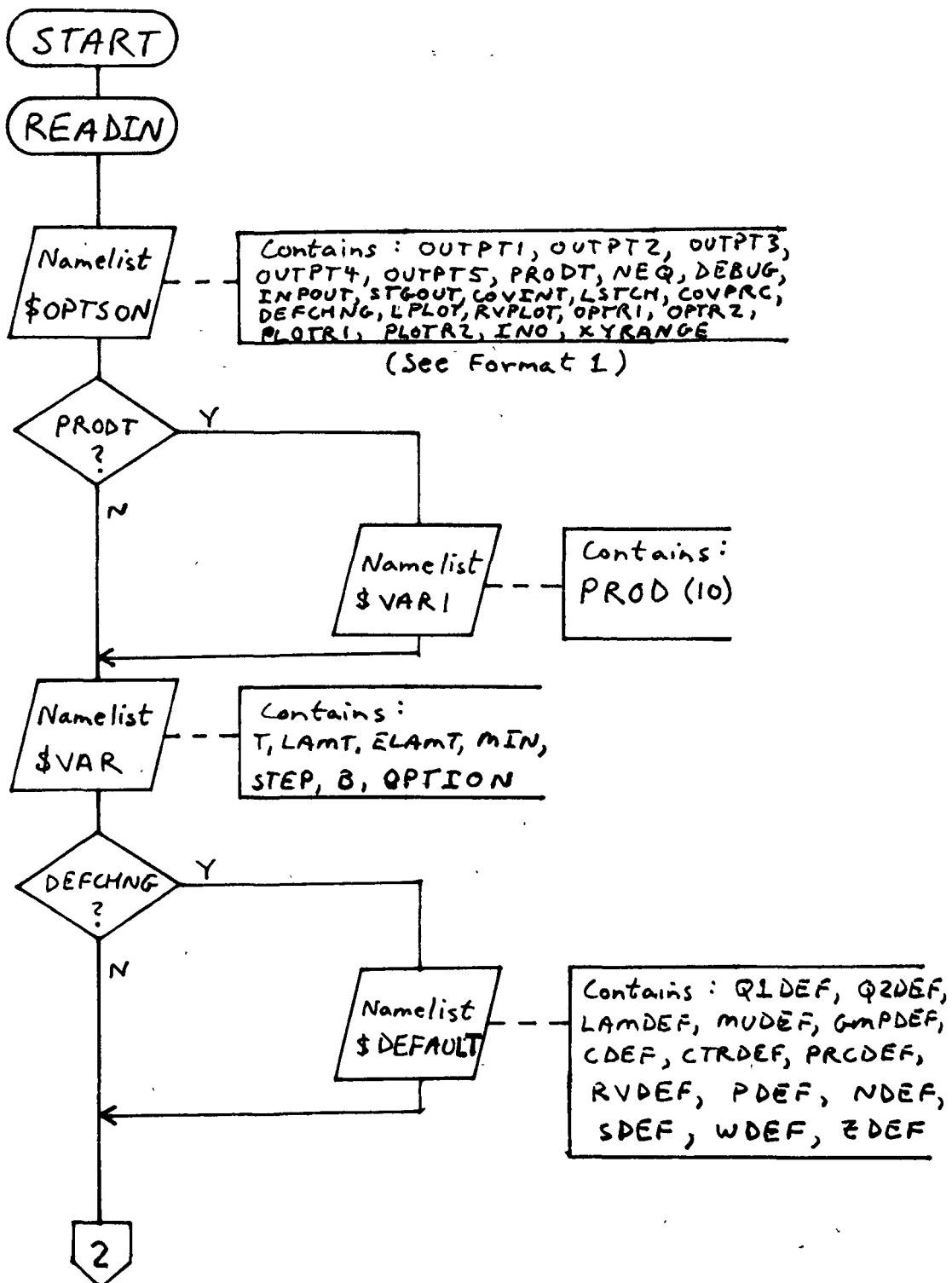


FIGURE 5-1 (Cont.)

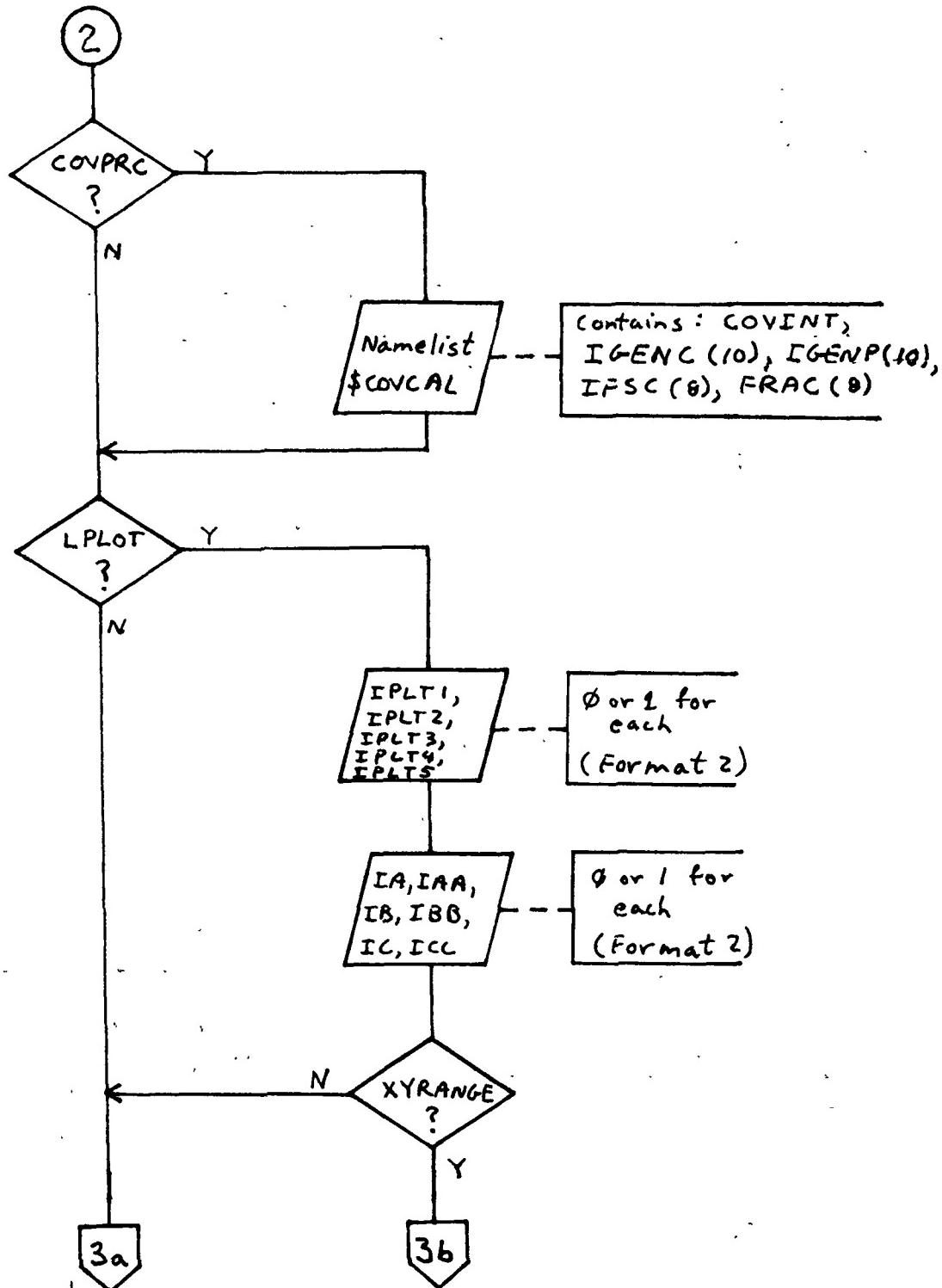


FIGURE 5-1 (Cont.-2)

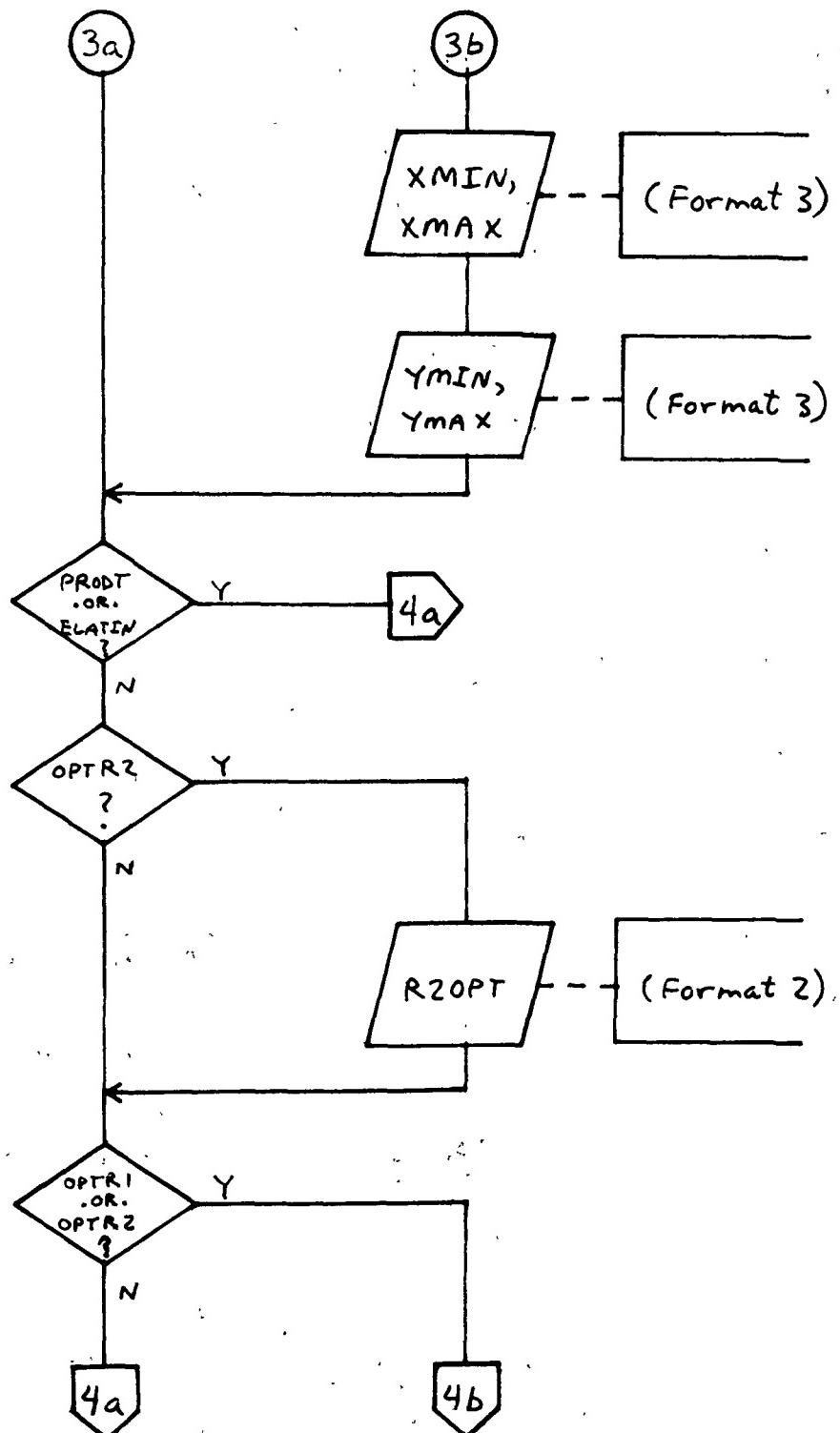


FIGURE 5-1 (Cont.-3)

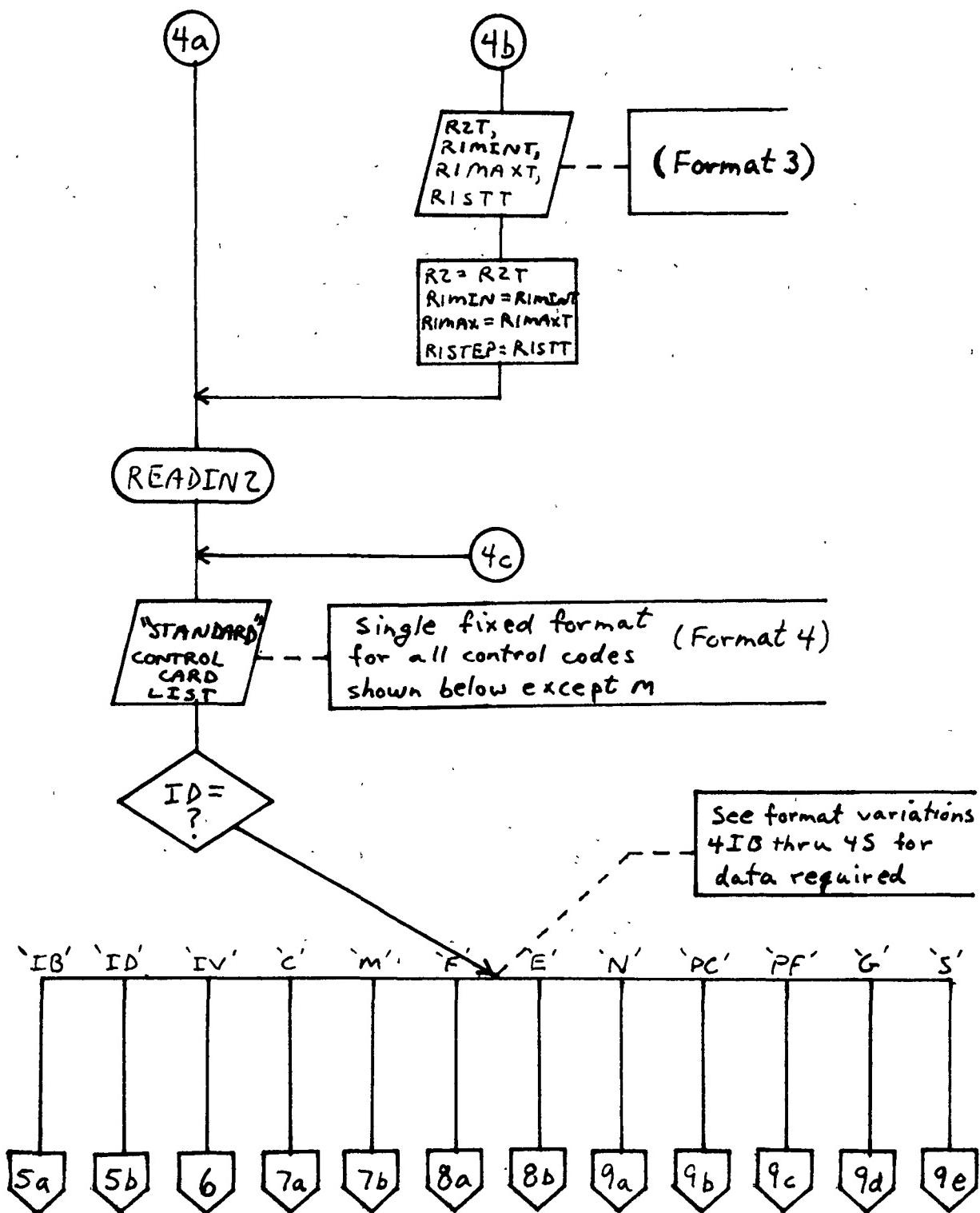


FIGURE 5-1 (Cont.-4)

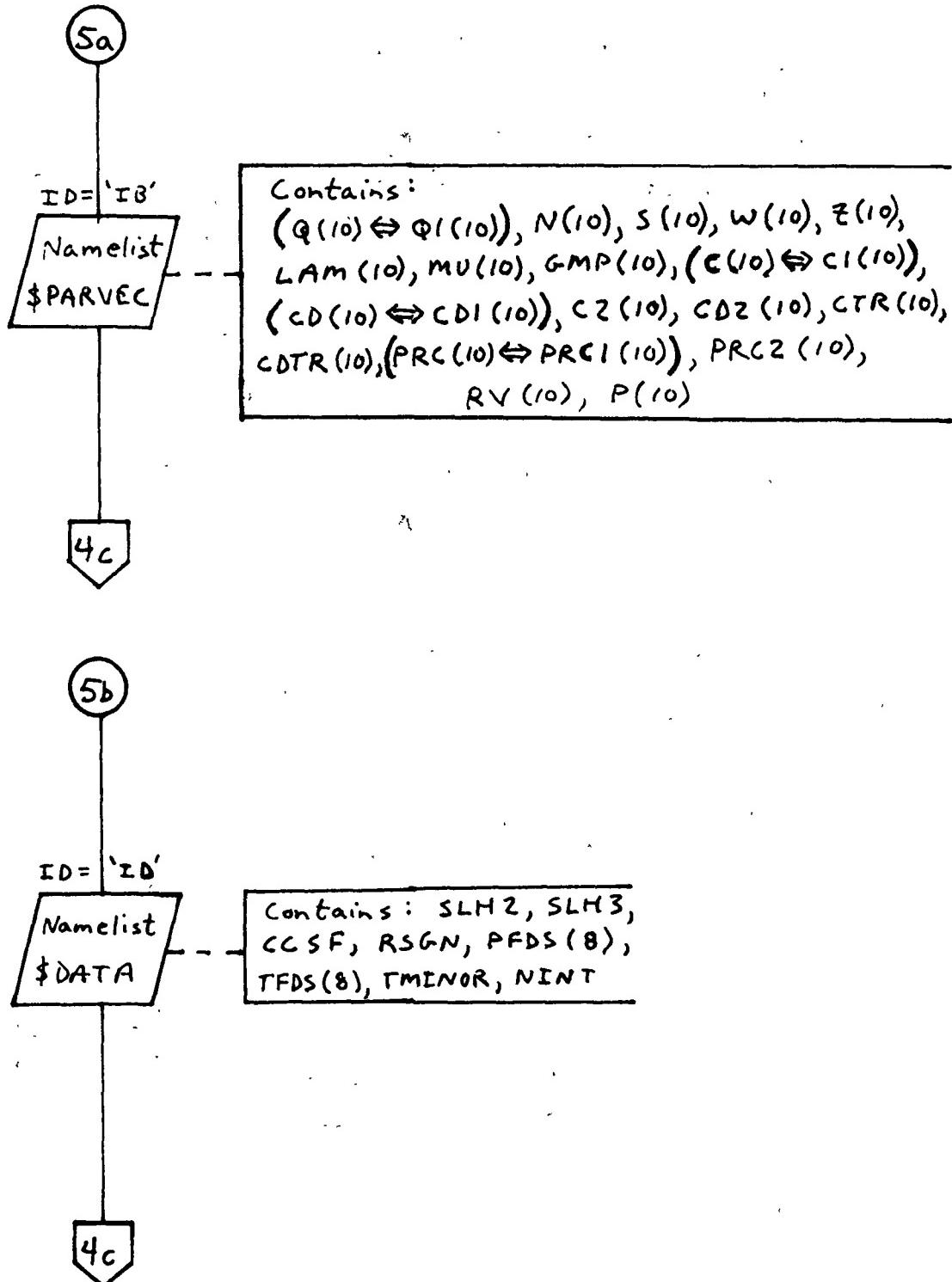


FIGURE 5-1 (Cont.-5)

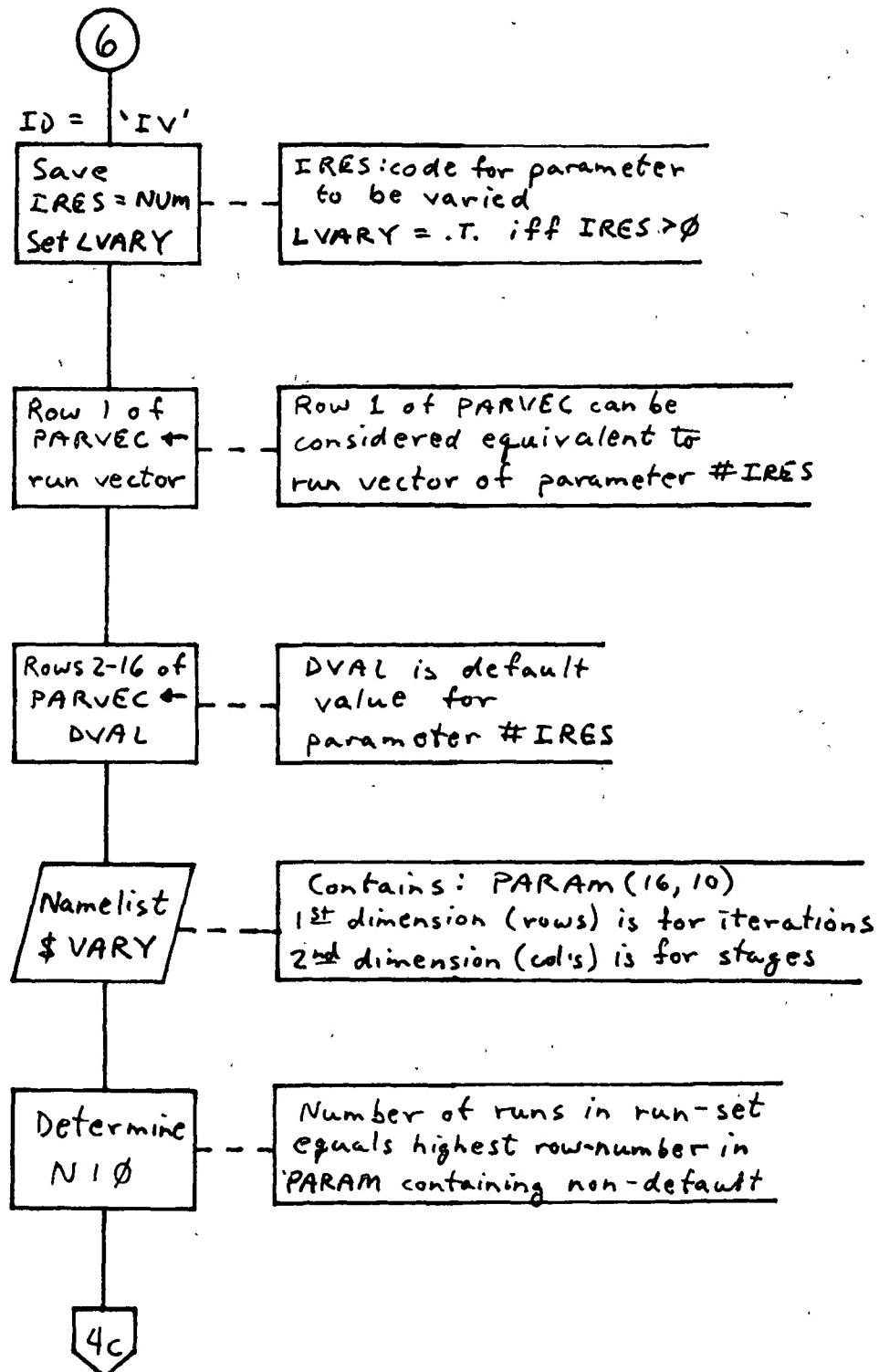


FIGURE 5-1 (Cont.-6)

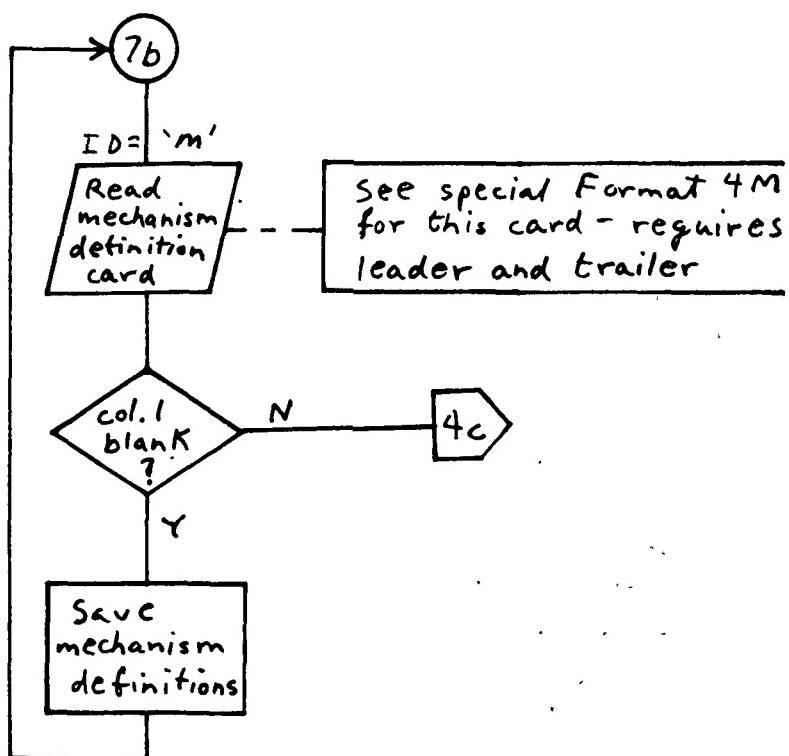
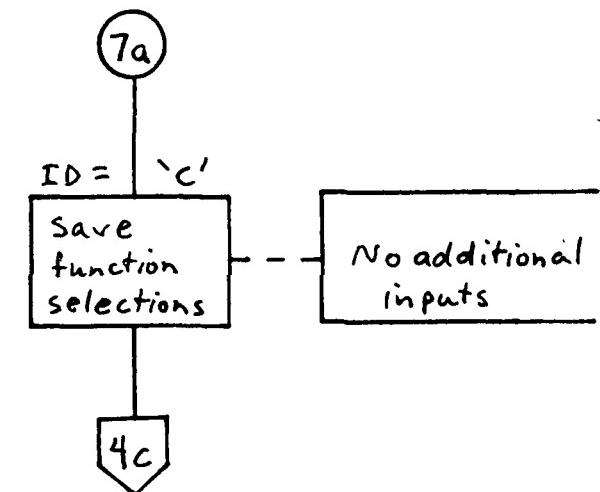


FIGURE 5-1 (Cont.-7)

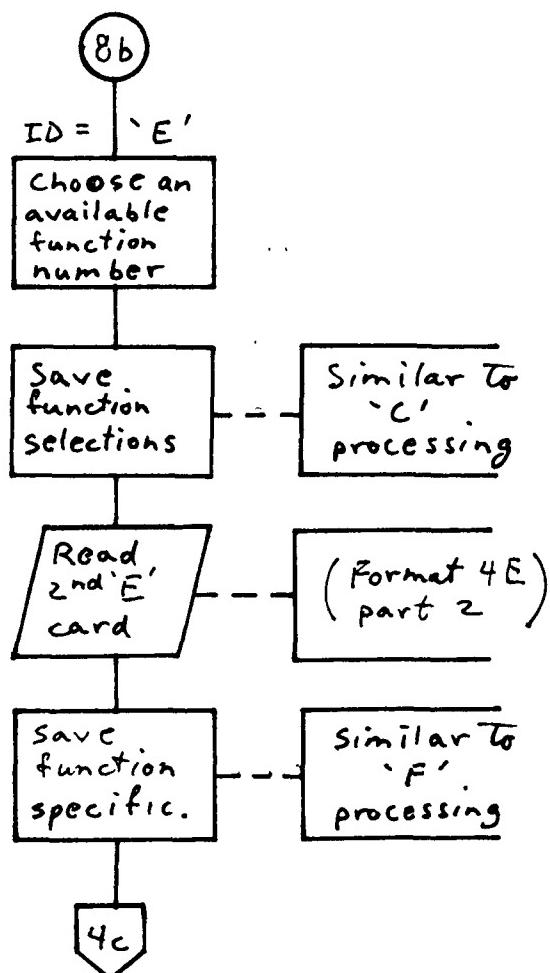
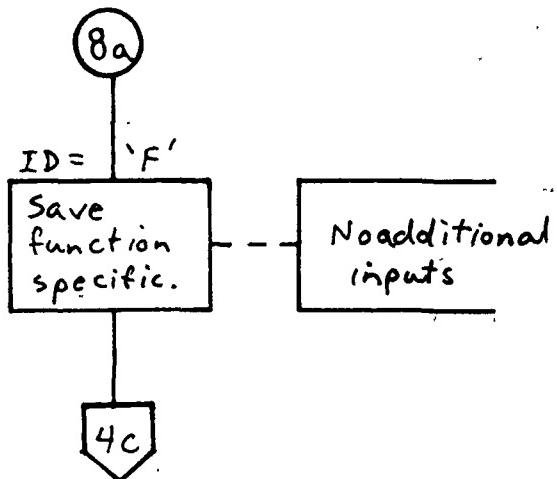


FIGURE 5-1 (Cont.-8)

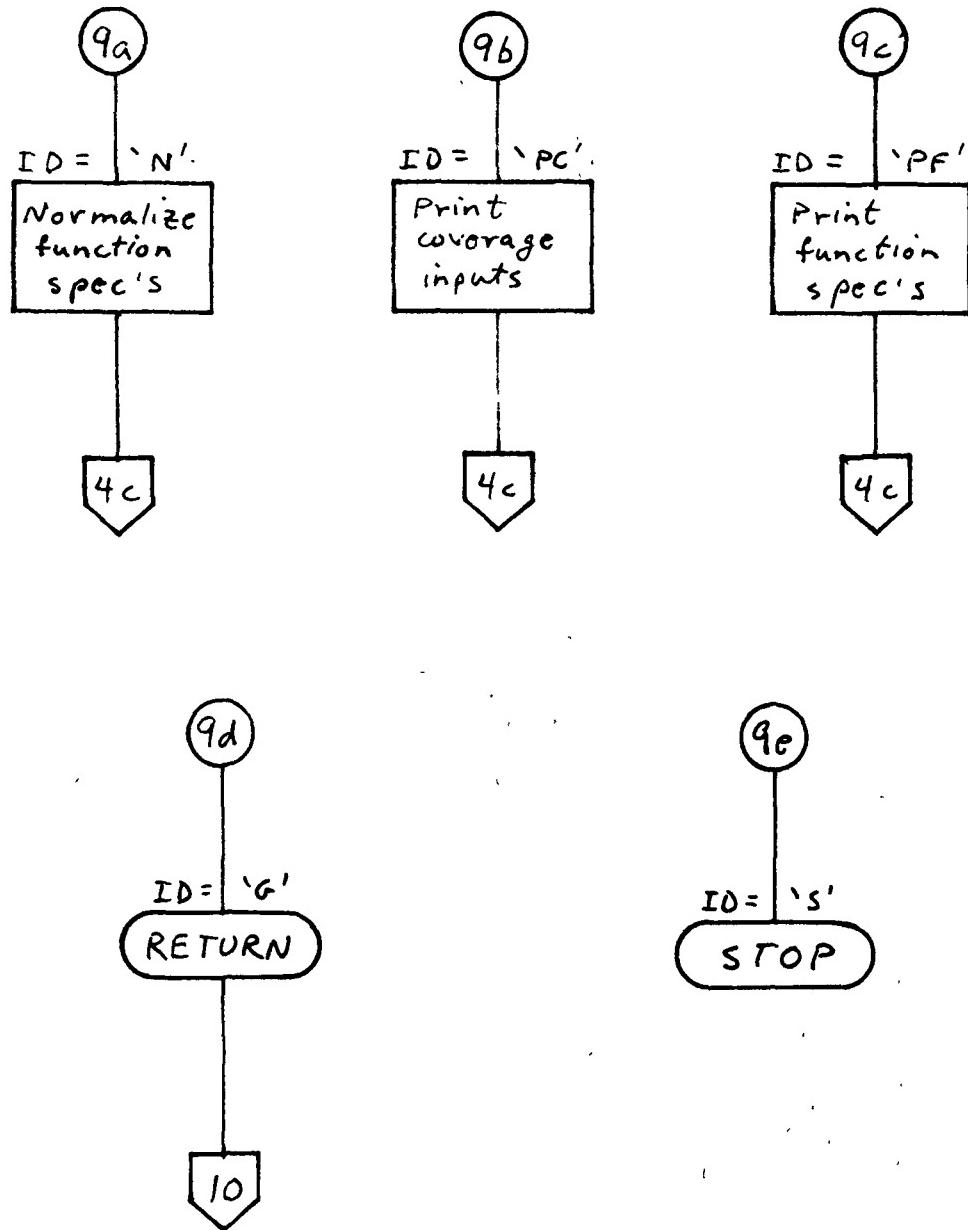


FIGURE 5-1 (Cont.-9)

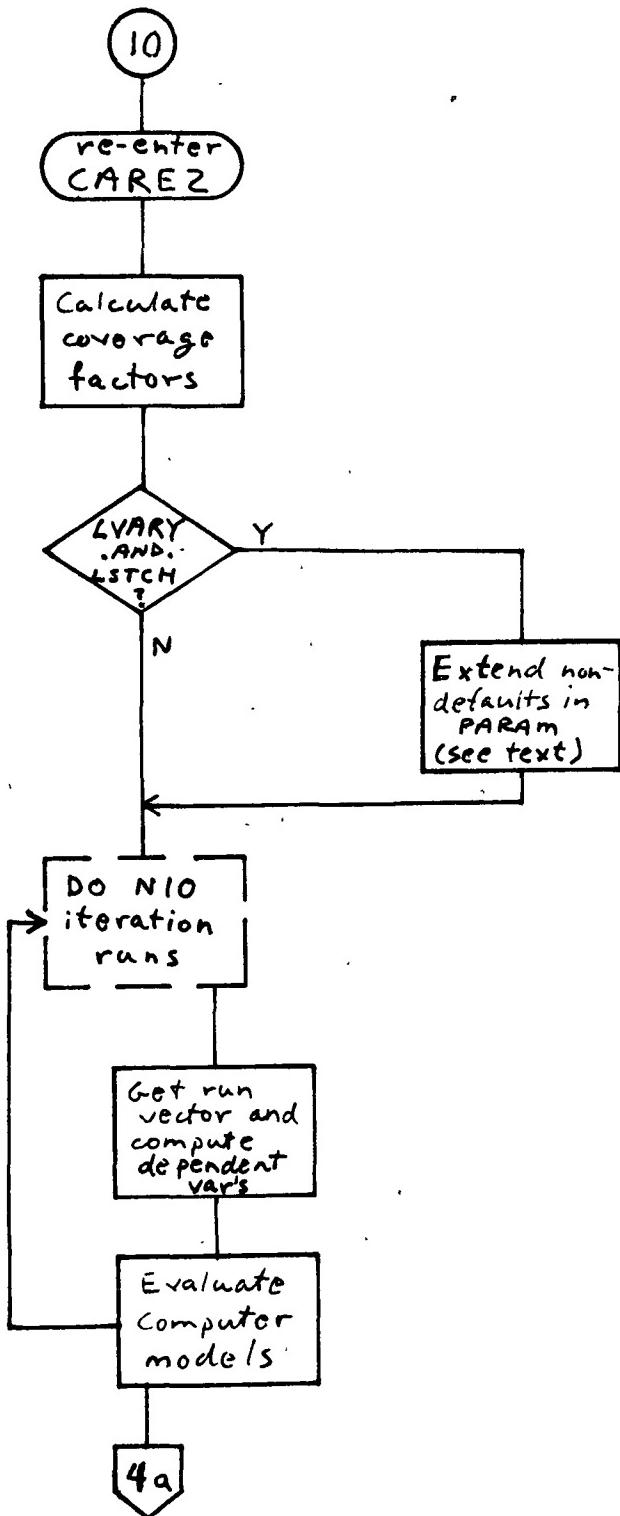


TABLE 5-1

DEFINITIONS OF LOGICAL AND CONTROL VARIABLES

PRODT	Logical: Specifies whether a list of equation numbers is desired rather than a single equation.
NEQ	Control: Specifies the single equation to be evaluated.
DEBUG	Logical: Specifies (if TRUE) that input format errors detected in READIN2 will not cause the job to abort, and that the reliability models will not be exercised.
INPOUT	Logical: Specifies (if TRUE) that a table of parameter values to be used for the subsequent run-set will be printed (regardless of the setting of DEBUG)
STGOUT	Logical: Specifies (if TRUE) that mode 1 reliability results for the dual mode model are to be printed.
COVINT	Logical: Specifies (if TRUE) that individual mechanism contributions are to be printed during the calculation of coverage.
LSTCH	Logical: Determines the convention used in the pre-processing of parameter iteration data in array PARAM. If TRUE, non-default elements replace default elements along the iteration dimension (those of increasing row subscript are replaced). For example, if the parameter default is 0, and a 1 is placed in PARAM (1,3), 0's in positions (2,3), (3,3), etc. will be replaced by 1's, up to the next non-default.
COVPRC	Logical: Specifies (if TRUE) that some coverage factors will be calculated (under the condition that subsequent requirements are met).
DEFCHNG	Logical: Specifies (if TRUE) that some default values for parameter vector initialization are to be changed.

TABLE 5-1 (cont.)

L PLOT Logical: Specifies (if TRUE) that the reliability product table is to be plotted on the line printer.

PROD(10) Control: The list of equation numbers for a product of reliabilities, to specify the number of stages in the dual mode model, or both.

T Control: The upper limit for reliability tables when the independent variable is time. Time must be used when the dual mode model is evaluated.

LAMT Control: The upper limit for reliability tables when the independent variable is failure rate * time.

ELAMT Control: The upper limit for reliability tables when the independent variable is the exponential of (failure rate * time).

MIN Control: The lower limit of the independent variable. This must be 0.0 when the dual mode model is evaluated.

STEP Control: The increment of the independent variable.

ID Control: The 1 or 2 letter code beginning in column 1 of a READIN2 control card, which identifies an input or processing request.

XYRANGE,OPTR2 See original CARE documentation.

TABLE 5-2
CONTROL CARDS

<u>Identifier</u>	<u>Control Function</u>
IB	- Input the base-run parameter vectors (for reliability models) via namelist PARVEC
ID	- Input system data via namelist DATA, specifically: SLH2, SLH3, CCSF, RSGN, PFDS, TFDS, TMINOR, and NINT.
IV	- Input the variation parameter type code, followed by namelist VARY with changed values for array PARAM.
C	- Read a subset of the D/I/R mechanism data base (function number arrays). One function number is specified for one process (detection, isolation, recovery (1 of 2)), but the number may be distributed over any or all of 4 dimensions: <ul style="list-style-type: none"> ● subclass of faults (1 thru 8) ● mode (0, 1 or 2) ● error type (1 = permanent, 2 = transient) ● mechanism (1 thru 20)
M	- Begin reading D/I/R mechanism definitions (function number selections) at the rate of one mechanism (for one fault subclass) per card. The selections must completely define the characteristics of the 4 processes comprising the mechanism, for all conditions of mode and error type.
F	- Read one function specification for one process (detection, isolation, recovery) of the recovery system. Function number and specifications use a common fixed format (based on the scheduled detection function), but fields which do not apply may be left blank.

TABLE 5-2 (Cont.)

<u>Identifier</u>	<u>Control Function</u>
E	- Read an explicitly defined subset of the D/I/R mechanism data base. This is a combination of the C and F control cards, in which the function number selection is automatic. The formats for the auxiliary information (on 2 cards) are identical to those of the C and F cards.
N	- Normalize the function specifications. The normalization involves all defined functions for all 4 processes. A trial integration is performed for detection and isolation rate functions over their specified non-zero ranges. The respective P1 values are then adjusted to obtain an integral value of 1.0 (P1 is assumed to be an internal coefficient of each function). The recovery probability functions are sampled over their specified ranges, and must be ≤ 1.0 at each sample point. Finally, the explicit coefficients for all functions (each of 4 specification arrays) are tested, and must be ≤ 1.0 . Appropriate messages are printed during or after normalization.
PC	- Display the contents of the D/I/R mechanism data base. The function numbers selected to define recovery subsystems are printed, with conditions which may cause errors flagged with the letter X.
PF	- Display the specifications of all defined functions,
G	- Exit READIN2 and execute the run-set. Coverage and reliability models will be exercised if the DEBUG flag is not set. Otherwise, the requested coverage calculations are performed and the selected runset input data is printed (including coverage and iteration values), prior to re-entering READIN2.
S	- Stop the program (optional, equivalent to an end-of-file on input).

Format 1 - Sample Namelist Reference	
1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 23 24 25 26 27 28 29 30 31 32 33 34 35 36 37 38 39 40 41 42 43 44 45 46 47 48 49 50 51 52 53 54 55 56 57 58 59 60 61 62 63 64 65 66 67 68 69 70 71 72 73 74 75 76 77 78 79 80	
<code>NAMELIST FIRSTY=1.0, NEXT=2, ARRAY(1,1)=3, 0, 4*4, ARRAY(2,3)=6\$</code>	<ul style="list-style-type: none"> - repetition shown by '*' - some operating systems require array subscripts - separate entries or values with commas - only variable included in the Namelist - Namelist identifier as given in Fortran Namelist declaration - is in column 2 of first input record, and after last data item - column 1 blank on all input records
<code>IJKMN</code>	<ul style="list-style-type: none"> - one digit integers, one per column
<code>(4 F8.0)</code>	
<code>AA-BB</code>	<ul style="list-style-type: none"> - matched 1-decimal point assumed after last digit in field
<code>C.DDDDD.D</code>	<ul style="list-style-type: none"> - matched 2-decimal point shown overrides format specification

TABLE 5-3
INPUT FORMATS AND EXAMPLES

1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 23 24 25 26 27 28 29 30 31 32 33 34 35 36 37 38 39 40 41 42 43 44 45 46 47 48 49 50 51 52 53 54 55 56 57 58 59 60 61 62 63 64 65 66 67 68 69 70 71 72 73 74 75 76 77 78 79 80	
<u>Format 4 - (2A3,2I4,2I2,6E10.5) Standard READINZ Control Card</u>	
based on requirements of 'F' card with scheduled detector specifications.	
<u>A' B' I I I I I I I I K L M N M N C C C C . C C C C G D D D D . D D D D E E E E . E E E E E F F F F . F F F F F G G G G . G G G G H H H H . H H H H H H</u>	
COEF TDEI P1 P2 P3 TDUU (real) (real) (real) (real)	
TREP or MKN (4 digit integer, rt, just, *)	
ISCH or IET (1 digit integer)	
LINTA or MD (1 digit integer)	
IIGFT or ISU (4 digit integer, rt, just)	
Num (4 digit integer, rt, init.)	
IP (3 character code, lf, just)	
ID (3 character code, lf, just)	

TABLE 5-3 (Cont..)

<pre> 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 23 24 25 26 27 28 29 30 31 32 33 34 35 36 37 38 39 40 41 42 43 44 45 46 47 48 49 50 51 52 53 54 55 56 57 58 59 60 61 62 63 64 65 66 67 68 69 70 71 72 73 74 75 76 77 78 79 80 </pre>																					
<p>Format 4IB - Input base run vectors</p>																					
<p>'A'</p> <p>'I B'</p>	<p>'IB' in col's 1 & 2</p>																				
<p>Format 4ID - Input system data</p>	<p>'A'</p>																				
<p>'I D'</p>	<p>'ID' in col's 1 & 2</p>																				
<p>Format 4IN - Input variation data</p>	<p>'A'</p>																				
<p>'I I'</p>	<p>'II' Parameter vector to be replaced prior to each run specification:</p>																				
<p>'I I'</p>	<table> <tbody> <tr> <td>1 \Rightarrow Q = Q1(10)</td> <td>6 \Rightarrow Z(10)</td> <td>11 \Rightarrow C01(10)</td> <td>16 \Rightarrow PRC1(10)</td> </tr> <tr> <td>2 \Rightarrow Q2(10)</td> <td>7 \Rightarrow LAM(10)</td> <td>12 \Rightarrow C2(10)</td> <td>17 \Rightarrow ARC2(10)</td> </tr> <tr> <td>3 \Rightarrow N(10)</td> <td>8 \Rightarrow MUL(10)</td> <td>13 \Rightarrow C02(10)</td> <td>18 \Rightarrow RV(10)</td> </tr> <tr> <td>4 \Rightarrow S(10)</td> <td>9 \Rightarrow CMP(10)</td> <td>14 \Rightarrow CTR(10)</td> <td>19 \Rightarrow PC(10)</td> </tr> <tr> <td>5 \Rightarrow W(10)</td> <td>10 \Rightarrow C=C1(10)</td> <td>15 \Rightarrow CSTR(10)</td> <td></td> </tr> </tbody> </table> <p>'II Y' in col's 1 & 2</p>	1 \Rightarrow Q = Q1(10)	6 \Rightarrow Z(10)	11 \Rightarrow C01(10)	16 \Rightarrow PRC1(10)	2 \Rightarrow Q2(10)	7 \Rightarrow LAM(10)	12 \Rightarrow C2(10)	17 \Rightarrow ARC2(10)	3 \Rightarrow N(10)	8 \Rightarrow MUL(10)	13 \Rightarrow C02(10)	18 \Rightarrow RV(10)	4 \Rightarrow S(10)	9 \Rightarrow CMP(10)	14 \Rightarrow CTR(10)	19 \Rightarrow PC(10)	5 \Rightarrow W(10)	10 \Rightarrow C=C1(10)	15 \Rightarrow CSTR(10)	
1 \Rightarrow Q = Q1(10)	6 \Rightarrow Z(10)	11 \Rightarrow C01(10)	16 \Rightarrow PRC1(10)																		
2 \Rightarrow Q2(10)	7 \Rightarrow LAM(10)	12 \Rightarrow C2(10)	17 \Rightarrow ARC2(10)																		
3 \Rightarrow N(10)	8 \Rightarrow MUL(10)	13 \Rightarrow C02(10)	18 \Rightarrow RV(10)																		
4 \Rightarrow S(10)	9 \Rightarrow CMP(10)	14 \Rightarrow CTR(10)	19 \Rightarrow PC(10)																		
5 \Rightarrow W(10)	10 \Rightarrow C=C1(10)	15 \Rightarrow CSTR(10)																			

TABLE 5-3 (Cont. -2)



TABLE 5-3 (Cont. -3)

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TABLE 5-3 (Cont. -4)

5.1.3 Specific Input Information

Inputs for the dual mode model are described in Sections 2.3 and 3.3, and are relatively easy to comprehend. For reason of its greater flexibility, coverage model input requirements are considerably more complex, and thus additional learning aids might well prove useful.

In particular, it is felt that preliminary experimentation, by the user, may be required in order to become sufficiently familiar with the tool to use it effectively. For this reason, a set of input values is provided (cf. Tables 5-4 and 5-5) which reflect the coverage system described in Section 2.2.

Table 5-4 gives specifications for the above referenced detection, isolation and recovery characteristics, which, in turn, may then be applied to measure the effects of these processes on different subclasses of faults, under various conditions, e.g., permanent versus transient faults, mode 1 versus mode 2 operation, etc.. Table 5-6 defines the individual variables which comprise the specification of a single function, (cf. Format 4F in Table 5-3 for individual specification requirements of the 4 processes) as well as the other important variables in the coverage model.

Table 5-5 gives the function selection data for a complete system of fault coverage. For example, the 4 numbers in the upper right hand corner of the table (under the heading "Permanent Fault/Mode 0") indicate the non-competitive (i.e., stand-alone) effectiveness of detector #2 and its associated isolation and recovery processes, under a particular set of specified conditions (i.e., that a permanent failure has occurred in the stage linked with fault subclass 1, and that the recovery is predicted on degenerating from mode 1 to mode 2 operation (shown as mode 0)).

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TABLE 5-4

FUNCTION SPECIFICATIONS

FUNCTION	#	IGFT	ISCH	IREP	INTF	COEF	TDEL	A _{P1}	B _{P2}	C _{P3}	TDUR
DETECTION (D)	1	0	0	-	1	1	0	-	-	-	-
"	2	0	0	-	1	0.25	0	-	-	-	-
"	3	0	0	-	1	0.1	0	-	-	-	-
"	4	0	1	1	1	0.05	19.3	-	-	-	-
"	5	0	0	-	1	0.025	0	-	-	-	-
"	6	0	0	-	1	.9844	0	-	-	-	-
"	7	0	1	1	1	0.05	19.7	-	-	-	-
"	8	0	1	1	1	1	19.7	-	-	-	-
"	9	3	0	-	1	1	0	.0910	0.09	0	50
"	10	3	1	1	1	0.95	0	.7218	0.7	0	5
"	11	1	1	1	1	0.8	5	0.5	-	-	2
"	12	1	1	1	1	0.05	5	0.5	-	-	2
"	13	1	1	1	1	0.2	5	0.5	-	-	2
"	14	1	1	1	1	0.05	0	0.2	-	-	5
"	15	1	1	1	1	0.2	0	0.2	-	-	5
"	16	1	0	-	1	0.1	0	0.1	-	-	10
"	17	1	0	-	1	0.25	0	0.1	-	-	10
"	18	0	1	4	1	1	19.3	-	-	-	0
"	19	0	1	4	1	0.8	19.3	-	-	-	0
ISOLATION (I)	1	0	-	-	1	1	0.5	-	-	-	-
"	2	1	-	-	1	0.99	0	0.04	-	-	25
"	3	0	-	-	1	0.8	20	-	-	-	-
RECOVERY (E)	1	1	-	-	1	1	-	1	-	-	10,000
"	2	3	-	-	1	.1	-	1	.0063	0	200
RECOVERY (T)	1	1	-	-	1	.9999	-	1	-	-	10,000
"	2	3	-	-	1	.9999	-	1	0.023	-	200

Note: column heading mnemonics are defined on the second sheet
of Table 5-6.

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TABLE 5-5
FUNCTION SELECTIONS - BY FAULT SUBCLASS

Mechanism Number	Permanent Fault/Mode 1	Permanent Fault/Mode 2	Transient Fault/Mode 1	Transient Fault/Mode 2	Permanent Fault/Mode 0 (Transitional)
	D I E T	D I E T	D I E T	D I E T	D I E T
	Subclass 1				
2	9 2 1 2	0 ---*	9 3 1 2	0 ---	9 2 1 2
3	11 1 1 1	11 1 2 2	0 ---	0 ---	11 1 1 1
5	2 1 1 1	2 1 1 2	2 1 1 1	2 1 1 2	2 1 1 1
6	3 1 1 1	3 1 1 2	3 1 1 1	3 1 1 2	3 1 1 1
	Subclass 2				
2	9 2 1 2	0 ---	9 3 1 2	0 ---	9 2 1 2
3	12 2 1 1	12 2 2 2	0 ---	0 ---	12 2 1 1
4	10 1 1 1	10 1 2 2	0 ---	0 ---	10 1 1 1
5	16 2 1 1	16 2 1 2	16 3 1 1	16 3 1 2	16 2 1 1
6	17 2 1 1	17 2 2 2	17 3 1 1	17 3 2 2	17 2 1 1
7	2 1 1 1	2 1 1 2	2 1 1 1	2 1 1 2	2 1 1 1
8	4 2 1 1	4 2 2 2	0 ---	0 ---	4 2 1 1
9	5 1 1 1	5 1 1 2	5 3 1 1	5 3 1 2	5 1 1 1
10	5 1 1 1	5 1 1 2	5 3 1 1	5 3 1 2	5 1 1 1
12	7 2 1 1	7 2 2 2	0 ---	0 ---	7 2 1 1
	Subclass 3				
1	1 1 1 1	1 1 1 2	1 1 1 1	1 1 1 2	1 1 1 1
2	9 2 1 2	0 ---	9 3 1 2	0 ---	9 2 1 2
3	12 2 1 1	12 2 2 2	0 ---	0 ---	12 2 1 1
4	14 2 1 1	14 2 2 2	0 ---	0 ---	14 2 1 1
5	16 2 1 1	16 2 1 2	16 3 1 1	16 3 1 2	16 2 1 1
8	18 1 1 1	18 1 2 2	18 3 1 1	18 3 2 2	18 1 1 1
9	5 1 1 1	5 1 1 2	5 3 1 1	5 3 1 2	5 1 1 1
10	5 1 1 1	5 1 1 2	5 3 1 1	5 3 1 2	5 1 1 1
12	7 2 1 1	7 2 2 2	0 ---	0 ---	7 2 1 1
	Subclass 4				
2	9 2 1 2	0 ---	9 3 1 2	0 ---	9 2 1 2
3	13 2 1 1	13 2 2 2	0 ---	0 ---	13 2 1 1
4	15 2 1 1	15 2 2 2	0 ---	0 ---	15 2 1 1
5	16 2 1 1	16 2 1 2	16 3 1 1	16 3 1 2	16 2 1 1
6	3 1 1 1	3 1 1 2	3 1 1 1	3 1 1 2	3 1 1 1
8	19 1 1 1	19 1 2 2	0 ---	0 ---	19 1 1 1
9	5 1 1 1	5 1 1 2	5 3 1 1	5 3 1 2	5 1 1 1
10	5 1 1 1	5 1 1 2	5 3 1 1	5 3 1 2	5 1 1 1
11	6 1 1 1	6 1 1 2	6 1 1 1	6 1 1 2	6 1 1 1
12	8 1 1 1	8 1 2 2	0 ---	0 ---	8 1 1 1
	Subclass 5				
3	11 1 1 1	11 1 2 2	0 ---	0 ---	11 1 1 1
6	3 1 1 1	3 1 1 2	3 1 1 1	3 1 1 2	3 1 1 1

*0 --- represents a null contribution to coverage. Accordingly, when setting up program input data, no entry need be provided.

TABLE 5-6
COVERAGE MODEL PARAMETERS

COVAGE Arguments

- ISU - Fault subclass number (1-8)
- MD - Mode of operation:
 - 1 for full up
 - 2 for degenerate
 - 0 for transitional (from MD = 1 to MD = 2)
- IET - Fault type code:
 - 1 for permanent
 - 2 for transient
- JS - Number of spare LRU's which must be checked out before recovery can proceed. (normally 0 or 1).

Basic Working Variables

- Function Pointer Arrays (Common Block CVB1).
 - NDET(20,8) - Detection rate function numbers
 - NISO(20,8) - Isolation rate function numbers
 - NEPR(20,8) - Error propagation recovery function numbers
 - NTLR(20,8) - Time lost recovery function numbers
 - where:
 - o 1st subscript is D/I/R mechanism
 - o 2nd subscript is fault subclass number
- Function Specification Arrays (Common Block CVB2)
 - FDET(7,200) - Detection function specifications
 - FISO(7,50) - Isolation function specifications
 - FEPR(7,25) - Error propagation recovery function specifications
 - FTLR(7,25) - Time lost recovery function specifications
 - where:
 - o 1st subscript is word within a specification
 - o 2nd subscript is function number within the specification array.

TABLE 5-6 (Cont.)

Function Specification Element Descriptors

- - CODES - (Word #1) - contains 5 packed integer codes:
 - IGFT - Function Model Identifier (specifies a characteristic curve), (0 = impulse, 1 = constant, 2 = pulse train, 3 = decaying exponential), (0 not applicable for recovery)
 - ISCH - Scheduling code (0 = no, 1 = yes), (detectors only)
 - IREP - Repetition factor in minor cycles, (scheduled detectors only)
 - IDEF - Function defined flag (0 = no, 1 = yes), (set automatically when specifications are input)
 - INTF - Integral defined flag (0 = no, 1 = yes).
- COEF - (Word #2) - Explicit function multiplier
- TDEL - (Word #3) - Delay before the function becomes non-zero (must be zero for recovery functions)
- P1, P2, P3 - (Word #4, 5, 6) - Arbitrary parameters passed to the function model for evaluation. Note that if automatic normalization is requested by the user, all function models used by detection or isolation functions must use P1 as the normalizing coefficient
- TDUR - (Word #7) - Time during which the function is non-zero (must be zero for impulse functions).
- Computer System Dependent Variables (Common Blocks CVBO, CVB5 and CVB6)
 - PFDS(8) - Probability of detecting a failure in a spare LRU during initial checkout, for each of 8 fault subclasses
 - TFDS(8) - Time delay incurred in checking out a spare LRU, for each of 8 fault subclasses

TABLE 5-6 (Cont. -2)

- LCM - Least common multiple of the ni's where ni is the repetition factor (where applicable) of the ith detector, expressed in terms of minor cycles, and automatically generated by CARE2
- TMINOR - Duration of a minor cycle, in units compatible with all rate functions
- IFSC(8) - Reliability model stage in which the a fault subclass is located, for each of 8 subclasses
- FRAC(8) - Fraction of total stage (class) faults which occur in a fault subclass, for each of 8 subclasses. (Used in conjunction with IFSC to specify the relationship between subclasses and stages, thus enabling calculation of stage coverage values on the basis of weighted average subclass coverages)

COVAGE Call Level Intermediate Variables

- NDSAV(20) - Detector rate function numbers
- NISAV(20) - Isolation rate function numbers
- NR1SAV(20) - Error Propogation recovery function numbers
- NR2SAV(20) - Time lost recovery function numbers
- ICHAR(20) - Characteristic of detection/recovery mechanism:
 - 0 if mechanism is inoperative
 - 1 if detector is unscheduled - impulse
 - 2 if detector is unscheduled - finite
 - 3 if detector is scheduled-impulse
 - 4 if detector is scheduled-finite
- IREPAR(20) - Repetition rate of detector (if applicable)

TABLE 5-6 (Cont. -3)

- PERIAR(20) - Period of repetition (if applicable) of detection functions
- TDELAR(20) - Delay times for detection functions
- PDIRAR(20) - Non-competitive probability of detection, isolation, and recovery, given that JS spares must be checked before recovery can proceed
- INDEX - Function of arguments IET and MD as follows:

<u>IET</u>	<u>MD</u>	<u>INDEX</u>
-	0	5
1	1	1
1	2	2
2	1	3
2	2	4

- GPFLG - Flag indicating the meaning of array CVGP:
when .FALSE., GPAR = $g'(i, \tau)$
when .TRUE., GPAR = $G'(i, \tau)$

D/I/R Evaluation Level Intermediate Variables

- IMPG (logical) - = .TRUE. when detector is an impulse
- IMPH (logical) - = .TRUE. when isolator is an impulse
- GPAR(N) - one row of the GPAR(20,N) array, which is alternately used to hold values of $g'(i, \tau)$ and $G'(i, \tau)$
- INDEX - (constant for COVAGE call) - function of MD and IET
- TGFIN - Last time at which $g(t)$ is non-zero
- THFIN - Last time at which $h(t')$ is non-zero
- TR1FIN - Last time at which $r'(\tau')$ is non-zero
- TR2FIN - Last time at which $r'(\tau + \tau')$ is non-zero

5.2 OPERATIONAL LIMITS

The numerical limits of CARE2 are shown in Table 5-7. Most of these are self explanatory, however particular attention is directed to the last item, entitled numerical integration steps. As noted, there are three independent step-size controls, applicable to the various integration algorithms, all of which use the Simpson 3-point parabolic integration scheme. (This standard numerical integration method was chosen because of its affinity for exponential curves).

For the dual mode model, the integrations performed in subprograms DCT and DCT2 divide the integrand into 3-point Simpson's Rule segments, with a base width of STEP time units. Optimal condition accuracy tests performed here show minor variation in the 8th decimal digit, given a T/STEP ratio of 10 or more.

The integrations performed in COVAGE, and its secondary subprograms, use a fixed number of 3-point segments controlled by NINT, and pre-determine the non-zero portion of the integrands for optimum efficiency. Since new function models, of any form, may be added to the current set (cf. section 4.2.4.21), it necessarily falls to the user to determine their accuracy. This may be accomplished by experimenting with NINT, which may be set at run time via control card ID in READIN2.

The last integration control is variable N in FINTEG (the coverage characteristic curve (function) integrator). N may be altered by recompiling FINTEG.

The user is encouraged to provide a corresponding integral model for each function model that is added, thereby precluding the need for numerical integration (cf. Section 4.2.4.15). Otherwise, the corresponding function specifications must be tagged as "integral not defined" (INTF=0), and the attendant inaccuracies of an additional integration contended with (cf. INTF discussion in section 4.2.4.9).

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TABLE 5-7
OPERATIONAL LIMITATIONS

<u>Item</u>	<u>Upper Limit</u>	<u>Comment</u>
Stages per equation type		
- equations 1 thru 6	1	
- equation 7	8	
Stages per system	10	
Total Equations of type		
- 1 thru 6 per system	10	
- 7 per system	1	
Fault classes/subclasses		
- per stage (equations 1,4,5,6)	0	
- per stage (equations 2,3,7)	8	
- per system	8	
Fault types		
- equations 1 thru 6	1	(permanent)
- equation 7	2	(permanent and transient)
Fault rates per stage		
- equations 1,2,3,4	2	(on-line and standby)
- equations 5,6	1	(on-line)
- equation 7	3	(on-line,standby and transient)
Modes		
- equations 1,2,3,5,6	1	(full-up)
- equation 4	2	(triplex, simplex)
- equation 7	2	(full-up, degenerate)
Calculated Coverage types		
- equations 1,4,5,6	0	
- equations 2,3	1	(permanent)
- equation 7	5	(permanent modes 1 and 2, transient modes 1 and 2, transitional)

TABLE 5-7 (Cont.)

<u>Item</u>	<u>Upper Limit</u>	<u>Comment</u>
Detectors per fault subclass		
- equations 1,4,5,6	0	
- equations 2,3,7	20	
D/I/R mechanisms per system	20	
Function specifications per system		
- Detection	200	
- Isolation	50	
- Recovery type E	25	
- Recovery type T	25	
Function models	4096	(4 currently defined)
Variable parameters per function model	3	
Time steps	121	
Parameter variations in run-set	16	
Run-sets per batch run	No limit	
Finite K	$<10^5$	(higher value, specified as λ/μ , calls K= ∞ model)
Numerical integration steps		
- Equation 7	$2 * [T/STEP]$	
- Coverage model	100	(may be changed between run-sets)
- Function models with undefined integrals	20	(may be increased w/o limit by changing data statement)

SECTION 6

EXAMPLES AND TEST CASE DATA

The test case data contained in this section was submitted to Langley Research Center, under separate cover, in compliance with Work Statement Paragraph 9.0. The sample problems so outlined were executed, first at the Raytheon computer facility and second at the Langley computer facility, in order to demonstrate both proper program execution and transferability between sites.

Test cases and data were selected on the combined basis of reflecting realistic problem input situations, and exercising both new interface code and new subroutines as supplied by Raytheon. In addition, the cases were chosen to serve as a tutorial base both for new users of CARE/CARE2 and also for those with previous experience in original CARE, but unfamiliar with the changes incorporated in the revised program.

Each of the listings is annotated in order to facilitate its interpretation. In the interest of brevity, all but the first reliability plot has been deleted.

6.1 JOB #1 - PRODUCT OF EQUATIONS 4 AND 2

Specifics:

- The first stage is a hybrid/simplex configuration consisting of 3 active LRU's and 1 spare LRU.
- The second stage is a standby replacement configuration consisting of 2 series LRU's, each with a single dedicated spare LRU.
- Lambda, for both stages, equals 1.0×10^{-4} failures per hour per LRU.
- Mu, for the first stage, equals 1.0×10^{-4} failures per hour per LRU initially and then, in sequence, takes on the values 5.0×10^{-5} and 0.0 respectively.
- Mu, for the second stage, is held constant at 0.0.
- Mission time equals 3×10^4 hours.
- Time step (for print and plot purposes) equals 10^3 hours.
- Coverage and Voter Reliability are defaulted.
- Output request is for both tabular reliability print-out and plot.

6.2 JOB #2 - PRODUCT OF EQUATION 4 AND 2, WITH CALCULATED COVERAGE

Specifics:

- Same as Job #1 except for Coverage values as related to permanent faults.
- Coverage for the second stage is to be calculated.

- Two stage 2 detectors are employed, each with the following characteristics:
 - Scheduled
 - Truncated exponential distribution
 - 95% detection probability
 - Run time of 0.01 seconds
 - One repetition per second
 - First delayed 0.0 seconds, second delayed 0.5 seconds
- Given detection of the fault, isolation and recovery probabilities are unity.

6.3 JOB #3 - DUAL MODE MODEL (DUAL CHANNEL) WITH PRESET COVERAGE
Specifics:

- Dual Channel configuration with two stages.
- Each stage has a single spare LRU.
- Spares reassignment, in the event of a single channel loss, is not allowed.
- Operation in degenerate mode (mode 2) is allowed, and requires one fully operational channel.
- Lambda, for both stages, is equal to $1*10^{-4}$ failures per hour.
- Mu, for both stages, is equal to $5.0*10^{-5}$ failures per hour.
- The transient error rate, for both stages, equals $1.1*10^{-5}$ per hour.
- Category 2 and 3 switch failure rates are $1.0*10^{-7}$ and $2.0*10^{-8}$ per hour respectively.

- Coverage values for the first stage are unity.
- Coverage values for the second stage, for full-up/ degenerate operation respectively, are:
 - Permanent - 0.999/0.98, with deltas of
0.999/0.998
 - Transitional - 0.999, with delta of 0.999
 - Transient - 0.99/0.95
- Mission time equals 10^4 hours.
- Time step equals 10^3 hours.
- Output request is for both tabular reliability printout and plot.

6.4 JOB #4 - DUAL MODE MODEL (DUAL CHANNEL) WITH PRESET COVERAGE,
MULTIPLE RUNS WITHIN RUNSET, AND SPARES REASSIGNMENT

Specifics:

- Same as Job #3 except for run time variation in spares quantity, and allowance of spares reassignment.
- Parameter selected for variation is the quantity of spare LRU's associated with Stage 1.
- This quantity takes on the values 0, 1 and 2 for runs 1, 2 and 3 respectively.
- Reassignment of spares, in the event of singular channel loss, is allowed.

6.5 JOB #5 - DUAL MODE MODEL (DUAL CHANNEL) WITH CALCULATED COVERAGE AND MULTIPLE RUNSETS

Specifics:

- Same as Job #3 except for Stage 2 coverage and multiple Stage 1 parameter variations.
- Lambda/Mu values, for the first stage, are as follows:
 - Run 1, Runset 1 - $1.0 \times 10^{-4} / 5.0 \times 10^{-5}$ failures per hour.
 - Run 2, Runset 1 - $1.0 \times 10^{-4} / 1.0 \times 10^{-4}$ failures per hour.
 - Run 1, Runset 2 - $1.0 \times 10^{-3} / 5.0 \times 10^{-4}$ failures per hour.
 - Run 2, Runset 2 - $1.0 \times 10^{-3} / 1.0 \times 10^{-3}$ failures per hour.
- Coverage, for Stage 2, is to be calculated based on the presence of Output Compare and CPU Selftest D/I/R mechanisms, using default data values.

6.6 JOB #6 - DUAL MODE MODEL (HYBRID CHANNEL) WITH CALCULATED COVERAGE AND MULTIPLE RUNSETS

Specifics:

- The first stage requires 3 operating LRU's in mode 1, 2 in mode 2, and has 1 spare LRU.
- The second stage requires 1 operating LRU in both modes, and has 2 spare LRU's.
- The third stage requires 2 operating LRU's in mode 1, 1 in mode 2, and has 1 spare LRU.

- Lambda, for stages 1, 2 and 3, equals 1.0×10^{-5} ,
 2.5×10^{-4} and 0.5×10^{-4} failures per hour per LRU,
respectively.
- K, for all stages, equals 2.0.
- Spares reassignment is allowed.
- Coverage values for the first stage, for mode 1/mode 2
operation respectively, are
 - Permanent - 0.998/0.99, with deltas of
0.995/0.99
 - Transitional - 0.996, with delta of 0.995
 - Transient - 0.99/0.97
- Coverage for the second stage is to be calculated
based on the presence of CPU Selftest, Invalid In-
struction and CPU Code, D/I/R mechanisms, using
default data values.
- Coverage for the third stage is to be calculated
assuming 2 fault subclasses, as described in suc-
ceeding line items.
- The first fault subclass accounts for 63% of LRU
faults, and employs memory code as the sole D/I/R
mechanism. Default data values are to be used.
- The second fault subclass accounts for 37% of LRU
faults, and employs address feedback as the sole
D/I/R mechanism. Default data values are to be used
only where not over-ridden by the following:

- Checkout time, for a spare, equals 0.1 seconds
- Detection probability equals 0.9996
- Isolation probability equals 0.99985 and has a pulse distribution of length 0.2 seconds
- Error propagation recovery coefficient equals 0.96 for mode 2 operation
- A second run to be performed, in which CPU Selftest for Stage 2 is to be executed every 0.4 seconds.
- Mission time equals 16×10^3 hours.
- Time step equals 2×10^3 hours.
- Output request is for tabular reliability data only.

6.7 JOB #7 - PRODUCT OF EQUATIONS 7, 4 AND 2

Specifics:

- Run consists of producing a product reliability, assuming the configurations of Job #3 and Job #1 to be in series in a reliability block diagram.
- All data values are as defined in the respective jobs with the exception of Mission time, which is set equal to 10^4 hours for the combined configuration.

FIGURE 6-1
JOB #1 INPUT/OUTPUT LISTINGS

\$OPTSON OUTPT1=T,OUTPT3=T,LPLOT=T,PRODT=T\$

\$VAR1 PROD(1)=4,2\$

\$VAR T=3.0E4,STEP=1.0E3,OPTION=1\$

10000

100000

IB

\$PARVEC Q(2)=1,Z(2)=2,S(1)=1,1,LAM(1)=2*1.0E-4,MU(1)=1.0E-4,0,0\$

IV 8

\$VARY PARAM(1,1)=1.0E-4,5.0E-5,0,0, PARAM(1,2)=3*0.0\$

G

S

CARE2 (COMPUTER-AIDED RELIABILITY ESTIMATION)

FIGURE 6-1 (Cont. -2)

DO YOU WISH TO HAVE YOUR RESPONSES TO MY
QUESTIONS PRINTED BACK FOR VERIFICATION.
DO YOU WISH TO FORM A COMPLEX EQUATION WHICH IS
THE PRODUCT OF THE PRIMARY EQUATIONS.

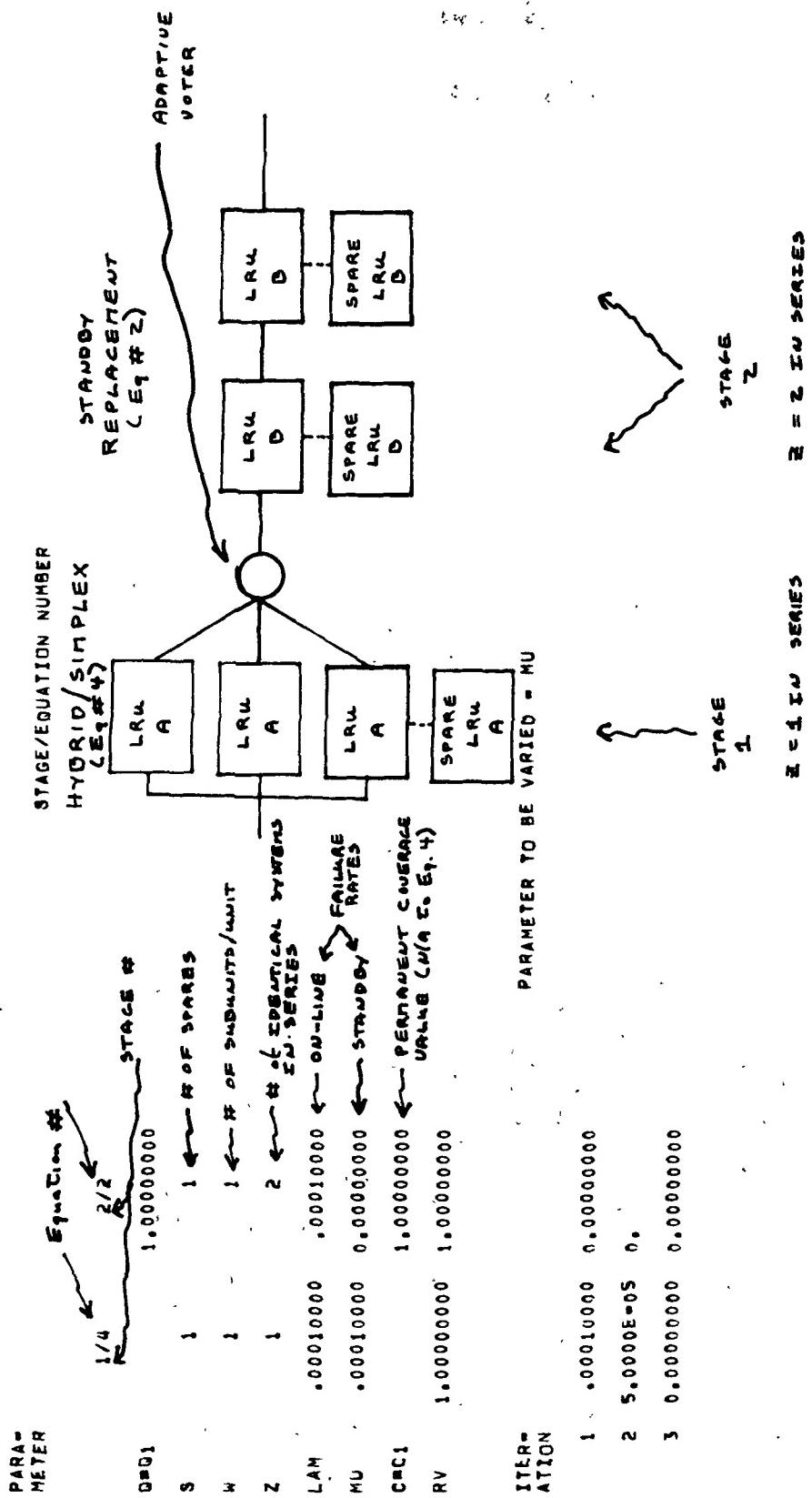
```

SVARI
PROD = 4, 2, 0, 0, 0, 0, 0, 0, 0,
SEND
DO YOU WISH TO HAVE 2-D RELIABILITY PLOTS?
INPUT A 1 IN THE COLUMN SPECIFIED BELOW IF YOU WISH
THE CORRESPONDING PLOT OPTION. OTHERWISE INPUT 0.
NOTE: WHEN PERFORMING PRODUCT OF RELIABILITIES, NO OTHER
PLOT OPTION BESESIDES PRODUCT OF RELIABILITIES MAY BE SPECIFIED.
COLUMN 1 = PLOTS PRODUCT OF RELIABILITIES,
COLUMN 2 = PLOTS RELIABILITY
COLUMN 3 = PLOTS DIFF, RIF, AND GAIN
COLUMN 4 = PLOTS MTF AND RELIABILITY AT MTF
COLUMN 5 = PLOTS UNRELIABILITY
10000
FOR ABSISSA, INPUT 1 IN COLUMN 1 IF ABSISSA IS 1,
1 IN COLUMN 2 IF ABSISSA IS LOG(T) = BASE 10,
1 IN COLUMN 3 IF ABSISSA IS LAMT,
1 IN COLUMN 4 IF ABSISSA IS LOG(LAMT) = BASE 10,
1 IN COLUMN 5 IF ABSISSA IS EXP(-LAMBDA(T)),
1 IN COLUMN 6 IF ABSISSA IS LOG(EXP(-LAMT)) = BASE 10.
100000
DO YOU WISH TO HAVE PRINTED TABLE OF RELIABILITY RESULTS
DO YOU WISH TO HAVE PRINTED TABLE OF DIFF, RIF,
AND GAIN RESULTS
DO YOU WISH MTF AND RELIABILITY AT MTF RESULTS PRINTED
DO YOU WANT PRINTED RESULTS OF THE MAXIMUM MISSION
TIME CALCULATIONS

```

DATA BASE FOR RUN-SET

FIGURE 6-1 (Cont.-3)



RUN 1 RELIABILITY RESULTS

FIGURE 6-1 (Cont.-4)

VALUES OF MU USED ARE
AS SPECIFIED IN ITERATION
1 ABOVE

STAGE 1 EQUATION NUMBER 4

T	REL	SIMREL	SIMGAIN	SIMRIF
0.0000000	1.0000000	1.0000000	1.0000000E+00	1.0000000E+00
1000.000	.9983584	.9048374	1.1033567E+00	5.7970848E+01
2000.000	.9891672	.8187308	1.2081715E+00	1.6733367E+01
3000.000	.9696913	.0303087	1.3089646E+00	8.5914063E+00
4000.000	.9401482	.6798518	1.4025200	5.5082705E+00
5000.000	.9021363	.0978637	1.4025844E+00	4.0205844E+00
6000.000	.8577434	.1422566	1.481713E+00	3.1716526E+00
7000.000	.8090678	.1909322	1.562905E+00	2.636152E+00
8000.000	.7579842	.2420158	1.6292628E+00	2.2753518E+00
9000.000	.7060520	.2939480	1.6869249E+00	1.4849209E+00
10000.000	.6545004	.3454996	1.7368794	2.0188277E+00
11000.000	.6042512	.3957466	1.7791165E+00	1.8295840E+00
12000.000	.5559707	.4440293	1.8152078E+00	1.6637467E+00
13000.000	.5100961	.4899037	1.8496018E+00	1.5737831E+00
14000.000	.4669006	.5310994	1.8716486E+00	1.4849209E+00
15000.000	.4265211	.5734789	1.9115394E+00	1.3946615E+00
16000.000	.3889951	.6110049	1.9267053E+00	1.3062145E+00
17000.000	.3542673	.6457127	1.9393501E+00	1.2657588E+00
18000.000	.3223112	.6776888	1.9498694E+00	1.2316879E+00
19000.000	.2929458	.7070542	1.9495686	1.9586044E+00
20000.000	.2660485	.7339513	1.9513353	1.9658475E+00
21000.000	.2414651	.7585349	1.95244564	1.9718452E+00
22000.000	.2190363	.7809637	1.9768937E+00	1.9588928E+00
23000.000	.1966032	.8013960	1.980941E+00	1.9227161E+00
24000.000	.1800105	.8199895	1.984281E+00	1.1088947E+00
25000.000	.1631092	.8368908	1.98707172E+00	1.0968158E+00
26000.000	.1477581	.8522419	1.9891766E+00	1.0862250E+00
27000.000	.1338243	.8661757	1.992715E+00	1.0769115E+00
28000.000	.1211641	.8788159	1.9928291E+00	1.068693E+00
29000.000	.1097224	.8902776	1.994115E+00	1.0614406E+00
30000.000	.0933335	.9006665	1.9951659E+00	1.0550108E+00

STAGE 2 EQUATION NUMBER 2

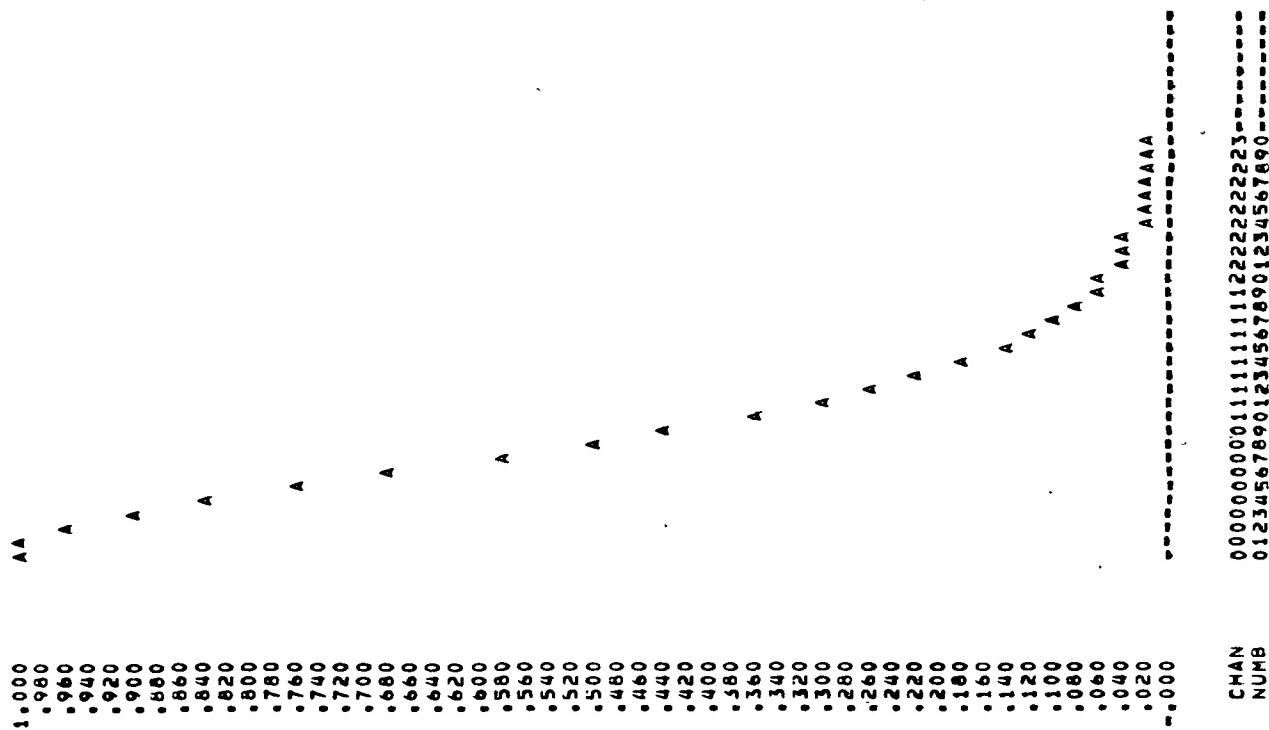
T	KEL	SIMREL	SIMGAIN	SIMRIF
0.000	1.0000000	1.0000000	1.0000000E+00	1.0000000E+00
1000.000	.9906642	.9048374	1.0948533E+00	1.0193309E+01
2000.000	.9652609	.0347391	1.1789723E+00	5.2180129E+00
3000.000	.9274917	.0725083	1.2519828E+00	3.5745101E+00
4000.000	.8806648	.1193152	1.3118277E+00	2.7631003E+00
5000.000	.8227287	.1722713	1.3646940E+00	2.2840104E+00
6000.000	.7710572	.2289428	1.4049578E+00	1.9707470E+00
7000.000	.7126652	.2873348	1.455115E+00	1.7920149E+00
8000.000	.6541447	.3458553	1.455206E+00	1.592207E+00
9000.000	.5967290	.4032710	1.4677165E+00	1.4715423E+00
10000.000	.5413411	.4586589	1.4715178E+00	1.3781933E+00
11000.000	.4886419	.5113581	1.467915E+00	1.3046219E+00
12000.000	.4390749	.5609251	1.4577000E+00	1.2458094E+00
13000.000	.3929072	.6070928	1.446352E+00	1.1982818E+00
14000.000	.3502660	.6497340	1.420385E+00	1.1595560E+00
15000.000	.311692	.6888308	1.3945035E+00	1.1278093E+00
16000.000	.2755525	.724475	1.366825E+00	1.1016719E+00
17000.000	.2432911	.7967089	1.3317629E+00	1.080937E+00

RELIABILITY, ETC. OF FIRST
STAGE AS F(T)

18000.000	.2142180	1.2952989
19000.000	.1681382	.16522551E+00
20000.000	.1648407	.1495686
21000.000	.1441075	.8351553
22000.000	.1257200	.8558925
23000.000	.1094645	.8742800
24000.000	.0951359	.8905355
25000.000	.0825399	.9048641
26000.000	.0714947	.9174601
27000.000	.0618320	.9285053
28000.000	.0533972	.9381680
29000.000	.0460491	.9466028
30000.000	.0396600	.9539509

REL. PRODUCT	T	SYSTEM RELIABILITY (\equiv PRODUCT OF STATE RELIABILITIES) AS F(CT)
0.000	1.0000000	1.0622551E+00
1000.000	.9890380	1.2578721E+00
2000.000	.9548044	1.0475076E+00
3000.000	.8993806	1.2180175E+00
4000.000	.8279742	1.0353292E+00
5000.000	.7467241	1.1768063E+00
6000.000	.6613692	1.0252963E+00
7000.000	.5765945	1.1346243E+00
8000.000	.498314	1.0918188E+00
9000.000	.4213217	1.0486995E+00
10000.000	.3543080	1.0055412E+00
11000.000	.2952634	1.0004938E+00
12000.000	.2441126	1.9700712E+01
13000.000	.2004205	9.3004347E+01
14000.000	.1635394	9.9427133E+01
15000.000	.1327202	9.7809730E+01
16000.000	.1071686	9.3690318E+01
17000.000	.0861950	9.9059269E+01
18000.000	.0690449	9.8945474E+01
19000.000	.0551143	
20000.000	.0438556	
21000.000	.0347969	
22000.000	.0275372	
23000.000	.0217400	
24000.000	.0171255	
25000.000	.0134630	
26000.000	.0105639	
27000.000	.0082746	
28000.000	.0064709	
29000.000	.0050526	
30000.000	.0039396	

FIGURE 6-1 (Cont.-6)



CHANNEL VALUES FOR X AXIS

CHAN	0000000001111111122222222223-----
NUMB	0123456789012345678901234567890-----
CHAN	00

CONTENTS OF CHANNELS FOR HISTOGRAM A FOLLOW

FIGURE 6-1 (Cont.-7)

PRODUCT NPI
(NPI MEANS NOT INPUTTED OR DEFAULTED)

1 PLOT(S) COMPLETED

PRODUCT OF RELIABILITY VS MISSION TIME
PLOT FOR EQUATIONS 4 & 2
(N1 MEANS NOT INPUTTED OR DEFAULT VALUE USED)

6 - 14

RUN 2 RELIABILITY RESULTS

FIGURE 6-1 (Cont.-8)

WITHT SECOND VALUE
OF REL

STAGE 1 EQUATION NUMBER 4

T	REL	SIMREL	SIMGAIN	SIMRIP
0.0000000	1.0000000	1.0000000	1.0000000E+00	1.0000000E+35
1000.000	.9983462	.9048374	1.1035642E+00	6.5458759E+01
2000.000	.992986	.0097014	1.2099534E+00	1.4684824E+01
3000.000	.9723751	.0274249	1.3128390E+00	9.495842E+00
4000.000	.9453251	.0546749	1.41023200	6.0298192E+00
5000.000	.9098163	.0901837	1.5000335E+00	4.3629757E+00
6000.000	.8678538	.1321462	1.5811326E+00	3.4143109E+00
7000.000	.8213362	.1786638	1.6539681E+00	2.8176655E+00
8000.000	.7720221	.2279779	1.7181692E+00	2.4154384E+00
9000.000	.7214221	.2785779	1.7744120E+00	2.1302132E+00
10000.000	.6707658	.3292342	1.823305E+00	1.9197242E+00
11000.000	.6210096	.3789904	1.8656150E+00	1.7602790E+00
12000.000	.5728642	.4271358	1.9019761E+00	1.6360272E+00
13000.000	.5268314	.4731686	1.9331066E+00	1.5374396E+00
14000.000	.4832409	.5167591	1.9596385E+00	1.4579386E+00
15000.000	.4422859	.5577141	1.9821879E+00	1.3929535E+00
16000.000	.4040534	.5959466	2.018965	1.3392199E+00
17000.000	.3685506	.6314492	2.0174277E+00	1.2943503E+00
18000.000	.3357268	.6642732	2.0302665E+00	1.2565629E+00
19000.000	.3054689	.6945111	2.0424664E+00	1.2245036E+00
20000.000	.2777170	.7222830	2.0520631E+00	1.1971273E+00
21000.000	.2522737	.7477263	2.06249564	1.1736160E+00
22000.000	.2290121	.7709879	2.0668376E+00	1.153214E+00
23000.000	.2078722	.7922178	2.0724572E+00	1.1357244E+00
24000.000	.1884343	.8115657	2.0971180	1.1204048E+00
25000.000	.1708230	.8291770	.0820850	1.1070194E+00
26000.000	.1548084	.8451916	.0742736	2.084303E+00
27000.000	.1402580	.8597420	.0672055	1.0952859E+00
28000.000	.1270472	.8729528	.0608101	1.0849703E+00
29000.000	.1150595	.8864905	.0550232	1.0758771E+00
30000.000	.1041870	.8958130	.0497871	1.0607269E+00

STAGE 2 EQUATION NUMBER 2

T	REL	SIMREL	SIMGAIN	SIMRIP
0.000	1.0000000	0.0000000	1.0000000E+00	1.0000000E+35
1000.000	.9906642	.9048358	1.0948333E+00	1.0193309E+01
2000.000	.962609	.0347391	.8187308	1.1789723E+00
3000.000	.9274917	.0725083	.7408182	1.2519828E+00
4000.000	.8866848	.1193152	.6703200	1.3118273E+00
5000.000	.8277287	.1722713	.6065307	1.3646940E+00
6000.000	.7710572	.2289428	.5488116	1.4049578E+00
7000.000	.7126652	.2873348	.4965853	1.4351115E+00
8000.000	.6541447	.3458553	.4493290	1.4558258E+00
9000.000	.5967290	.4032710	.4065697	1.4677165E+00
10000.000	.5413411	.4586589	.3678794	1.4715178E+00
11000.000	.4886419	.5113581	.3328711	1.4679615E+00
12000.000	.4390749	.5609251	.3011942	1.4577800E+00
13000.000	.3929072	.6070928	.2725318	1.592007E+00
14000.000	.3502660	.6497340	.2465970	1.416932E+00
15000.000	.3111692	.6888308	.2231302	1.4203985E+00
16000.000	.2755525	.7244475	.2018965	1.3648209E+00
17000.000	.2432911	.7567089	.18266835	1.3317629E+00

RUN 3 RELIABILITY RESULTS

FIGURE 6-1 (Cont.-10)

WITH THIRD VALUE
OF MU

STAGE 1 EQUATION NUMBER 4

T	REL	SIMREL	SIMGAIN	SIMRIF
0.000	1.0000000	1.0000000	1.0000000+00	1.0000000+35
1000.000	.9987387	.9048374	1.1037769E+00	7.5046916E+01
2000.000	.9914862	.8187308	1.2110039E+00	2.1291123E+01
3000.000	.9756726	.0243274	1.3170202E+00	1.0693893E+01
4000.000	.9510108	.0489892	1.4187414E+00	6.7296472E+00
5000.000	.9184337	.0815663	1.5102411E+00	4.8239183E+00
6000.000	.8794336	.1205664	1.6024384E+00	3.7422388E+00
7000.000	.8356671	.1643329	1.6828270E+00	3.0633844E+00
8000.000	.7887312	.2112688	1.4493290	2.6064946E+00
9000.000	.7400474	.2599952	1.4065697	2.2824066E+00
10000.000	.6908143	.3091857	1.3678794	2.044690E+00
11000.000	.64419988	.3580012	1.3328711	1.8634821E+00
12000.000	.5943496	.4056504	1.3011942	1.9733102E+00
13000.000	.5484224	.4584224	1.2715776	2.0123245E+00
14000.000	.5046080	.4953920	1.2465970	1.6109485E+00
15000.000	.4631614	.5368386	1.2231302	2.0757453E+00
16000.000	.4242286	.5757714	1.2018965	2.1012180E+00
17000.000	.3878703	.6121297	1.1826835	2.1231816E+00
18000.000	.3540820	.6459180	1.1652989	2.1420713E+00
19000.000	.3228109	.6771891	1.1495686	2.1568279E+00
20000.000	.2919697	.7060303	1.1353353	1.4471199E+00
21000.000	.2674472	.7325528	1.1224564	1.3861464E+00
22000.000	.2431174	.7568826	1.1108032	1.3552015E+00
23000.000	.2208458	.7791542	1.102588	1.2922710E+00
24000.000	.2004945	.7999505	1.0907180	1.2558256E+00
25000.000	.1819258	.8180742	1.0820850	1.2246850E+00
26000.000	.1650054	.8349946	1.0742736	1.1979254E+00
27000.000	.1496036	.8503964	1.0672055	1.1748148E+00
28000.000	.1355971	.8644029	1.0608101	1.1547665E+00
29000.000	.1228694	.8771306	1.0550232	1.0773501E+00
30000.000	.1113113	.8886887	1.0497871	1.0692303E+00

STAGE 2 EQUATION NUMBER 2

T	REL	SIMREL	SIMGAIN	SIMRIF
0.000	1.0000000	0.0000000	1.0000000+00	1.0000000+35
1000.000	.9906642	.09093358	1.9048374	1.0948535E+00
2000.000	.9652609	.0347391	.8187308	1.1769212E+00
3000.000	.9274917	.0725083	.7408182	1.251828E+00
4000.000	.8806848	.1193152	.6703200	1.3138273E+00
5000.000	.8277287	.1722713	.6065307	1.3646947E+00
6000.000	.7710572	.2289428	.5488116	1.4049576E+00
7000.000	.7126652	.2873348	.4965853	1.435315E+00
8000.000	.6541447	.3458553	.4493290	1.4558258E+00
9000.000	.5967290	.4032710	.4065697	1.4677165E+00
10000.000	.5413411	.4586589	.3678794	1.4715178E+00
11000.000	.4886419	.5113581	.3328711	1.4679615E+00
12000.000	.4390749	.5609251	.3011942	1.4578094E+00
13000.000	.3929072	.6070928	.2725318	1.446922E+00
14000.000	.3502660	.6497340	.2465970	1.4203985E+00
15000.000	.3111692	.6888308	.2231302	1.3945635E+00
16000.000	.2755525	.7244475	.2018965	1.3648205E+00
17000.000	.2432911	.7567089	.18266835	1.3317629E+00
				1.0800937E+00

FIGURE 6-1 (Cont.-11)

00000000	• 2142180	• 1652989	• 1.2999433E+00	1.0622553E+00
90000000	• 1881382	• 1495686	• 1.2578721E+00	1.0475076E+00
00000000	• 1644807	• 1353353	• 1.2180175E+00	1.0353292E+00
100000000	• 14441075	• 12456925	• 1.1768063E+00	1.0252965E+00
200000000	• 1257200	• 1108032	• 1.1346624E+00	1.0170618E+00
300000000	• 1094645	• 8905355	• 1.1025886	1.0105337E+00
400000000	• 0951359	• 9048641	• 1.0918188E+00	1.0048824E+00
500000000	• 0825399	• 9174601	• 1.0486995E+00	1.00004958E+00
600000000	• 0714947	• 9285053	• 1.0055412E+00	9.9700712E-01
700000000	• 0618320	• 9381680	• 9.6258557E-01	9.9427233E-01
800000000	• 0533972	• 9466028	• 0.608101	9.9216893E-01
900000000	• 0460491	• 9539509	• 0.550232	9.9059269E-01
000000000	• 0396600	• 9603400	• 0.497871	9.88945474E-01

REL.	PRODUCT
1.000000	*9894147
1.000000	*9570428
1.000000	*9469282
1.000000	*8375407
1.000000	*7602139
1.000000	*6780936
1.000000	*5955509
1.000000	*5159443
1.000000	*4416077
1.000000	*3795662
1.000000	*3137075
1.000000	*2609640
1.000000	*2154791
1.000000	*1767470
1.000000	*1441215
1.000000	*1168972
1.000000	*0943654
1.000000	*0758507
1.000000	*0607331
1.000000	*04664582
1.000000	*0385641
1.000000	*0305647
1.000000	*0241748
1.000000	*0190742
1.000000	*0150161
1.000000	*0117970
1.000000	*0092503
1.000000	*0072405
1.000000	*0056580
1.000000	*0044146

FIGURE 6-2
JOB #2 INPUT/OUTPUT LISTINGS

\$OPTSON OUTPT1=T,OUTPT3=T,COVINT=T,PRODT=T,COVPRC=TS

\$VAR1 PRUD(1)=4,2\$

\$VAR T=3.0E4,STEP=1.0E3,OPTION=1\$

\$COVCAL IGENC(2)=1,IFSC(1)=2,FRAC(1)=1.0\$

ID

SDATA PFDS(1)=1.0, TFDS(1)=0.0, TMINDR=1.0\$

IB

\$PARVEC Q(2)=1,Z(2)=2,S(1)=1,1,LAM(1)=2*1.0E-4,MU(1)=1.0E-4,0.0\$

IV 8

\$VARY PARAM(1,1)=1.0E-4,5.0E-5,0.0, PARAM(1,2)=3*0.0\$

F	D	1	311	1	0.95	0.0	1.0	100.0	0.0	0.01
F	D	2	311	1	0.95	0.5	1.0	100.0	0.0	0.01
F	I	1	010		1.0	0.0	1.0	0.0	0.0	0.0

RAYTHEON COMPANY

EQUIPMENT DIVISION

RAYTHEON

FIGURE 6-2 (Cont.-2)

F E 1 110 1.0 0.0 1.0 0.0 0.0 100.0

F T 1 110 1.0 0.0 1.0 0.0 0.0 100.0

C D 1 111 1

C D 2 111 2

C I 1 111 50

C E 1 111 50

C T 1 111 50

PC

N

PF

G

S

CARE2 (COMPUTER-AIDED RELIABILITY ESTIMATION)

FIGURE 6-2 (Cont.-3)

DO YOU WISH TO HAVE YOUR RESPONSES TO MY
QUESTIONS PRINTED BACK FOR VERIFICATION.
DO YOU WISH TO FORM A COMPLEX EQUATION WHICH IS
THE PRODUCT OF THE PRIMARY EQUATIONS.

```

SVAR1
PROD = 4, 2, 0, 0, 0, 0, 0, 0, 0,
SEND
DO YOU WISH TO HAVE 2-D RELIABILITY PLOTS.
DO YOU WISH TO HAVE PRINTED TABLE OF RELIABILITY RESULTS
DO YOU WISH TO HAVE PRINTED TABLE OF DIFF, RIF,
AND GAIN RESULTS.
DO YOU WISH MTF AND RELIABILITY AT MTF RESULTS PRINTED
DO YOU WANT PRINTED RESULTS OF THE MAXIMUM MISSION
TIME CALCULATIONS.

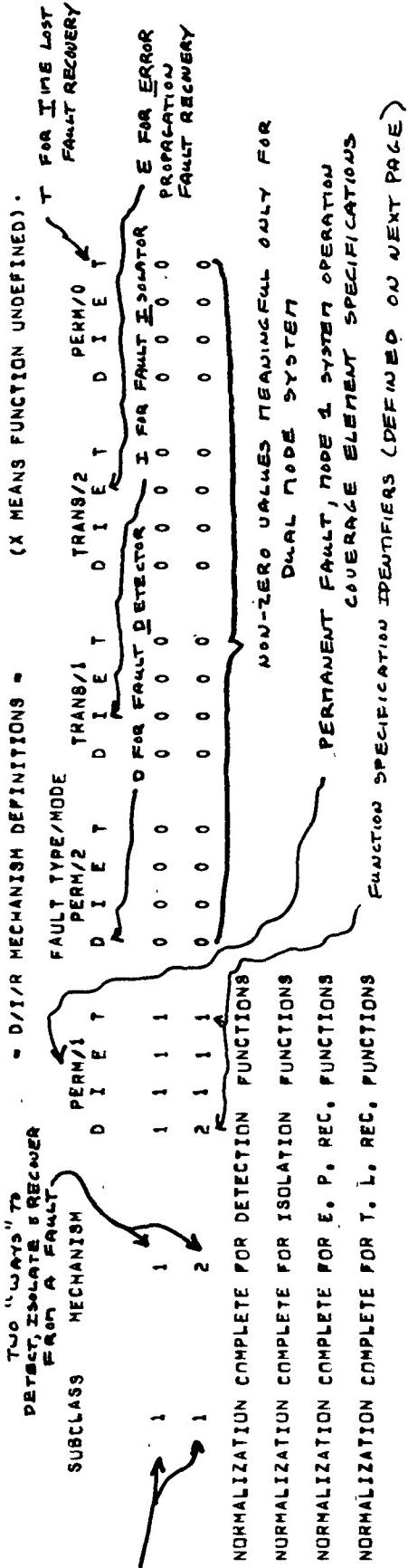
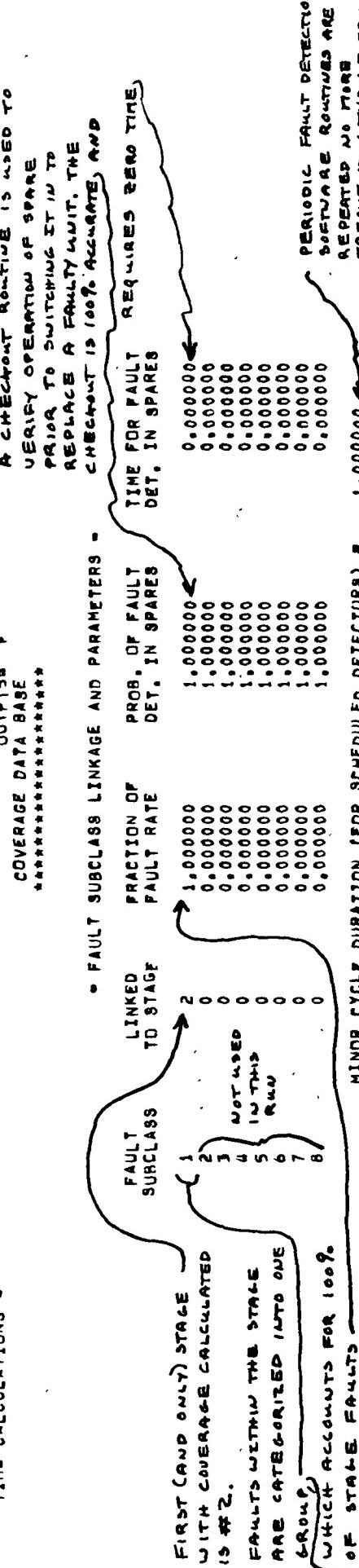
```

SAME SYSTEM CONFIGURATION
AS 3OD # 1, BUT WITH
PERSISTENT COVERAGE
CALCULATED FOR SECOND
STAGE

```

OUTPUT#1
OUTPUT#1 = T
PRODUCT#1
OUTPUT#2= F
OUTPUT#4= F
OUTPUT#5= F
*****COVERAGE DATA BASE*****
* FAULT SUBCLASS LINKAGE AND PARAMETERS =

```



DATA BASE FOR BIM-SET FIGURE 6-2 (Cont.-5)

FIGURE 6-2 (Cont.-5)

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PARA
METER

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二

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6881 89750000

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THESE VALUES ARE COMPUTED VIA ITERATIONS OF THE EQUATION SHOWN IN SECTION 3.2.3. THEY ARE THEN SUMMED, AS PER THE EQUATION IN 3.2.2, TO FORM SUBCLASS COVERAGE FOR THE STATED CONDITIONS ($C_{IS4} = 2$, $MD = 1$, ETC.). STAGE COVERAGE, IN TURN, IS COMPUTED VIA THE FIRST EQUATION IN SECTION 3.2, BY MEANS OF WEIGHTING AND TOTALING APPLICABLE SUBCLASS COVERS AND IN TURN PRINTED OUT HERE.

NOTE THAT IN THIS PARTICULAR EXAMPLE, THE USER HAS SPECIFIED C AS INDICATED BY THE LINAGE TABLE ON PAGE 6-21) THAT THE STAGE CONTAINS ONLY ONE FAULT SUBCLASS. AS A CONSEQUENCE, SUBCLASS AND STAGE COVERAGES ARE EQUAL. IN A LESS TRIVIAL SITUATION, THIS IS FREQUENTLY NOT THE CASE.

RUN 1 RELIABILITY RESULTS

FIGURE 6-2 (Cont.-6)

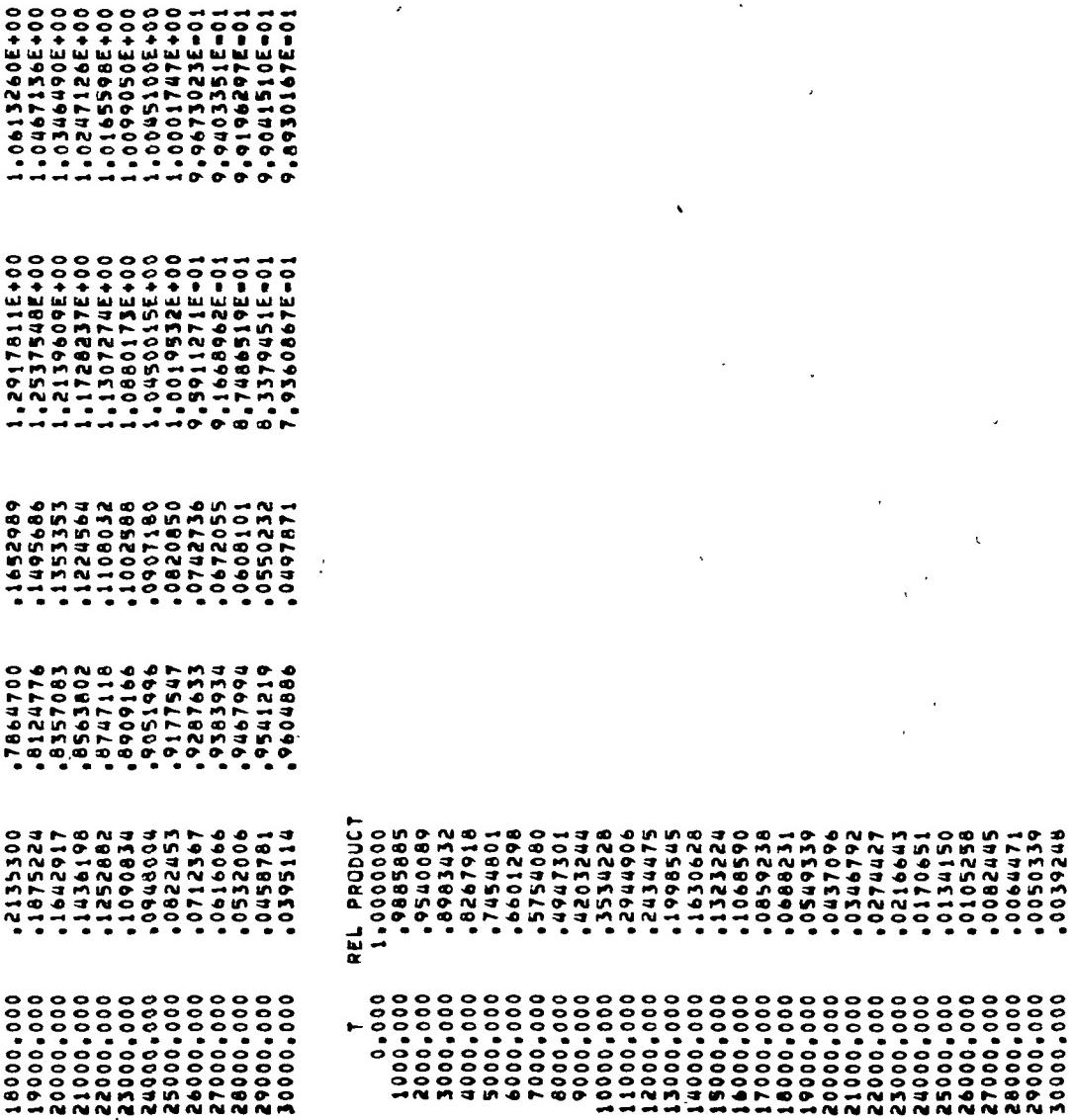
STAGE 1 EQUATION NUMBER 4

T	REL	UNREL	SIMREL	SIMGAIN	SIMRIF
0.000	1.0000000	0.0000000	1.0000000	1.0000000E+00	1.0000000E+35
1000.000	0.9981584	0.0016416	0.9048374	1.1033567E+00	5.7970848E+01
2000.000	0.9891672	0.0108328	0.8187308	1.2081719E+00	1.6733167E+01
3000.000	0.9669113	0.0303087	0.7408182	1.3089464E+00	6.554083E+00
4000.000	0.9401482	0.0598518	0.6703200	1.4025363E+00	5.5082701E+00
5000.000	0.9021363	0.0978637	0.6065307	1.4873713E+00	4.0205844E+00
6000.000	0.8577434	0.1422566	0.5468116	1.5629105E+00	3.1716526E+00
7000.000	0.8090678	0.1909322	0.4965853	1.6292625E+00	2.6366192E+00
8000.000	0.7579842	0.2420158	0.4493290	1.6869249E+00	2.2751818E+00
9000.000	0.7060520	0.2939480	0.4065697	1.7366077E+00	2.0188277E+00
10000.000	0.6545004	0.3454996	0.3678794	1.7791165E+00	1.8295840E+00
11000.000	0.6042532	0.3957468	0.3328711	1.8152769E+00	1.6857467E+00
12000.000	0.5559707	0.4440293	0.3011942	1.8458878E+00	1.5737831E+00
13000.000	0.5100963	0.4899037	0.2725318	1.8716948E+00	1.4849209E+00
14000.000	0.4669006	0.5330994	0.24655970	1.8933755E+00	1.4132507E+00
15000.000	0.4245211	0.5734789	0.2231302	1.9115349E+00	1.35466152E+00
16000.000	0.3889951	0.6110049	0.2018965	1.9267053E+00	1.3062145E+00
17000.000	0.3542873	0.6457127	0.1826835	1.9303502E+00	1.2657588E+00
18000.000	0.3223112	0.6776888	0.1652989	1.9498691E+00	1.2316879E+00
19000.000	0.2929458	0.7070542	0.14955686	1.9586044E+00	1.2027810E+00
20000.000	0.2660485	0.7339515	0.1353353	1.96580475E+00	1.1780952E+00
21000.000	0.2414651	0.7585349	0.1224564	1.9718452E+00	1.1568928E+00
22000.000	0.2190363	0.7809637	0.1108032	1.9768057E+00	1.1385892E+00
23000.000	0.1986032	0.8013968	0.1025888	1.9809041E+00	1.1227161E+00
24000.000	0.1800105	0.8199895	0.0971800	1.9842871E+00	1.1088947E+00
25000.000	0.1631092	0.8368906	0.0820850	1.9870772E+00	1.0968158E+00
26000.000	0.1475811	0.8522449	0.0742736	1.9893766E+00	1.0862250E+00
27000.000	0.1338243	0.8661757	0.0672055	1.9912704E+00	1.0769115E+00
28000.000	0.1211841	0.8788159	0.0608101	1.9928291E+00	1.0686993E+00
29000.000	0.1097224	0.8902776	0.0550232	1.9941115E+00	1.0614406E+00
30000.000	0.0933335	0.9006665	0.0497871	1.9951659E+00	1.0590108E+00

STAGE 2 EQUATION NUMBER 2

T	REL	UNREL	SIMREL	SIMGAIN	SIMRIF
0.000	1.0000000	0.0000000	1.0000000	1.0000000E+00	1.0000000E+35
1000.000	0.9902140	0.0097860	0.9048374	1.0948357E+00	9.7243202E+00
2000.000	0.9644566	0.0355434	0.8187308	1.1779990E+00	5.0999482E+00
3000.000	0.9264218	0.0735782	0.7408182	1.25051886E+00	3.5225345E+00
4000.000	0.8794271	0.1205729	0.6703200	1.3119511E+00	2.7142790E+00
5000.000	0.823498	0.1736502	0.6065307	1.3624204E+00	2.2658728E+00
6000.000	0.7696121	0.2303879	0.5488116	1.4023247E+00	1.9581859E+00
7000.000	0.7111987	0.2888013	0.4965853	1.4321784E+00	1.7431180E+00
8000.000	0.6526919	0.3473081	0.4493290	1.4525925E+00	1.5859403E+00
9000.000	0.5953165	0.4046815	0.4065697	1.4642424E+00	1.46640612E+00
10000.000	0.5399886	0.4600114	0.3678794	1.4678413E+00	1.3741412E+00
11000.000	0.4873630	0.5126317	0.3328711	1.4641193E+00	1.3013671E+00
12000.000	0.4378782	0.5621216	0.3011942	1.4538669E+00	1.2431973E+00
13000.000	0.3917976	0.6082024	0.2725318	1.4376217E+00	1.1960956E+00
14000.000	0.3492451	0.6507549	0.2465970	1.4162581E+00	1.1571717E+00
15000.000	0.3102364	0.6897636	0.2231302	1.3903294E+00	1.1262841E+00
16000.000	0.2747053	0.7252947	0.2018965	1.3606242E+00	1.103851E+00
17000.000	0.2425258	0.7574742	0.1826635	1.3275716E+00	1.0790024E+00

FIGURE 6-2 (Cont.-7)



RUN 2 RELIABILITY RESULTS

FIGURE 6-2 (Cont.-8)

STAGE 1 EQUATION NUMBER 4

T	REL	UNREL	SIMREL	SIMGAIN	SIMRIF
0.000	1.0000000	0.0000000	1.0000000	1.0000000E+00	1.0000000E+35
1000.000	0.9985462	0.0014538	.9048374	1.1035642E+00	6.5458759E+01
2000.000	0.9902986	0.0097014	.8187308	1.2095534E+00	1.8684824E+01
3000.000	0.9725751	0.0274249	.7408182	1.328890E+00	9.4505842E+00
4000.000	0.9453251	0.0546749	.6703200	1.410293E+00	6.0298192E+00
5000.000	0.9098163	0.0901837	.6065307	1.5000135E+00	4.3629757E+00
6000.000	0.8678538	0.1321462	.5468116	1.583326E+00	3.4143109E+00
7000.000	0.8213362	0.1786638	.4965853	1.653968E+00	2.8176698E+00
8000.000	0.7720221	0.2279779	.4493290	1.7181669E+00	2.41549584E+00
9000.000	0.7214221	0.2785779	.4065697	1.7744612E+00	2.1302132E+00
10000.000	0.6707658	0.3292342	.3678794	1.823309E+00	1.919724E+00
11000.000	0.6210096	0.3789904	.3328711	1.8658158E+00	1.7602790E+00
12000.000	0.5728642	0.4271358	.3019492	1.901961E+00	1.6360272E+00
13000.000	0.5268314	0.4731686	.2725318	1.931106E+00	1.5374396E+00
14000.000	0.4832409	0.5167591	.24665970	1.9596385E+00	1.4579386E+00
15000.000	0.44222859	0.5577141	.2231302	1.9821875E+00	1.3929535E+00
16000.000	0.4040534	0.5959466	.2018496	2.0012898E+00	1.3592199E+00
17000.000	0.3685506	0.6314492	.1826639	2.0174977E+00	1.2943503E+00
18000.000	0.3357268	0.6642732	.1652989	2.0310286E+00	1.2565629E+00
19000.000	0.3054889	0.6945111	.1495686	2.0424664E+00	1.2245036E+00
20000.000	0.2777170	0.7222830	.1353353	2.0520661E+00	1.1971273E+00
21000.000	0.2522737	0.7477263	.124564	2.0601095E+00	1.1756160E+00
22000.000	0.2290121	0.7709487	.1108032	2.0668176E+00	1.153214E+00
23000.000	0.2077822	0.7922178	.102588	2.0724512E+00	1.1357244E+00
24000.000	0.184343	0.8115657	.0907180	2.0771449E+00	1.1204048E+00
25000.000	0.1708230	0.8291770	.0820450	2.0810303E+00	1.1070194E+00
26000.000	0.1548084	0.8451916	.0742736	2.0841003E+00	1.0952859E+00
27000.000	0.1402580	0.8597420	.0672055	2.087021E+00	1.0849703E+00
28000.000	0.1270472	0.8729528	.0608101	2.0892460E+00	1.0758771E+00
29000.000	0.1150595	0.8849409	.0550232	2.0911060E+00	1.06678422E+00
30000.000	0.1041870	0.8958130	.04947871	2.0926318E+00	1.0607269E+00

STAGE 2 EQUATION NUMBER 2

T	REL	UNREL	SIMREL	SIMGAIN	SIMRIF
0.000	1.0000000	0.0000000	1.0000000	1.0000000E+00	1.0000000E+35
1000.000	0.9902140	0.0097460	.9048374	1.093557E+00	9.7943202E+00
2000.000	0.9644566	0.0355034	.8187308	1.177900E+00	5.099482E+00
3000.000	0.9264216	0.0735782	.7408182	1.2505186E+00	3.925345E+00
4000.000	0.8794271	0.1205729	.6703200	1.311911E+00	2.7342790E+00
5000.000	0.8263498	0.1736502	.6065307	1.3624204E+00	2.2658728E+00
6000.000	0.7696121	0.2303879	.5488116	1.4023247E+00	1.9583659E+00
7000.000	0.7111987	0.2888013	.4965853	1.4521784E+00	1.7431180E+00
8000.000	0.6526919	0.3473081	.4493290	1.4525925E+00	1.5855403E+00
9000.000	0.5933165	0.4046835	.4065697	1.464224E+00	1.4664061E+00
10000.000	0.5399886	0.4600114	.3678794	1.4678412E+00	1.3741412E+00
11000.000	0.4873630	0.5126370	.3328711	1.4641193E+00	1.3013671E+00
12000.000	0.4378782	0.5621218	.3011942	1.453869E+00	1.2431573E+00
13000.000	0.3911976	0.6082024	.2725318	1.452617E+00	1.1960956E+00
14000.000	0.3492451	0.6507549	.24645970	1.4162507E+00	1.157370E+00
15000.000	0.3102364	0.6897636	.2231302	1.3903829E+00	1.1262841E+00
16000.000	0.2747053	0.7252947	.2018965	1.3606242E+00	1.103851E+00
17000.000	0.2425258	0.7574742	.1826835	1.3275116E+00	1.0790024E+00

180000.000	.2135300	.78864700	.1652989	.2917811E+00
190000.000	.1875224	.8124776	.1495686	.2537548E+00
200000.000	.1642917	.8357083	.1355353	.2139609E+00
210000.000	.1436198	.8563802	.1224564	.1728237E+00
220000.000	.1252882	.8747118	.1108032	.10247126E+00
230000.000	.1090834	.8909166	.1002588	.105598E+00
240000.000	.0948004	.9051996	.0907180	.0450015E+00
250000.000	.0822453	.9177547	.0820850	.0019532E+00
260000.000	.0712367	.9287633	.0742736	.1728237E+00
270000.000	.0616066	.9383934	.067055	.95911271E-01
280000.000	.0512006	.9467994	.0608101	.1668962E-01
290000.000	.0458781	.9541219	.0550232	.3379451E-01
300000.000	.0395114	.9604886	.0497871	.9360867E-01

T	REL PRODUCT
0.000	1.0000000
1000.000	.9887744
2000.000	.9551001
3000.000	.9010147
4000.000	.8313445
5000.000	.7518265
6000.000	.6679108
7000.000	.5841333
8000.000	.5038926
9000.000	.4294745
10000.000	.3622059
11000.000	.3026571
12000.000	.2508448
13000.000	.2064113
14000.000	.1687695
15000.000	.1372132
16000.000	.1099956
17000.000	.0893831
18000.000	.0716877
19000.000	.0572860
20000.000	.0456266
21000.000	.0362315
22000.000	.0286925
23000.000	.0226656
24000.000	.0178656
25000.000	.0140494
26000.000	.0110280
27000.000	.0086408
28000.000	.0067590
29000.000	.0052787
30000.000	.0041166

FIGURE 6-2 (Cont.-9)

RUN 3 RELIABILITY RESULTS

FIGURE 6-2 (Cont.-10)

STAGE 1 EQUATION NUMBER 4

T	REL	UNREL	SIMREL	SIMGAIN	SIMRIF
0.000	1.0000000	0.0000000	1.0000000E+00	1.0000000E+35	1.0000000E+35
1000.000	.9987387	.0012613	.9048374	1.1037769E+00	7.546916E+01
2000.000	.9914862	.0085138	.8187308	1.2110395E+00	2.1291123E+01
3000.000	.9756726	.0243274	.7408182	1.3170202E+00	1.0653893E+01
4000.000	.9510108	.0489892	.6703200	1.4187741E+00	6.7296472E+00
5000.000	.9184337	.0815663	.6065307	1.5142411E+00	4.8219183E+00
6000.000	.8794336	.1205664	.5488116	1.6024524E+00	3.7423882E+00
7000.000	.8356671	.1643329	.4965853	1.6828270E+00	3.0633844E+00
8000.000	.7887312	.2112668	.4493290	1.7553535E+00	2.6064946E+00
9000.000	.7400474	.2599526	.4065697	1.8202229E+00	2.288406E+00
10000.000	.6908143	.3091857	.3678794	1.8778280E+00	2.0444690E+00
11000.000	.6419988	.3580012	.3328711	1.9286708E+00	1.8634821E+00
12000.000	.5943496	.4056504	.3011942	1.9733102E+00	1.7226800E+00
13000.000	.5404224	.4515776	.2725318	2.0123245E+00	1.6109485E+00
14000.000	.5046080	.4953920	.2465970	2.0462863E+00	1.5208219E+00
15000.000	.4631614	.5368386	.2231302	2.0797453E+00	1.4471199E+00
16000.000	.4242286	.5757714	.2018965	2.1012180E+00	1.3861464E+00
17000.000	.3878703	.6121297	.1826835	2.1231616E+00	1.3152015E+00
18000.000	.3540820	.6459180	.1652989	2.1420713E+00	1.2922710E+00
19000.000	.3228109	.6771891	.1495686	2.1582798E+00	1.2558256E+00
20000.000	.2939697	.7060303	.1353353	2.1721585E+00	1.2246850E+00
21000.000	.2674472	.7325528	.1224564	2.18401195E+00	1.197254E+00
22000.000	.2431174	.7568826	.1108032	2.1941381E+00	1.1748148E+00
23000.000	.2208458	.7791542	.102588	2.1427564E+00	1.1547765E+00
24000.000	.2004945	.7995055	.0907180	2.2100857E+00	1.1371055E+00
25000.000	.1819258	.8180742	.0820850	2.2163103E+00	1.1220437E+00
26000.000	.1650054	.8349946	.0742736	2.2215897E+00	1.1086616E+00
27000.000	.1496036	.8503964	.0672055	2.22660621E+00	1.0468918E+00
28000.000	.1355971	.8644029	.0608101	2.22984466E+00	1.0865187E+00
29000.000	.1228694	.8771306	.0550232	2.2330457E+00	1.0773501E+00
30000.000	.1113113	.8886887	.0497871	2.2357472E+00	1.0692303E+00

STAGE 2 EQUATION NUMBER 2

T	REL	UNREL	SIMREL	SIMGAIN	SIMRIF
0.000	1.0000000	0.0000000	1.0000000E+00	1.0000000E+35	1.0000000E+35
1000.000	.9902140	.0097460	.9048374	1.0943557E+00	9.7243202E+00
2000.000	.9644566	.0355434	.8187308	1.1779900E+00	5.0999482E+00
3000.000	.9264218	.0735782	.7408182	1.2505198E+00	3.52251452E+00
4000.000	.8794271	.1205729	.6703200	1.3119511E+00	2.7342790E+00
5000.000	.8263498	.1736502	.6065307	1.3634204E+00	2.2658728E+00
6000.000	.7696121	.2303879	.5488116	1.4023247E+00	1.9583859E+00
7000.000	.7111987	.2888013	.4965853	1.4321784E+00	1.7431180E+00
8000.000	.6526919	.3473081	.4493290	1.4525925E+00	1.5055403E+00
9000.000	.5953165	.4046835	.4065697	1.4642424E+00	1.4664061E+00
10000.000	.5399886	.4600114	.3678794	1.4678413E+00	1.3741412E+00
11000.000	.4873630	.5126370	.3328711	1.4641193E+00	1.3013671E+00
12000.000	.4378782	.5621218	.3011942	1.4538069E+00	1.2431573E+00
13000.000	.3917976	.6082024	.2725318	1.4376217E+00	1.1960956E+00
14000.000	.3492451	.6507549	.24665970	1.4162587E+00	1.1577370E+00
15000.000	.3102364	.6897636	.2018965	1.3903829E+00	1.1262841E+00
16000.000	.2747053	.7252947	.22357472E+00	1.36066242E+00	1.1003851E+00
17000.000	.2425258	.7574742	.18266835	1.3275736F+00	1.0790024E+00

FIGURE 6-2 (Cont.-11)

T	REL PRODUCT
18000.000	*2115300
19000.000	*1875224
20000.000	*1642917
21000.000	*1416198
22000.000	*1252882
23000.000	*1090834
24000.000	*0948004
25000.000	*0822453
26000.000	*0712367
27000.000	*0616066
28000.000	*0532006
29000.000	*0458781
30000.000	*0395114
99000.000	*7864700
100000.000	*1652989
101000.000	*12917811E+00
102000.000	*10613260E+00
103000.000	*1.0467136E+00
104000.000	*1.2537548E+00
105000.000	*1.195686
106000.000	*1.357083
107000.000	*1.8561802
108000.000	*1.224564
109000.000	*1.108032
110000.000	*1.1307274E+00
111000.000	*1.002588
112000.000	*1.0880173E+00
113000.000	*0909166
114000.000	*9051996
115000.000	*9177547
116000.000	*9287633
117000.000	*9363934
118000.000	*9467994
119000.000	*9541219
120000.000	*9604886
121000.000	*0550232
122000.000	*0497871
123000.000	7.9360867E-01
124000.000	9.0930167E-01
125000.000	9.9196297E-01
126000.000	9.9403351E=01
127000.000	9.1668962E=01
128000.000	9.0686519E=01
129000.000	8.3379451E=01
130000.000	8.9041510E=01
131000.000	9.0943350167E=01
132000.000	1.00045100E+00
133000.000	1.00450015E+00
134000.000	1.0019532E+00
135000.000	1.0001747E+00
136000.000	9.5911271E=01
137000.000	9.9673023E=01
138000.000	9.9973023E=01
139000.000	9.9916297E=01
140000.000	9.99041510E=01
141000.000	9.9943350167E=01
142000.000	9.99041510E=01
143000.000	9.9943350167E=01
144000.000	9.9943350167E=01
145000.000	9.9943350167E=01
146000.000	9.9943350167E=01
147000.000	9.9943350167E=01
148000.000	9.9943350167E=01
149000.000	9.9943350167E=01
150000.000	9.9943350167E=01
151000.000	9.9943350167E=01
152000.000	9.9943350167E=01
153000.000	9.9943350167E=01
154000.000	9.9943350167E=01
155000.000	9.9943350167E=01
156000.000	9.9943350167E=01
157000.000	9.9943350167E=01
158000.000	9.9943350167E=01
159000.000	9.9943350167E=01
160000.000	9.9943350167E=01
161000.000	9.9943350167E=01
162000.000	9.9943350167E=01
163000.000	9.9943350167E=01
164000.000	9.9943350167E=01
165000.000	9.9943350167E=01
166000.000	9.9943350167E=01
167000.000	9.9943350167E=01
168000.000	9.9943350167E=01
169000.000	9.9943350167E=01
170000.000	9.9943350167E=01
171000.000	9.9943350167E=01
172000.000	9.9943350167E=01
173000.000	9.9943350167E=01
174000.000	9.9943350167E=01
175000.000	9.9943350167E=01
176000.000	9.9943350167E=01
177000.000	9.9943350167E=01
178000.000	9.9943350167E=01
179000.000	9.9943350167E=01
180000.000	9.9943350167E=01
181000.000	9.9943350167E=01
182000.000	9.9943350167E=01
183000.000	9.9943350167E=01
184000.000	9.9943350167E=01
185000.000	9.9943350167E=01
186000.000	9.9943350167E=01
187000.000	9.9943350167E=01
188000.000	9.9943350167E=01
189000.000	9.9943350167E=01
190000.000	9.9943350167E=01
191000.000	9.9943350167E=01
192000.000	9.9943350167E=01
193000.000	9.9943350167E=01
194000.000	9.9943350167E=01
195000.000	9.9943350167E=01
196000.000	9.9943350167E=01
197000.000	9.9943350167E=01
198000.000	9.9943350167E=01
199000.000	9.9943350167E=01
200000.000	9.9943350167E=01
201000.000	9.9943350167E=01
202000.000	9.9943350167E=01
203000.000	9.9943350167E=01
204000.000	9.9943350167E=01
205000.000	9.9943350167E=01
206000.000	9.9943350167E=01
207000.000	9.9943350167E=01
208000.000	9.9943350167E=01
209000.000	9.9943350167E=01
210000.000	9.9943350167E=01
211000.000	9.9943350167E=01
212000.000	9.9943350167E=01
213000.000	9.9943350167E=01
214000.000	9.9943350167E=01
215000.000	9.9943350167E=01
216000.000	9.9943350167E=01
217000.000	9.9943350167E=01
218000.000	9.9943350167E=01
219000.000	9.9943350167E=01
220000.000	9.9943350167E=01
221000.000	9.9943350167E=01
222000.000	9.9943350167E=01
223000.000	9.9943350167E=01
224000.000	9.9943350167E=01
225000.000	9.9943350167E=01
226000.000	9.9943350167E=01
227000.000	9.9943350167E=01
228000.000	9.9943350167E=01
229000.000	9.9943350167E=01
230000.000	9.9943350167E=01

FIGURE 6-3
JOB #3 INPUT/OUTPUT LISTINGS

```
$OPTSON OUTPT1=T,OUTPT3=T,LPLOT=T,PRODT=T,STGOUT=T$  
  
$VAR1 PRUD(1)=7,7$  
  
$VAR T=1.0E4,STEP=1.0E3,OPTION=1$  
  
10000  
  
100000  
  
IB  
  
$PARVEC Q1(1)=2,2, Q2(1)=1,1, S(1)=1,1,  
LAM(1)=2*1.0E-4, MU(1)=2*5.0E-5, GMP(1)=2*1.1E-5,  
C1(1)=1.0,0.999,CD1(1)=1.0,0.999,C2(1)=1.0,0.98,CD2(1)=1.0,0.998,  
CTR(1)=1.0,0.999,CDTR(1)=1.0,0.999,PRC1(1)=1.0,0.99,PRC2(1)=1.0,0.955  
  
ID  
  
$DATA SLH2=1.0E-7, SLH3=2.0E-8, RSGN=FS  
  
G  
  
S
```

CARE2 (COMPUTER-AIDED RELIABILITY ESTIMATION)

FIGURE 6-3 (Cont. -2)

DO YOU WISH TO HAVE YOUR RESPONSES TO MY
QUESTIONS PRINTED BACK FOR VERIFICATION.
DO YOU WISH TO FORM A COMPLEX EQUATION WHICH IS
THE PRODUCT OF THE PRIMARY EQUATIONS.

```

SYAH1
PROD = 7, 7, 0, 0, 0, 0, 0, 0, 0, 0,
SEND
DO YOU WISH TO HAVE 2-D RELIABILITY PLOTS?
INPUT A 1 IN TIME COLUMN SPECIFIED BELOW IF YOU WISH
THE CORRESPONDING PLOT OPTION. OTHERWISE INPUT 0.
NOTE: WHEN PERFORMING PRODUCT OF RELIABILITIES, NO OTHER
PLOT OPTION BESESIDES PRODUCT OF RELIABILITIES MAY BE SPECIFIED.
COLUMN 1 = PLOTS PRODUCT OF RELIABILITIES
COLUMN 2 = PLOTS RELIABILITY
COLUMN 3 = PLOTS DIFF, RIF, AND GAIN
COLUMN 4 = PLOTS MTF AND RELIABILITY AT MTF
COLUMN 5 = PLOTS UNRELIABILITY
10000
FOR ABSISSA, INPUT 1 IN COLUMN 1 IF ABSISSA IS 1,
1 IN COLUMN 2 IF ABSISSA IS LOG(T) = BASE 10,
1 IN COLUMN 3 IF ABSISSA IS LAMT,
1 IN COLUMN 4 IF ABSISSA IS LOG(LAMT) = BASE 10,
1 IN COLUMN 5 IF ABSISSA IS EXP(-LAMBDA(T)),
1 IN COLUMN 6 IF ABSISSA IS LOG(EXP(-LAMT)) = BASE 10.
10000
DO YOU WISH TO HAVE PRINTED TABLE OF RELIABILITY RESULTS
DO YOU WISH TO HAVE PRINTED TABLE OF DIFF, RIF,
AND GAIN RESULTS?
DO YOU WISH MTF AND RELIABILITY AT MTF RESULTS PRINTED
DO YOU WANT PRINTED RESULTS OF THE MAXIMUM MISSION
TIME CALCULATIONS?

```

```

OUTPUT1= T
OUTPUT2= F
OUTPUT4= F
OUTPUT5= F

```

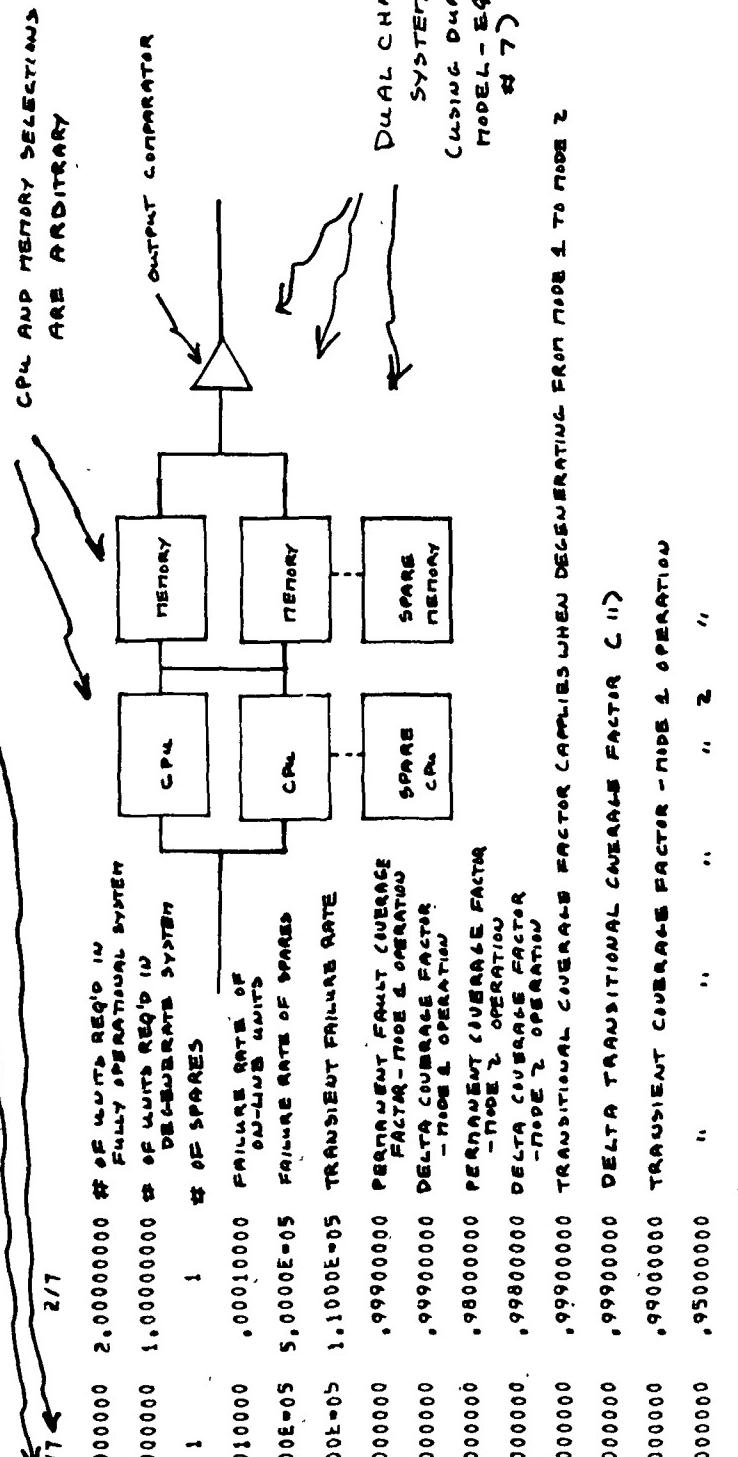
DATA BASE FOR RUN-N-SET

FIGURE 6-3 (Cont.-3)

PARA-METER

STAGE/EQUATION NUMBER

001	2.00000000	2.00000000 # OF UNITS REQ'D IN FULLY OPERATIONAL SYSTEM
02	1.00000000	1.00000000 # OF UNITS REQ'D IN DEGRADABLE SYSTEM
S	1	1 # OF SPARES
LAM	.00010000	.00010000 FAILURE RATE OF ON-LINE UNITS
MU	5.0000E-05	5.0000E-05 FAILURE RATE OF SPARES
GMP	1.0000E-03	1.0000E-03 TRANSIENT FAILURE RATE
C=C1	1.00000000	.99900000 PERMANENT FAULT COVERAGE FACTOR - MODE 1 OPERATION
CD1	1.00000000	.99900000 DELTA COVERAGE FACTOR - MODE 2 OPERATION
C2	1.00000000	.98000000 PERMANENT COVERAGE FACTOR - MODE 2 OPERATION
CD2	1.00000000	.99800000 DELTA COVERAGE FACTOR - MODE 2 OPERATION
CTR	1.00000000	.99900000 TRANSITIONAL COVERAGE FACTOR CAPPILES WHEN DECCELERATING FROM MODE 1 TO MODE 2
CDTH	1.00000000	.99900000 DELTA TRANSITIONAL COVERAGE FACTOR C 11
PRC1	1.00000000	.99000000 TRANSIENT COVERAGE FACTOR - MODE 2 OPERATION
PRC2	1.00000000	.95000000



DUAL MODE SYSTEM PARAMETERS

NUMBER OF STAGES	2	00000010 WHICH WOULD TAKE OUT ENTIRE CHANNEL
CHANNEL FAILURE RATE	.00000002 "SWITCH POINT" FAILURE RATE (E.G. COMPARTOR)	"SWITCH POINT" FAILURE RATE (E.G. COMPARTOR)
SYSTEM FAILURE RATE	.00000002 COVERAGE VALUE TO BE APPLIED IN EVENT OF CHANNEL LOSS DUE TO "SWITCH" FAILURE	COVERAGE VALUE TO BE APPLIED IN EVENT OF CHANNEL LOSS DUE TO "SWITCH" FAILURE
CHANNEL FAILURE COV.	1.00000000	F (FALSE) SPECIFIES THAT, GIVEN THE LOSS OF A SINGLE CHANNEL, TWO UNITS WHICH ARE STILL FUNCTIONAL <u>CANNOT</u> BE USED AS SPARES FOR THE REMAINING CHANNEL

ALL COVERAGE VALUES
ARE PRE-PROGRAMMED,
NOT COMPUTED

CPU AND MEMORY SELECTIONS
ARE ARBITRARY

$T(\text{TRUE}) = \overline{F}$

F (FALSE) SPECIFIES THAT, GIVEN THE LOSS OF A SINGLE CHANNEL, TWO UNITS WHICH ARE STILL FUNCTIONAL CANNOT BE USED AS SPARES FOR THE REMAINING CHANNEL

RUN 1 RELIABILITY RESULTS

FIGURE 6-3 (Cont.-4)

COMPUTED BY EQUATIONS IN
SECTION 3.1.7

COMPUTED BY EQUATIONS IN
SECTION 3.1.7

TIME	SYSTEM RELIABILITY	STAGE 1	STAGE 2
0.000	1.0000000	1.0000000	1.0000000
1000.000	.9569892	.9781833	
2000.000	.8558788	.9254776	.9250189
3000.000	.7295625	.8545920	.8540043
4000.000	.6000171	.7751271	.7744604
5000.000	.4799951	.6933780	.6926714
6000.000	.3756112	.6134504	.6127336
7000.000	.2887028	.5378840	.5371840
8000.000	.2186291	.46681415	.4674637
9000.000	.1635062	.4048975	.4042575
10000.000	.1209855	.3483364	.3477407

COMPUTED BY EQUATIONS IN
SECTION 3.1.7

T	REL	UNREL	SIMREL	SIMRNF
0.000	1.0000000	0.0000000	1.0000000	1.000000E+35
1000.000	.9980114	.0019886	.9187308	9.1153913E+01
2000.000	.987321	.0129679	.6703200	2.5422673E+01
3000.000	.9616920	.0381080	.5488116	1.4724788E+00
4000.000	.9208261	.0791739	.4493290	1.7523171E+00
5000.000	.8662972	.1337028	.3678794	2.0493361E+00
6000.000	.8015662	.1984318	.3011942	2.3548400E+00
7000.000	.7306558	.2694342	.2465970	2.9625905E+00
8000.000	.6569852	.3430148	.2018965	3.2540691E+00
9000.000	.5839004	.4160996	.1652989	3.5323914E+00
10000.000	.5136460	.4863540	.1353353	3.7953591E+00

T	REL PRODUCT
0.000	1.000000
1000.000	.9980114
2000.000	.987321
3000.000	.9616920
4000.000	.9208261
5000.000	.8662972
6000.000	.8015662
7000.000	.7306558
8000.000	.6569852
9000.000	.5839004
10000.000	.5136460

FIGURE 6-4
JOB #4 INPUT/OUTPUT LISTINGS

\$OPTSON OUTPT1=T, OUTPT3=T, PRMDT=T, LSTCH=T, STGOUT=T\$

\$VAR1 PRUD(1)=7,7\$

\$VAR T=1.0E4, STFP=1.0E3, OPTIONN=1\$

IB

\$PARVEC Q1(1)=2,2, Q2(1)=1,1, S(1)=0,1,

LAM(1)=2*1.0E-4, MU(1)=2*5.0E-5, GMP(1)=2*1.1E-5,

C1(1)=1.0,0,999,CD1(1)=1.0,0,999,C2(1)=1.0,0,98,CD2(1)=1.0,0,998,

CTR(1)=1.0,0,999,CDTR(1)=1.0,0,999,PRC1(1)=1.0,0,99,PRC2(1)=1.0,0,958

ID

\$DATA SLH2=1.0E-7, SLH3=2.0E-8, RSGN=T\$

IV 4

\$VARY PARAM(1,1)=0,1,2\$

G

S

FIGURE 6-4 (Cont.-2)

CARE2 (COMPUTER-AIDED RELIABILITY ESTIMATION)

DO YOU WISH TO HAVE YOUR RESPONSES TO MY
QUESTIONS PRINTED BACK FOR VERIFICATION.
DO YOU WISH TO FORM A COMPLEX EQUATION WHICH IS
THE PRODUCT OF THE PRIMARY EQUATIONS.

SVAKI
PROD = 7, 7, 0, 0, 0, 0, 0, 0,
SEND
DO YOU WISH TO HAVE 2-D RELIABILITY PLOTS?
DO YOU WISH TO HAVE PRINTED TABLE OF RELIABILITY RESULTS
DO YOU WISH TO HAVE PRINTED TABLE OF DIFF, RIF,
AND GAIN RESULTS
DO YOU WISH MTF AND RELIABILITY AT MTF RESULTS PRINTED
DO YOU WANT PRINTED RESULTS OF THE MAXIMUM MISSION
TIME CALCULATIONS

DATA BASE FOR RUN-SET

FIGURE 6-4 (Cont.-3)

PARAMETER

STAGE/EQUATION NUMBER

1/7

Q#01 2.00000000

Q#2 1.00000000

S 0 1

LAM .00010000

MU 5.0000E-05

GMP 1.1000E-05

C#C1 1.00000000

CD1 1.00000000

C2 1.00000000

CD2 1.00000000

CTR 1.00000000

CDTH 1.00000000

PRC1 1.00000000

PRC2 1.00000000

ITERATION

1 0.00000000

2 1.00000000

3 2.00000000

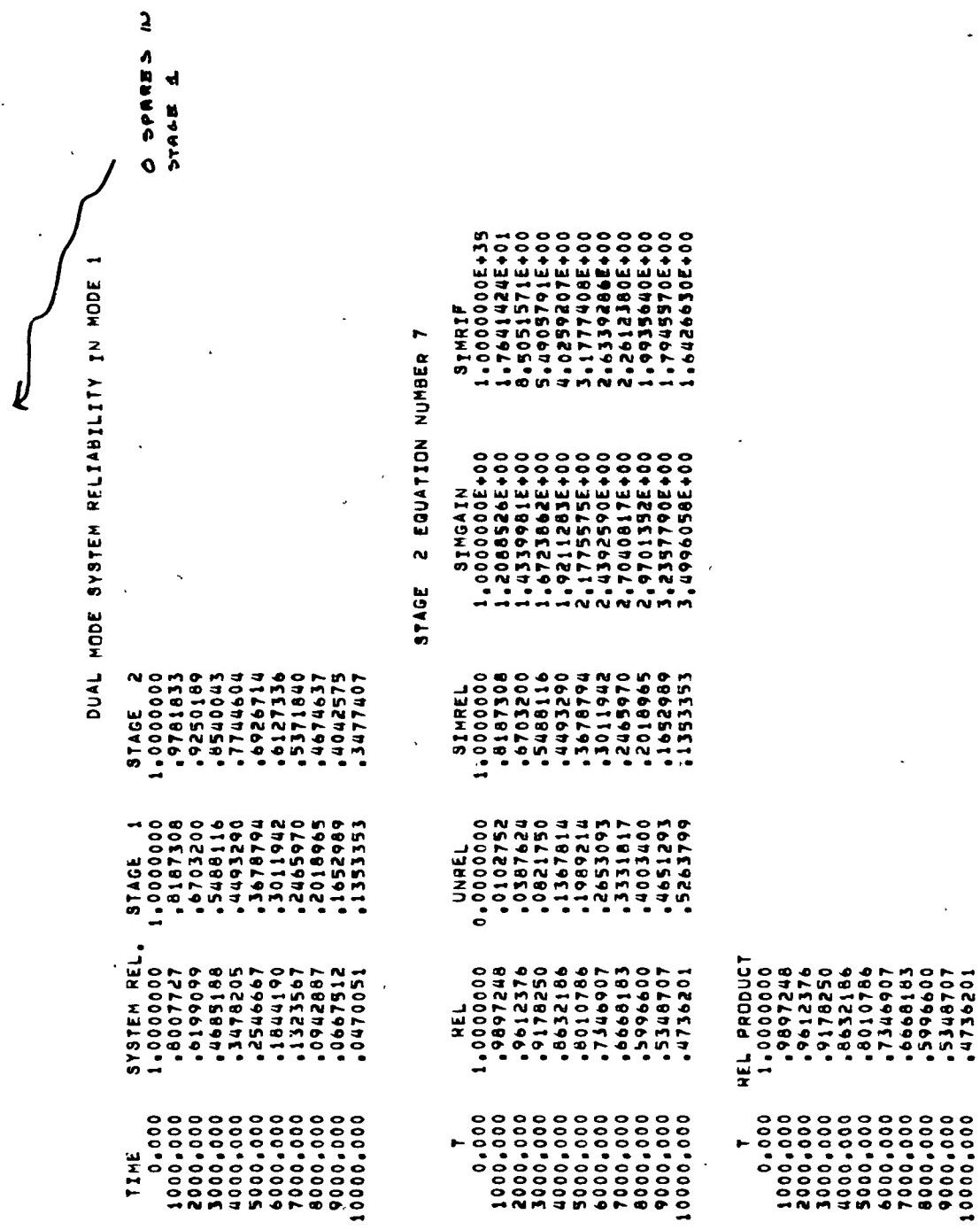
PARAMETER TO BE VARIED = S (S FOR SPARES)

DUAL MODE SYSTEM PARAMETERS

NUMBER OF STAGES	2
CHANNEL FAILURE RATE	.0000010
SYSTEM FAILURE RATE	.0000002
CHANNEL FAILURE COV.	.1.0000000
REASSIGNMENT SWITCH	T

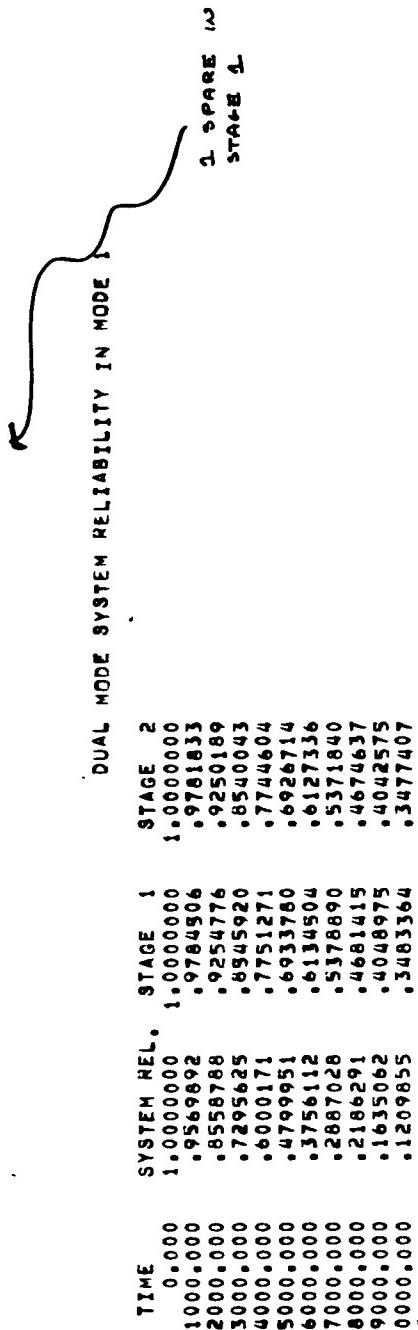
RUN 1 RELIABILITY RESULTS

FIGURE 6-4 (Cont.-4)



RUN 2 RELIABILITY RESULTS

FIGURE 6-4 (Cont.-5)



STAGE 2 EQUATION NUMBER 7

T	KEL	UNREL	SIMREL	SIMGAIN	SIMRIF
0.000	1.0000000	0.0000000	1.0000000	1.0000000E+00	1.0000000E+35
1000.000	.9982021	.0017979	.8187308	1.2192068E+00	1.0082331E+02
2000.000	.9891514	.0108486	.6703200	1.4756405E+00	5.0389128E+01
3000.000	.9692395	.0307605	.5488116	1.7660696E+00	1.4667793E+01
4000.000	.9376641	.0623359	.4493290	2.0866098E+00	8.8139292E+00
5000.000	.8953913	.1046087	.3678794	2.4339299E+00	6.0427147E+00
6000.000	.8443679	.1556321	.3011942	2.8034000E+00	4.4901123E+00
7000.000	.7869564	.2130436	.2465970	3.1912657E+00	3.5363800E+00
8000.000	.7255372	.2744442	.2018965	3.5937081E+00	2.9080864E+00
9000.000	.6623751	.3376249	.1652989	4.0071360E+00	2.4722737E+00
10000.000	.5992955	.4007045	.1135353	4.4282277E+00	2.1578610E+00

REL PRODUCT

0.000	1.0000000
1000.000	.9982021
2000.000	.9891514
3000.000	.9692395
4000.000	.9376641
5000.000	.8953913
6000.000	.8443679
7000.000	.7869564
8000.000	.7255372
9000.000	.6623751
10000.000	.5992955

NOTE THE IMPROVEMENT IN RELIABILITY DUE
TO THE ENDING OF SPARES CANVASLIA
(OR RE-ASSIGNMENT). COMPARE THIS COLUMN
WITH THAT OF STD # 3.

FOR EXAMPLE, AT T = 10,000, SYSTEM RELIABILITY
HAS GONE FROM 0.514 TO 0.599
NOTE ALSO THAT THIS EFFECT IS MUCH LESS pronounced,
FOR THIS SYSTEM, AT A MORE REASONABLE VALUE
OF T. FOR EXAMPLE, AT T = 1000, SYSTEM RELIABILITY
HAS GONE FROM 0.99801 TO 0.99820

RUN 3 RELIABILITY RESULTS

FIGURE 6-4 (Cont. -6)

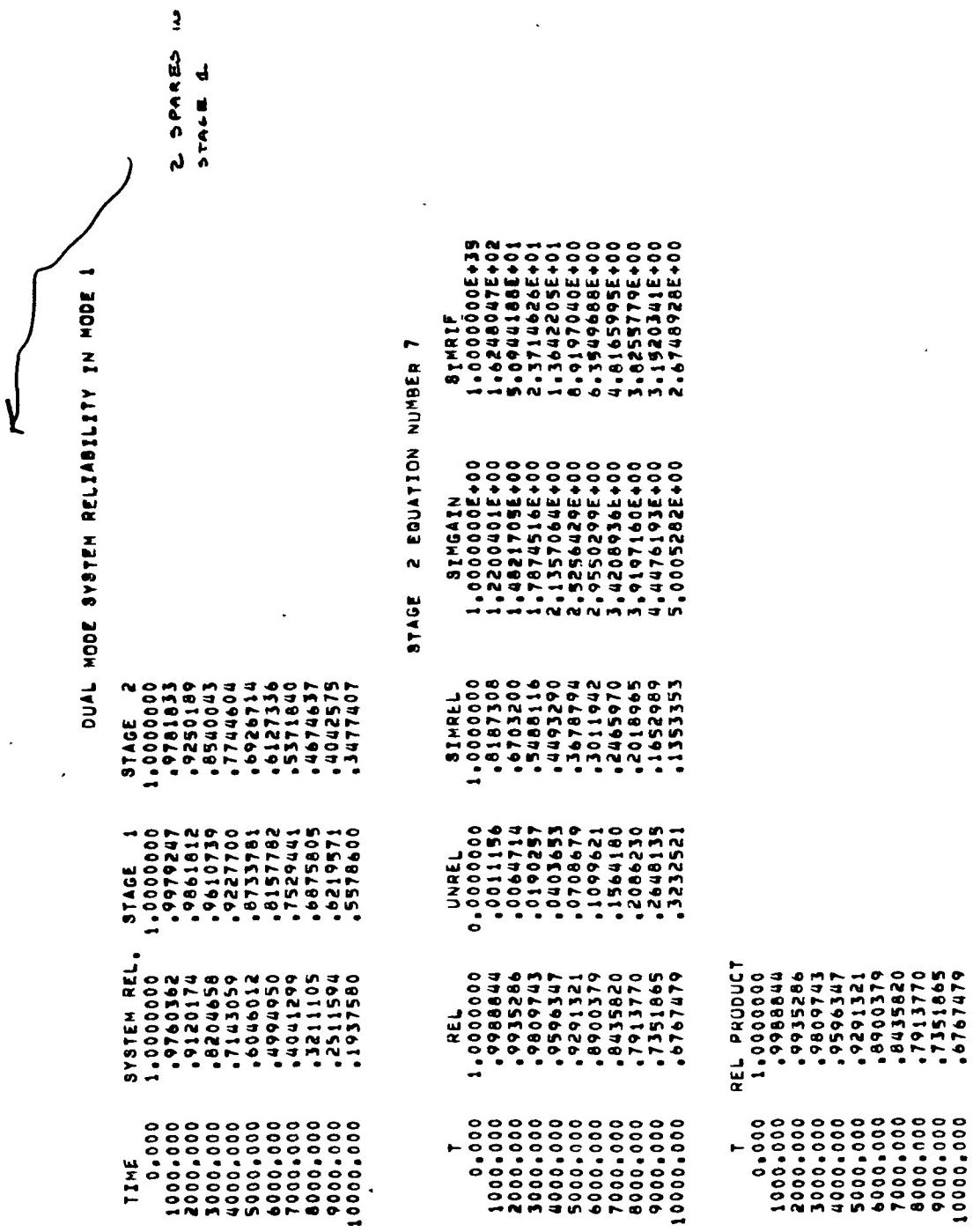


FIGURE 6-5
JOB #5 INPUT/OUTPUT LISTINGS

\$OPT\$ON OUTPT1=T, OUTPT3=T, PRODT=T, LSTCH=T, COVPRC=T, STGOUT=T\$

\$VAR1 PROD(1)=7,7\$

\$VAR T=1.0E4, STEP=1.0E3, OPTION=1\$

\$COVCAL COVINT=T, IGENC(2)=1, IGENP(2)=1, IFSC(2)=2, FRAC(2)=1.0\$

IB

\$PARVEC Q1(1)=2,2, Q2(1)=1,1, S(1)=1,1,

LAM(1)=2*1.0E-4, MU(1)=2*5.0E-5, GMP(1)=2*1.1E-5\$

ID

\$DATA SLH2=1.0E-7, SLH3=2.0E-8, RSGN=F, TMINOR=1000.0\$

IV 8

\$VARY PARAM(1,1)=5.0E-5,1.0E-4\$

F	D	9	310	1.0	0.0	.091011	.09	0.0	50.0
F	D	10	311	1 .95	0.0	.721796	.7	0.0	5.0
F	I	1	01	1.0	0.5				
F	I	2	11	.99	0.0	.04			25.0
F	I	3	01	0.8	0.0				

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FIGURE 6-5 (Cont.-2)

F E 1 11 1.0 1.0 10000.0

F E 2 31 1.0 1.0 .00625 0.0 200.0

F I 1 11 .9999 1.0 10000.0

F I 2 31 .9999 1.0 .023 0.0 200.0

M

2 2 9 2 1 2 9 3 1 2 9 2 1 2

2 4 10 1 1 1 10 1 2 2 10 1 1 1

W

PC

N

PF

G

IB

SPARVEC LAM(1)=1.0E-3\$

IV 8

SVARY PARAM(1,1)=5.0E-4,1.0E-3\$

G

S

CARE? (COMPUTER-AIDED RELIABILITY OPTIMIZATION)

FIGURE 6-5 (Cont.-3)

DO YOU WISH TO HAVE YOUR RESPONSES TO MY
QUESTIONS PRINTED BACK FOR VERIFICATION.
DO YOU WISH TO FORM A COMPLEX EQUATION WHICH IS
THE PRODUCT OF THE PRIMARY EQUATIONS.

OUTPT3 T
PRODT T

COVERAGE DATA BASE

• FAULT SUBCLASSES LINKAGE AND PARAMETERS •

FAULT COVERAGE FOR STAGE 2	LINKED TO STAGE
0.0	0
0.2	1
0.4	2
0.6	3
0.8	4
1.0	5

MINOR CYCLE DURATION (FOR SCHEDULED DETECTORS) = 1000.000000

◆ D/L/A MECHANISM DEFINITIONS

SUBCLASS	MECHANISM	FAULT TYPE/MODE	PERM/1 D I E T	PERM/2 D I E T	TRANS/1 D I E T	TRANS/2 D I E T	PERM/0 D I E T
2	2	9 2 1 2	0 0 0 0	9 3 1 2	0 0 0 0	9 2 1 2	
2	4	10 1 1 1	10 1 2 2	0 0 0 0	0 0 0 0	10 1 1 1	

NORMALIZATION COMPLETE FOR ISOLATION FUNCTIONS
NORMALIZATION COMPLETE FOR E. P. REC. FUNCTIONS
NORMALIZATION COMPLETE FOR I. L. REC. FUNCTIONS

SIMILAR TO JIGS AT 2 EXCEPT THAT THE DUAL MODE
MIDGE ALLEGRA'S ADDITIONAL FEATURES ARE CANCELLED

***** COVERAGE FUNCTION SPECIFICATIONS *****

FIGURE 6-5 (Cont.-4)

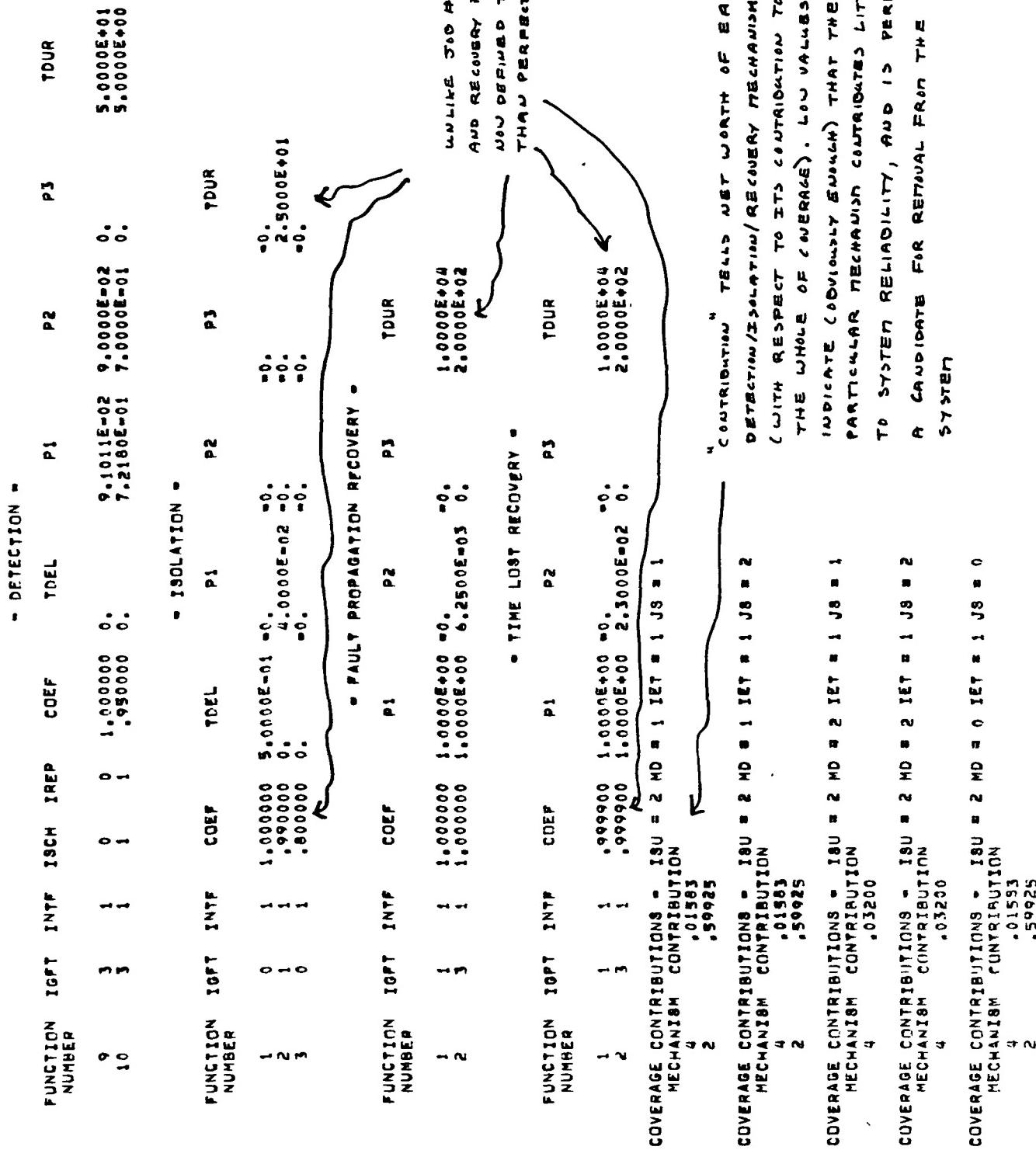


FIGURE 6-5 (Cont.-5)

COVERAGE CONTRIBUTIONS " ISU = 2 MD = 0 IET = 1 JS = 1
COVERAGE CONTRIBUTION MECHANISM CUNTRIBUTION
4 .01583
2 .59925

COVERAGE CONTRIBUTIONS " ISU = 2 MD = 1 IET = 2 JS = 0
COVERAGE CONTRIBUTION MECHANISM CONTRIBUTION
2 ,64202

COVERAGE CONTRIBUTIONS " ISU = 2 MD = 2 IET = 2 JS = 0
COVERAGE CONTRIBUTION MECHANISM CUNTRIAUTION

DATA BASE FOR RUN=SET
1

FIGURE 6-5 (Cont.-6)

PARAMETER

STAGE/EQUATION NUMBER

	1/7	2/7
Q=Q1	2.0000000	2.0000000
Q2	1.0000000	1.0000000
S	1	1
LAH	.000010000	.000010000
MU	5.0000E+05	5.0000E+05
GMP	1.1000E+05	1.1000E+05
C=C1	1.0000000	.61507954
CD1	1.0000000	1.0000000
C2	1.0000000	.03200396
CD2	1.0000000	1.0000000
CTR	1.0000000	.61507954
CDTR	1.0000000	1.0000000
PRC1	1.0000000	.64201783
PRC2	1.0000000	0.0000000

ITERATION

1	5.0000E-05	5.0000E-05
2	1.0000E-04	5.0000E-05

PARAMETER TO BE VARIED • MU

DUAL MODE SYSTEM PARAMETERS		
NUMBER OF STAGES	2	
CHANNEL FAILURE RATE	.00000010	
SYSTEM FAILURE RATE	.00000002	
CHANNEL FAILURE COV.	1.0000000	
REASSIGNMENT SWITCH	F	

RUN 1 RELIABILITY RESULTS

FIGURE 6-5 (Cont.-7)

DUAL MODE SYSTEM RELIABILITY IN MODE 1

TIME	SYSTEM REL.	STAGE 1	STAGE 2
0.000	1.0000000	1.0000000	1.0000000
1000.000	.8935777	.9784506	.9111674
2000.000	.7594777	.9254776	.8207726
3000.000	.6221214	.8545420	.7282169
4000.000	.4955078	.7751271	.6395670
5000.000	.3859877	.6933780	.5570113
6000.000	.2953104	.6134504	.4817391
7000.000	.2226007	.5378890	.4141090
8000.000	.1657121	.4681415	.3543188
9000.000	.1220597	.4048975	.3017840
10000.000	.0990893	.3483364	.2506355

STAGE 2 EQUATION NUMBER 7

T	REL	SIMREL	SIMMAIN	SIMRIF
0.000	1.0000000	1.0000000	1.0000000E+00	1.0000000E+00
1000.000	.9212702	.0787298	.8187308	.1252419E+00
2000.000	.8440753	.1559247	.6703200	.2592124E+00
3000.000	.7665343	.2334657	.5468114	.13967165E+00
4000.000	.6889366	.3110634	.4493290	.153325652E+00
5000.000	.6126042	.3873958	.3678794	.177028532E+00
6000.000	.5391237	.4608763	.3011942	.16652309E+00
7000.000	.4699996	.5300904	.2465970	.1789937E+00
8000.000	.4060078	.5939922	.2018965	.19055772E+00
9000.000	.3480503	.6519497	.1652989	.20109698E+00
10000.000	.2962916	.7037084	.1353353	.21055818E+00

T	REL PRODUCT
0.000	1.0000000
1000.000	.9212702
2000.000	.8440753
3000.000	.7665343
4000.000	.6889366
5000.000	.6126042
6000.000	.5391237
7000.000	.4699996
8000.000	.4060078
9000.000	.3480503
10000.000	.2962916

RUN 2 RELIABILITY RESULTS

FIGURE 6-5 (Cont.-8)

DUAL MODE SYSTEM RELIABILITY IN MODE 1

TIME	SYSTEM REL.	STAGE 1	STAGE 2
0.000	1.00000000	1.00000000	1.00000000
1000.000	.8915207	.9745558	.9133674
2000.000	.7494644	.9133369	.8207726
3000.000	.6129182	.8332956	.7262369
4000.000	.4744313	.7455985	.6395670
5000.000	.3459473	.6573780	.5570113
6000.000	.2752306	.5729849	.4817361
7000.000	.2048004	.49468780	.4141690
8000.000	.1501768	.4242536	.3543188
9000.000	.1099724	.3614856	.3017840
10000.000	.07933710	.30664317	.2560635

STAGE 2 EQUATION NUMBER 7

T	REL	UNREL	SIMRFL	SIMGAIN	SIMRIF
0.000	1.00000000	0.00000000	1.00000000E+00	1.00000000E+00	1.00000000E+15
1000.000	.9211050	.07888950	.8167308	.11250402E+00	.22976025E+00
2000.000	.8410631	.1469370	.6703200	.12577022E+00	.21007149E+00
3000.000	.7649538	.2360462	.5488116	.13920148E+00	.19114105E+00
4000.000	.6843440	.3156360	.4493290	.15230800E+00	.17446293E+00
5000.000	.6050776	.3940224	.3679794	.1647217AE+00	.16042756E+00
6000.000	.5266737	.4693263	.3011042	.1761A986E+00	.14RA9550E+00
7000.000	.4610749	.5399531	.2465070	.18655821E+00	.1395120E+00
8000.000	.3952172	.6047828	.2019965	.19575237E+00	.1319631E+00
9000.000	.3345106	.66331894	.1692989	.20375850E+00	.12586166E+00
10000.000	.2850254	.7149746	.1355353	.21060686E+00	.12091642E+00

T REL PRODUCT

0.000	1.00000000
1000.000	.9211050
2000.000	.8410630
3000.000	.7639538
4000.000	.6843460
5000.000	.6050776
6000.000	.5306737
7000.000	.4600469
8000.000	.3952172
9000.000	.3368106
10000.000	.2850254

DATA BASE FOR RUN=SET

FIGURE 6-5 (Cont.-9)

PARAMETER

STAGE/EQUATION NUMBER

	1/7	2/7
G=01	2.00000000	2.00000000
02	1.00000000	1.00000000
S	1	1
LAM	.000100000	.000100000
MU	5.0000E-05	5.0000E-05
GMP	1.1000E-05	1.1000E-05
C=C1	1.00000000	.61507954
CD1	1.00000000	1.00000000
C2	1.00000000	.03200396
CD2	1.00000000	1.00000000
CTR	1.00000000	.61507954
CDTR	1.00000000	1.00000000
PRC1	1.00000000	.64201783
PRC2	1.00000000	0.00000000

ITERATION

- 1 5.0000E-04 5.0000E-05
- 2 1.0000E-03 5.0000E-05

PARAMETER TO BE VARIED • MU

DUAL MODE SYSTEM PARAMETERS

NUMBER OF STAGES	2
CHANNEL FAILURE RATE	.00000010
SYSTEM FAILURE RATE	.00000002
CHANNEL FAILURE COV.	1.0000000
REASSIGNMENT SWITCH	F

RUN 1 RELIABILITY RESULTS

FIGURE 6-5 (Cont. -10)

DUAL MODE SYSTEM RELIABILITY IN MODE 1					
TIME	SYSTEM REL.	STAGE 1	STAGE 2		
0.000	1.0000000	1.0000000	1.0000000		
1000.000	.3181210	.3483364	.9133674		
2000.000	.0530309	.0646264	.8207726		
3000.000	.0074118	.0101814	.7202369		
4000.000	.0009561	.0014937	.6395670		
5000.000	.0011811	.0002121	.5570113		
6000.000	.0001422	.0000295	.4817391		
7000.000	.0000017	.0000041	.4141890		
8000.000	.0000002	.0000006	.3543188		
9000.000	.0000000	.0000001	.3017840		
10000.000	.0000000	.0000000	.2560635		

STAGE 2 EQUATION NUMBER 7					
T	REL	SIMREL	SIMMAIN	SIMRIF	
0.000	1.0000000	1.0000000	1.0000000E+00	1.0000000E+00	
1000.000	.7017676	.3328711	2.1082263E+00	2.2169410E+00	
2000.000	.3119092	.6880908	.1108032	2.8149830E+00	1.292668E+00
3000.000	.1192445	.8847555	.0348832	3.1245830E+00	1.0885684E+00
4000.000	.0396967	.9603033	.0122773	3.2533315E+00	1.0285528E+00
5000.000	.0133108	.9866892	.0040868	3.2570340E+00	1.0093484E+00
6000.000	.004177	.9955823	.0013604	3.2474126E+00	1.0030709E+00
7000.000	.0014605	.9985396	.0004528	3.2252297E+00	1.001091E+00
8000.000	.0004821	.9995179	.0001507	3.1983624E+00	1.0003315E+00
9000.000	.0001590	.9998641	.0000502	3.1697815E+00	1.0001089E+00
10000.000	.0000525	.9999947	.0000167	3.1405663E+00	1.0000358E+00

REL PRODUCT					
T	REL	PRODUCT			
0.000	1.0000000	1.0000000			
1000.000	.7017676	.7017676			
2000.000	.3119092	.3119092			
3000.000	.1192445	.1192445			
4000.000	.0396967	.0396967			
5000.000	.0133108	.0133108			
6000.000	.004177	.004177			
7000.000	.0014605	.0014605			
8000.000	.0004821	.0004821			
9000.000	.0001590	.0001590			
10000.000	.0000525	.0000525			

RUN 2 RELIABILITY RESULTS

FIGURE 6-5 (Cont.-11)

TIME	SYSTEM REL.	STAGE 1	STAGE 2
0.000	1.0000000	1.0000000	1.0000000
1000.000	*2798512	*3064317	*9133674
2000.000	*0410201	*0499894	*8207726
3000.000	*0052337	.0071894	*7282169
4000.000	*0006355	*0009941	*6395670
5000.000	*0000755	*0001356	*5570113
6000.000	*0000089	*0000184	*4817391
7000.000	*0000010	*0000025	*4141890
8000.000	*0000001	*000003	*3543188
9000.000	*0000000	*000000	*3017840
10000.000	*0000000	*000000	*2560635

STAGE 2 EQUATION NUMBER 7

T	REL	SIMREL	SIMGAIN	SIMRIF
0.000	1.0000000	0.0000000	1.000000E+00	1.0000000E+35
1000.000	*4802679	*3197321	*3328711	*2.0436378E+00
2000.000	*2908902	*7091098	*2.6252877E+00	*1.2539621E+00
3000.000	*1050750	*8949250	*0368832	*2.8488615E+00
4000.000	*0559036	*9641964	*C122773	*1.0761984E+00
5000.000	*0119488	*9880512	*0040868	*1.0243986E+00
6000.000	*0039579	*9960421	*0013604	*1.0079571E+00
7000.000	*0013075	*9986925	*0004926	*1.0026079E+00
8000.000	*0004315	*9995685	*0001507	*1.0005557E+00
9000.000	*0001423	*9998577	*0000502	*1.0002808E+00
10000.000	*0000469	*9999531	*0000167	*1.0000922E+00

T	REL PRODUCT
0.000	1.000000
1000.000	*4802679
2000.000	*2908902
3000.000	*1050750
4000.000	*0358036
5000.000	*0119488
6000.000	*0039579
7000.000	*0013075
8000.000	*0004315
9000.000	*0001423
10000.000	*0000469

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FIGURE 6-6
JOB #6 INPUT/OUTPUT LISTINGS

\$OPTSON OUTPT1=T, OUTPT3=T, PRODT=T, COVPRC=T, STGOUT=T\$

\$VAR1 PROD(1)=7,7,7\$

\$VAR T=1.6E4, STEP=2.0E3, OPTION=1\$

\$COUVCAL COVINT=T, IGENC(2)=-1,1, IGENP(2)=1,1,

IFSC(2)=2,3,3, FRAC(2)=1.0,0.63,0.37\$

IB

\$PARVEC Q1(1)=3,1,2, Q2(1)=2,1,1, S(1)=1,2,1, LAM(1)=1.0F-5,2.0E-4,5.0E-5,

MU(1)=5.0E-6,1.25E-4,2.5E-5, C1(1)=.998, C2(1)=.99, CD1(1)=.995,

CD2(1)=.99, CTR(1)=.996, CDTR(1)=.995, PRC1(1)=.99, PRC2(1)=.97\$

ID

\$DATA SLH2=0.0, SLH3=0.0, RSGN=T, TFD9(4)=100., TMINOR=1000.0\$

F	D	1	010	1.0	0.0
---	---	---	-----	-----	-----

F	D	2	010	.25	0.0
---	---	---	-----	-----	-----

F	D	5	010	.025	0.0
---	---	---	-----	------	-----

F	D	10	311	1 .95	0.0	.721796	0.7	0.0	5.0
---	---	----	-----	-------	-----	---------	-----	-----	-----

F	D	20	01		.9996	0.0
---	---	----	----	--	-------	-----

F	I	1	01	1.0	0.5
---	---	---	----	-----	-----

F	I	3	01	0.8	20.0
---	---	---	----	-----	------

F	I	4	11	.99985	0.0	.005	200.0
---	---	---	----	--------	-----	------	-------

RAYTHEON COMPANY

EQUIPMENT DIVISION

RAYTHEON

FIGURE 6-6 (Cont.-2)

F	E	1	11	1.0	1.0		10000.0	
F	E	2	31	1.0	1.0	.00625	0.0	200.0
F	E	3	11	.96	1.0		10000.0	
F	I	1	11	.9999	1.0		10000.0	
F	T	2	31	.9999	1.0	.023	0.0	200.0

M

2	4	10	1	1	1	10	1	2	2		10	1	1	1							
2	7	2	1	1	1	2	1	1	2	2	1	1	1	2	1	2	2	1	1	1	
2	9	5	1	1	1	5	1	1	2	5	3	1	1	5	3	1	2	5	1	1	1
3	1	1	1	1	1	1	1	1	2	1	1	1	1	1	1	1	2	1	1	1	1
4	11	20	4	1	1	20	4	3	2	20	4	1	1	20	4	3	2	20	4	1	1

W

PC

N

PF

G

ID

S DATA TMINOR=400.0\$

G

CARE2 (COMPUTER-AIDED RELIABILITY ESTIMATION)

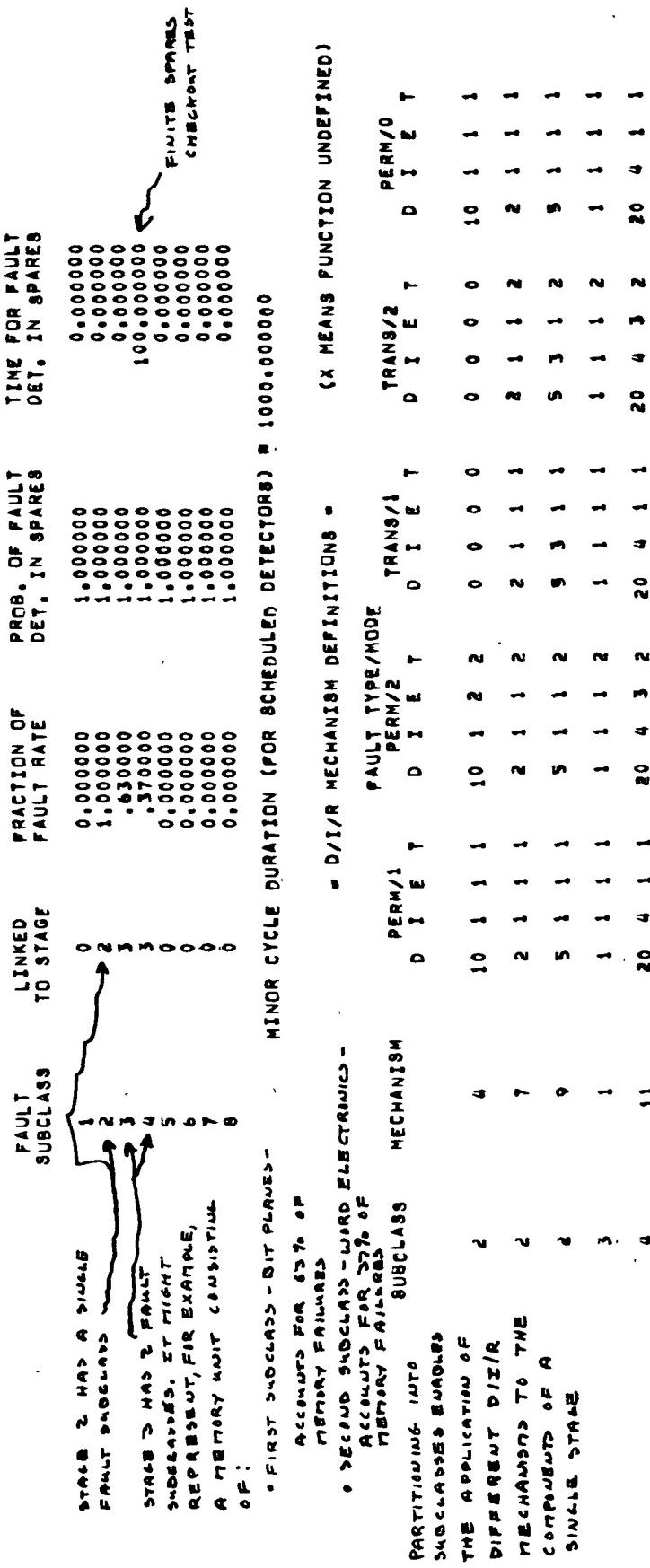
FIGURE 6-6 (Cont. -3)

DO YOU WISH TO HAVE YOUR RESPONSES TO MY
QUESTIONS PRINTED BACK FOR VERIFICATION.
DO YOU WISH TO FORM A COMPLEX EQUATION WHICH IS
THE PRODUCT OF THE PRIMARY EQUATIONS.

SVANS
PROD = 7, 7, 7, 0, 0, 0, 0, 0,
SEND
DO YOU WISH TO HAVE 2-D RELIABILITY PLOTS?
DO YOU WISH TO HAVE PRINTED TABLE OF RELIABILITY RESULTS
DO YOU WISH TO HAVE PRINTED TABLE OF DIFF, RIP,
AND GAIN RESULTS?
DO YOU WISH MIF AND RELIABILITY AT MTP RESULTS PRINTED
DO YOU WANT PRINTED RESULTS OF THE MAXIMUM MISSION
TIME CALCULATIONS?

OUTPUT3= !
PRODT= !
LPLOTS F
OUTPUT1= !
OUTPUT2= F
OUTPUT4= F
OUTPUT5= F

- FAULT SUBCLASS LINKAGE AND PARAMETERS -



- D/I/R MECHANISM DEFINITIONS -

- D/I/R MECHANISM DEFINITIONS -

PARTITIONING INTO SUBCLASSES	Mechanism	PERM/1	PERM/2/MODE	TRANS/1	TRANS/2	D I E T	D I E T	PERM/0
THE APPLICATION OF DIFFERENT D/I/R MECHANISMS TO THE COMPONENTS OF A SINGLE STATE	4	10 1 1	10 1 2	2 0 0 0	0 0 0 0	0 0 0 0	0 0 0 0	10 1 1 1
	2	7	2 1 1	2 1 2	2 1 1	2 1 1	2 1 1	2 1 1 1
	0	5 1 1	5 1 2	5 3 1	5 3 1	5 3 1	5 3 1	5 1 1 1
	3	1 1 1	1 1 2	1 1 1	1 1 1	1 1 1	1 1 1	1 1 1 1
	4	11 20 4 1 1	20 4 3 2	20 4 1 1	20 4 1 1	20 4 1 1	20 4 1 1	20 4 1 1

NORMALIZATION COMPLETE FOR DETECTION FUNCTIONS

NORMALIZATION COMPLETE FOR ISOLATION FUNCTIONS

NORMALIZATION COMPLETE FOR E, P, REC, FUNCTIONS

NORMALIZATION COMPLETE FOR T, L, REC, FUNCTIONS

***** COVERAGE FUNCTION SPECIFICATIONS *****

FIGURE 6-6 (Cont. -5)

FUNCTION NUMBER	I _{GFT}	I _{NTF}	I _{SCH}	I _{REP}	Coeff	TDEL	P ₁	P ₂	P ₃	TDUR
1	0	1	0	0	1.000000	0.	0.	0.	0.	0.
2	0	1	0	0	.250000	0.	0.	0.	0.	0.
3	0	1	0	0	.025000	0.	0.	0.	0.	0.
10	3	1	1	1	.999999	0.	7.2180E-01	7.0000E-01	0.	5.0000E+00
20	0	1	0	0	.999600	0.	0.	0.	0.	0.
* DETECTION *										
FUNCTION NUMBER	I _{GFT}	I _{NTF}	I _{SCH}	I _{REP}	Coeff	TDEL	P ₁	P ₂	P ₃	TDUR
1	0	1	1	0	1.000000	5.0000E-01	0.	0.	0.	0.
3	0	1	1	0	.800000	2.0000E-01	0.	0.	0.	0.
4	1	1	1	0	.999850	0.	5.0000E-03	0.	0.	2.0000E+02
* ISOLATION *										
FUNCTION NUMBER	I _{GFT}	I _{NTF}	I _{SCH}	I _{REP}	Coeff	TDEL	P ₁	P ₂	P ₃	TDUR
1	1	1	1	1	1.000000	1.0000E+00	0.	0.	0.	0.
2	3	1	1	1	1.000000	1.0000E+00	6.2500E-03	0.	0.	1.0000E+04
3	1	1	1	1	.999999	1.0000E+00	=0.	0.	0.	2.0000E+02
* FAULT PROPAGATION RECOVERY *										
FUNCTION NUMBER	I _{GFT}	I _{NTF}	I _{SCH}	I _{REP}	Coeff	TDEL	P ₁	P ₂	P ₃	TDUR
1	1	1	1	1	1.000000	1.0000E+00	0.	0.	0.	0.
2	3	1	1	1	1.000000	1.0000E+00	2.5000E-03	0.	0.	2.0000E+02
3	1	1	1	1	.999999	1.0000E+00	=0.	0.	0.	1.0000E+04
* TIME LOST RECOVERY *										
FUNCTION NUMBER	I _{GFT}	I _{NTF}	I _{SCH}	I _{REP}	Coeff	TDEL	P ₁	P ₂	P ₃	TDUR
1	1	1	1	1	.999990	1.0000E+00	0.	0.	0.	1.0000E+04
2	3	1	1	1	.999990	1.0000E+00	2.5000E-02	0.	0.	2.0000E+02
COVERAGE CONTRIBUTIONS = ISU = 2 MD = 1 IET = 1 JS = 1 MECHANISM CONTRIBUTION										
4										
7										
9										
COVERAGE CONTRIBUTIONS = ISU = 2 MD = 2 IET = 1 JS = 2 MECHANISM CONTRIBUTION										
4										
7										
9										
COVERAGE CONTRIBUTIONS = ISU = 2 MD = 2 IET = 1 JS = 2										
4										
7										
9										

FIGURE 6-6 (Cont. -6)

MECHANISM CONTRIBUTION												
COVERAGE CONTRIBUTIONS - ISU = 2 MD = 0 IET = 1 JS = 0												
MECHANISM CONTRIBUTION												
4	.02340											
7	.24403											
9	.02162											
COVERAGE CONTRIBUTIONS - ISU = 2 MD = 0 IET = 1 JS = 1												
MECHANISM CONTRIBUTION												
4	.69462											
7	.24685											
9	.02187											
COVERAGE CONTRIBUTIONS - ISU = 2 MD = 1 IET = 2 JS = 0												
MECHANISM CONTRIBUTION												
7	.24685											
9	.01750											
COVERAGE CONTRIBUTIONS - ISU = 2 MD = 1 IET = 2 JS = 0												
MECHANISM CONTRIBUTION												
7	.24403											
9	.01105											
COVERAGE CONTRIBUTIONS - ISU = 3 MD = 1 IET = 1 JS = 1												
MECHANISM CONTRIBUTION												
1	.99990											
COVERAGE CONTRIBUTIONS - ISU = 4 MD = 1 IET = 1 JS = 1												
MECHANISM CONTRIBUTION												
11	.99935											
COVERAGE CONTRIBUTIONS - ISU = 3 MD = 1 IET = 1 JS = 2												
MECHANISM CONTRIBUTION												
1	.99990											
COVERAGE CONTRIBUTIONS - ISU = 4 MD = 2 IET = 1 JS = 2												
MECHANISM CONTRIBUTION												
11	.98847											
COVERAGE CONTRIBUTIONS - ISU = 3 MD = 2 IET = 1 JS = 1												
MECHANISM CONTRIBUTION												
11	.01681											
COVERAGE CONTRIBUTIONS - ISU = 4 MD = 2 IET = 1 JS = 2												
MECHANISM CONTRIBUTION												
11	.98847											
COVERAGE CONTRIBUTIONS - ISU = 3 MD = 0 IET = 1 JS = 0												
MECHANISM CONTRIBUTION												
1	.99990											
COVERAGE CONTRIBUTIONS - ISU = 4 MD = 0 IET = 1 JS = 0												
MECHANISM CONTRIBUTION												
11	.99915											

FIGURE 6-6 (Cont. -7)

COVERAGE CONTRIBUTIONS = ISU = 1 MD = 0 IET = 1 JS = 1
 MECHANISM CONTRIBUTION
 1 .99990

COVERAGE CONTRIBUTIONS = ISU = 4 MD = 0 IET = 1 JS = 1
 MECHANISM CONTRIBUTION
 11 .99995

COVERAGE CONTRIBUTIONS = ISU = 3 MD = 1 IET = 2 JS = 0
 MECHANISM CONTRIBUTION
 1 .99990

COVERAGE CONTRIBUTIONS = ISU = 4 MD = 1 IET = 2 JS = 0
 MECHANISM CONTRIBUTION
 11 .99995

COVERAGE CONTRIBUTIONS = ISU = 3 MD = 2 IET = 2 JS = 0
 MECHANISM CONTRIBUTION
 1 .99995

COVERAGE CONTRIBUTIONS = ISU = 4 MD = 2 IET = 2 JS = 0
 MECHANISM CONTRIBUTION
 11 .99997

DATA BASE FOR RUN-SET

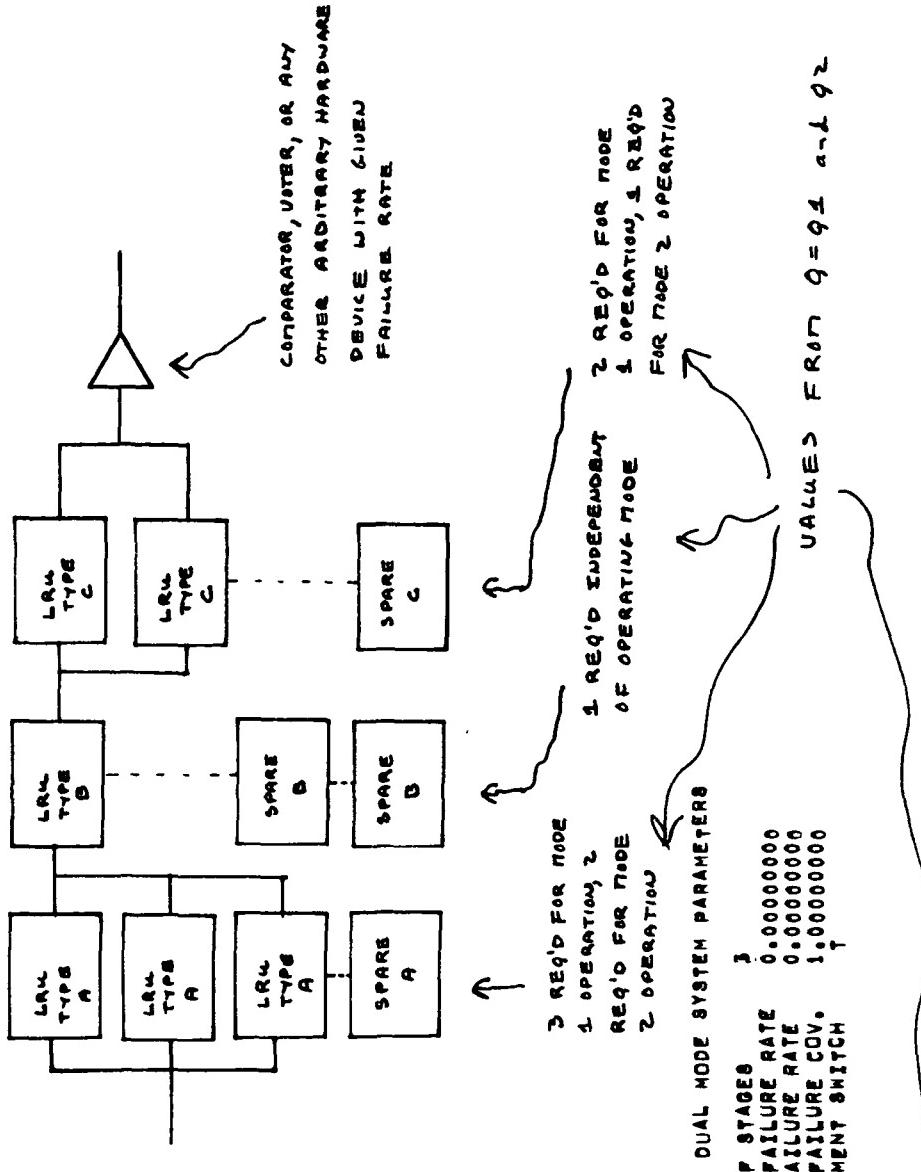
FIGURE 6-6 (Cont. -8)

PARAMETER

STAGE/EQUATION NUMBER

	1/7	2/7	3/7
Q=Q1	3.00000000	1.00000000	2.00000000
Q2	2.00000000	1.00000000	1.00000000
S	1	2	1
LAH	1.0000E+05	2.0000E+04	5.0000E+05
HU	5.0000E+06	1.2500E+04	2.5000E+05
GMP	1.0000E+06	1.0000E+06	1.0000E+06
CBC1	.999800000	.999334470	.999969654
CD1	.999500000	1.00000000	1.00000000
C2	.990000000	.288905341	.62969525
CD2	.990000000	1.00000000	.98894540
CTR	.999600000	.96334470	.999969654
CDTR	.999800000	1.00000000	1.00000000
PRC1	.990000000	.266434856	.999969654
PRC2	.970000000	.25507415	.69912694

HYBRID CONFIGURATION



DUAL MODE SYSTEM PARAMETERS

NUMBER OF STAGES 3
CHANNEL FAILURE RATE 0.00000000
SYSTEM FAILURE RATE 0.00000000
CHANNEL FAILURE COV. 1.00000000
REASSIGNMENT SWITCH T

1. REQ'D INDEPENDENTLY OF MODE
2. REQ'D FOR MODE OF OPERATION, 1 REQ'D FOR MODE 2 OPERATION

VALUES FROM Q = Q1 AND Q2

RUN 1 RELIABILITY RESULTS

FIGURE 6-6 (Cont. -9)

DUAL MODE SYSTEM RELIABILITY IN MODE 1

TIME	SYSTEM REL.	STAGE 1	STAGE 2	STAGE 3
0.000	1.0000000	1.0000000	1.0000000	1.0000000
2000.000	.9388961	.9978564	.9616839	.9784016
4000.000	.7854347	.9920432	.8555399	.9253990
6000.000	.5940845	.9830368	.7072456	.8544976
8000.000	.4165251	.9712447	.5533451	.7750263
10000.000	.2760450	.9570697	.4160345	.6932771
12000.000	.1753641	.9408529	.3038642	.6133534
14000.000	.1078972	.9229071	.2173059	.5377984
16000.000	.0646686	.9035139	.1529654	.4680584

STAGE 3 EQUATION NUMBER 7

T	REL	UNREL	SIMREL	SIMGAIN	SIMRIF
0.000	1.0000000	0.0000000	1.0000000	1.000000E+00	1.000000E+35
2000.000	.9590514	.0409486	.5945205	.16131510E+00	.99021591E+00
4000.000	.8425223	.1574777	.3534547	.28316783E+00	.41056319E+00
6000.000	.6803874	.3196126	.2101361	.32378422E+00	.24713170E+00
8000.000	.5151265	.4846715	.1249302	.41249306E+00	.16054903E+00
10000.000	.37222651	.6277149	.0742736	.50123490E+00	.14747562E+00
12000.000	.2596605	.7403395	.0441572	.58803708E+00	.12910872E+00
14000.000	.1763566	.8236412	.0262523	.67178292E+00	.11024735E+00
16000.000	.1173526	.8826472	.0156076	.75169753E+00	.1152729E+00

REL PRODUCT
MECHANISM CONTRIBUTION

0.000	1.0000000
2000.000	.9590514
4000.000	.8425223
6000.000	.6803874
8000.000	.5151265
10000.000	.37222651
12000.000	.2596605
14000.000	.1763566
16000.000	.1173526

COVERAGE CONTRIBUTIONS = ISU = 2 MD = 1 IET = 1 JS = 1
MECHANISM CONTRIBUTION

4	.69462
7	.24685
9	.02167

COVERAGE CONTRIBUTIONS = ISU = 2 MD = 2 IET = 1 JS = 1
MECHANISM CONTRIBUTION

4	.69462
7	.24685
9	.02167

COVERAGE CONTRIBUTIONS = ISU = 2 MD = 2 IET = 1 JS = 2

4	.05851
7	.024403
9	.02162

FIGURE 6-6 (Cont. -10)

MECHANISM	CONTRIBUTION
4	.05851
7	.24403
9	.02162

COVERAGE CONTRIBUTIONS = ISU = 2 MD = 0 IET = 1 JS = 0

MECHANISM	CONTRIBUTION
4	.69462
7	.24689
9	.02167

COVERAGE CONTRIBUTIONS = ISU = 2 MD = 0 IET = 1 JS = 1

MECHANISM	CONTRIBUTION
4	.69462
7	.24689
9	.02167

DATA BASE FOR RUN=SET

FIGURE 6-6 (Cont. -11)

PARAMETER
STAGE/EQUATION NUMBER

	1/7	2/7	3/7
Q&Q1	1.00000000	1.00000000	2.00000000
Q2	2.00000000	1.00000000	1.00000000
S	1	2	1
LAM	1.0000E-05	2.0000E-04	5.0000E-05
MU	5.0000E-06	1.2500E-04	2.5000E-05
GMP	1.0000E-06	1.0000E-06	1.0000E-06
C=C1	.99800000	.96334470	.99969654
CD1	.99900000	1.00000000	1.00000000
C2	.99000000	.322415782	.62969525
CD2	.99000000	1.00000000	.98894540
CTR	.99600000	.96334470	.99969654
CDTR	.99500000	1.00000000	1.00000000
PRC1	.99000000	.26434856	.99969654
PRC2	.97000000	.23507415	.69912694

DUAL MODE SYSTEM PARAMETERS

NUMBER OF STAGES	3
CHANNEL FAILURE RATE	0.0000000
SYSTEM FAILURE RATE	0.0000000
CHANNEL FAILURE COV.	1.0000000
REASSIGNMENT SWITCH	7

RUN 1 RELIABILITY RESULTS

FIGURE 6-6 (Cont. -12)

DUAL MODE SYSTEM RELIABILITY IN MODE 1

TIME	SYSTEM REL.	STAGE 1	STAGE 3
0.000	1.0000000	1.0000000	1.0000000
2000.000	.9988941	.9970364	.9961639
4000.000	.7854347	.9920432	.9955599
6000.000	.5940845	.9830308	.7072456
8000.000	.4165251	.9712447	.5533451
10000.000	.2760450	.9570697	.4160345
12000.000	.1753641	.9408529	.3036842
14000.000	.1078972	.9229071	.2173059
16000.000	.0646886	.9035139	.1529654

STAGE 3 EQUATION NUMBER 7

T	REL	UNREL	BINREL	SIMRIF	SIMGAIN	SIMRIF
0.000	1.0000000	0.0000000	1.0000000	1.000000E+00	1.000000E+35	1.000000E+35
2000.000	.9991357	.0408643	.5945205	1.6132928E+00	9.9225865E+00	9.9225865E+00
4000.000	.8429157	.1570643	.3534947	2.3647913E+00	4.1159118E+00	4.1159118E+00
6000.000	.6811611	.3188839	.2101361	3.2413099E+00	2.4476642E+00	2.4476642E+00
8000.000	.5162436	.4837564	.1249302	4.1322558E+00	1.8089058E+00	1.8089058E+00
10000.000	.3732119	.6367881	.0742736	5.0248278E+00	1.4769169E+00	1.4769169E+00
12000.000	.2604801	.7395199	.0441572	5.8989316E+00	1.2925181E+00	1.2925181E+00
14000.000	.1770195	.8229805	.0262923	6.7429980E+00	1.1631965E+00	1.1631965E+00
16000.000	.1178514	.8821486	.0156076	7.5509169E+00	1.1159032E+00	1.1159032E+00

T	REL PRODUCT
0.000	1.0000000
2000.000	.9991357
4000.000	.9429157
6000.000	.6811611
8000.000	.5162436
10000.000	.3732119
12000.000	.2604801
14000.000	.1770195
16000.000	.1178514

FIGURE 6-7
JOB #7 INPUT/OUTPUT LISTINGS

\$OPTSMN OUTPT1=T,OUTPT3=T,LPLDT=T,PRODT=T,LSTCH=T,DEFCHNG=T,STGOUT=T\$

\$VAR1 PROD(1)=7,7,4,2\$

\$VAR T=1.0E4, STEP=1.0E3, OPTION=1\$

\$DEFAULT LAMDEF=1.0E-4\$

10000

100000

IB

\$PARVEC Q1(1)=2,2,0,1, Q2(1)=1,1, S(1)=4*1, Z(2)=2,

MU(1)=2*5.0E-5,1.0E-4,0,0, GMP(1)=2*1.1E-5,

C1(2)=.999, CD1(2)=.999, C2(2)=.98, CD2(2)=.998, CTR(2)=.999, CDTR(2)=.999,

PRC1(2)=.99, PRC2(2)=.95\$

ID

\$DATA SLH2=1.0E-7,SLH3=2.0E-8, RSGN=F\$

IV 8

\$VARY PARAM(1,3)=1.0E-4,5.0E-5,0,0, PARAM(1,4)=0,0\$

G

S

CAREZ (COMPUTER-AIDED RELIABILITY ESTIMATION)

FIGURE 6-7 (Cont. -2)

DO YOU WISH TO HAVE YOUR RESPONSES TO MY
QUESTIONS PRINTED BACK FOR VERIFICATION.
DO YOU WISH TO FORM A COMPLEX EQUATION WHICH IS
THE PRODUCT OF THE PRIMARY EQUATIONS.

SVARI

PROD = 7, 7, 4, 2, 0, 0, 0, 0, 0,

SEND

DO YOU WISH TO HAVE 2-D RELIABILITY PLOTS?
INPUT A 1 IN THE COLUMN SPECIFIED BELOW IF YOU WISH
THE CORRESPONDING PLOT OPTION. OTHERWISE INPUT 0.
NOTE: WHEN PERFORMING PRODUCT OF RELIABILITIES, NO OTHER
PLOT OPTION BESESIDES PRODUCT OF RELIABILITIES MAY BE SPECIFIED.

COLUMN 1 = PLOTS PRODUCT OF RELIABILITIES

COLUMN 2 = PLOTS RELIABILITY

COLUMN 3 = PLOTS DIFF, RIF, AND GAIN

COLUMN 4 = PLOTS MTF AND RELIABILITY AT MTF

COLUMN 5 = PLOTS UNRELIABILITY

10000

FOR ABSISSA, INPUT 1 IN COLUMN 1 IF ABSISSA IS 10,
1 IN COLUMN 2 IF ABSISSA IS LOG(T) = BASE 10,
1 IN COLUMN 3 IF ABSISSA IS LANT,
1 IN COLUMN 4 IF ABSISSA IS LOG(LAMT) = BASE 10,
1 IN COLUMN 5 IF ABSISSA IS EXP(-LAMBDA(T)),
1 IN COLUMN 6 IF ABSISSA IS LOG(EXP(-LANT)) = BASE 10,
00000

DO YOU WISH TO HAVE PRINTED TABLE OF RELIABILITY RESULTS
DO YOU WISH TO HAVE PRINTED TABLE OF DIFF, RIF,
AND GAIN RESULTS
DO YOU WISH MTF AND RELIABILITY AT MTF RESULTS PRINTED
DO YOU WANT PRINTED RESULTS OF THE MAXIMUM MISSION
TIME CALCULATIONS

OUTPUT1 =
OUTPUT2 =
OUTPUT4 =
OUTPUT5 =

FIGURE 6-7 (Cont.-3)

DATA BASE FOR RUN-SET

PARA-
METER

SECTION

PARAMETER TO BE VARIED = MU

DUAL MODE SYSTEM PARAMETERS

2 5.0000E+05 5.0000E+05 5.0000E+05 0.

NUMBER OF STAGES	2
CHANNEL FAILURE RATE	.00000010
SYSTEM FAILURE RATE	.00000002
CHANNEL FAILURE COV.	1.00000001
REASSIGNMENT SWITCH	F

FIGURE 6-7 (Cont.-3)

CONFIGURATION IS THAT OF 500's #3 AND #4 WIRED IN SERIES (I.E. BOTH MUST SUCCEED) WITH EXCEPTION THAT THE STANDBY REPLACEMENT SYSTEM (EQ. #2) HAS ONLY 1 REPLICATION (EQ. 1) INSTEAD OF 2.

RUN 1 RELIABILITY RESULTS

FIGURE 6-7 (Cont.-4)

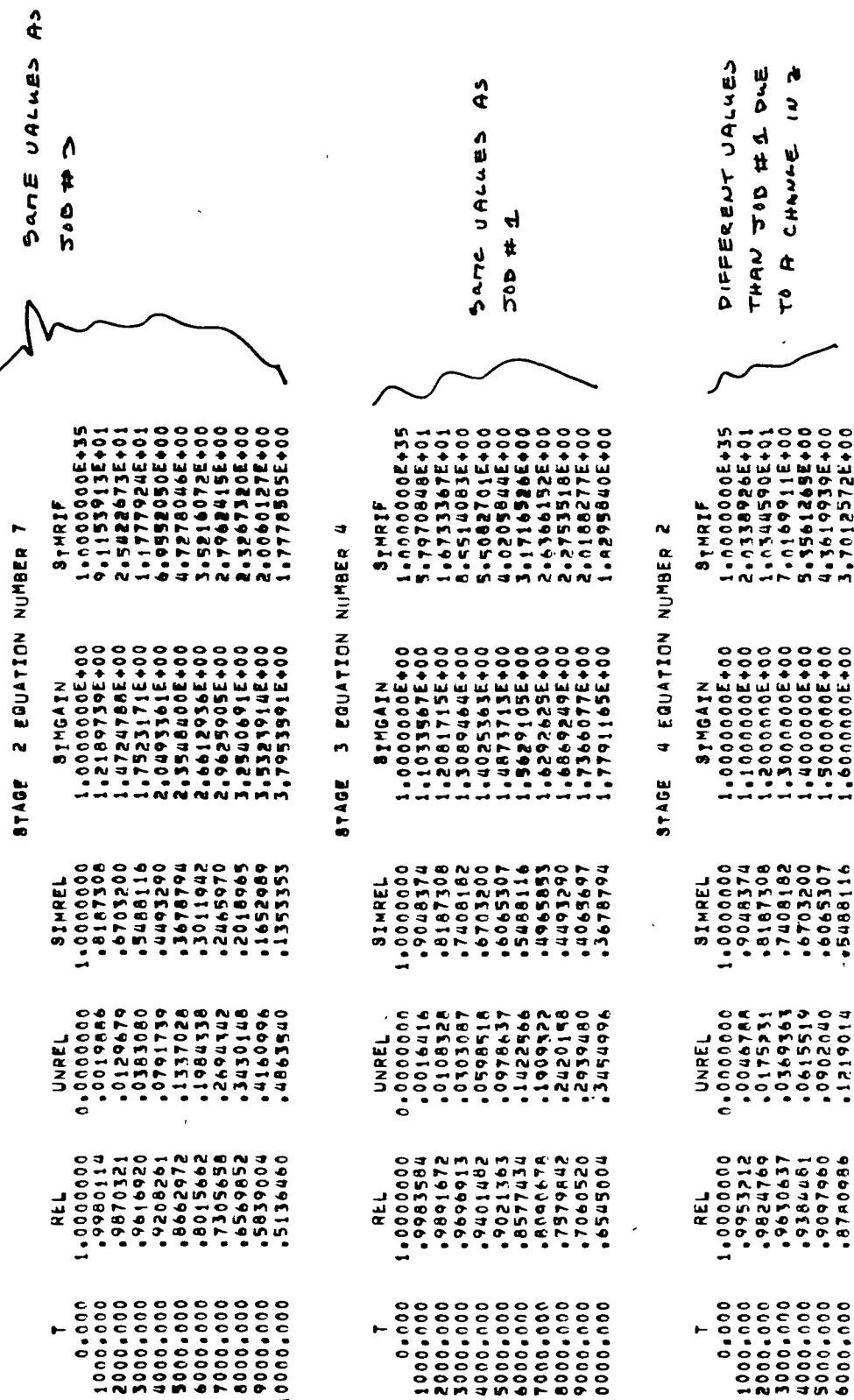
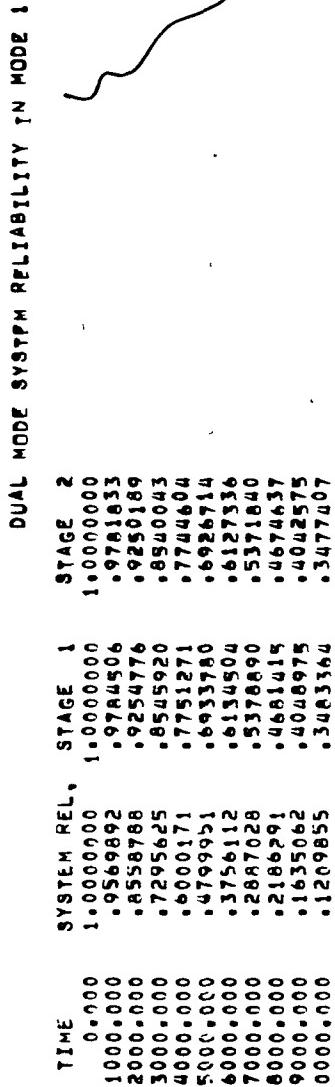
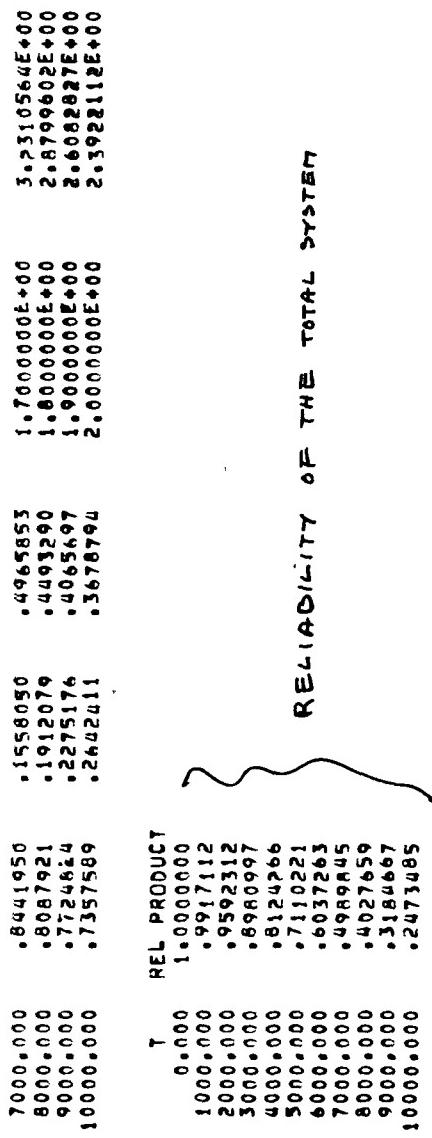


FIGURE 6-7 (Cont.-5)



RUN 2 RELIABILITY RESULTS

FIGURE 6-7 (Cont.-6)

DUAL MODE SYSTEM RELIABILITY IN MODE 1

TIME	SYSTEM REL.	STAGE 1	STAGE 2
0.000	1.0000000	1.0000000	1.0000000
1000.000	.9569892	.978456	.971133
2000.000	.8558788	.9254776	.9250169
3000.000	.7295625	.854592	.8540043
4000.000	.6000171	.7751271	.7744604
5000.000	.4799951	.6933780	.6926714
6000.000	.3756112	.6134504	.6127336
7000.000	.2887028	.5378890	.5371640
8000.000	.2186291	.4681415	.4674637
9000.000	.1635062	.4048975	.4042575
10000.000	.1209855	.3483364	.3477407

STAGE 2 EQUATION NUMBER 7

T	REL	UNREL	SIMREL	SIMGAIN	SIMRIF
0.000	1.0000000	0.0000000	1.0000000	1.0000000E+00	1.0000000E+15
1000.000	.9980114	.0019486	.8187308	.1.2189739E+00	.9.1153911E+01
2000.000	.9870521	.0129679	.6703200	.1.4724788E+00	.2.5422673E+01
3000.000	.9616920	.0343060	.5488116	.1.7523171E+00	.1.1777924E+01
4000.000	.9208261	.0791739	.4493290	.2.0493361E+00	.6.9552050E+00
5000.000	.8662972	.1337028	.3678794	.2.3548400E+00	.4.7278046E+00
6000.000	.8015662	.1984338	.3011942	.2.6612936E+00	.3.5216072E+00
7000.000	.7305658	.2694342	.2465970	.2.9628905E+00	.2.7962415E+00
8000.000	.6569852	.3430148	.2018965	.3.2540691E+00	.3.1267320E+00
9000.000	.5839004	.4160996	.1652989	.3.5323914E+00	.2.0060127E+00
10000.000	.5136460	.4863946	.1533353	.3.7953591E+00	.1.7778305E+00

STAGE 3 EQUATION NUMBER 4

T	REL	UNREL	SIMREL	SIMGAIN	SIMRIF
0.000	1.0000000	0.0000000	1.0000000	1.0000000E+00	1.0000000E+15
1000.000	.9985462	.0014938	.9048374	.1.1035642E+00	.6.5458795E+01
2000.000	.9902986	.0097014	.8187308	.1.2095534E+00	.1.8684824E+01
3000.000	.9725751	.0274249	.7408182	.1.3128390E+00	.9.4359842E+00
4000.000	.9453251	.0546749	.6703200	.1.4102693E+00	.6.029192E+00
5000.000	.9098163	.0901837	.6065307	.1.5000333E+00	.4.1629717E+00
6000.000	.8678538	.1321462	.5488116	.1.5813326E+00	.3.4143109E+00
7000.000	.8213362	.1786658	.4965853	.1.6539681E+00	.2.0176552E+00
8000.000	.7720221	.2279799	.4493290	.1.7181669E+00	.2.4154544E+00
9000.000	.7214221	.3292342	.406597	.1.7744120E+00	.2.1102112E+00
10000.000	.6707658	.3678794	.3678794	.1.8233303E+00	.1.9199724E+00

STAGE 4 EQUATION NUMBER 2

T	REL	UNREL	SIMREL	SIMGAIN	SIMRIF
0.000	1.0000000	0.0000000	1.0000000	1.0000000E+00	1.0000000E+15
1000.000	.9957212	.0046788	.9048374	.1.1000000E+00	.2.0338926E+01
2000.000	.9824769	.0175231	.8187308	.1.2000000E+00	.1.0344590E+01
3000.000	.9630637	.0169363	.7408182	.1.3000000E+00	.7.0169911E+00
4000.000	.9484481	.0165519	.6703200	.1.4000000E+00	.5.3561265E+00
5000.000	.9097960	.0902040	.6065307	.1.5000000E+00	.4.3619939E+00

FIGURE 6-7 (Cont.-7)

T	REL PRODUCT
6000.000	.8780986
7000.000	.8441950
8000.000	.8087921
9000.000	.7724824
10000.000	.7357589
1219014	.5488116
1558050	.4965853
1912079	.4493290
2275174	.4065697
2642411	.3678794
1219014	.5488116
1558050	.4965853
1912079	.4493290
2275174	.4065697
2642411	.3678794
1600000E+00	3.7012572E+00
1700000E+00	3.2310564E+00
1800000E+00	2.8799602E+00
1900000E+00	2.6062827E+00
2000000E+00	2.3922112E+00

RUN 3 RELIABILITY RESULTS

FIGURE 6-7 (Cont.-8)

DUAL MODE SYSTEM RELIABILITY IN MODE 1

TIME	SYSTEM REL.	STAGE 1	STAGE 2
0.000	1.0000000	1.0000000	1.0000000
1000.000	.9569892	.9784506	.9791833
2000.000	.8558708	.9254776	.9280189
3000.000	.7295625	.8545920	.8540043
4000.000	.6000171	.7751271	.7744604
5000.000	.4799951	.6933780	.6926714
6000.000	.3756112	.6134504	.6127336
7000.000	.2887028	.5371840	.5371840
8000.000	.2186291	.4681415	.4674637
9000.000	.1635062	.4048975	.4042575
10000.000	.1209855	.34833364	.3477407

STAGE 2 EQUATION NUMBER 7

T	REL	UNREL	SIMREL	SIMGAIN	SIMRIF
0.000	1.0000000	0.0000000	1.0000000	1.0000000E+00	1.0000000E+35
1000.000	.9980114	.0019886	.8187308	.1218919E+00	.91153913E+01
2000.000	.9870321	.0129679	.6703200	.472488E+00	.25422673E+01
3000.000	.9616920	.0383080	.5488116	.752371E+00	.11777924E+01
4000.000	.9208261	.0791739	.4493290	.049361E+00	.6952030E+00
5000.000	.8662972	.1337028	.3678794	.354840E+00	.47278046E+00
6000.000	.8015662	.1984338	.3011942	.661293E+00	.35216072E+00
7000.000	.7305658	.2694342	.2465970	.962593E+00	.27962415E+00
8000.000	.6569852	.3430148	.2018965	.2540691E+00	.23267320E+00
9000.000	.5839004	.4160996	.1652989	.532914E+00	.20060127E+00
10000.000	.5136460	.4863740	.1353353	.795359E+00	.17778505E+00

STAGE 3 EQUATION NUMBER 4

T	REL	UNREL	SIMREL	SIMGAIN	SIMRIF
0.000	1.0000000	0.0000000	1.0000000	1.0000000E+00	1.0000000E+35
1000.000	.9987387	.0012613	.9048374	.1037769E+00	.75446916E+01
2000.000	.9914862	.0085138	.8187308	.2110019E+00	.21291123E+01
3000.000	.9756726	.0243274	.7408182	.1317620E+00	.10653893E+01
4000.000	.9510108	.0489892	.6703200	.4187414E+00	.67296472E+00
5000.000	.9143337	.0815663	.6065307	.8142411E+00	.48239183E+00
6000.000	.8794336	.1205664	.5488116	.6024324E+00	.37422388E+00
7000.000	.8356671	.1643329	.4965853	.6828270E+00	.30633844E+00
8000.000	.7887312	.2112688	.4493290	.7553135E+00	.26064946E+00
9000.000	.7400474	.2599526	.4065697	.8202228E+00	.22828406E+00
10000.000	.6908143	.3091457	.3678794	.8778280E+00	.20444690E+00

STAGE 4 EQUATION NUMBER 2

T	REL	UNREL	SIMREL	SIMGAIN	SIMRIF
0.000	1.0000000	0.0000000	1.0000000	1.0000000E+00	1.0000000E+35
1000.000	.9953212	.0046788	.9048374	.1000000E+00	.20338926E+01
2000.000	.9824769	.0175231	.8187308	.2000000E+00	.10344590E+01
3000.000	.9630637	.0369361	.7408182	.3000000E+00	.70169911E+00
4000.000	.9384481	.0615519	.6703200	.4000000E+00	.53561265E+00
5000.000	.9097960	.0902040	.6065307	.5000000E+00	.43619939E+00

	REL PRODUCT
6000.000	•8780986
7000.000	•8441950
8000.000	•8087921
9000.000	•7724824
10000.000	•7357589
6000.000	•1219014
7000.000	•1558050
8000.000	•1912079
9000.000	•2275176
10000.000	•2644241
6000.000	•5488116
7000.000	•4965853
8000.000	•4491290
9000.000	•4065697
10000.000	•3678794

FIGURE 6-7 (Cont.-9)

T	REL PRODUCT
0.000	1.000000
1000.000	•9920889
2000.000	•9614800
3000.000	•9036393
4000.000	•8218135
5000.000	•7238669
6000.000	•6189930
7000.000	•5153894
8000.000	•4191037
9000.000	•3338004
10000.000	•2610723

2

SECTION 7

SUMMARY AND CONCLUSIONS

The mathematical models and computer program described in this report are viewed by the authors as but an early step in the development of adequate, fault tolerant computer, design evaluation aids.

The tool provided is by no means a panacea. For example, the requirement for user determination of individual fault detection, isolation and recovery process characteristics, is viewed as a rather significant drawback. There are others as well.

Nevertheless, we also view it as a major improvement over other available reliability evaluation aids. For example, the provision for two distinct operating modes contrasts favorably with the single mode approximations typically encountered. Similarly, the inclusion of a means for calculating multiple coverage factors, conditioned on failure type and location, operating mode, and spares status, goes far beyond the more usual mathematical reliability model.

In addition, the generality of the model enables its use on a wide variety of system configurations, and variations therein. These include TMR, TMR with spares switching, hybrid, and a majority of others as well.

There remains much to be done, however, prior to the transformation of fault tolerant computer design from that of a rather mystical art, to that of a science. Most noteworthy, perhaps, is the task of gathering adequate failure rate statistics within integrated circuit chips, and also the task of establishing and implementing measurement criteria for individual fault detection, isolation and recovery processes. Hopefully, these will prove to be forthcoming from other endeavors.

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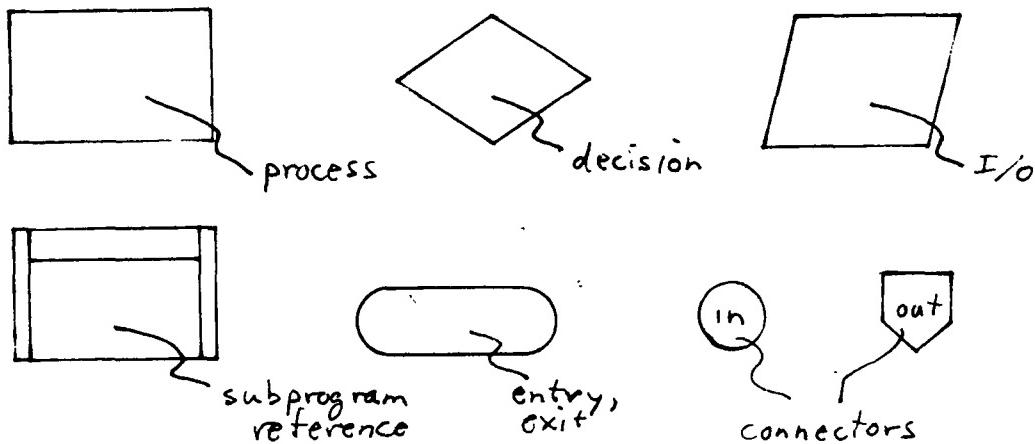
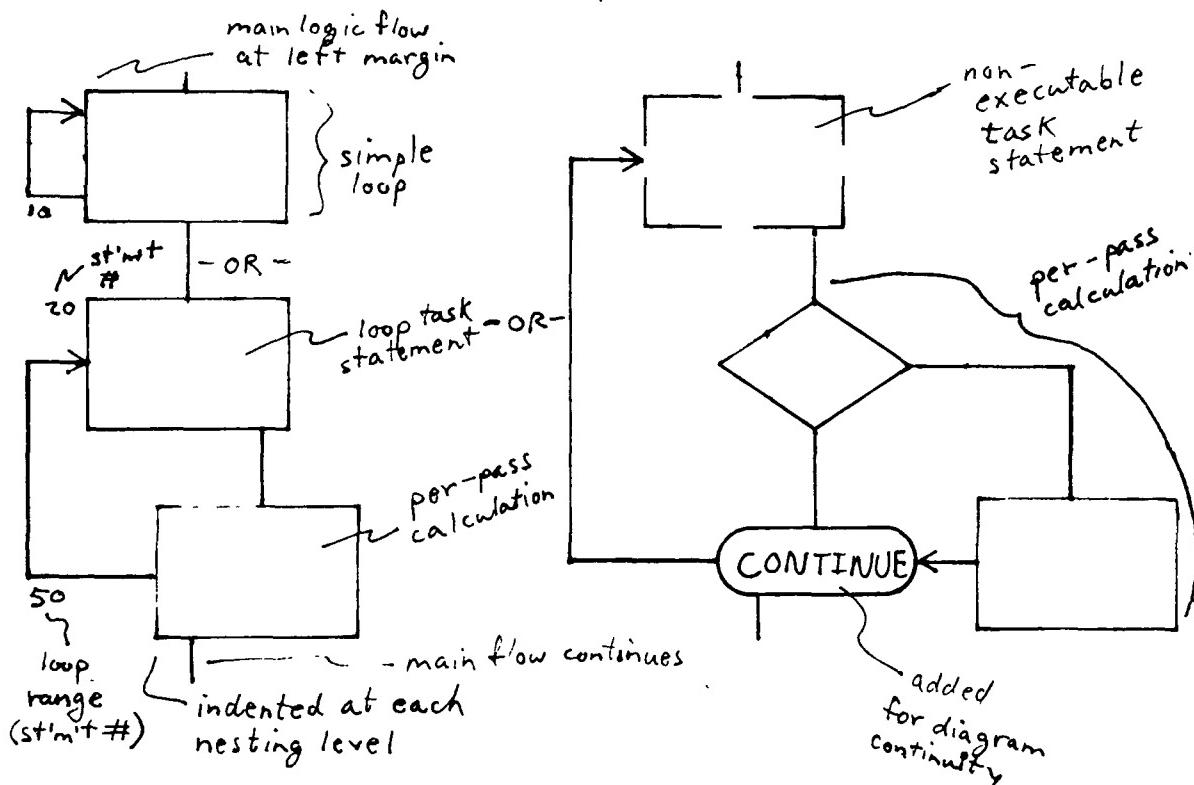


APPENDIX A

FLOW DIAGRAMS

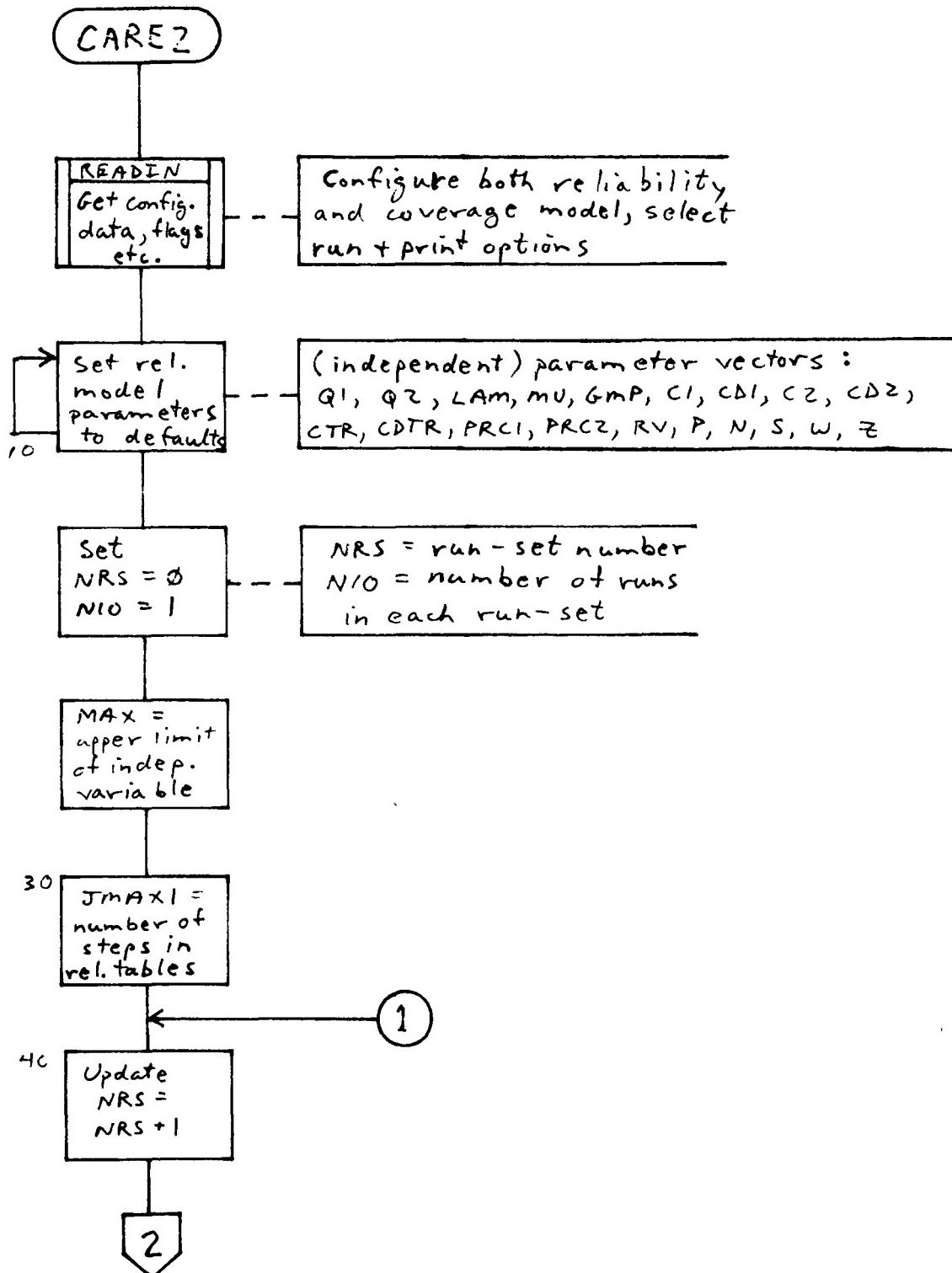
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A-0

FLOW DIAGRAM CONVENTIONSiterative procedures

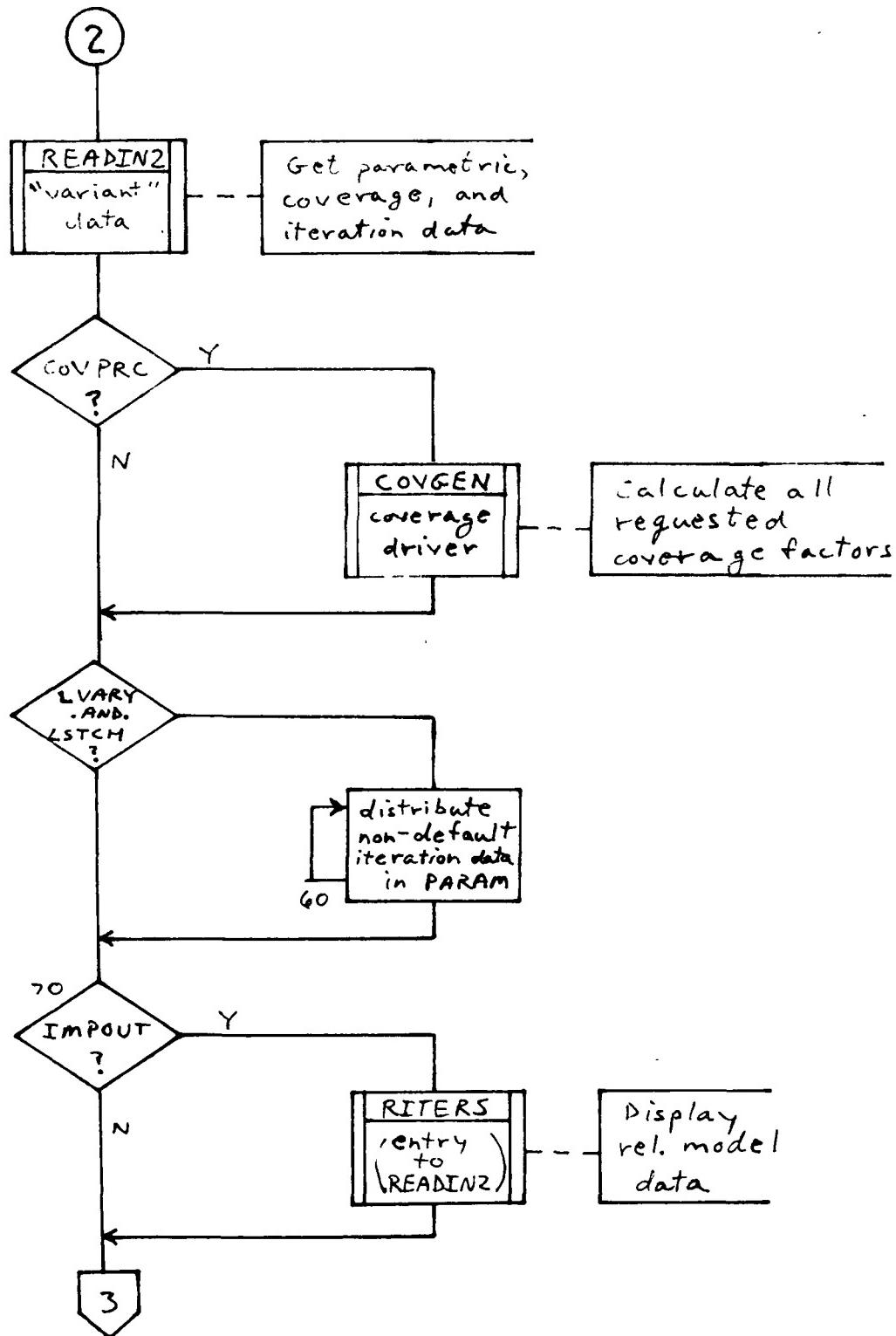
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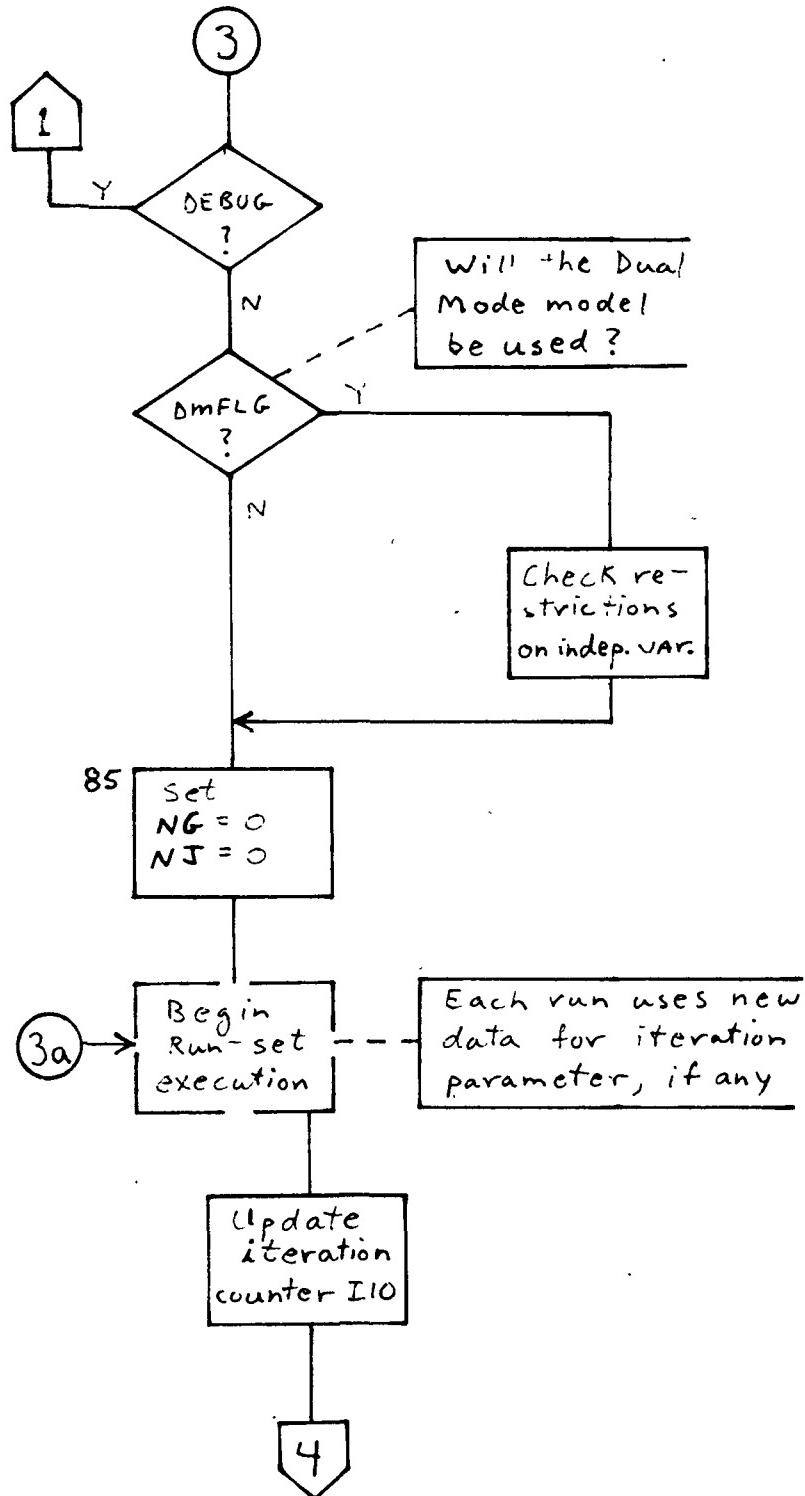
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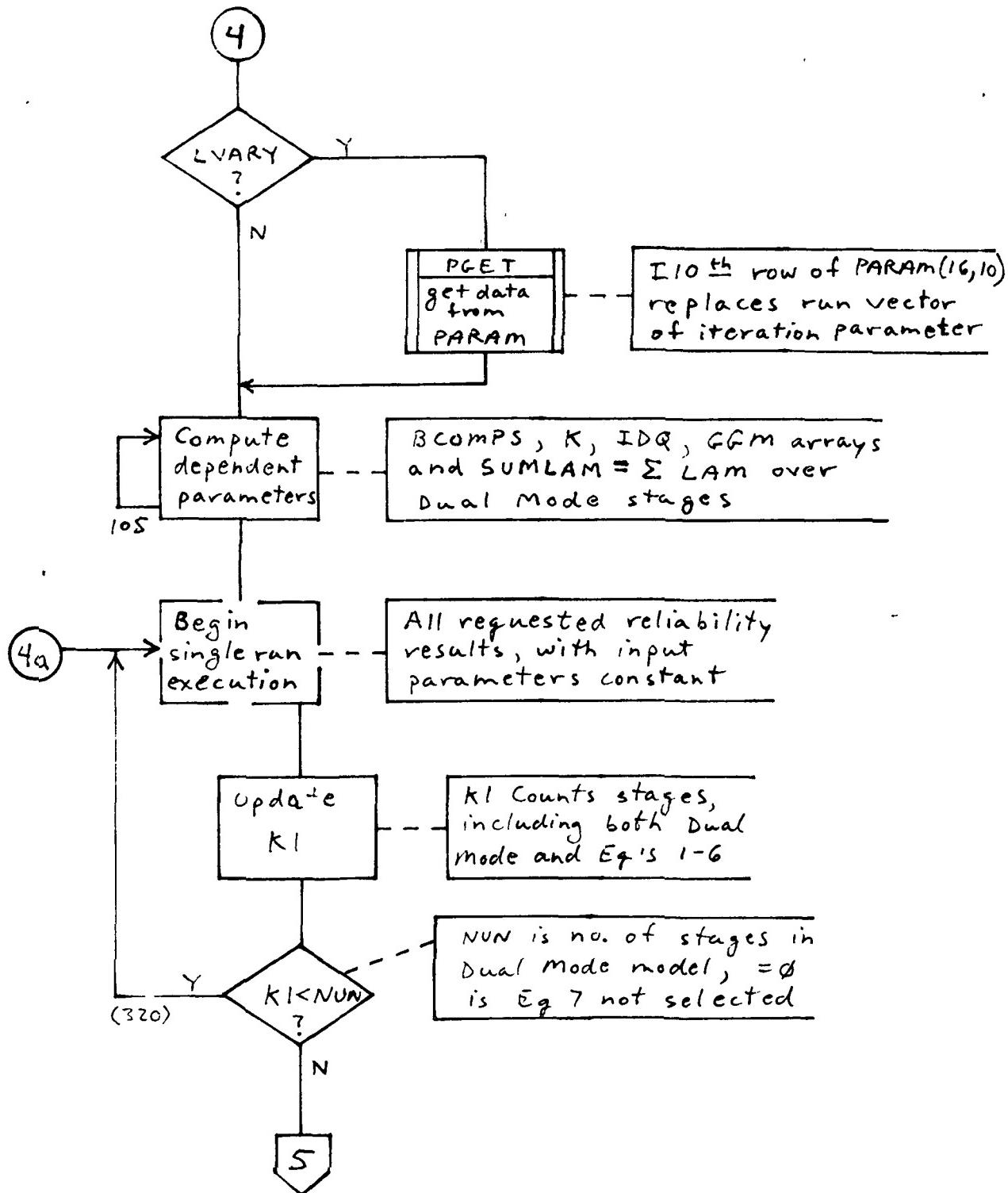
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A-1



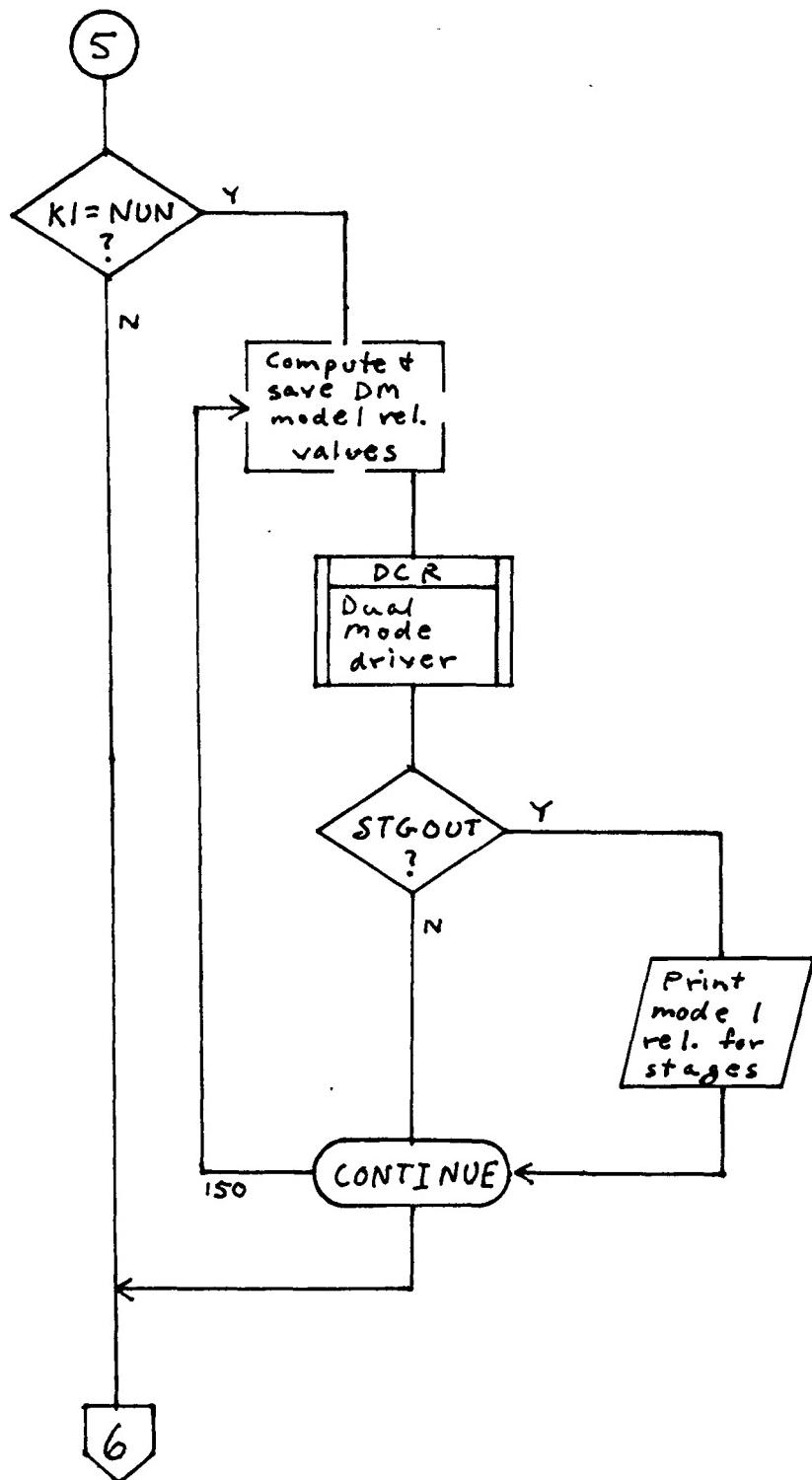
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A-1



FLOW DIAGRAM

A-1



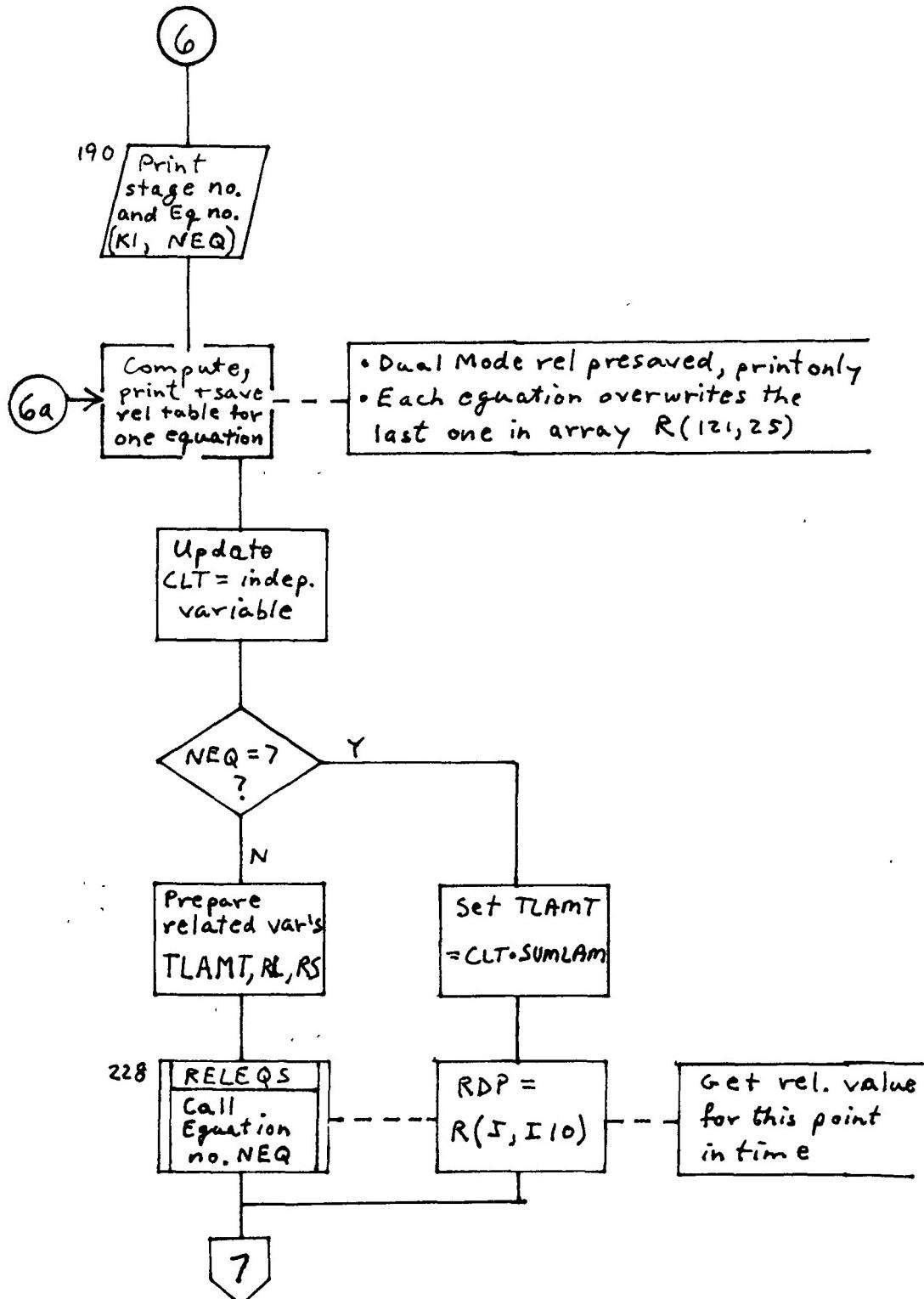
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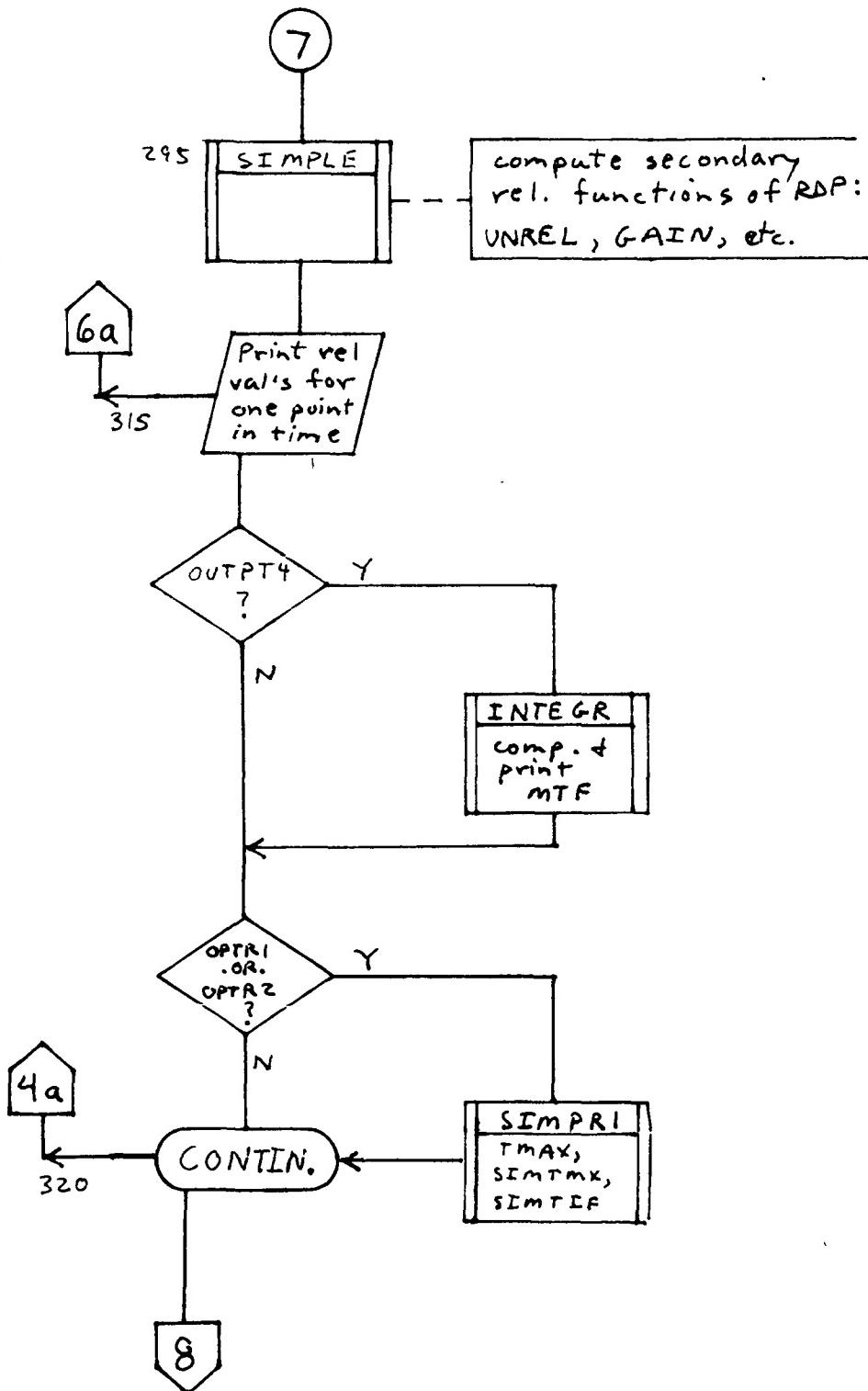
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A-1



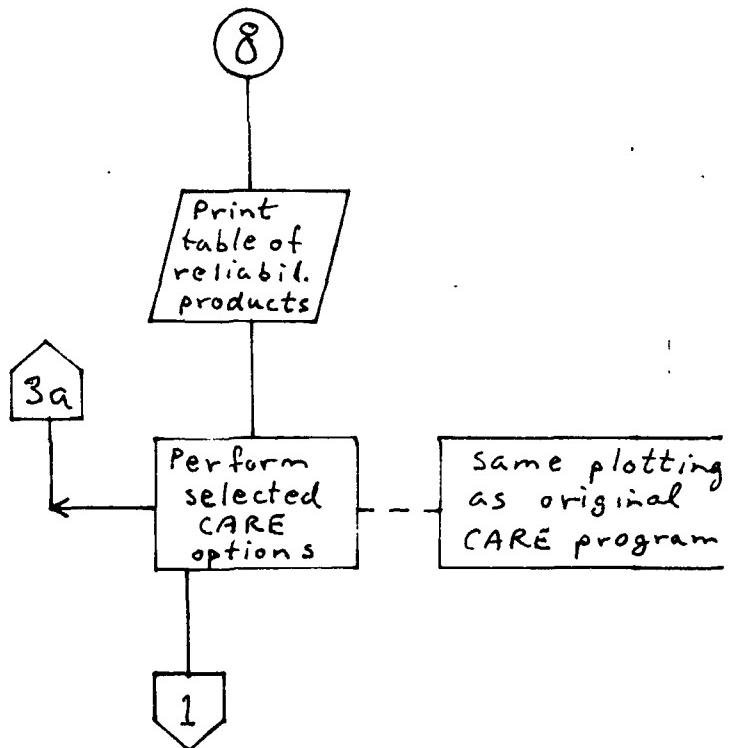
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A-1



FLOW DIAGRAM

A-1



FLOW DIAGRAM

A-2

NEQ1A

The original subroutine was corrected
as follows:

original lines

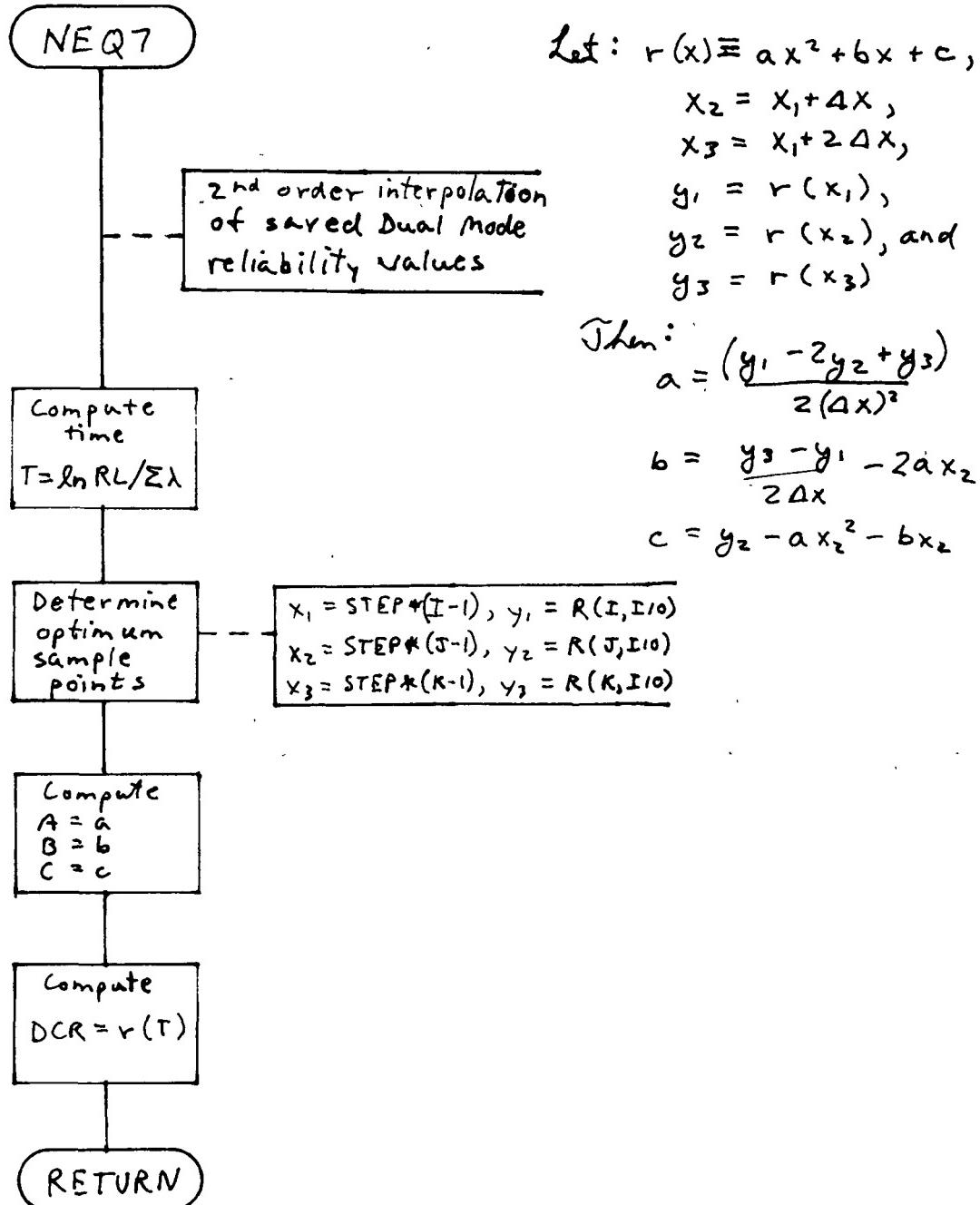
```
DO 70 LX=1,II  
L = LX - 1  
SUM1 = 0.0  
SUM2 = 0.0  
|  
|  
|  
60 SUM2 = ~~  
70 SUM1 = ~~
```

modified lines

```
SUM1 = 0.0  
DO 70 LX=1,II  
L = LX - 1  
SUM2 = 0.0  
|  
|  
|  
60 SUM2 = ~~  
70 SUM1 = ~~
```

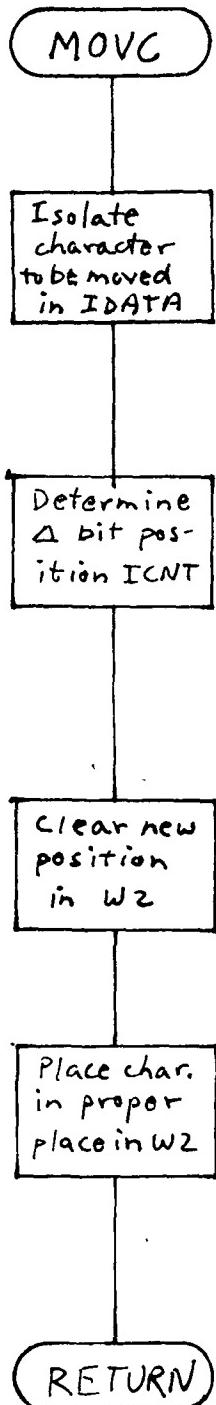
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A-3



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A-4

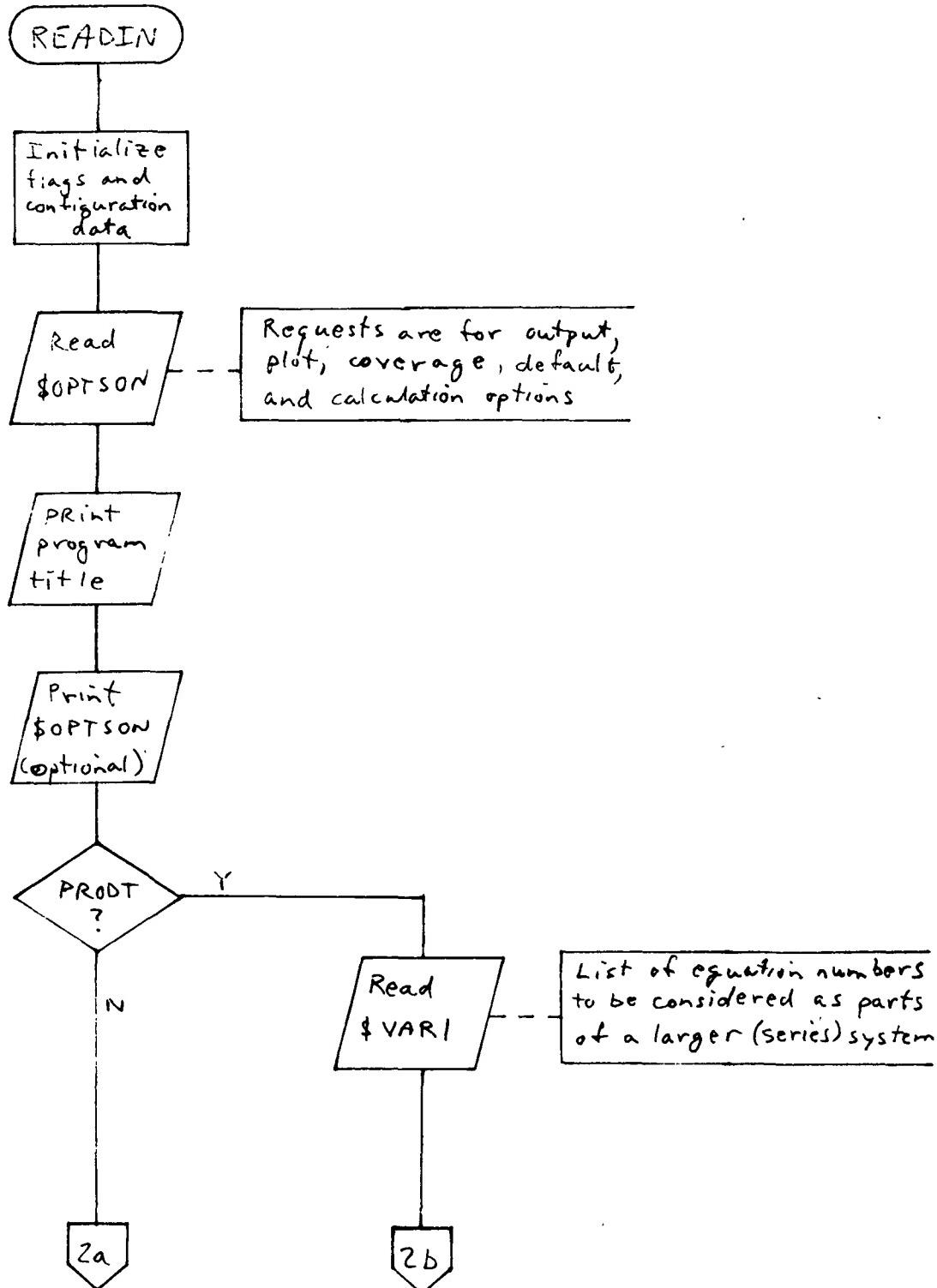


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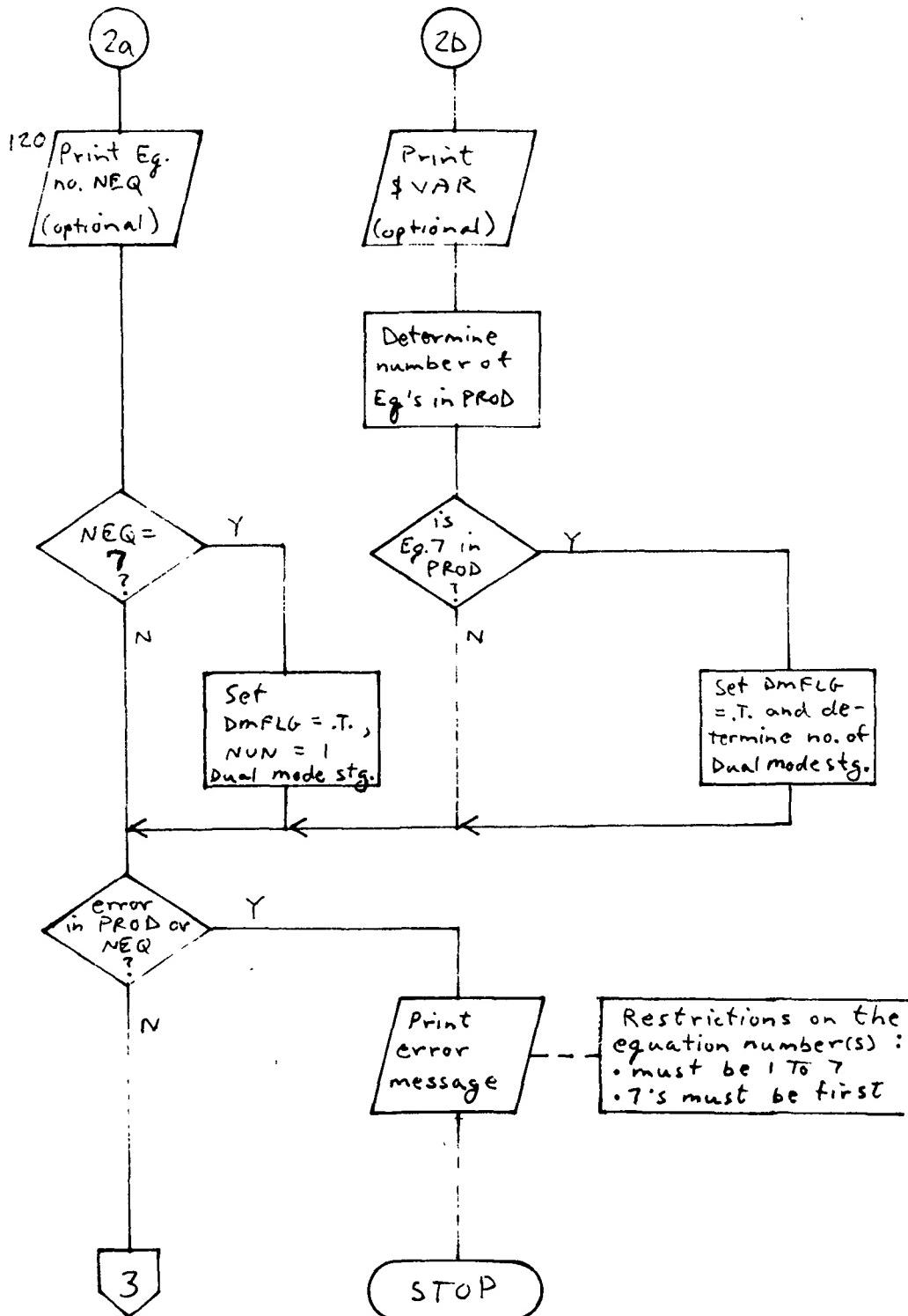
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A-5



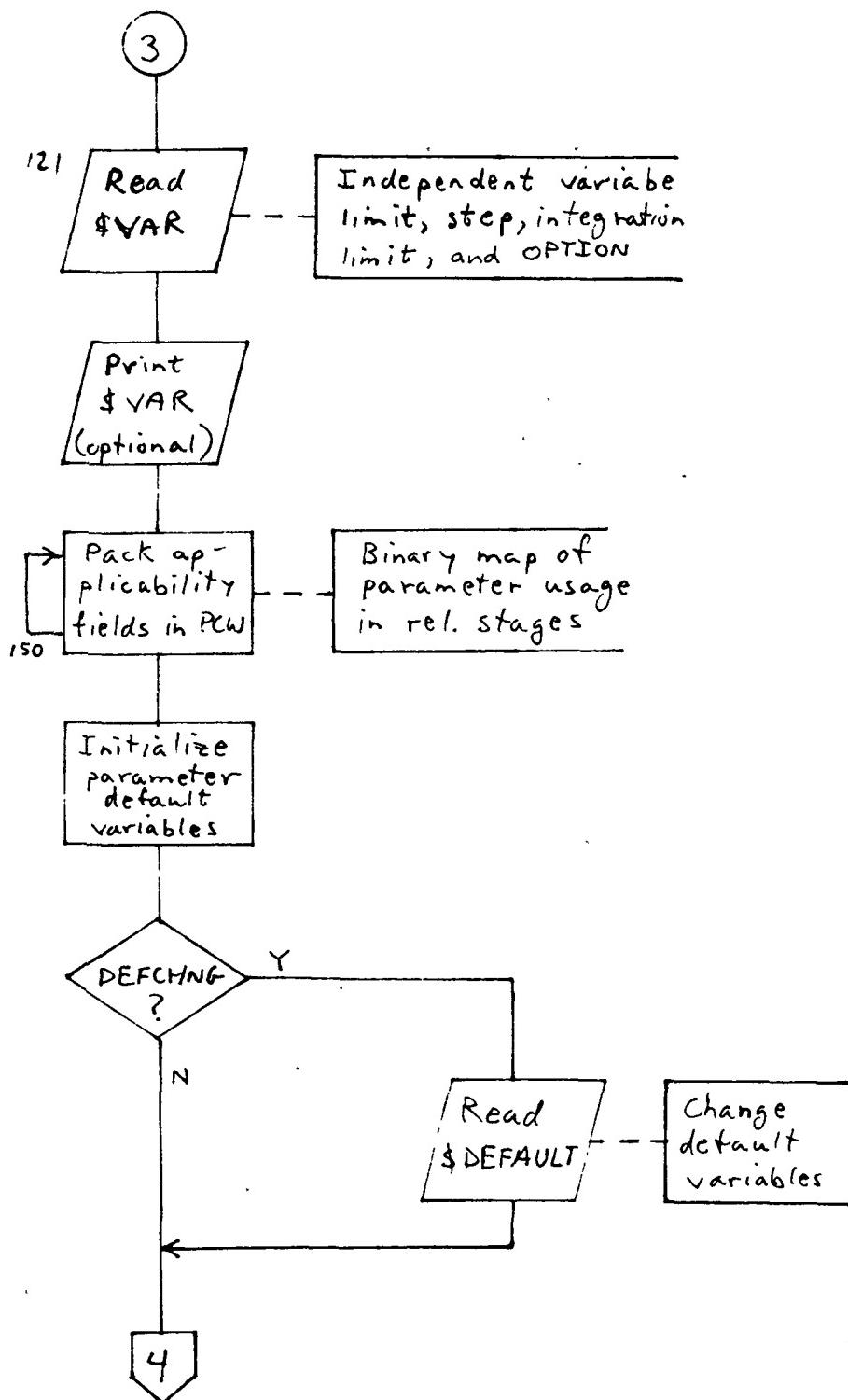
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A-5



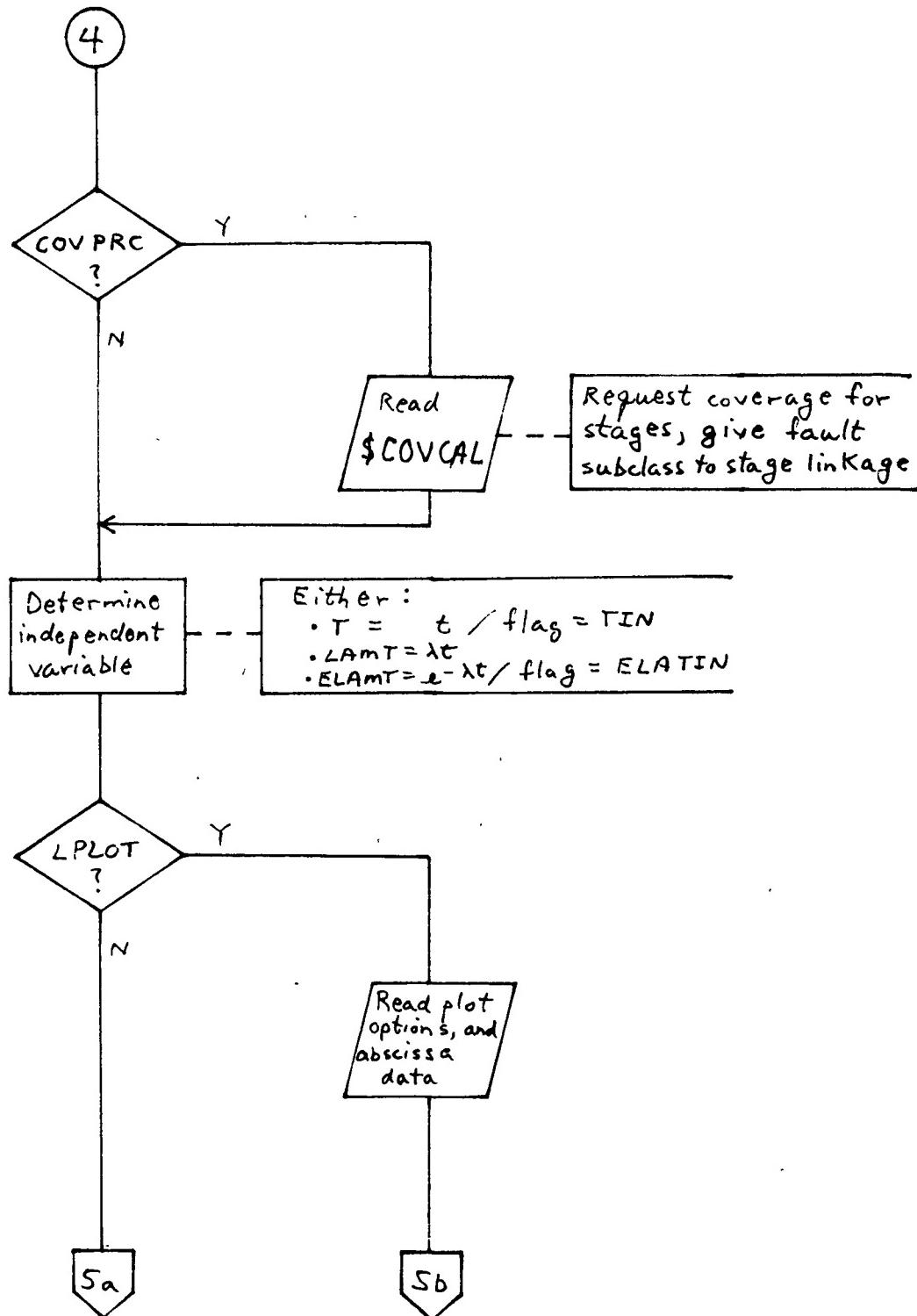
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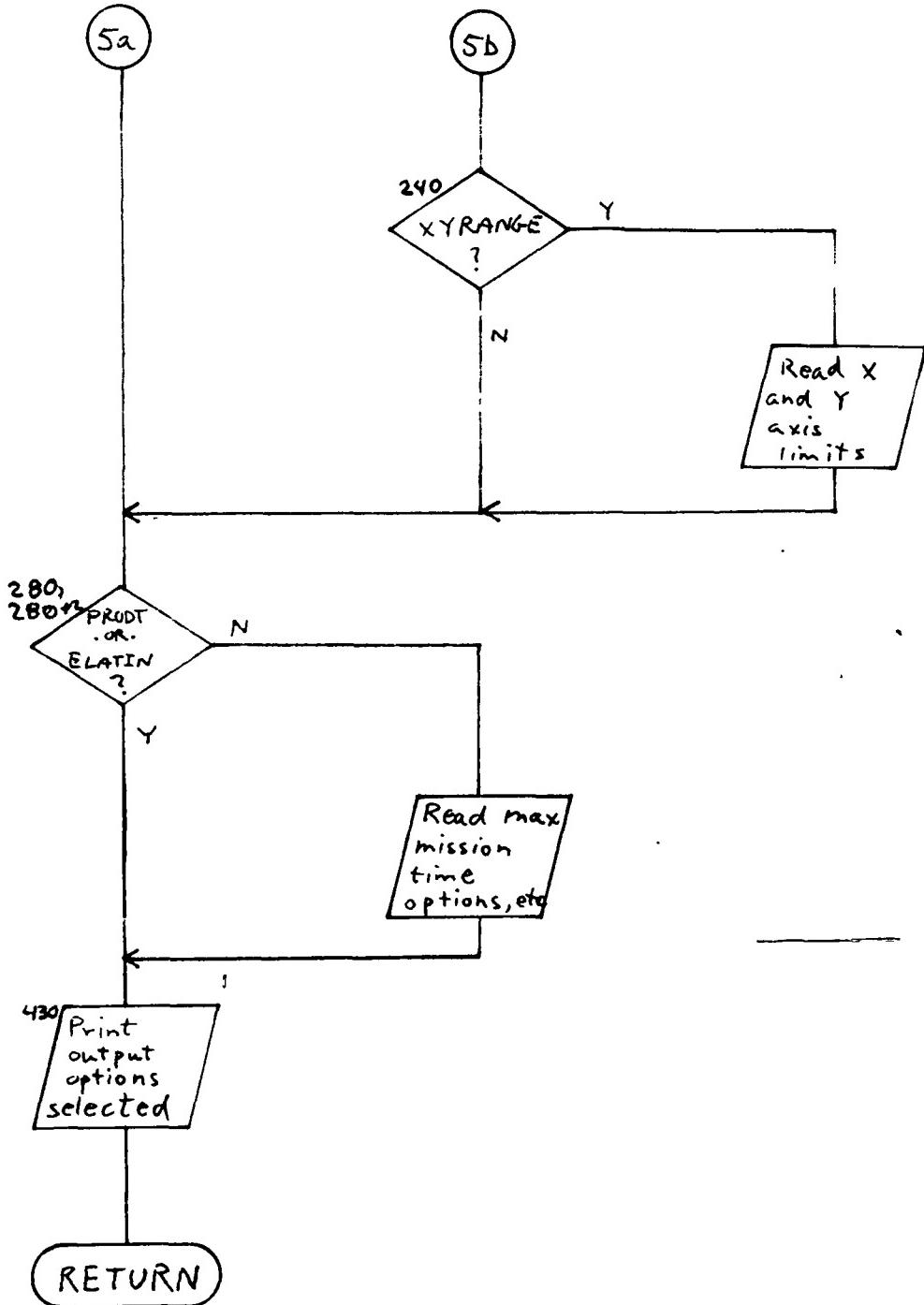
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A-5



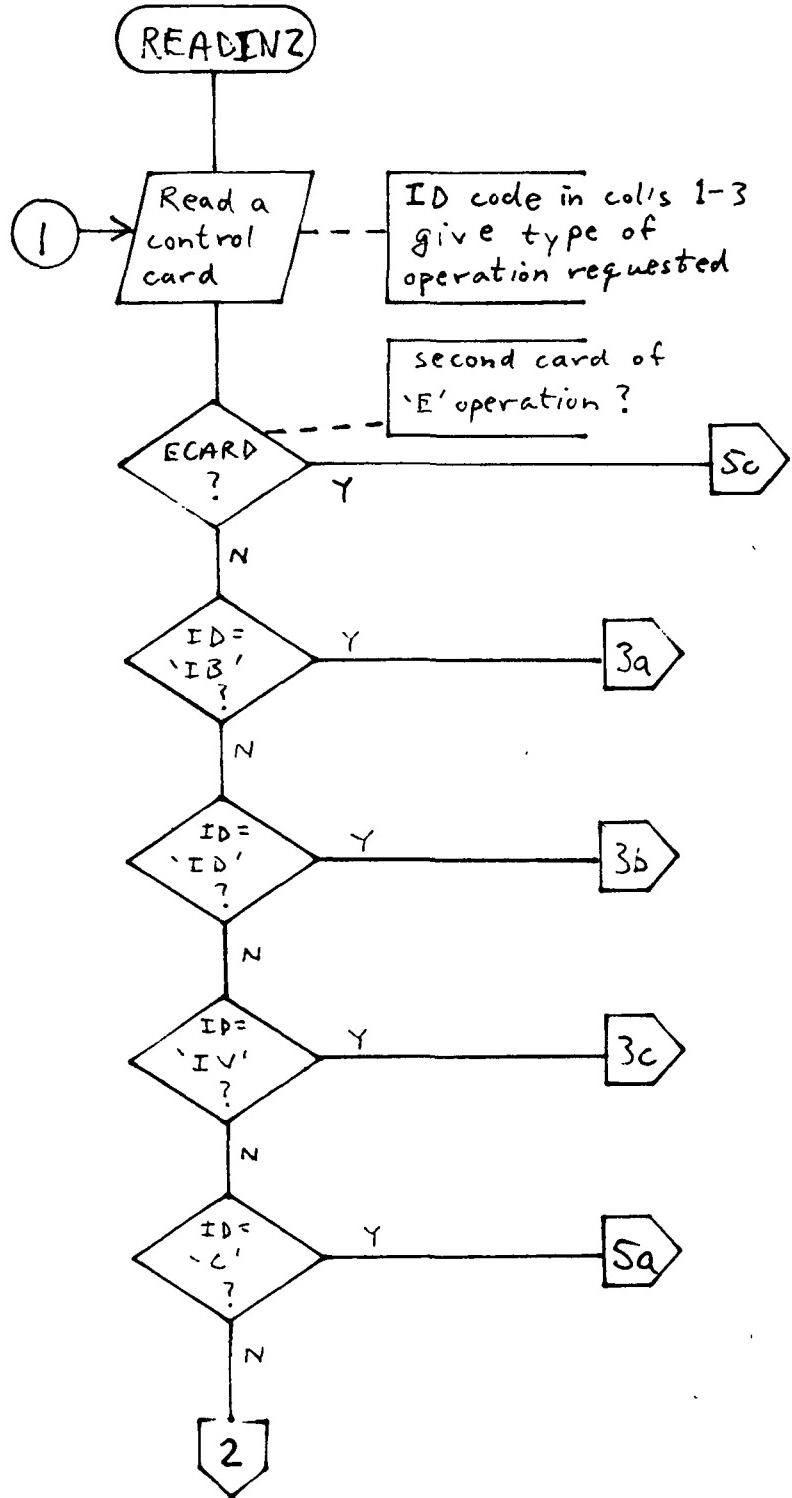
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A-5



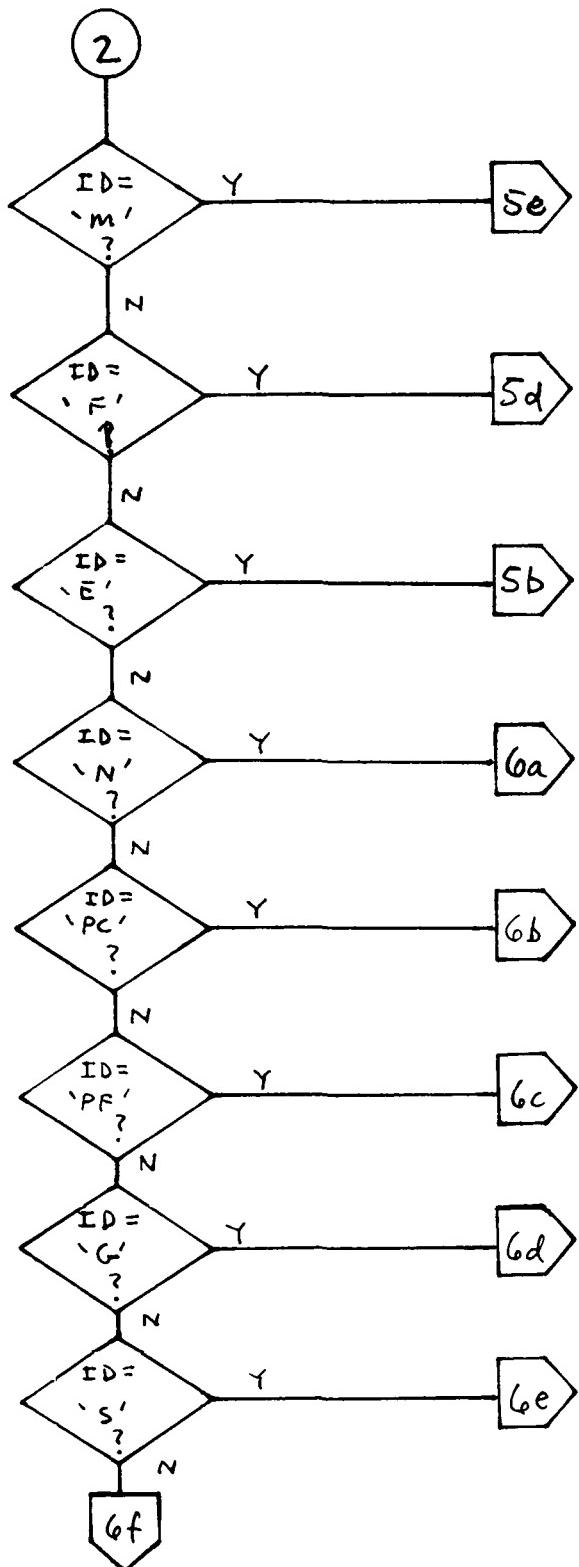
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A-6

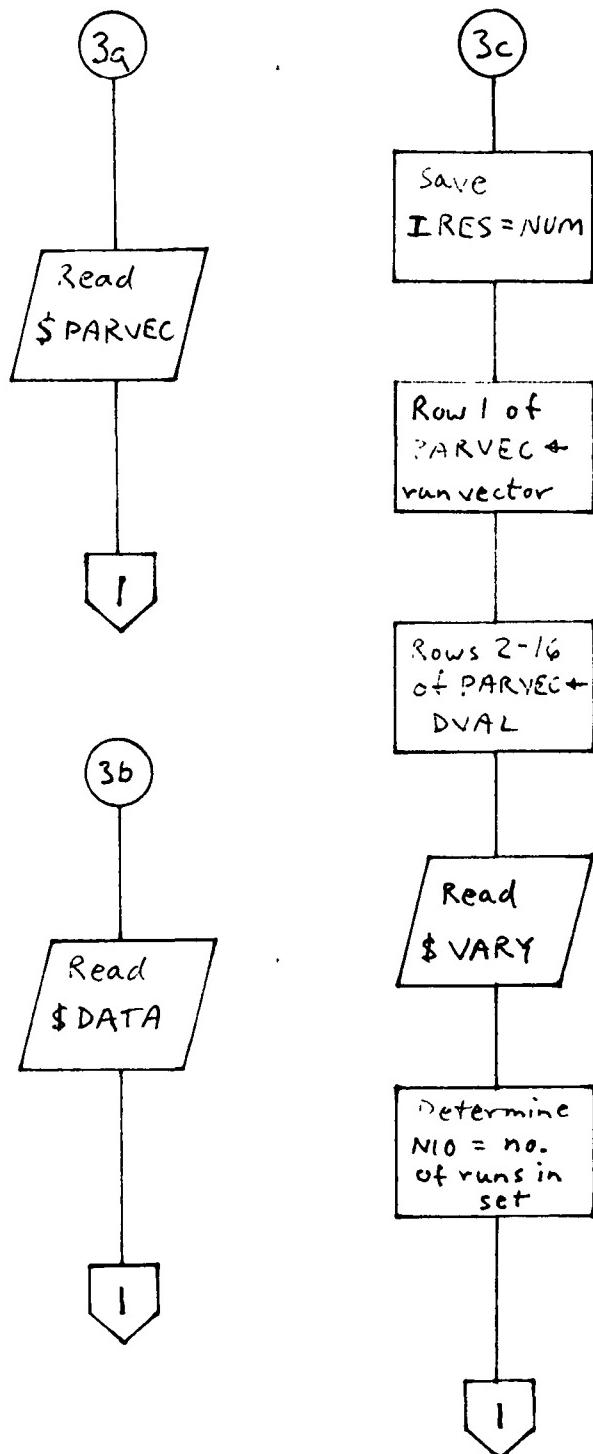


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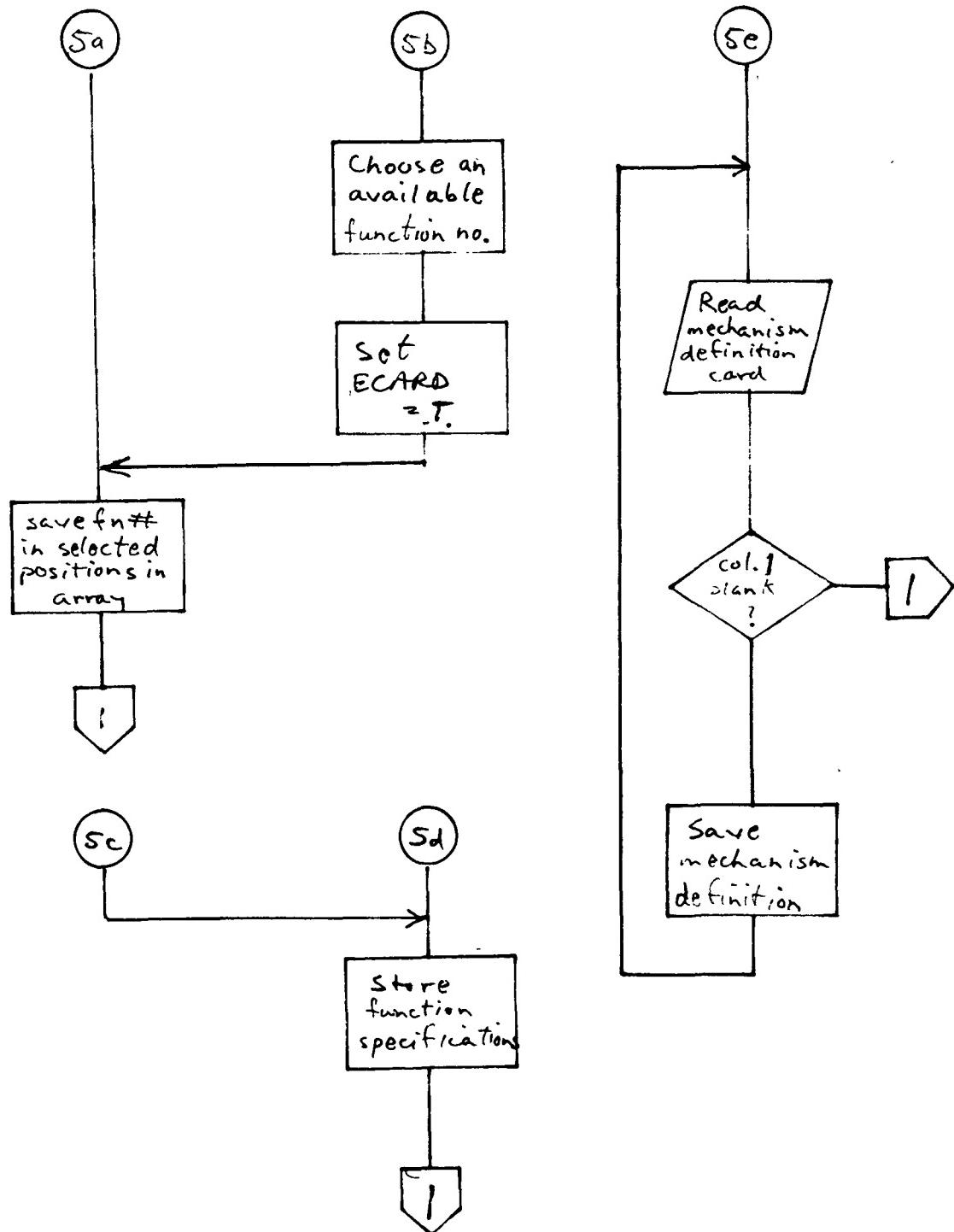


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A-6



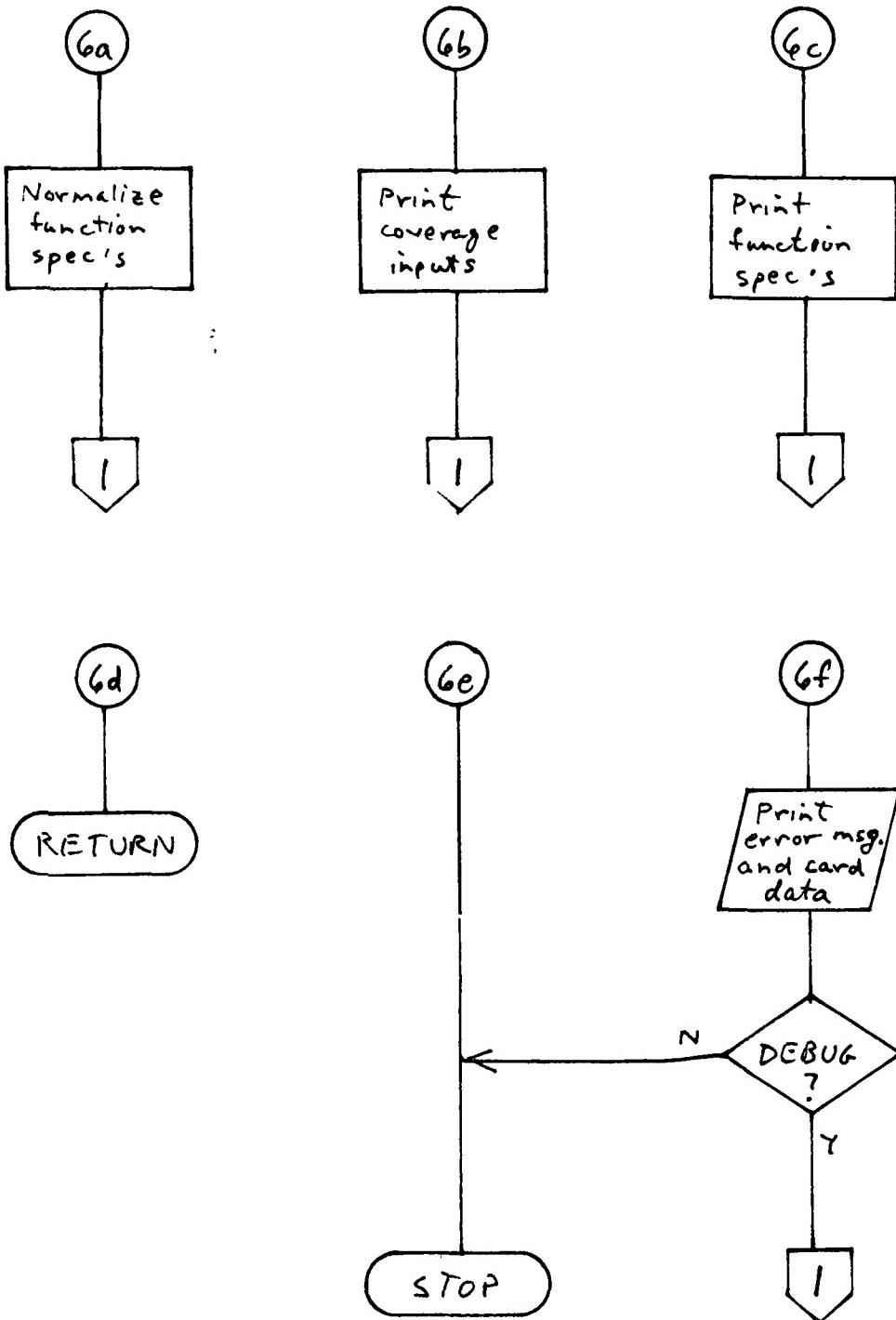
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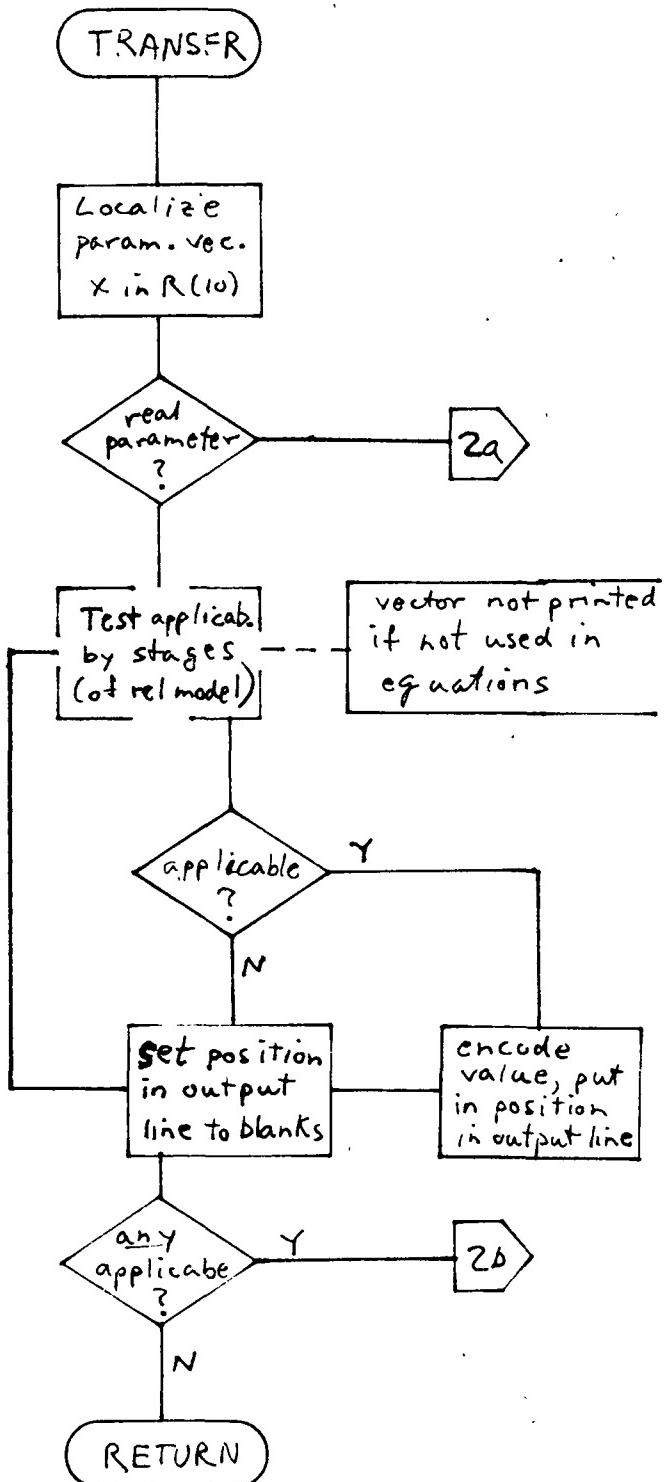
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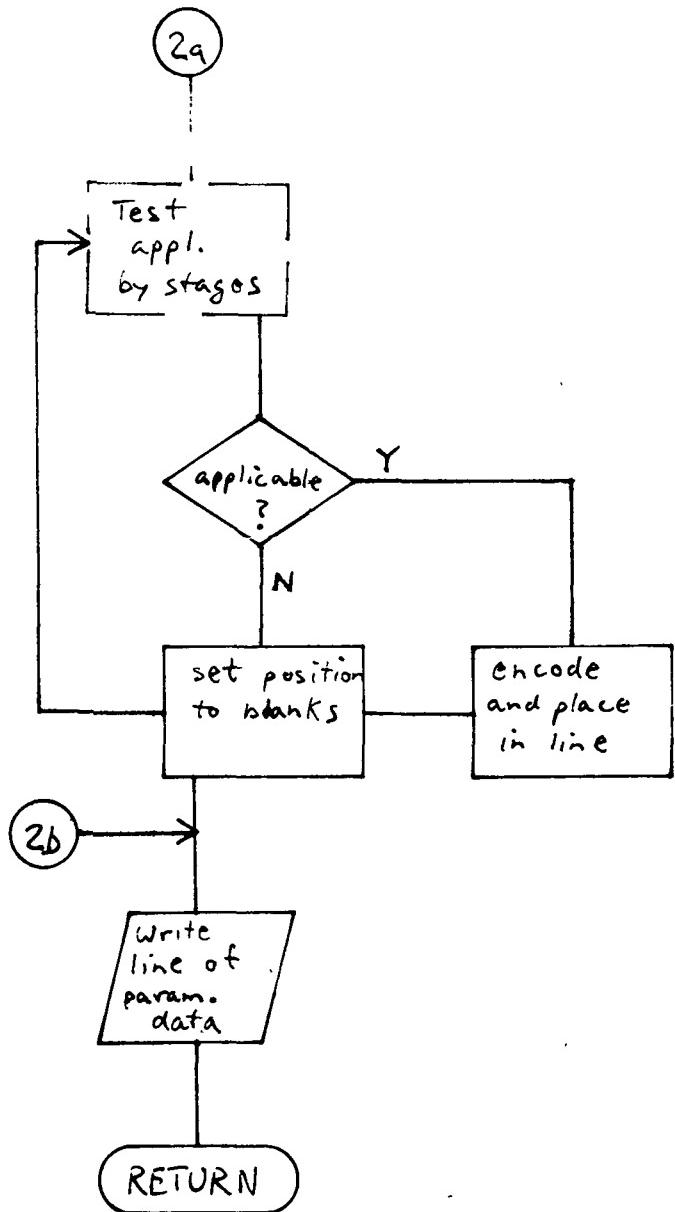
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A-7



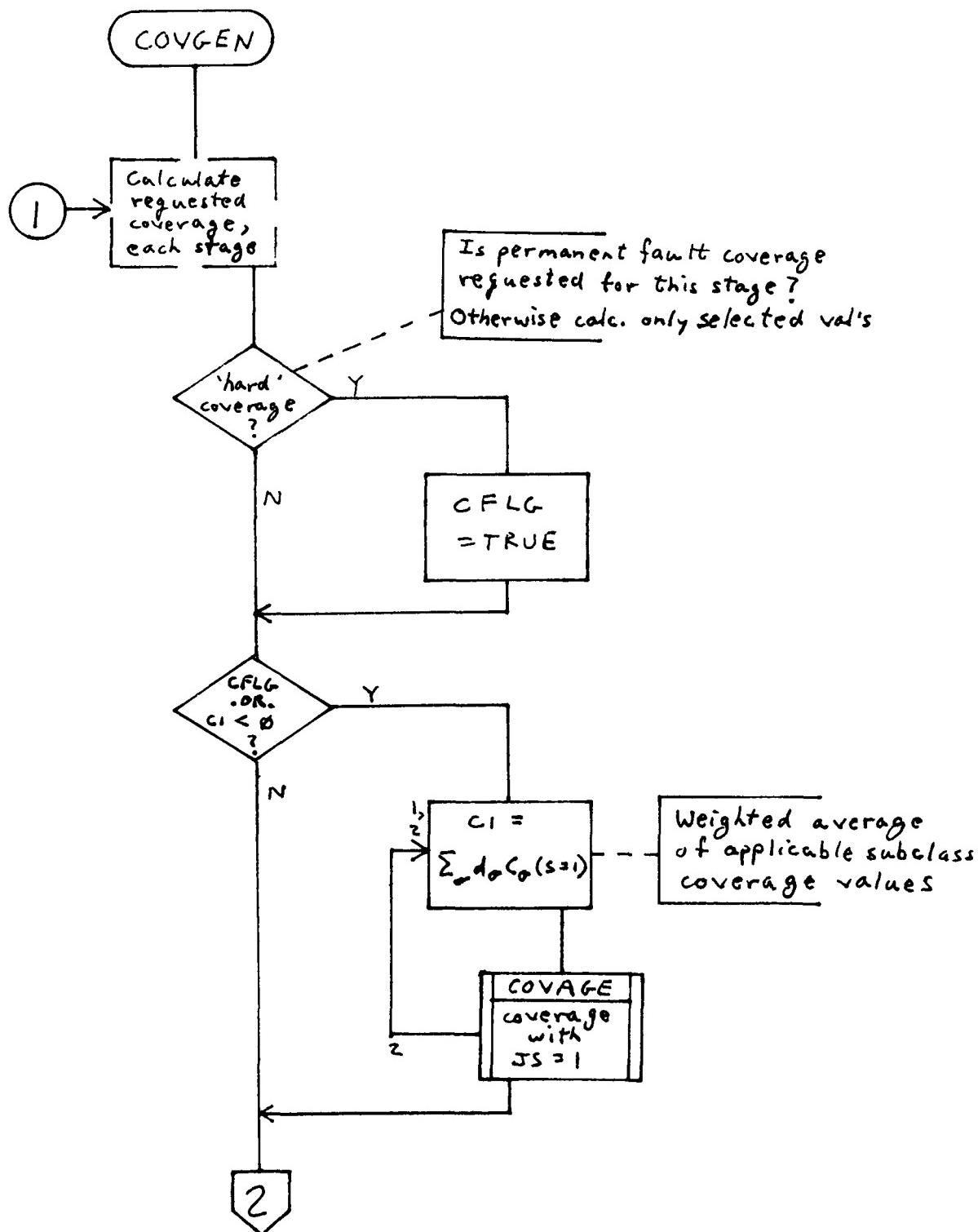
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A-7



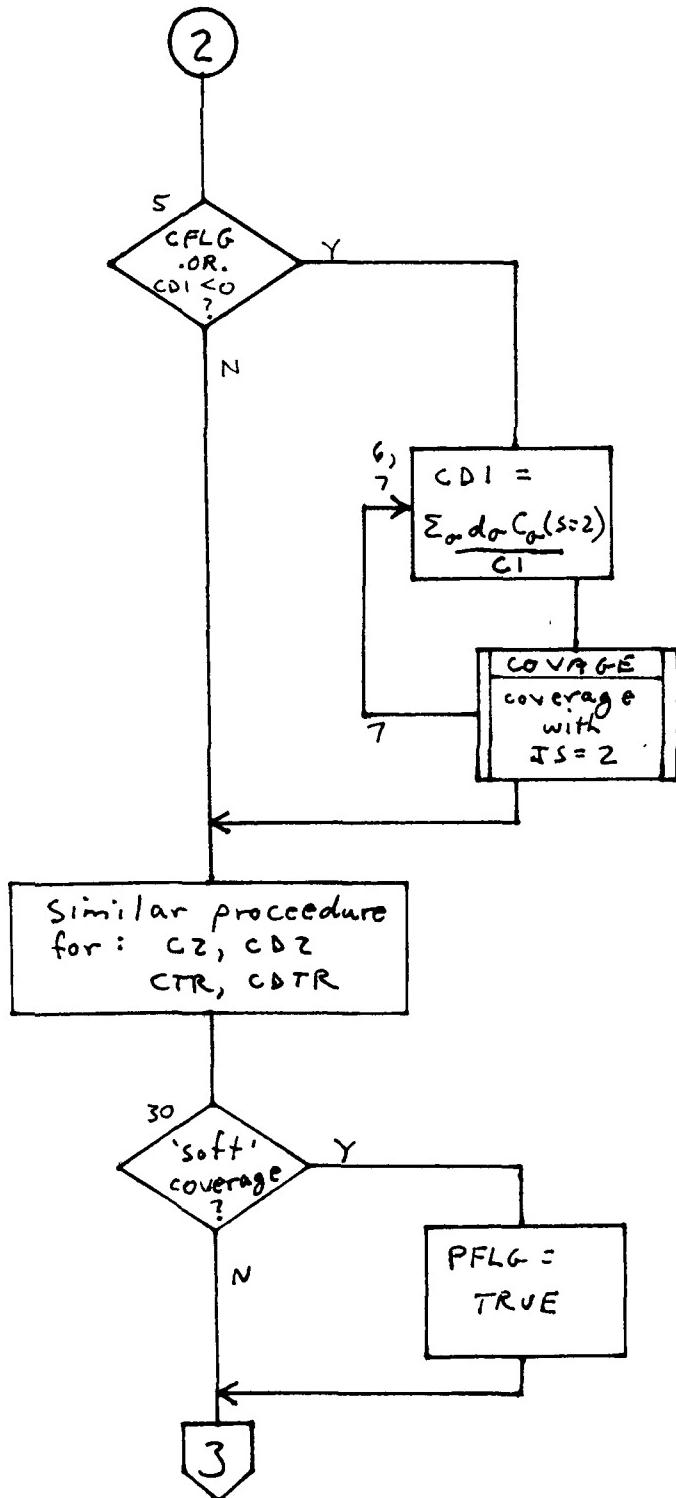
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A-8



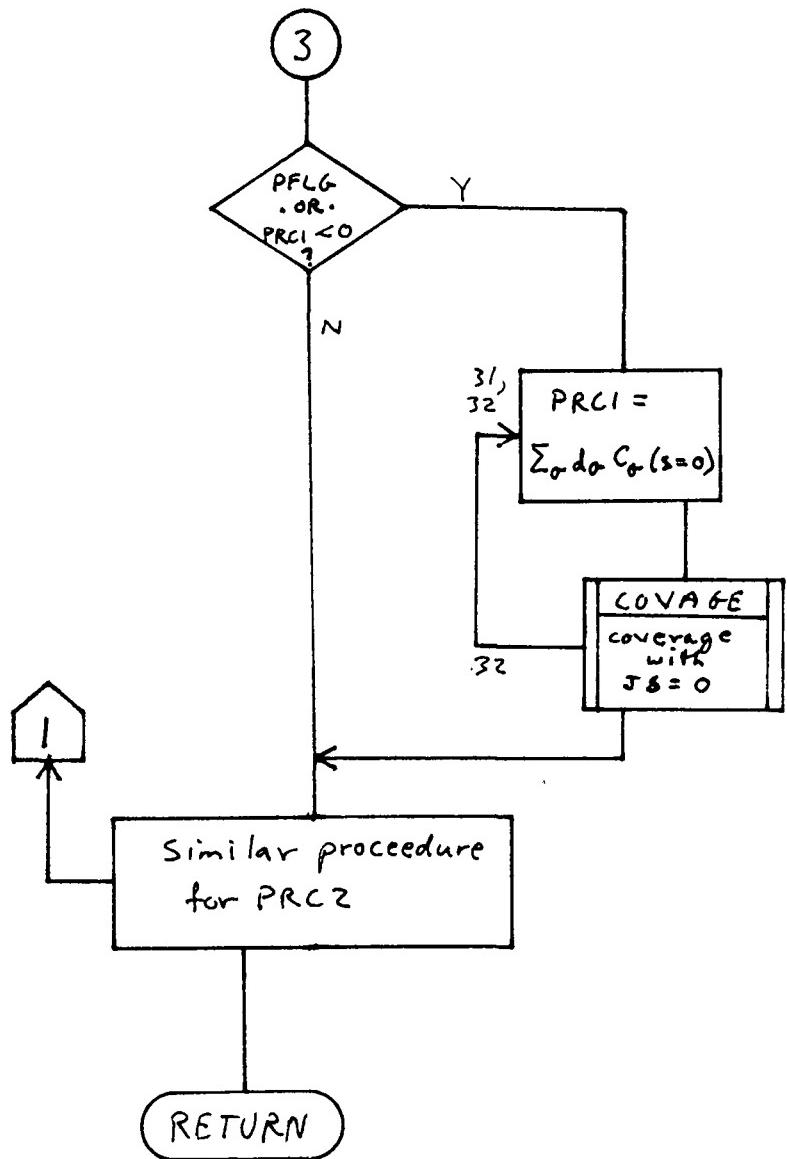
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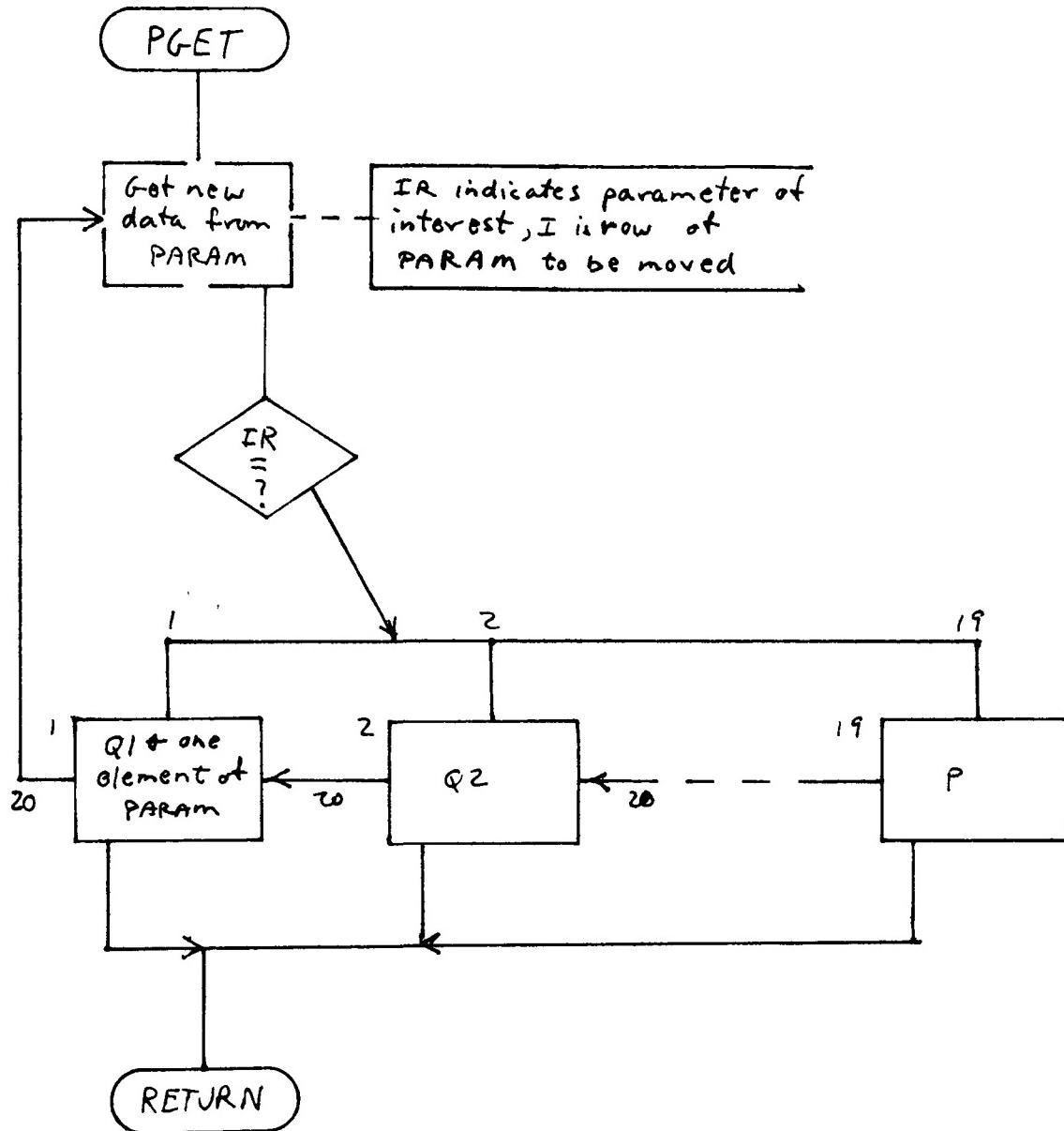
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A-8



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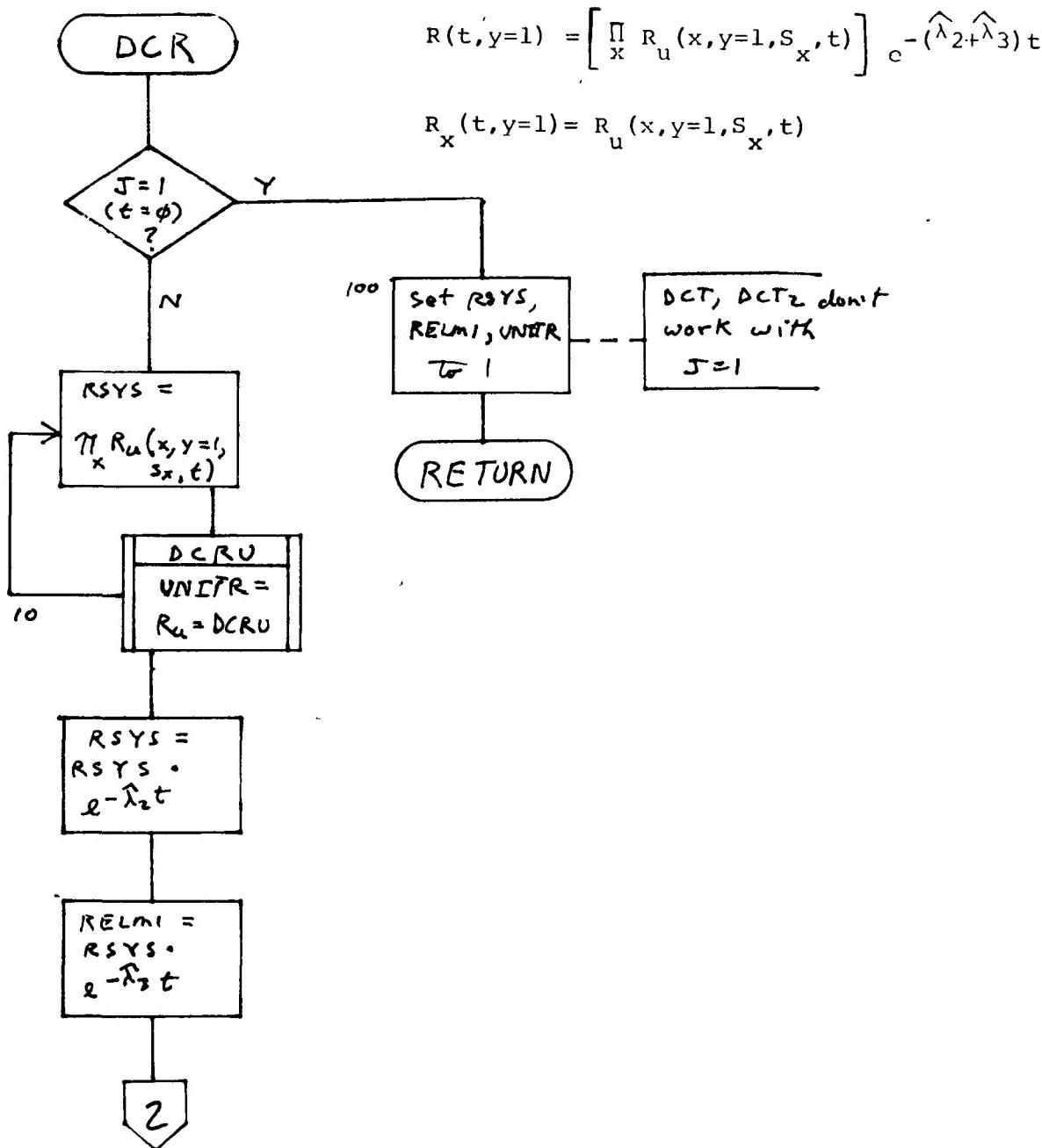
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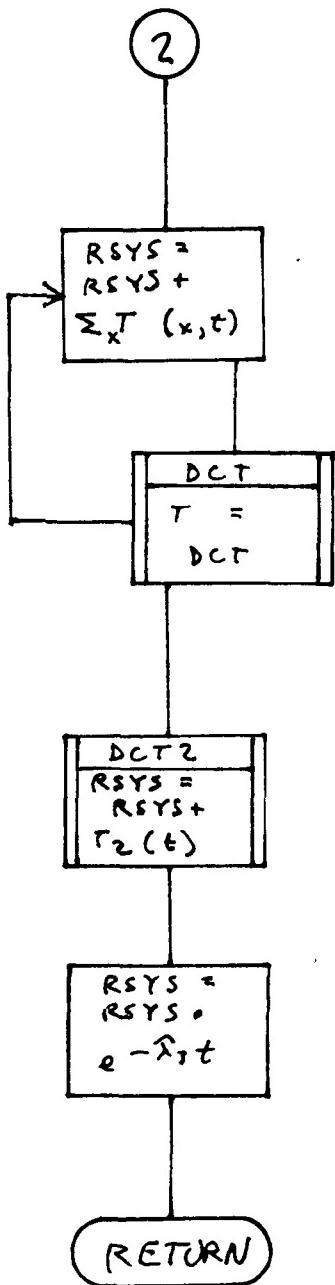
A-10

$$R(t) = \left[\prod_x \left\{ R_u(x, y=1, S_x, t) \right\} * e^{-(\hat{\lambda}_2)t} + r_2(t) + \sum_x \left\{ r(x, t) \right\} \right] e^{-(\hat{\lambda}_3)t}$$



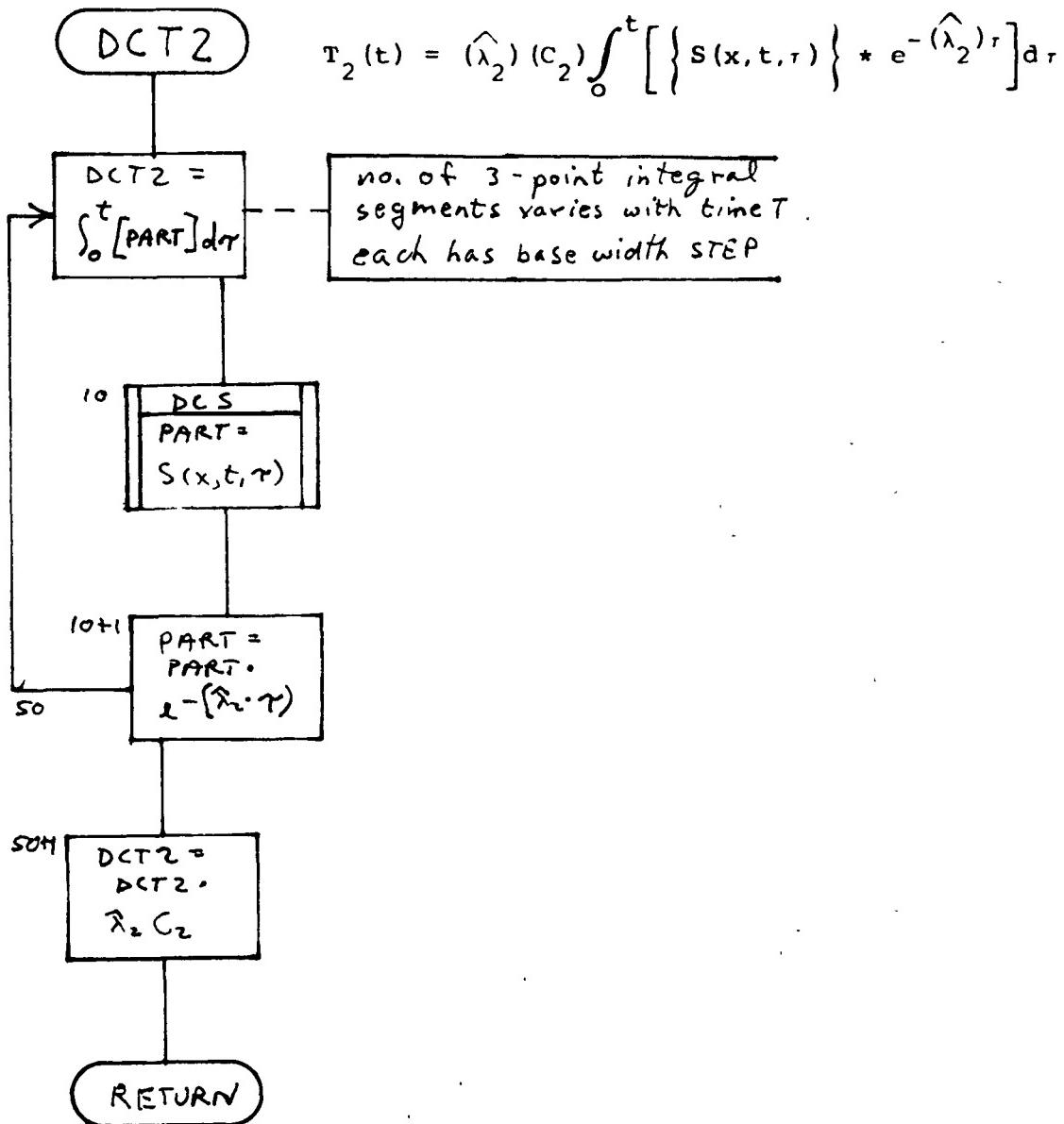
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A-10



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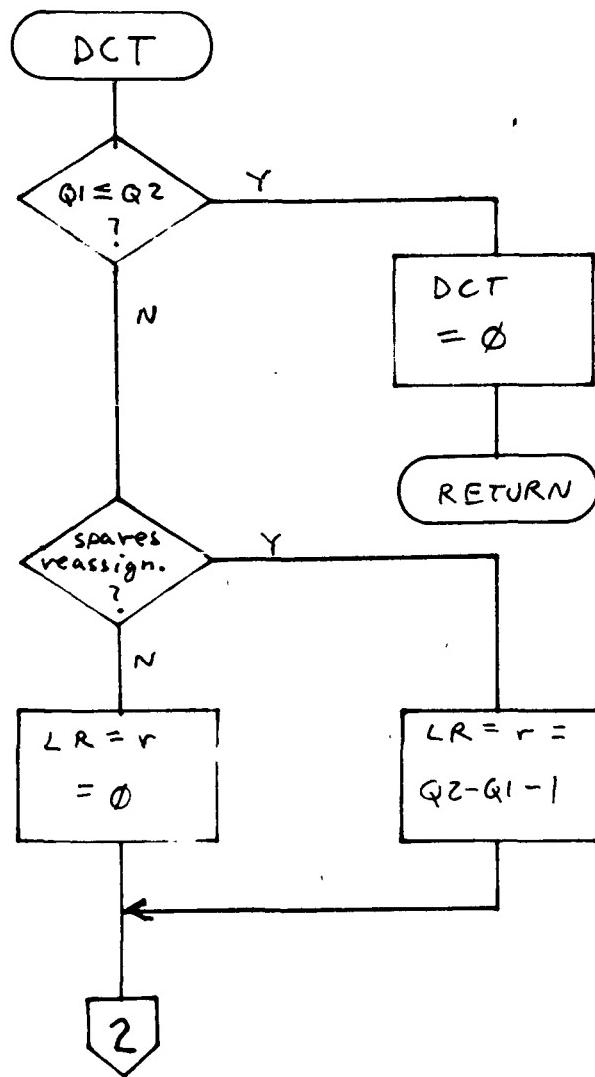
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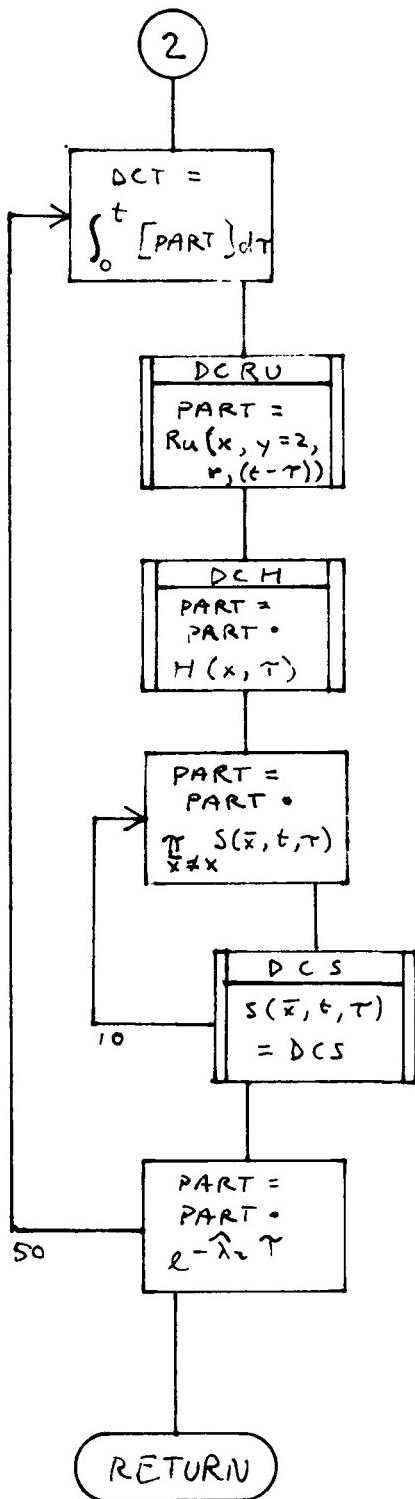
A-12

$$T(x,t) = \begin{cases} \int_0^t \left[\prod_{x \neq x} \left\{ S(\bar{x}, t, \tau) \right\} * R_u(x, y=2, r, (t-\tau)) * H(x, \tau) * e^{-(\lambda_2)^r} \right] d\tau, \\ \text{for } Q(x, 1) > Q(x, 2) \\ 0, \\ \text{for } Q(x, 1) \leq Q(x, 2) \end{cases}$$



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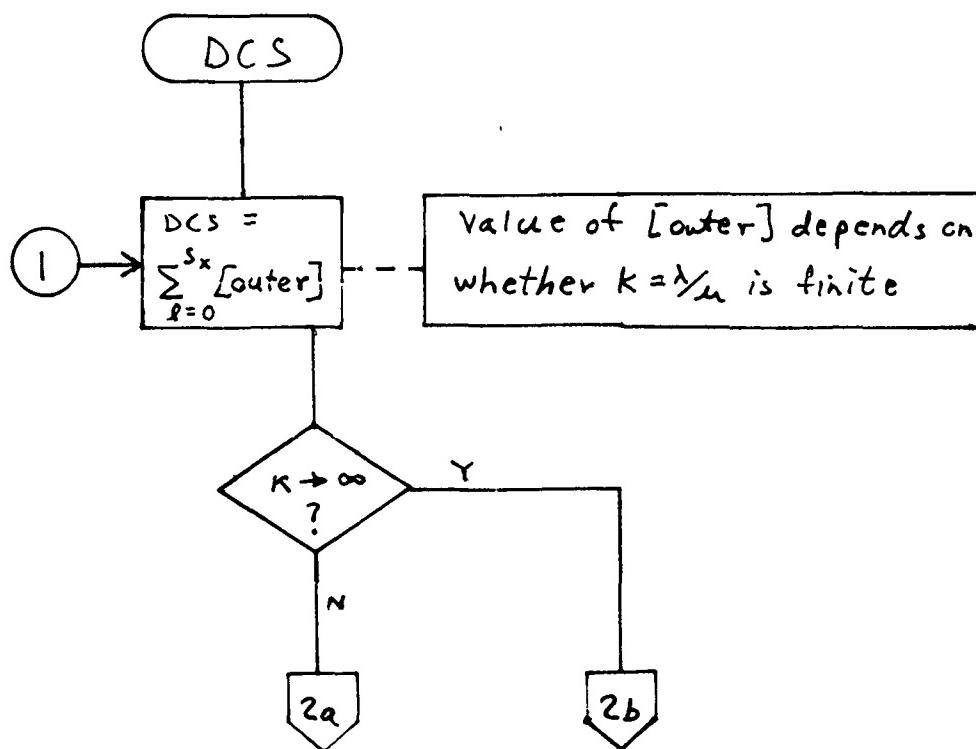
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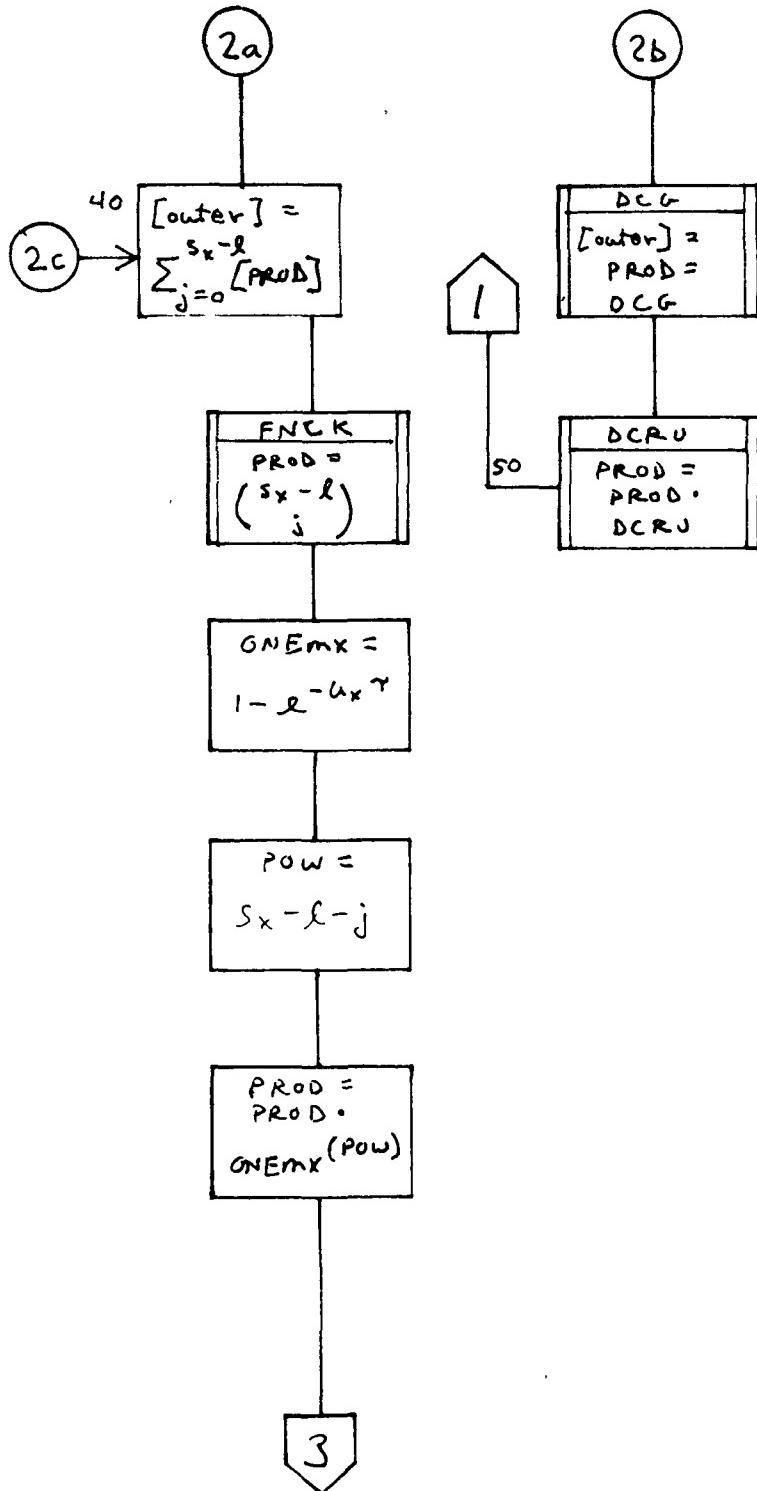
A-13

$$S(x, t, \tau) = \left\{ \begin{array}{l} \sum_{\ell=0}^{(S_x)} \left[\sum_{j=0}^{(S_x - \ell)} \left\{ \binom{(S_x) - \ell}{j} * (1 - e^{-(\mu_x) \tau}) ((S_x) - \ell - j) * \right. \right. \\ \left. \left. e^{-j(\mu_x) \tau} * G(x, y=1, \ell, \tau) * R_u(x, y=2, j, (t-\tau)) \right\} \right] \\ \text{for } K < \infty \\ \sum_{\ell=0}^{(S_x)} \left[G(x, y=1, \ell, \tau) * R_u(x, y=2, [(S_x) - \ell], (t-\tau)) \right], \\ \text{for } K = \infty \end{array} \right.$$



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A-13

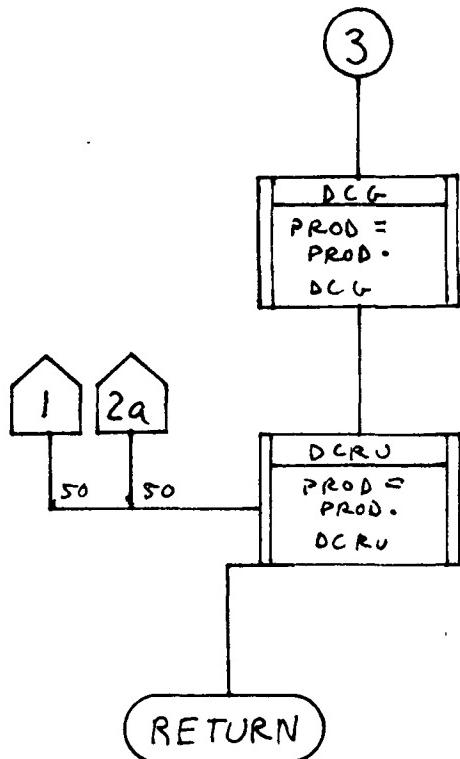


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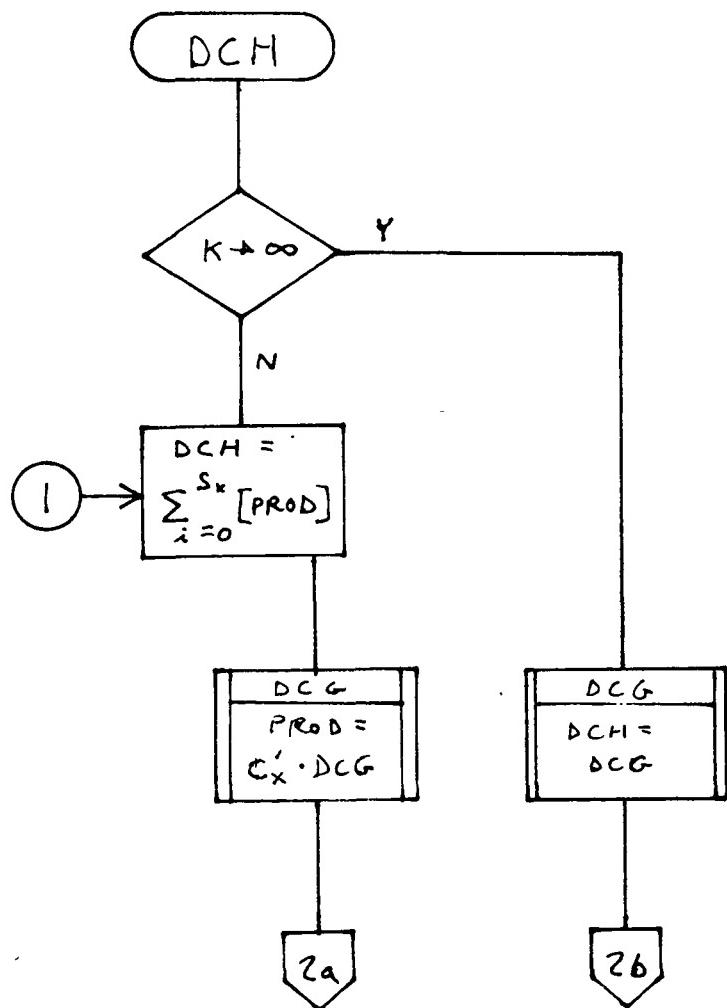
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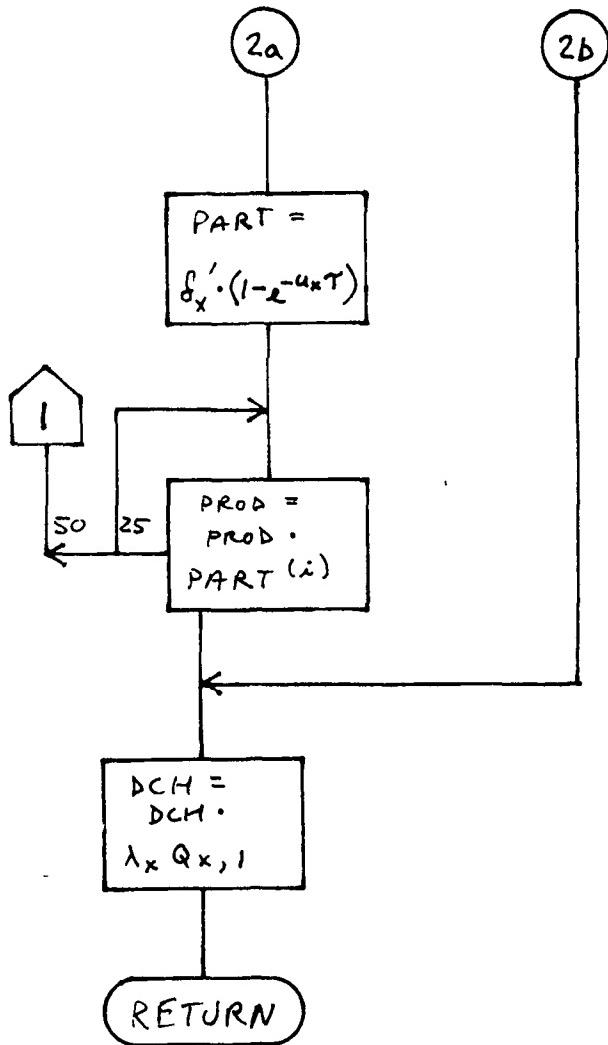
A-14

$$H(x, \tau) = \left\{ \begin{array}{l} Q_x, 1 - \lambda_x \sum_{i=0}^{(S_x)} \left\{ G(x, y=1, [(S_x)-i], \tau) * (C'_x) (\delta'_x)^i * (1-e^{-(\mu_x)\tau})^i \right\}, \\ \text{for } K < \infty \\ \lambda_x Q_x, 1 - (C'_x) * G(x, y=1, (S_x), \tau), \\ \text{for } K = \infty \end{array} \right.$$



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A-14



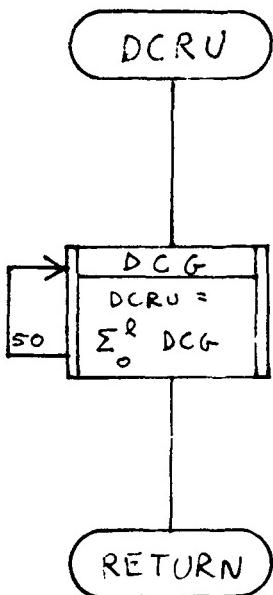
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A-15

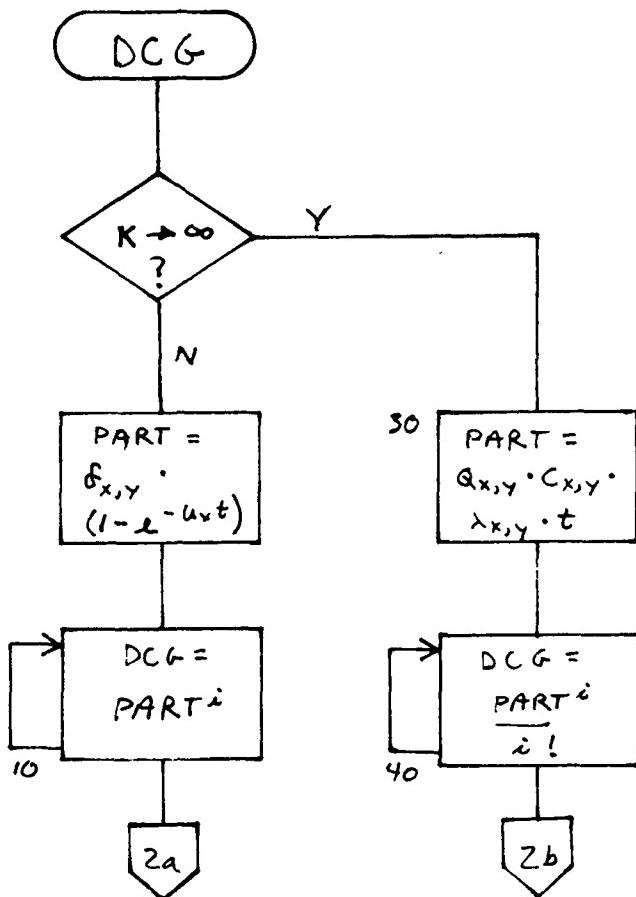


$$R_u(x, y, l, r) = \sum_{i=0}^l G(x, y, i, r)$$

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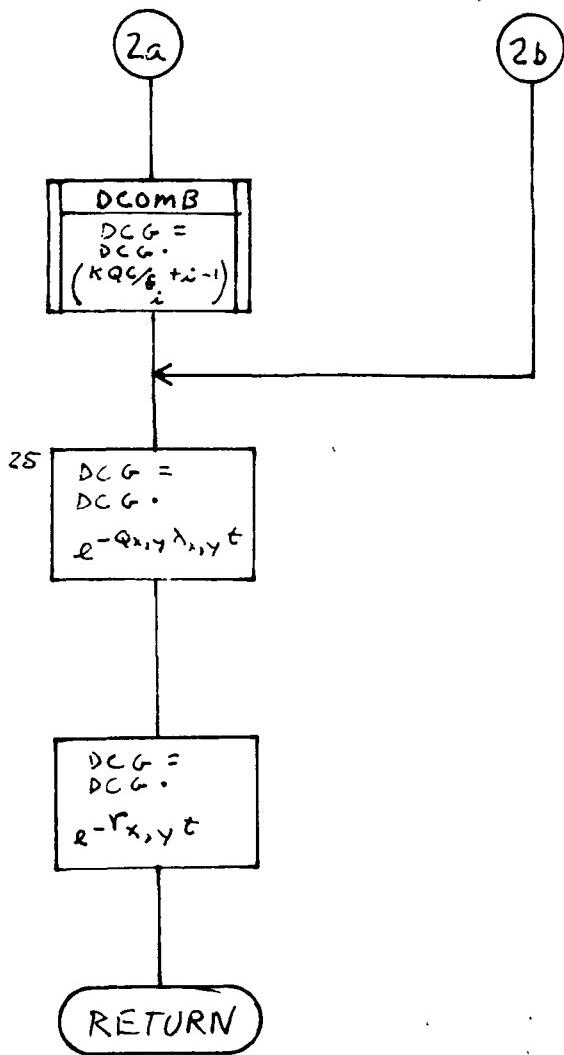
A-16

$$G(x,y,i,t) = \begin{cases} e^{-(\gamma_{x,y})t} * (\delta_{x,y})^i * \left(\frac{(\kappa_x)(Q_{x,y})(C_{x,y})(\lambda_{x,y})^{-1+i-1}}{i!} \right), & \text{for } K < \infty \\ (1-e^{-(\mu_x)t})^i * e^{-(Q_{x,y})(\lambda_x)t} \\ e^{-(\gamma_{x,y})t} * \left(\frac{(Q_{x,y})(C_{x,y})(\lambda_x)t}{i!} \right)^i * e^{-(Q_{x,y})(\lambda_x)t}, & \text{for } K = \infty \end{cases}$$



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A-16

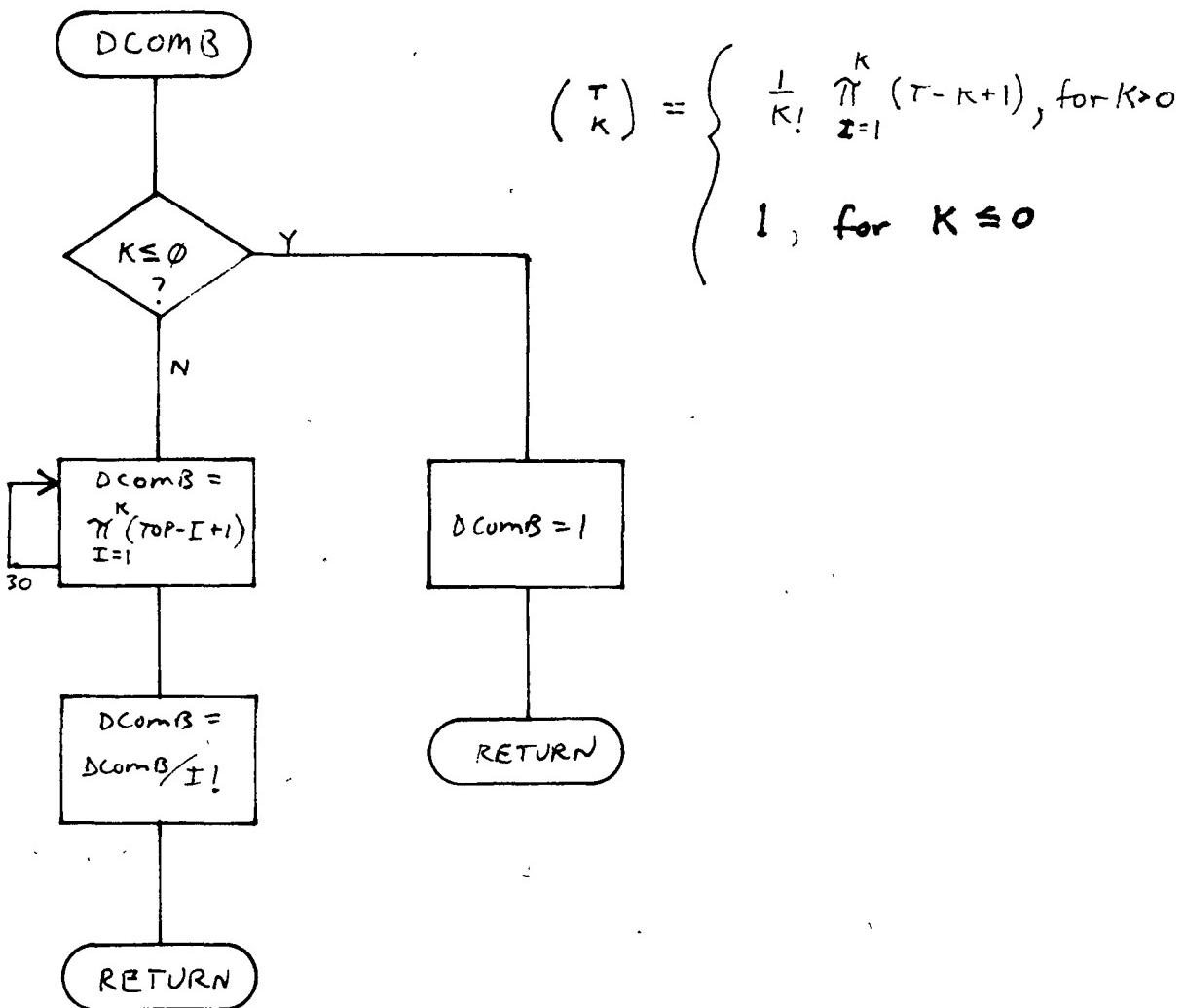


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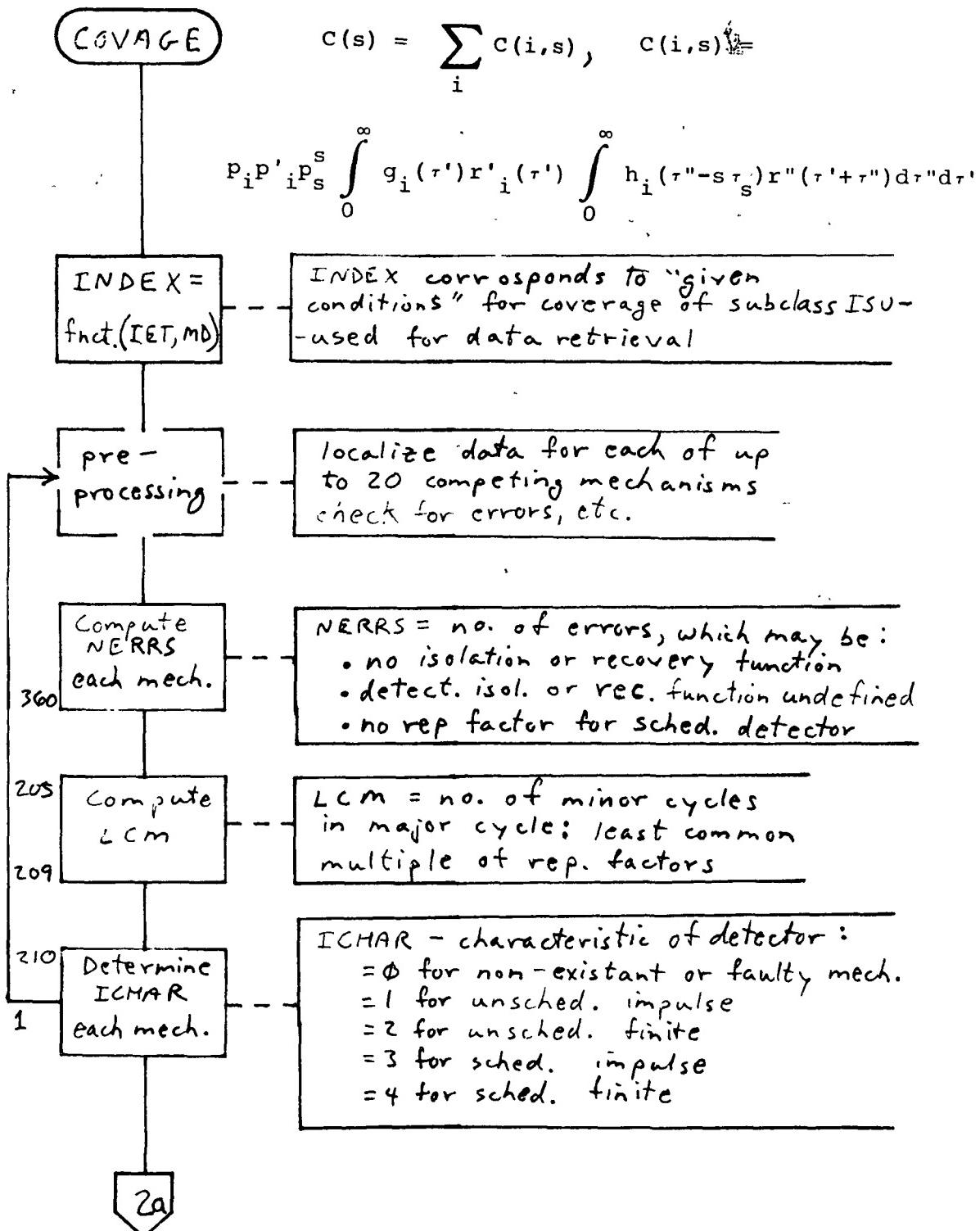
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A-17



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A-18

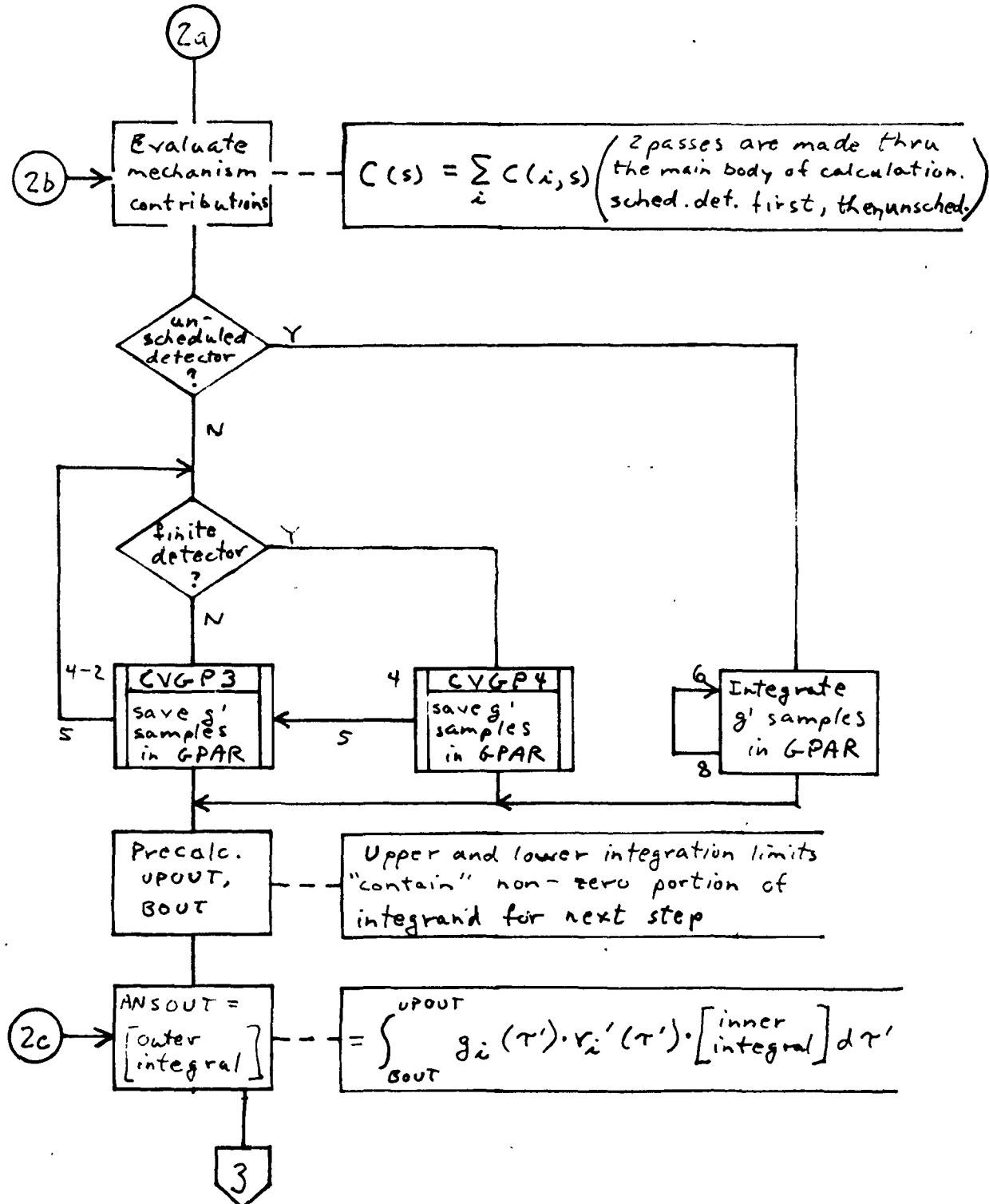


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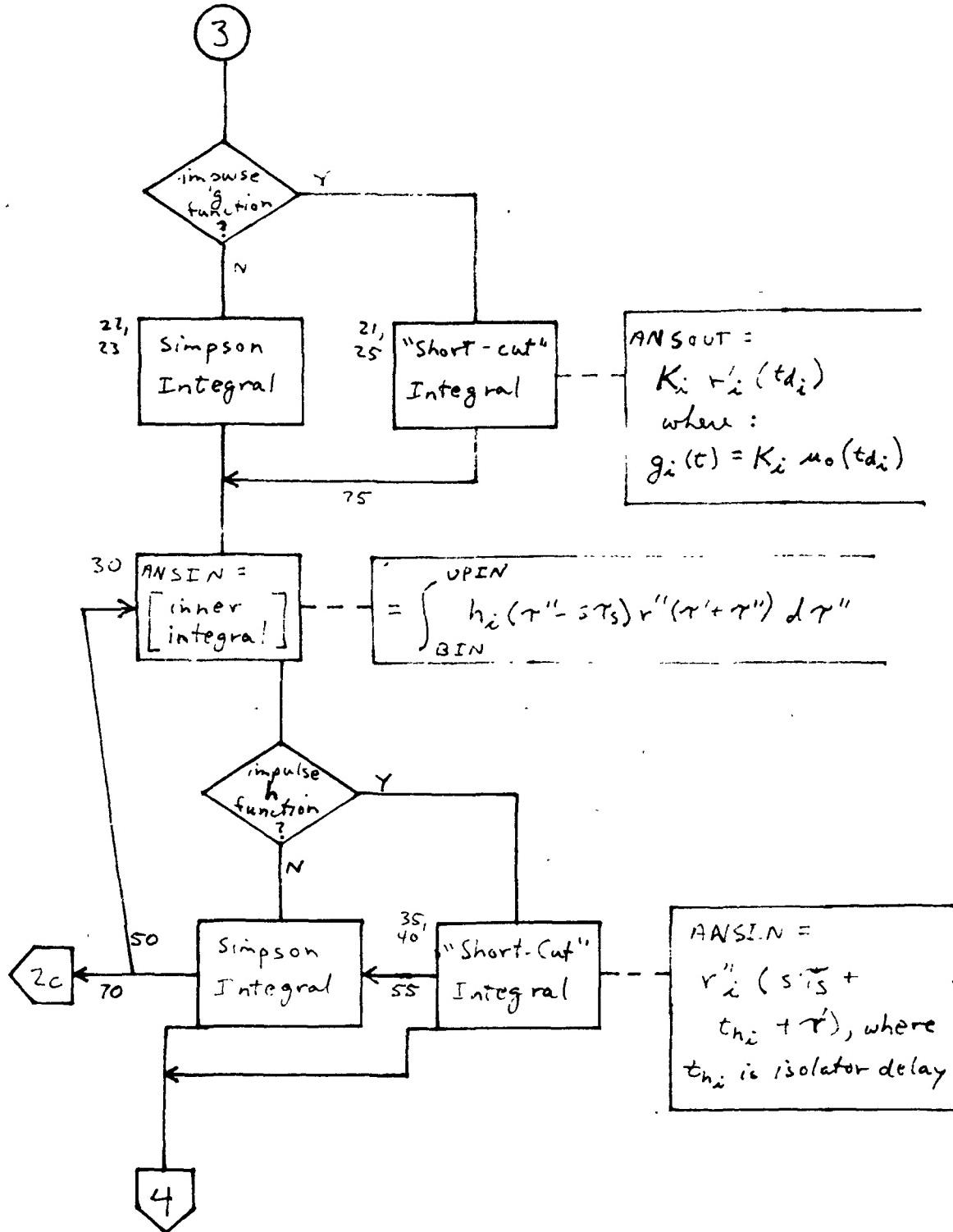
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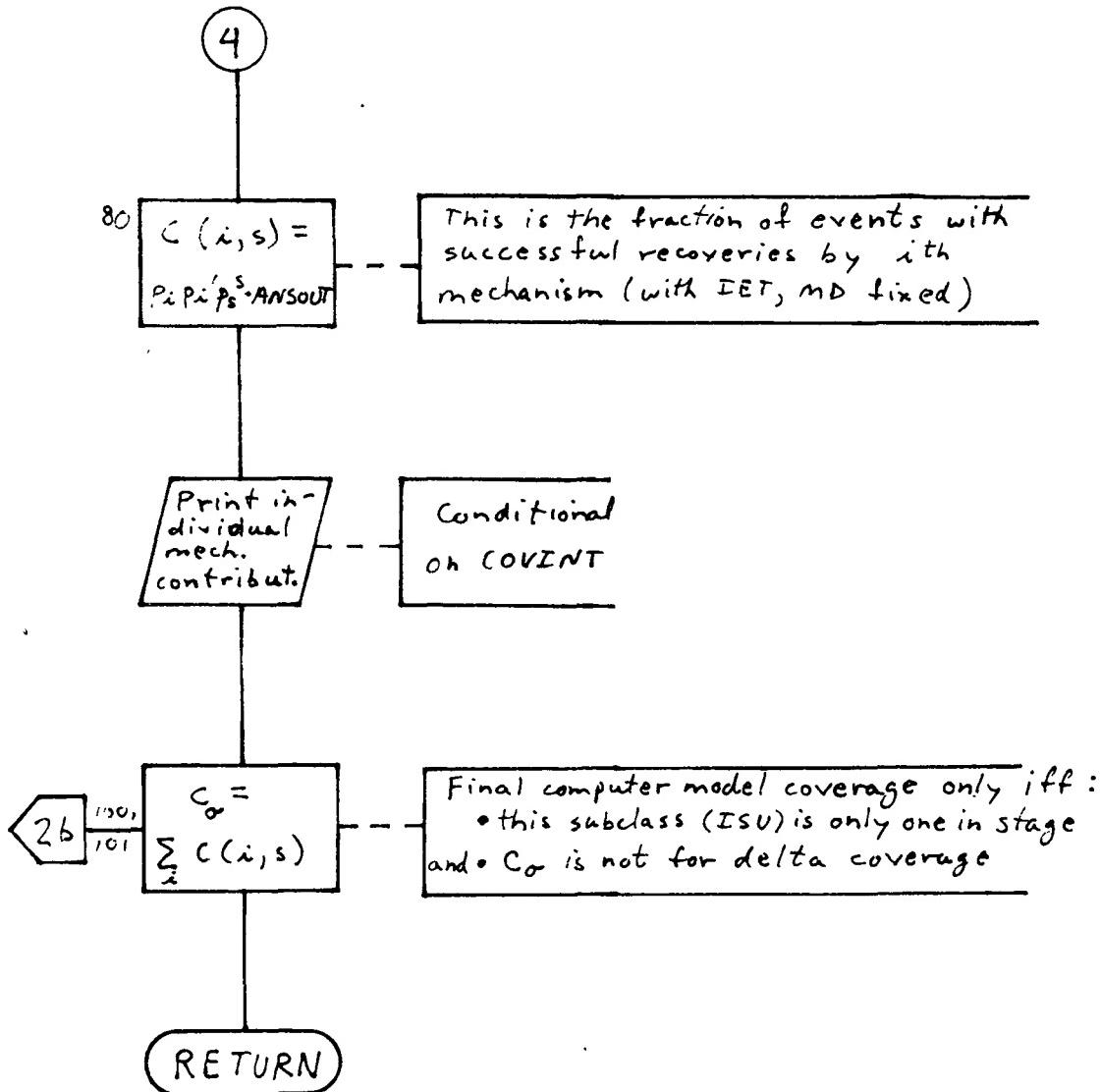
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FLOW DIAGRAM

A-18

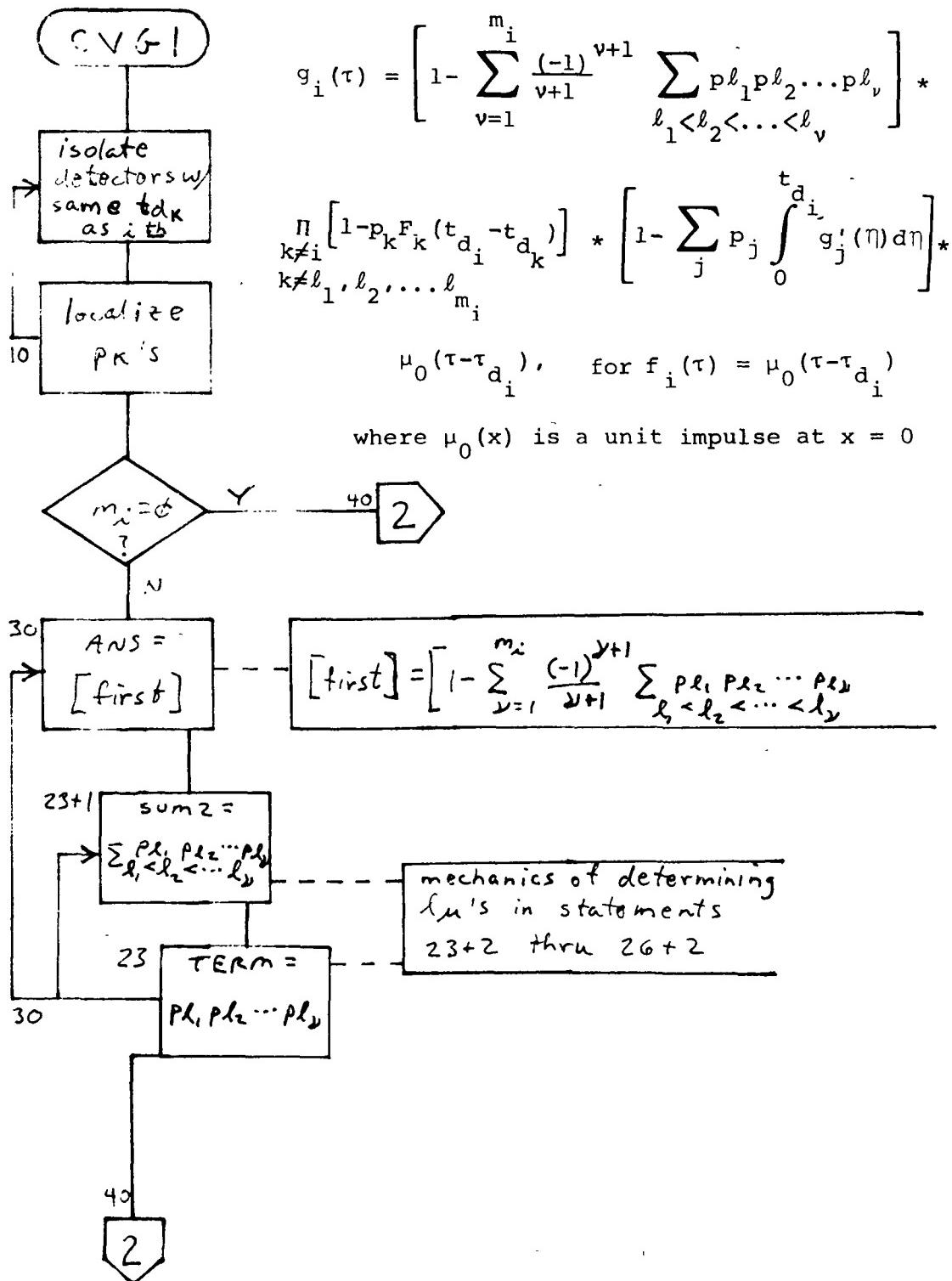


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EQUIPMENT DIVISION

RAYTHEON

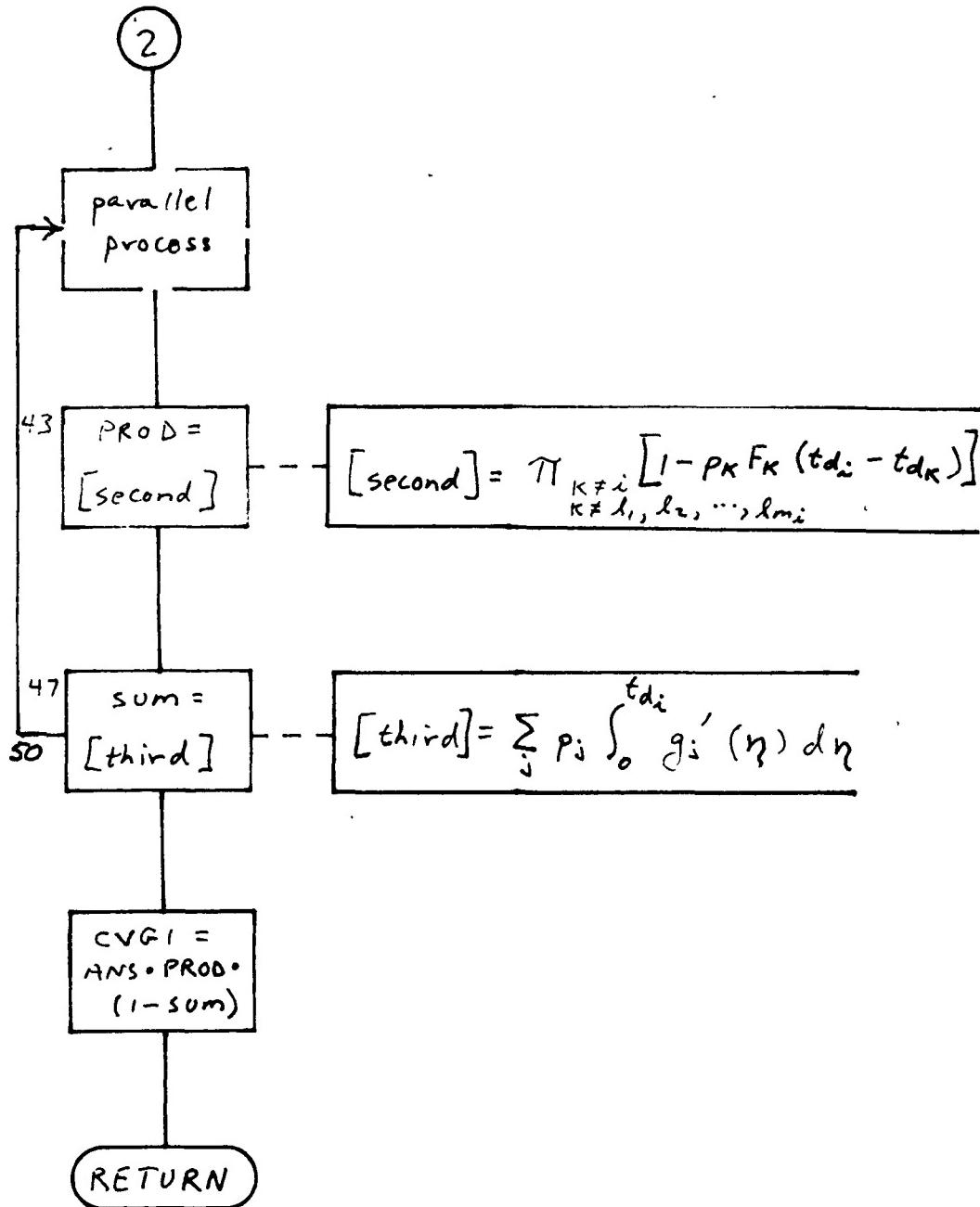
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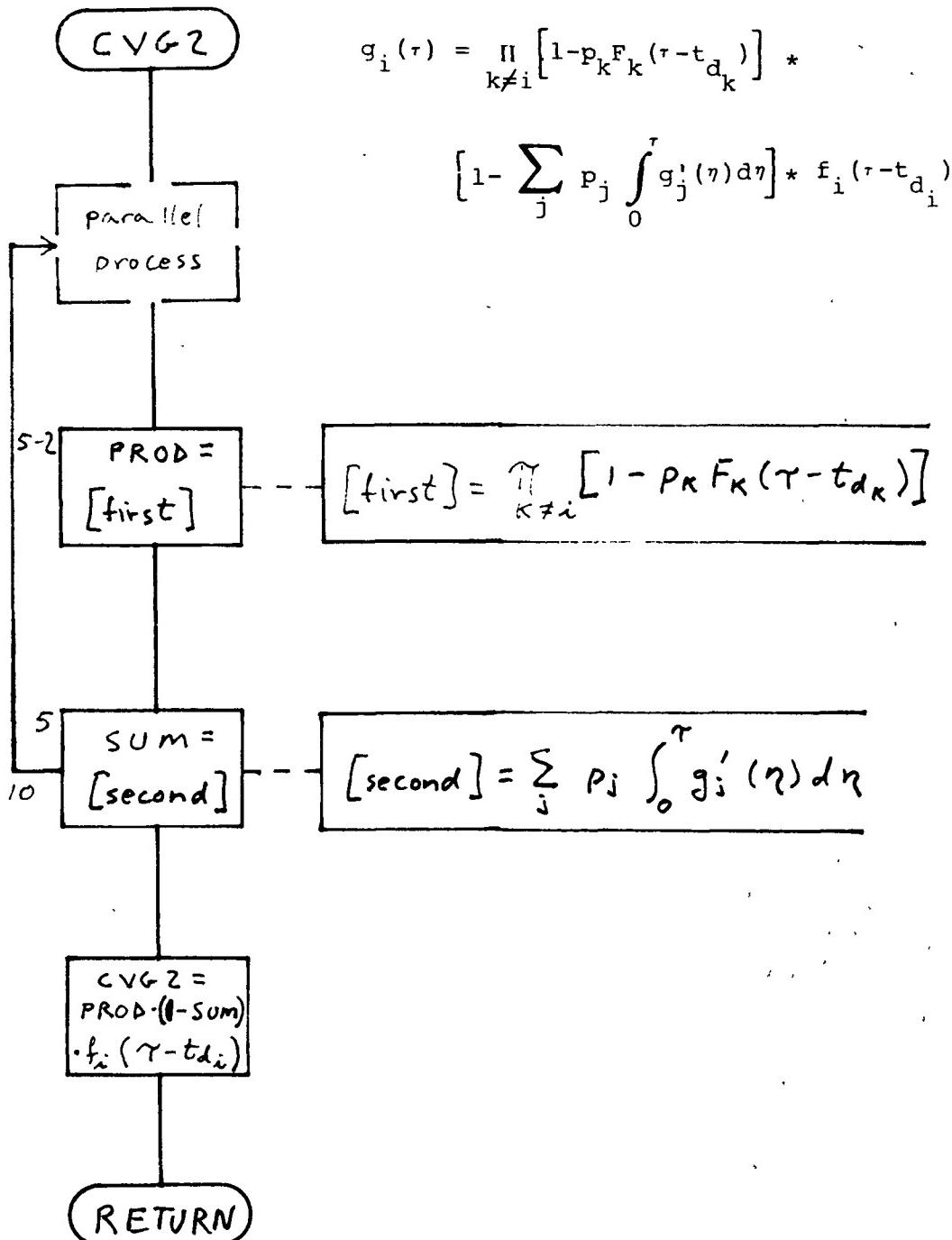
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A-20

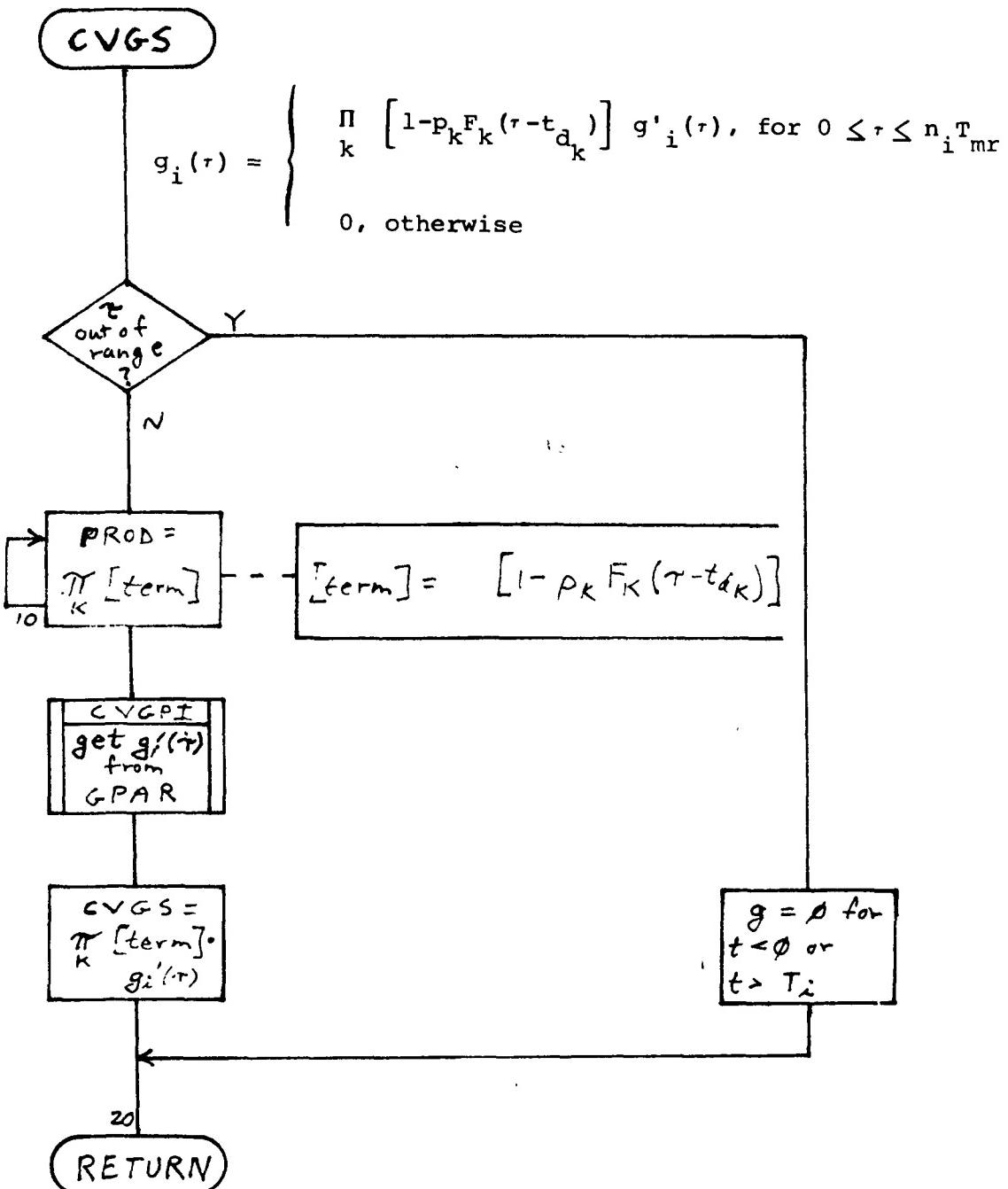


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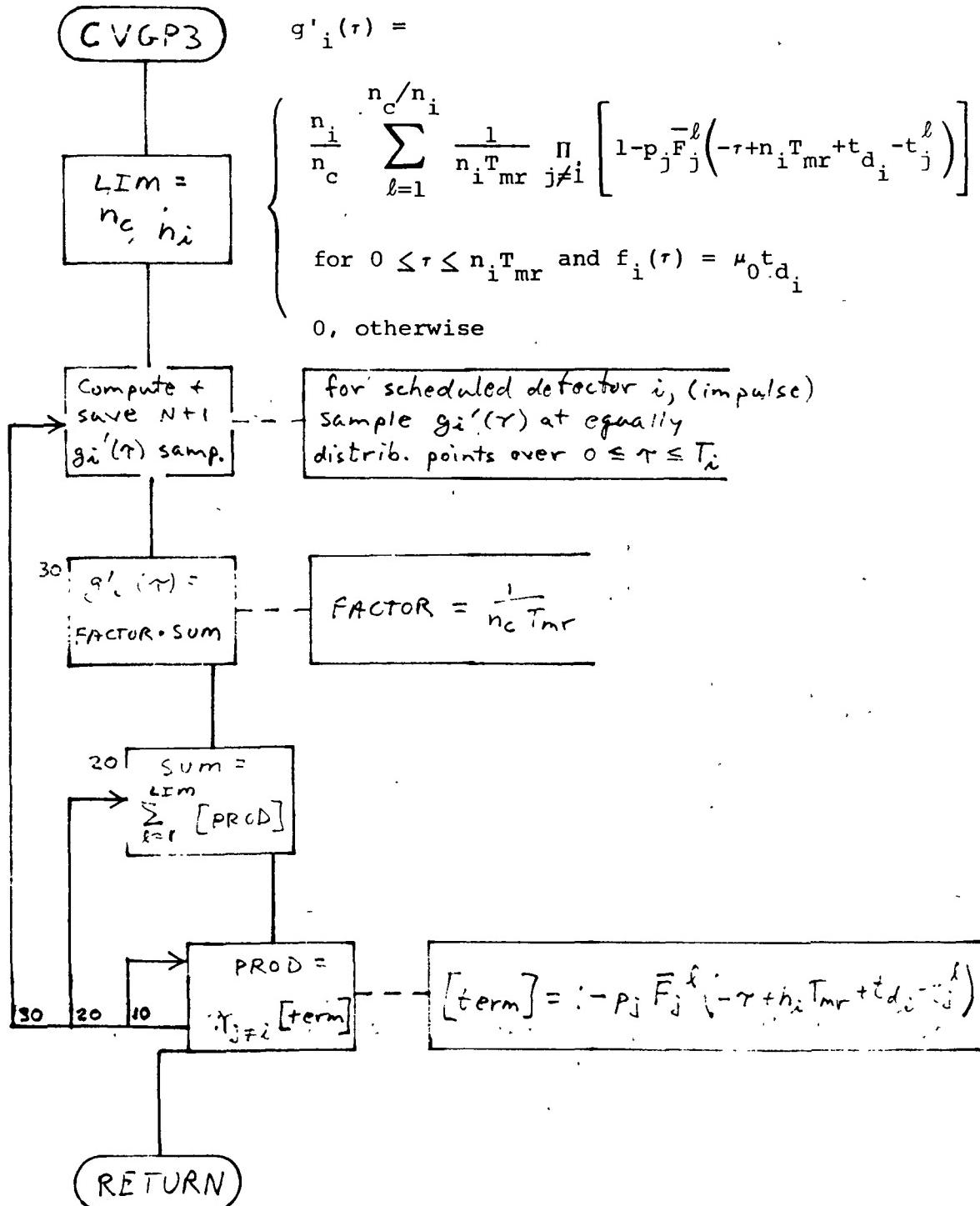
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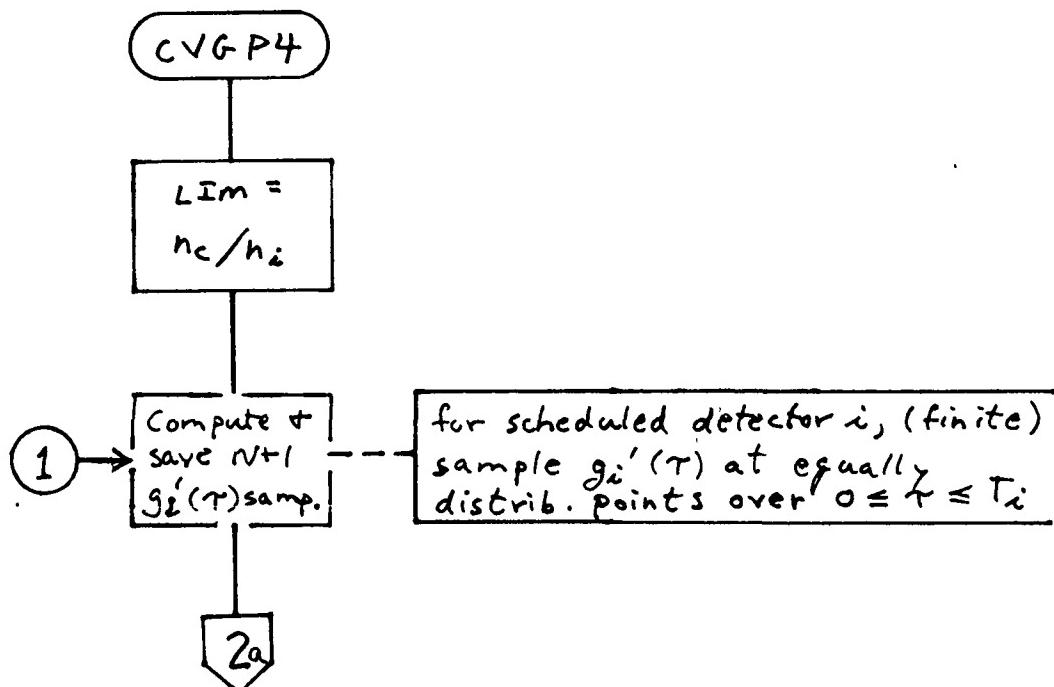
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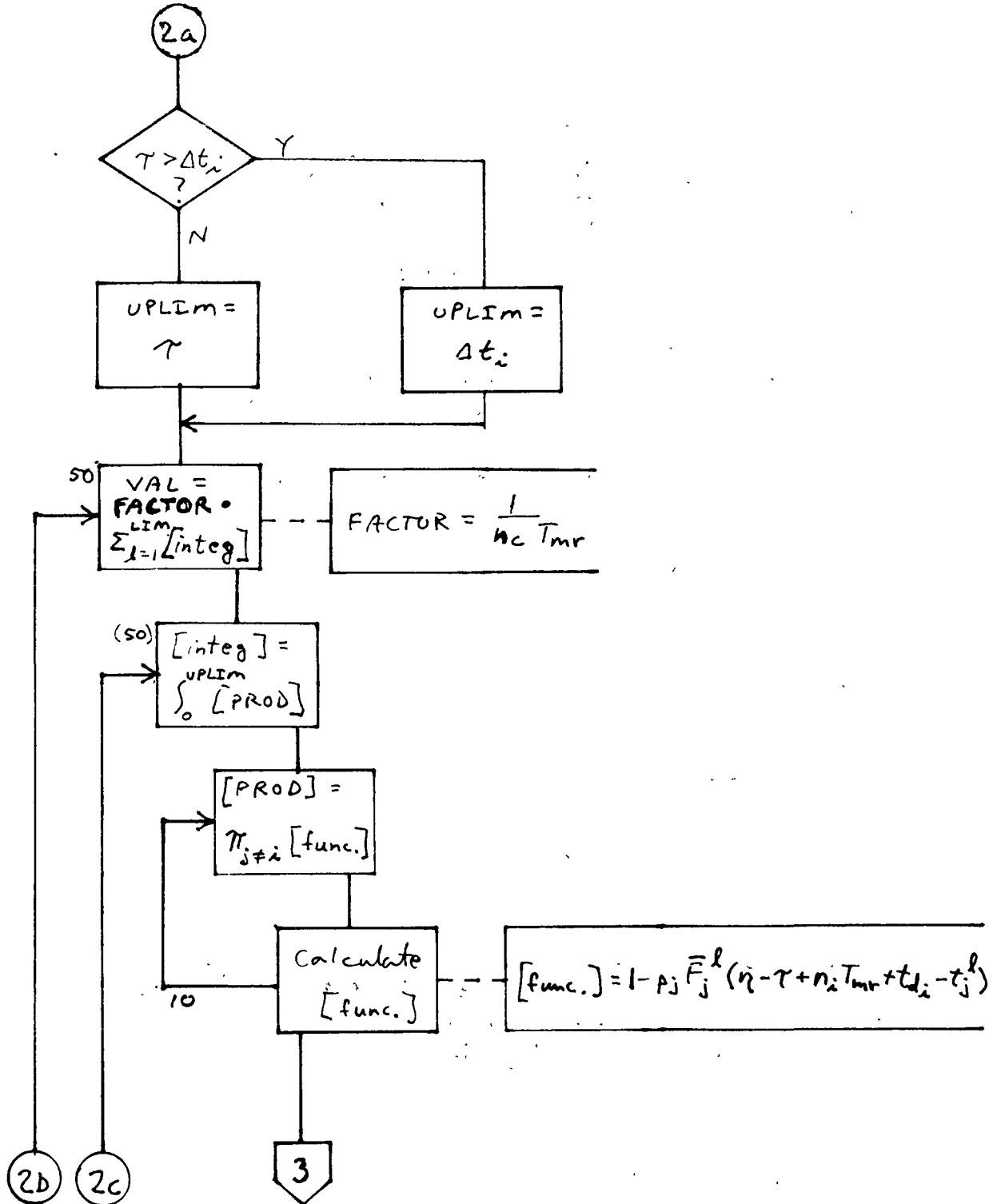
A-23

$$g'_i(\tau) = \begin{cases} \frac{1-F_i(\tau)}{n_i T_{mr}} + \frac{n_i}{n_c} \sum_{\ell=1}^{n_c/n_i} \frac{1}{n_i T_{mr}} \int_0^{\tau} \prod_{j \neq i} \left[1 - p_j^{-\ell} F_j(\eta - \tau + n_i T_{mr} + t_{d_i} - t_j^\ell) \right] \\ * f_i(\eta) d\eta & \text{for } 0 \leq \tau \leq \Delta t_i \\ \frac{n_i}{n_c} \sum_{\ell=1}^{n_c/n_i} \frac{1}{n_i T_{mr}} \int_0^{\Delta t_i} \prod_{j \neq i} \left[1 - p_j^{-\ell} F_j(\eta - \tau + n_i T_{mr} + t_{d_i} - t_j^\ell) \right] \\ * f_i(\eta) d\eta & \text{for } \Delta t_i < \tau \leq n_i T_{mr} \\ 0, \text{ otherwise} \end{cases}$$



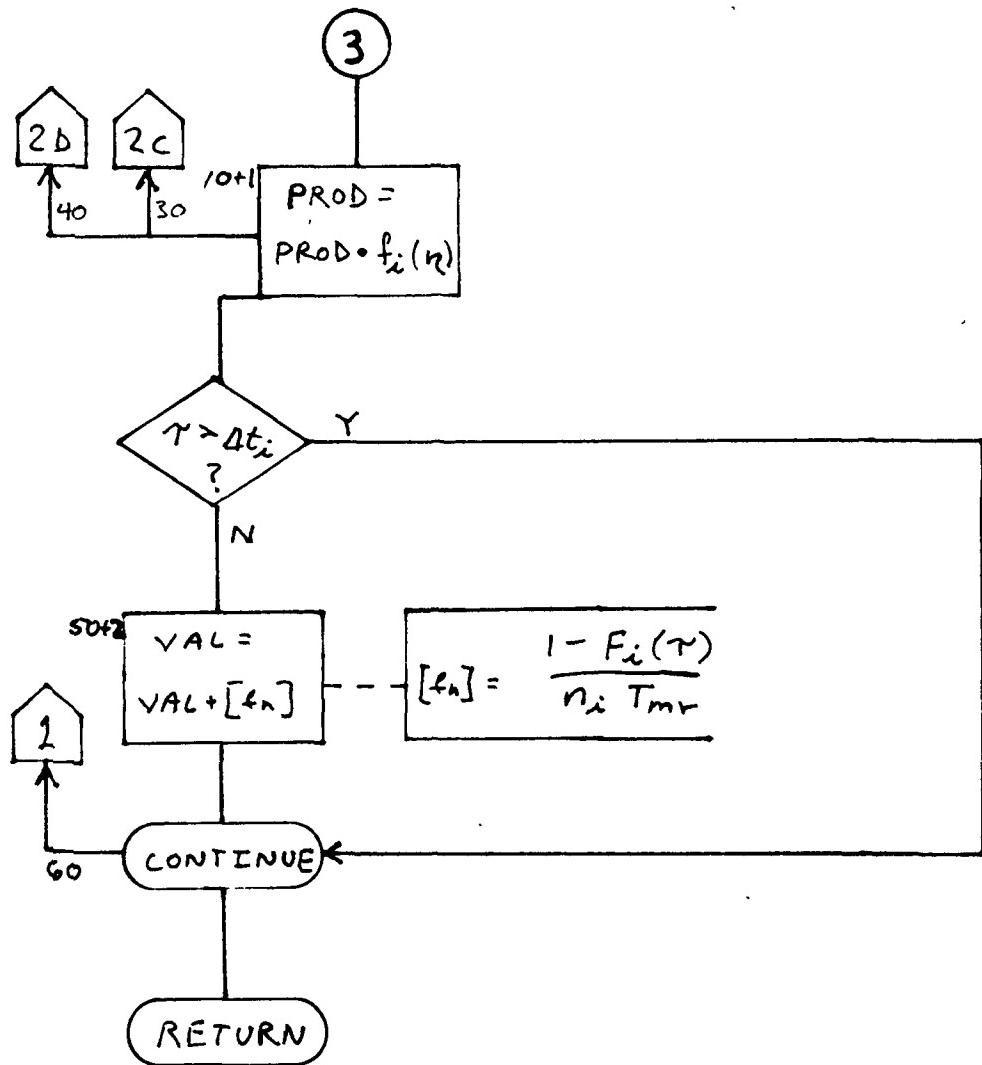
FLOW DIAGRAM

A-23



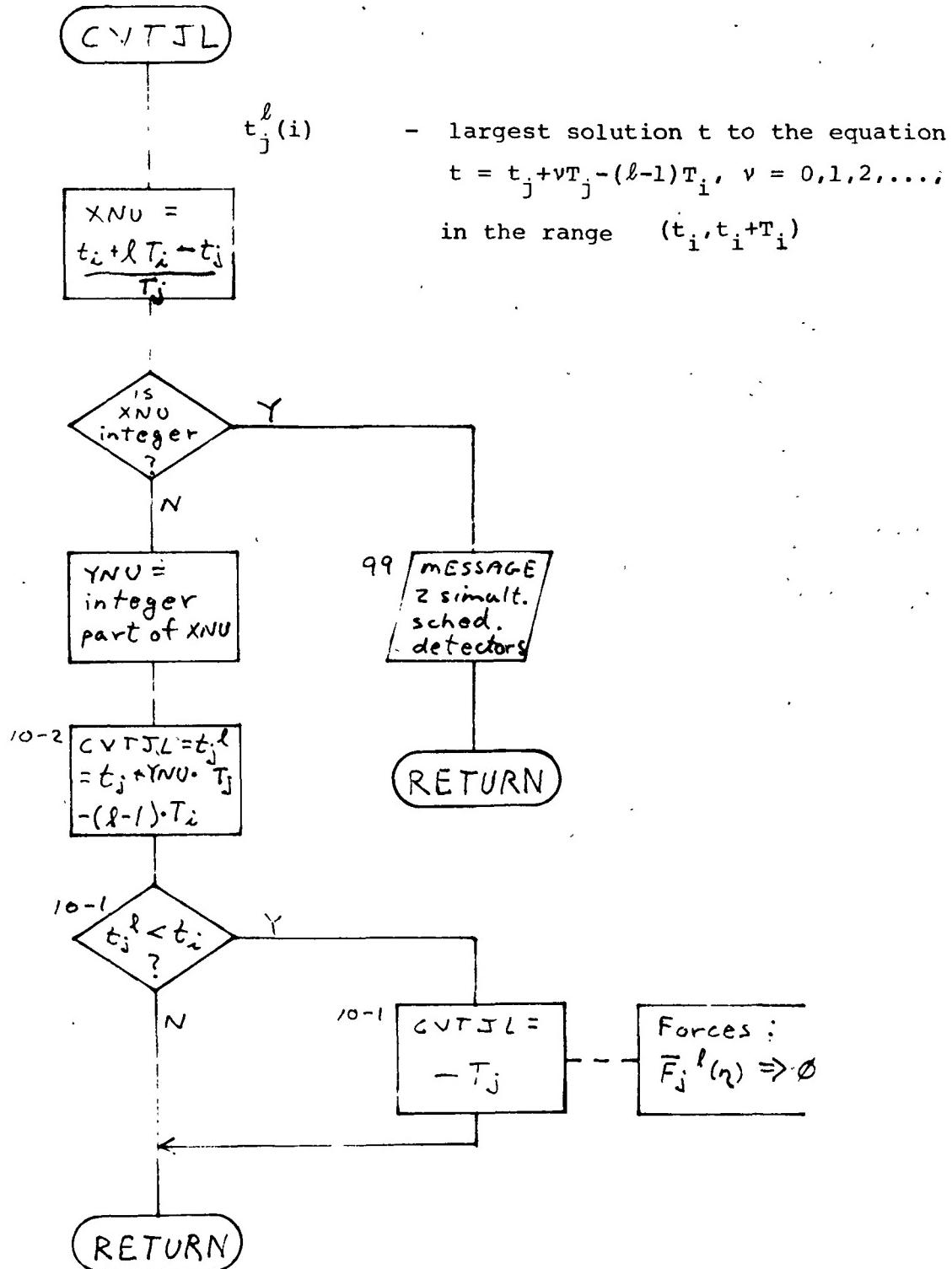
FLOW DIAGRAM

A-23



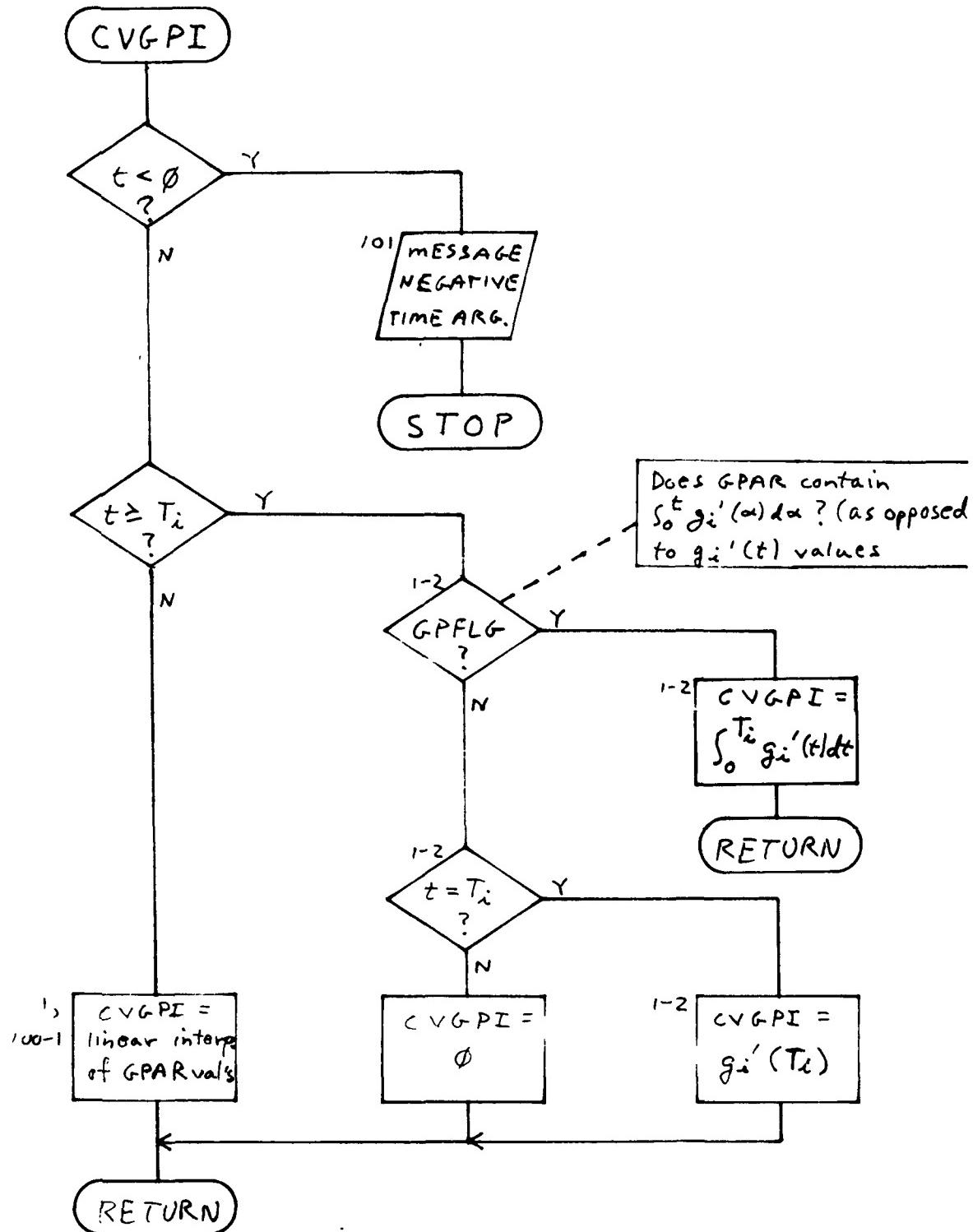
FLOW DIAGRAM

A-24



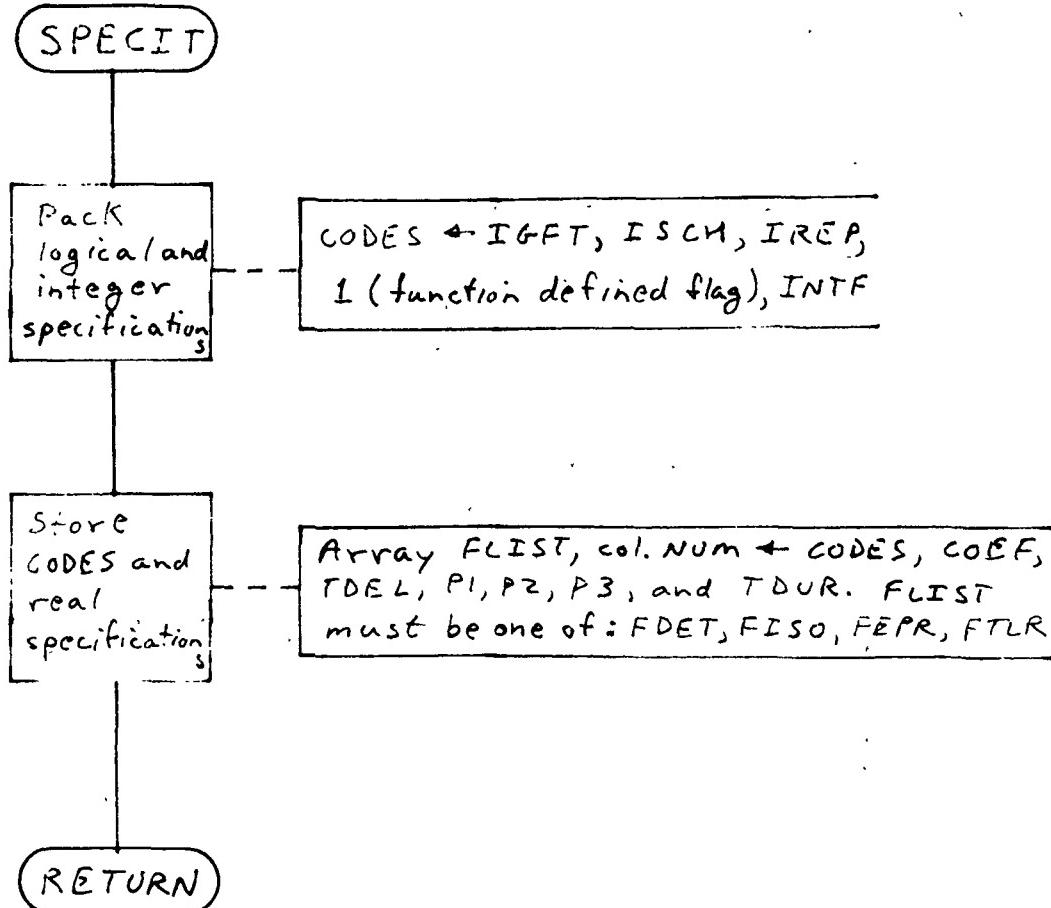
FLOW-DIAGRAM

A-25



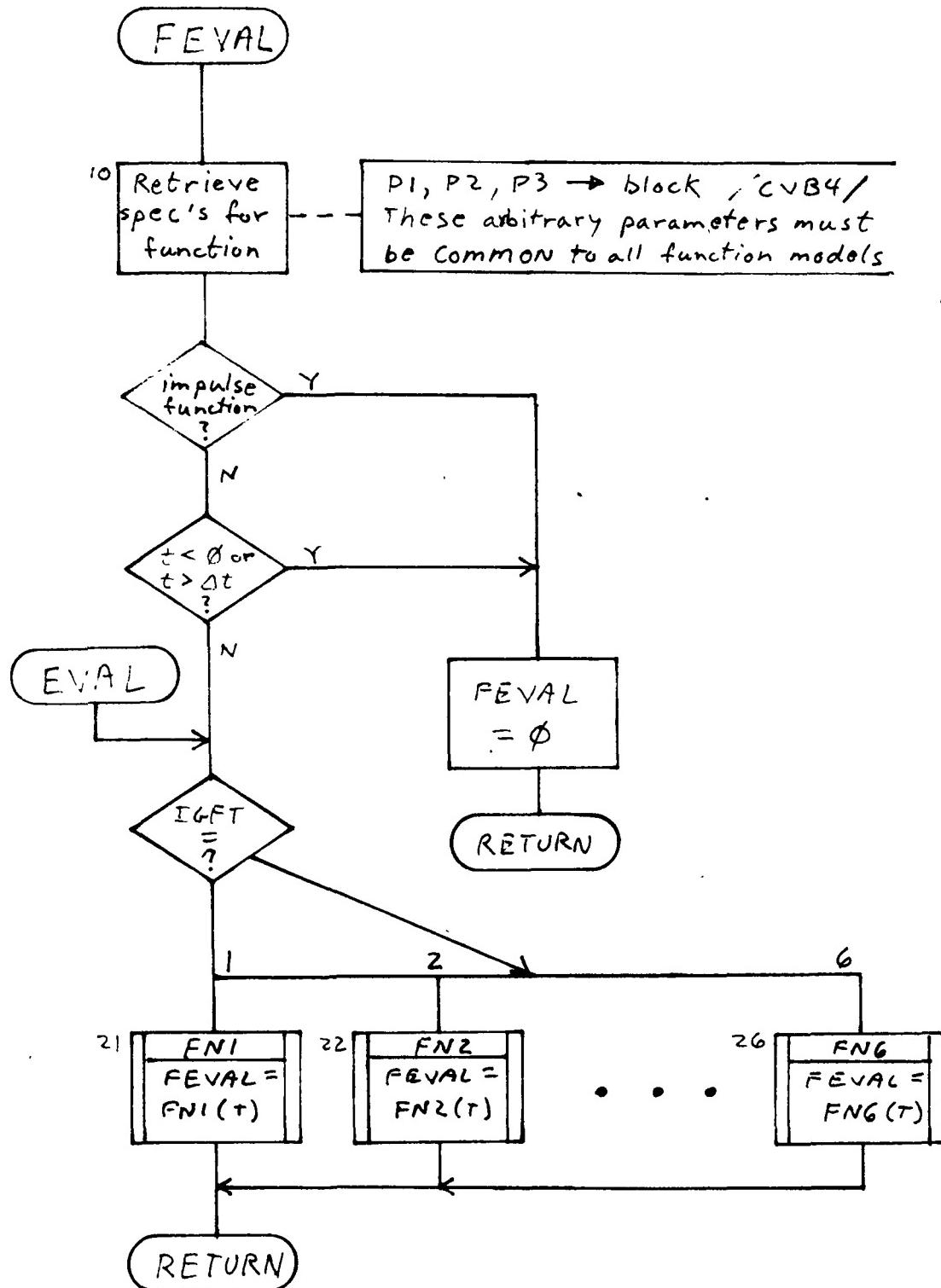
FLOW DIAGRAM

A-26



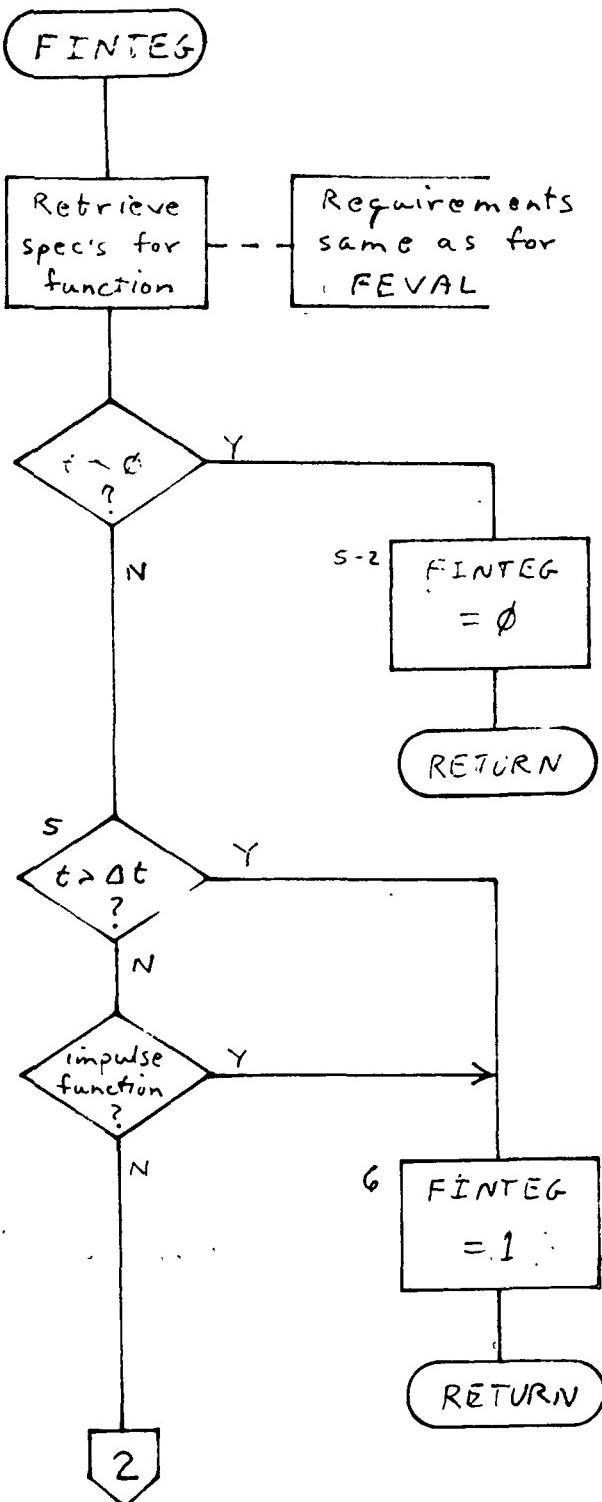
FLOW DIAGRAM

A-27



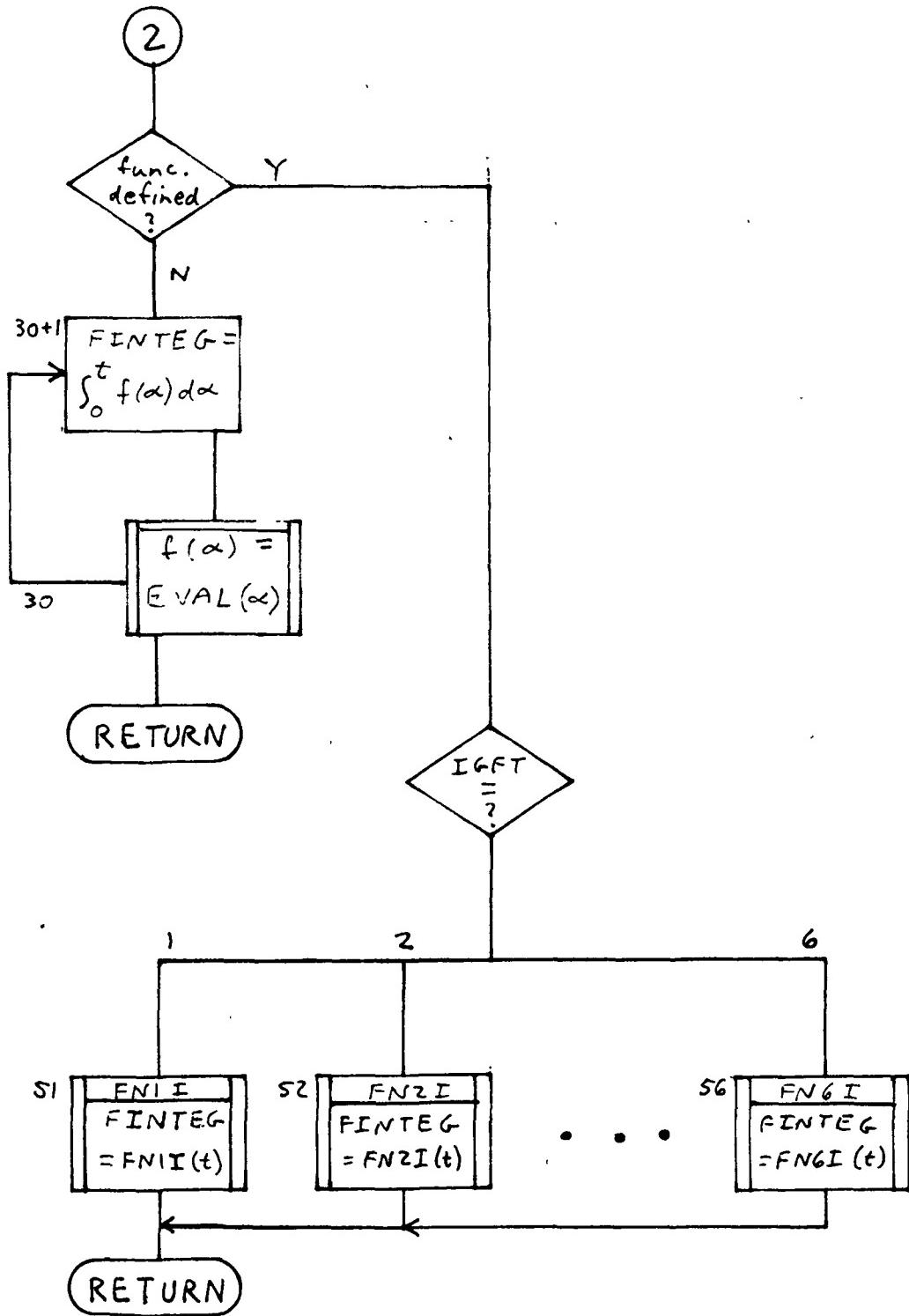
FLOW DIAGRAM

A-28



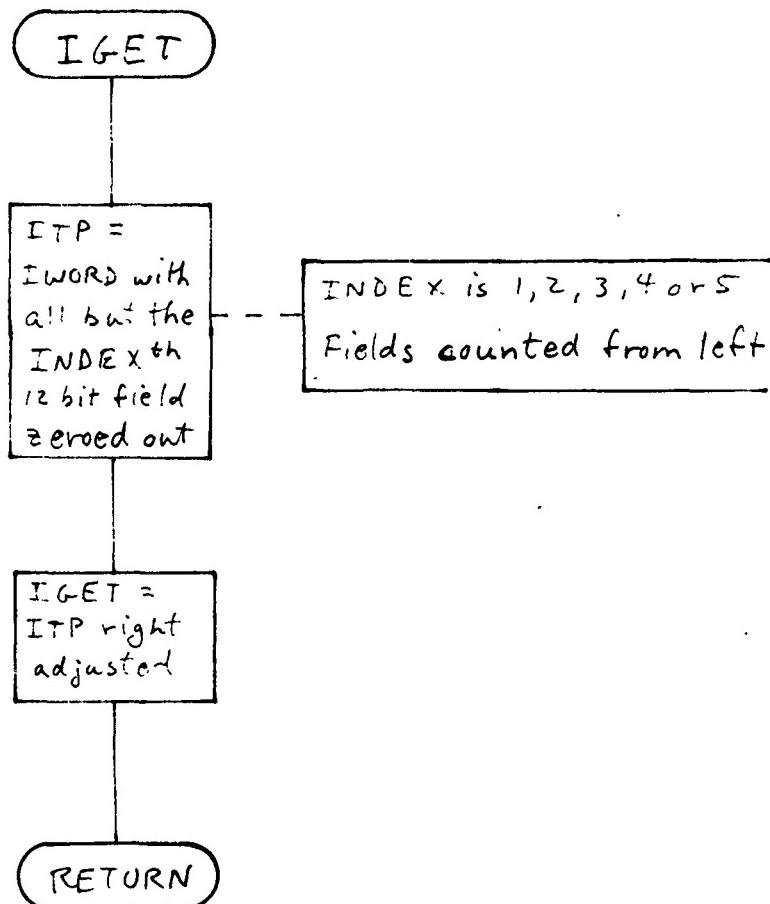
FLOW DIAGRAM

A-28



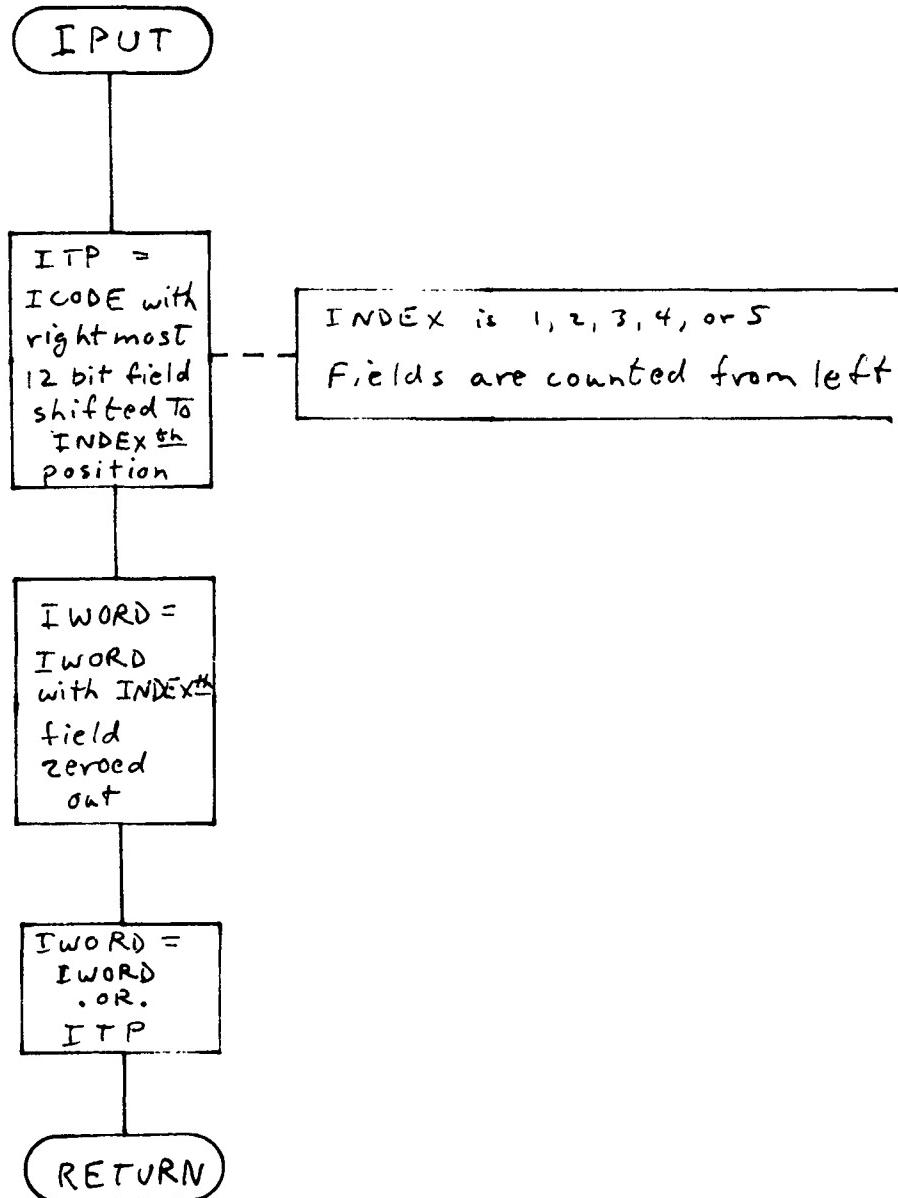
FLOW DIAGRAM

A-29



FLOW DIAGRAM

A-30

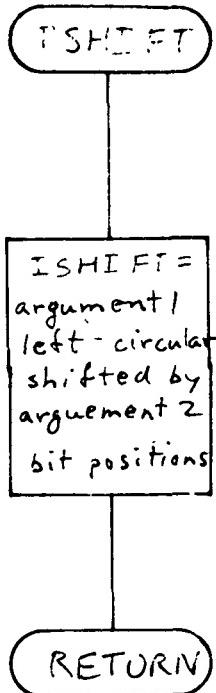


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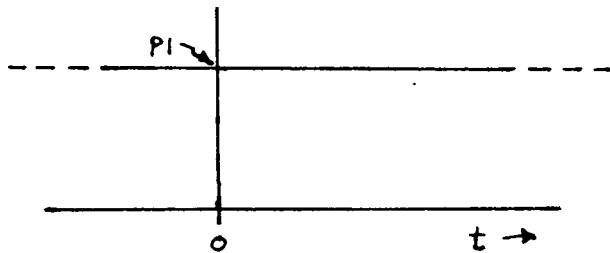
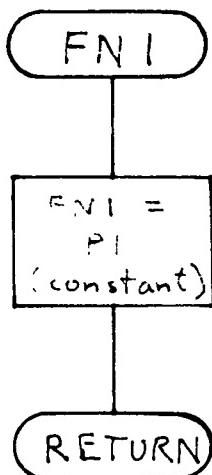
FLOW DIAGRAM

A-31



FLOW DIAGRAM

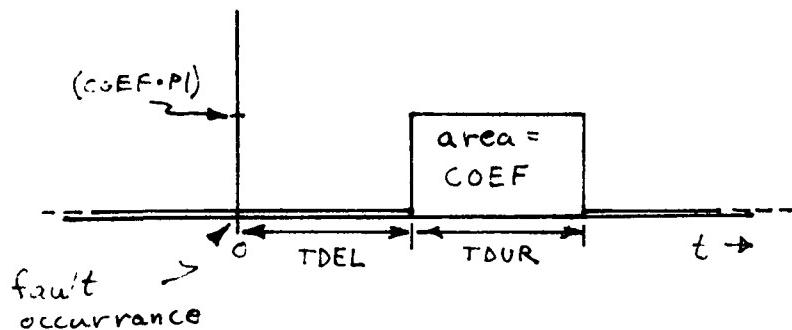
A-32



GRAPH OF $FN1(t)$
(SINGLE PULSE)

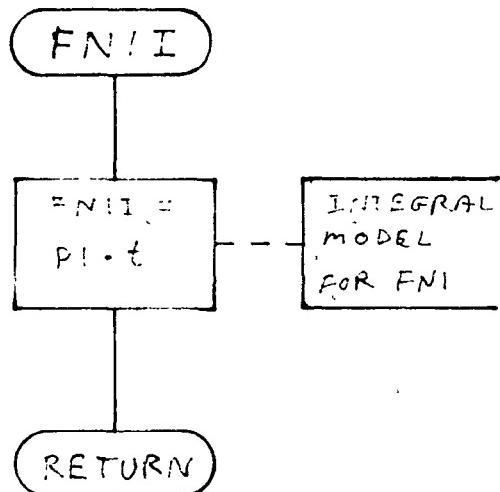
Note:

Function and integral models should be defined for all t as above. Evaluation functions FEVAL and FINTEG and their calling programs provide the additional constraints required by the coverage model. Thus an unscheduled detection function using FN1 is effectively like the figure below -



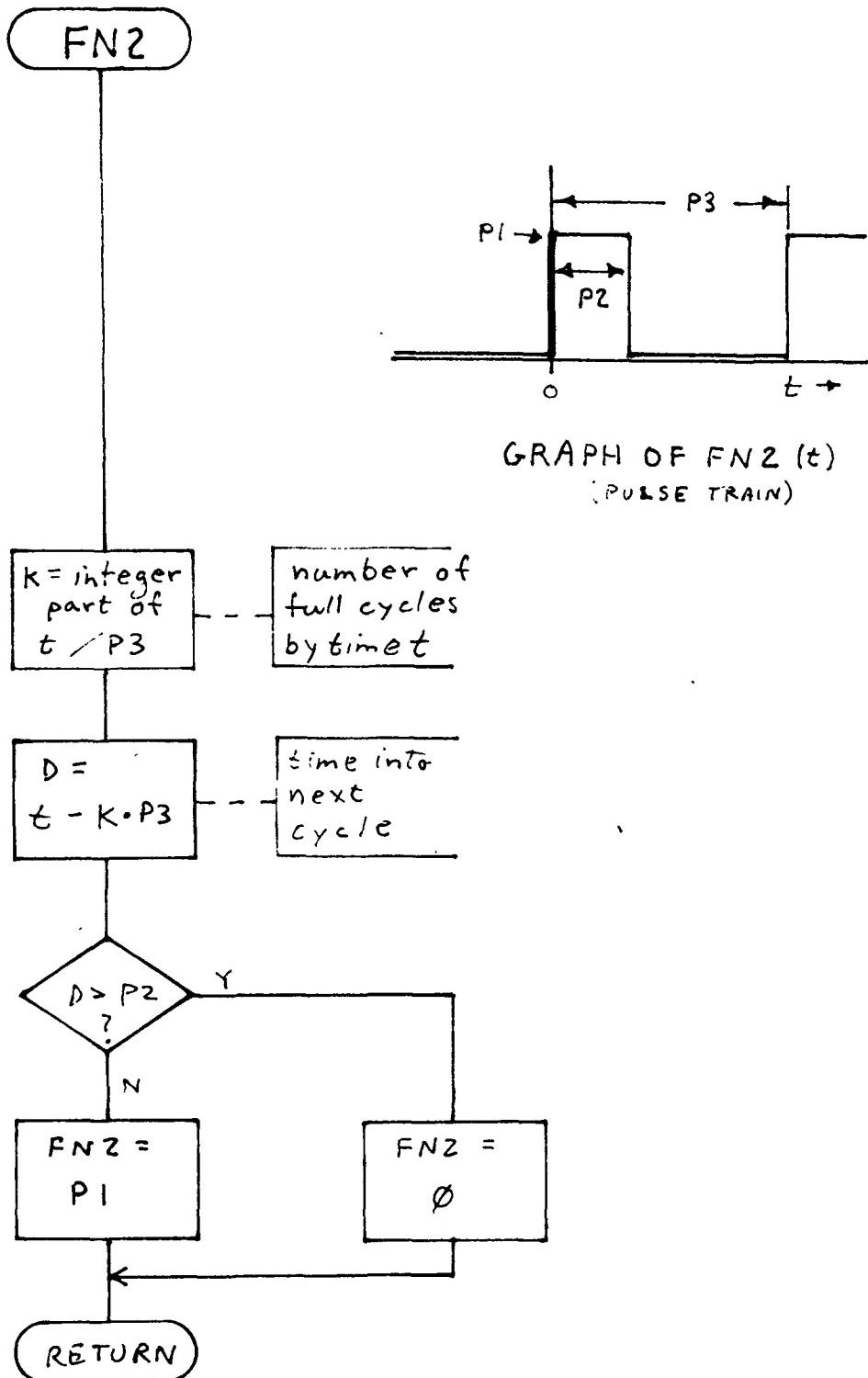
FLOW DIAGRAM

A-33



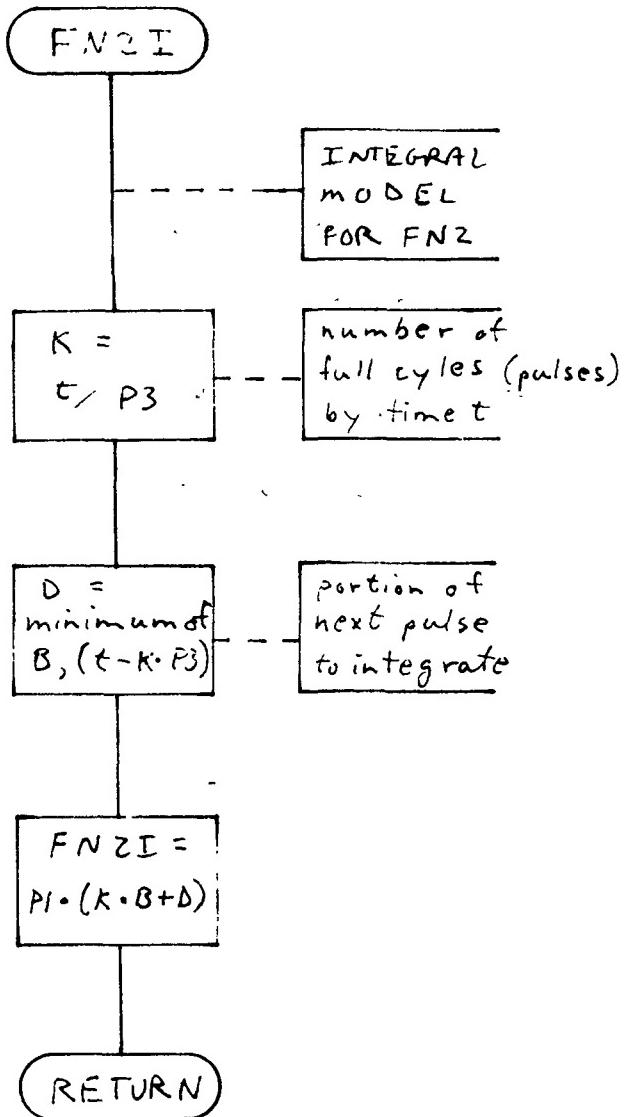
FLOW DIAGRAM

A-34



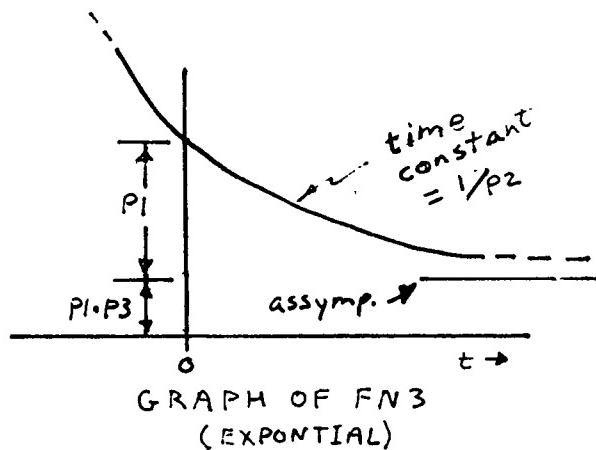
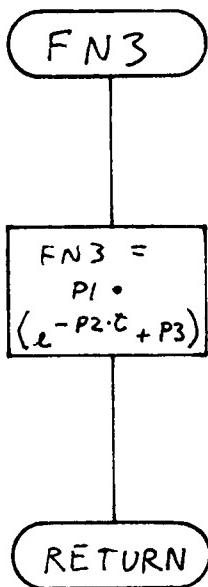
FLOW DIAGRAM

A-35



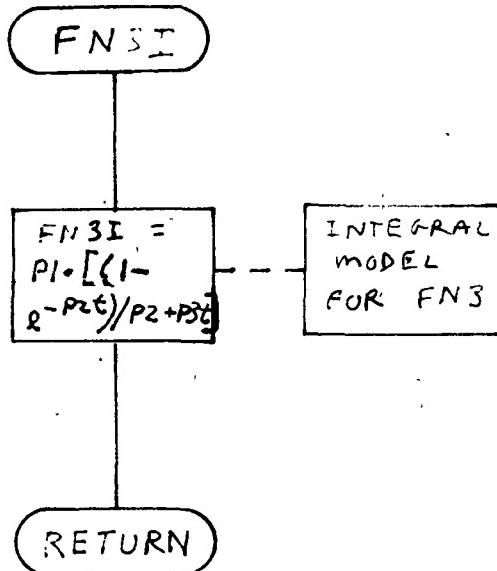
FLOW DIAGRAM

A-36



FLOW DIAGRAM

A-37



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APPENDIX B
PROGRAM SOURCE LISTING

PROGRAM CAHEZ{ INPUT=201, OUTPUT=201, TAPES=INPUT, TAPE6, OUTPUT}


```

      CALL READIN(NRS,DMFLG,IMES,LVARY,DVAL,DERUG)
C
C   CALCULATE ANY REQUESTED COVERAGE FACTORS, TO BE USED
C   AS INPUT FOR CURRENT RUN-SET
C
C   1+ (CUVPRC) CALL COVGLEN(NRS,NPROD)
C   IF(.NOT.(LVARY,AND,LSLCH)) GO TU 70
C   DO 50 K1=1,NPROD
C     XPAR=DVAL
C   50 DO 110=N1,N10
C     IF(CPAK((110,K1),ENQVAL,AND,XPAK,NE,DVAL))
C       PARAM((110,K1)=XPAK
C   60 XPAK=PARAM((110,K1))
C   70 IF(INPOUT) CALL RITERS(NRS,DMFLG,IMES,LVARY,DVAL,DEBUG)
C     IF(DBUG) GU TU 40
C     IF(.NOT.DMFLG) GO TU 85
C
C   CHECK THAT RESTRICTIONS ON INDEPENDENT VARIABLE
C   ARE MET IF DUAL MODE MODEL WILL BE USED
C
C   85 I+ (TIN) GU TU 80
C     WRITE(6,5000)
C     STOP
C   60 IF(MIN.EW,0,U) GO TU 85
C     WRITE(6,5001)
C     STUP
C   85 NG=0
C     NJEQ 0
C
C   DO LOOP FOR VARIATION OF PARAMETER OF INTEREST
C   BEGINS. FOR EACH RUN, THE PARAMETER VECTOR IS
C   REPLACED BY ONE ROW OF PARAM(16,10)
C
C   90 DO 110=N1,N10
C     I+ (LVARY) CALL PGET(IMES,110,NPROD)
C     SUMLAM=0.0
C
C   COMPUTE ANY REQUIRED DEPENDENT PARAMETERS FOR
C   EQUATIONS 1 THROUGH 7
C
C   100 DO 105 K1=1,NPROD
C     BCOMPS(K1)=MU(K1).LE.0.0
C     K(K1)=100000.
C     IF(BCOMPS(K1)) GU TU 101
C     K(K1)=LAM(K1)/MU(K1)
C     IF(K(K1).GE.100000.) HCOMPS(K1)=.T.
C   101 IF(K(K1).GT.NUN) GO TO 105
C     LQ(K1)=Q1(K1)-Q2(K1)
C     IF(LQ(K1).GE.0.0.RSGN) GO TO 102
C     RSGN=.T.
C     WRITE(6,3004)K1
C   102 SUMLAM=SUMLAM+LAM(K1)
C   103 DO 103 M=1,2
C     GM(K1,M)=GMP(K1)*(1.0-PPRC(K1,M))
C   105 CONTINUE
C     WRITE(6,5005)110
C   110 DO 120 J=1,JUIM
C   120 PDT(J)=1.0
C
C   DO LOOP FOR PRODUCT OF SYSTEM RELIABILITIES V.S.
C   TIME BEGINS. DUAL MODE RELIABILITY IS OUTPUT AS
C   THAT OF THE LAST STAGE OF THAT MODEL.
C
C   320 DO 320 K1=1,NPROD
C     IF (IPRODT) NEQ=PRND(K1)
C     BLUMPERCUMPS(K1)
C     IF (.NOT.DMFLG) GO TU 190
C
      MAINLOG 55
      FINAL 4
      FINAL 5
      FINAL 6
      FINAL 7
      MAINLOG 56
      MAINLOG 57
      MAINLOG 58
      MAINLOG 59
      MAINLOG 60
      MAINLOG 61
      MAINLOG 62
      MAINLOG 63
      MAINLOG 64
      MAINLOG 65
      MAINLOG 66
      MAINLOG 67
      MAINLOG 68
      MAINLOG 69
      MAINLOG 70
      MAINLOG 71
      MAINLOG 72
      MAINLOG 73
      CARE 137
      FINAL 10
      FINAL 9
      FINAL 8
      FINAL 7
      FINAL 6
      FINAL 5
      FINAL 4
      FINAL 3
      FINAL 14
      FINAL 15
      FINAL 16
      CARE 138
      MAINLOG 74
      MAINLOG 75
      MAINLOG 76
      MAINLOG 77
      MAINLOG 78
      MAINLOG 79
      MAINLOG 80
      MAINLOG 81
      MAINLOG 82
      MAINLOG 83
      MAINLOG 84
      MAINLOG 85
      MAINLOG 86
      MAINLOG 87
      MAINLOG 88
      MAINLOG 89
      MAINLOG 90
      MAINLOG 91
      CARE 139
      CARE 140
      FINAL 21
      FINAL 22
      FINAL 23
      FINAL 24
      CARE 141
      CARE 142
      MAINLOG 92
      MAINLOG 93

```

```

      IF(K1.LT.NUN) GO TO 320
      IF(K1.GT.NUN) GO TO 190
C
C     PREPARE TABLET OF RELIABILITY VALUES
C     FOR TIME DUAL MODE MODEL AND PRINT
C     MODE 1 REL FOR STAGES (OPTION)
C
C     IF(STGOUT) WRITE(6,3002)((STAGE,I),I=1,NUN)
C
C     DO 150 J=1,JMAX1
C        CLT=(J-1)*DMSTEP
C        CALL DCR(J,UNITH,REL1,DLRKL)
C        IP(37GOUT) WRITE(6,3005)CLT,REL1,(UNITH(I),I=1,NUN)
C
C     150 R(J,110)=DLRKL
C
C     190 RVLOC8=RVPLOT
C        WRITE(6,3006)K1,NEQ
C        IF(.NOT.(BCOMP.AND.ELATIN)) GO TO 194
C        WRITE(6,1003)
C
C     CALL EXIT
C
C     194 IF(.NOT.(BCOMP.AND.RVPLOT)) GO TU 198
C        RVLOC8=.FALSE.
C        WRITE(6,1005) NEQ
C
C     198 IF((HCUMP,UR,K(K1).GE.0.0) GU TU 200
C        WRITE(6,1050)K(K1)
C        GU TU 40
C
C
C     PREPARE TABLE OF RELIABILITY VALUES
C     FOR ONE EQUATION (NO,S 1 = 0)
C
C     200 IF(ELATIN) GO TU 204
C
C     201 IF(TIN) GU TU 201
C        WRITE(6,3007)
C        GU TU 210
C
C     201 WRITE(6,3008)
C        GU TU 210
C
C     204 WRITE(6,3009)
C     210 DO 315 J=1,JMAX1
C        CLT=(J-1)*STEP*MIN
C        IF(NTO,NT,7) GO TU 211
C        HDPBH(J,110)
C        TLAMT=CLT+SUMLAM
C        GO TO 295
C
C     211 IF(.NOT.ELATIN) GO TU 212
C        RL=CLT
C        IF(HL) 206,206,207
C
C     206 RS=0.0
C        GO TO 209
C
C     207 IF(HL.GT.,99999999)GO TO 208
C        IF(K(K1).LT.0.0) RS=RL**((1.0/K(K1)))
C        GU TU 209
C
C     208 RS=1.0
C
C     209 TLAMT=1.0
C        GU TU 228
C
C     212 TLAMT=CLT
C        IF(.NOT.TIN) GO TU 215
C        TLAMT=SLAM(K1)*CLT
C
C     215 RL=EXP(-TLAMT)
C        IF((K(K1).GT.0.0) RS=RL**((1.0/K(K1)))
C
C
C     COMPUTE RELIABILITY OF APPROPRIATE EQUATION
C
C     228 CALL RELEQS,NEQ,BCOMP,RL,RS,S(K1),W(K1),Q(K1),
C     * C(K1),RV(K1),Z(K1),W(K1),P(K1),TLAMT,RDP)
C
C     290 R(J,110)=RDP
C
C     *** COMPUTE UNRELIABILITY, SIMPLE RELIABILITY, ***
C     *** SIMPLE RIP, AND SIMPLE GAIN
C
C

```

```

295 CALL SIMPLE(ELATIN,TLMAT,RL,SIMPX(J),SIMPX(J),86,QI,RDP)
C
C   IF (.NOT.UOPT1) GO TO 310
C
C   WRITE RELIABILITY RESULTS
C
C   IF (ELATIN) GO TO 304
C   IF (TIN) GO TO 300
C   WRITE(6,1007)TLMAT,R(J,110),QI,SIMPX(J),9G,81MWF
C   GO TO 310
C
300 WRITE(6,1007)CLT,R(J,110),QI,SIMPX(J),3G,SIMRF
C   GO TO 310
C
304 WRITE(6,1008)RL,RS,R(J,110),GI,SG,SIMRF
C
C   *** COMPUTE ABSCESSA VALUES FOR PLOTS ***
C
310 ABSCE(J,1)=CLT
ABSCE(J,2)=TLMAT
ABSCE(J,3)=EXP(-TLMAT)
C
C   *** COMPUTE PRODUCT OF RELIABILITIES ***
PDT(J)=PDT(J)*R(J,110)
C
C 315 CONTINUE
NJ=NJ+1
IF(ELATIN) GO TO 318
IF(.NOT.OUTPUT4) GO TO 318
C
C   * CALL INTEGRATION ROUTINE TO COMPUTE *
C   * MTF AND THE RELIABILITY AT MTF   *
C   CALL INTEGH(TIN,BCOMP,LM(K1),MU(K1),S(K1),N(K1),K(K1),
Q(K1),C(K1),RV(K1),Z(K1),W(K1),P(K1),NEQB,MTF(NJ),FOFX(NJ))
PARMOD 27
C
C   COMPUTE TMAX, SIMTMX, AND SIMTIP
318 IF(OPTRA.0R.OPTR2) CALL SIMPR(TIN,BCOMP,LM(K1),S(K1),N(K1),
* K(K1),Q(K1),C(K1),RV(K1),Z(K1),W(K1),P(K1),NEQ,R2,RIMIN,
* RIMAX,RISTEP,PLOTTR1,OPTR1,110,TMAX)
C
C   CLT=MIN
ELATIN=.FALSE.
320 CONTINUE
C
C   END OF DO LOOP FOR PRODUCT OF RELIABILITY
C
C   IF (.NOT.(PRDT.AND.OUTPUT1)) GO TO 360
C
C   * WRITE TABLE OF VALUES FOR THE *
C   * PRODUCT OF RELIABILITIES   *
C   IF (TIN) GO TO 330
WHITE(6,2006)
GO TO 340
350 WRITE(6,2007)
340 CT*MIN
JP=1
350 WRITE(6,2008) CT,PDT(JP)
JP=JP+1
CTACT+YSTEP
IF (CT.LE.MAX) GO TO 350
C
360 IF(CRVLUS) CALL EQUAL(BCOMP,MU(K1),S(K1),N(K1),K(K1),Q(K1),
* C(K1),Z(K1),W(K1),P(K1),NEQ,110,RLRV,DELR)
IF (C110.EQ.1) GO TO 370
IF (R2OPT.EQ.1.AND.110.LT.N10) GO TO 364
C
C   COMPUTE TMAX1, TMAX2, AND RATIF
IF (OPTR2) CALL PARR1(R2,RIMIN,RIMAX,RISTEP,PLOTTR2,
C

```

```

      JOB 309
      CARE 310
      CARE 311
      CARE 312
      CARE 313
      CARE 314
      CARE 315
      CARE 316
      CARE 317
      CARE 318
      CARE 319
      CARE 320
      CARE 321
      CARE 322
      CARE 323
      CARE 324
      CARE 325
      CARE 326
      CARE 327
      CARE 328
      CARE 329
      CARE 330
      CARE 342
      CARE 343
      CARE 344
      CARE 345
      CARE 346
      CARE 347
      CARE 348
      CARE 349
      CARE 350
      CARE 351
      CARE 352
      CARE 353
      CARE 354
      CARE 355
      CARE 356
      CARE 357
      CARE 358
      CARE 359
      CARE 360
      CARE 361
      CARE 362
      CARE 363
      CARE 364
      CARE 365
      POSTPCH 3
      POSTPCH 4
      MAINLOG 131
      MAINLOG 132
      MAINLOG 133
      MAINLOG 134
      MAINLOG 135
      MAINLOG 136
      MAINLOG 137
      MAINLOG 138
      MAINLOG 139
      MAINLOG 140
      MAINLOG 141
      MAINLOG 142
      MAINLOG 143
      MAINLOG 144
      MAINLOG 145

      K2UPT,I10,TMAX)
      364 IF (IPTION,EQ,1,AND,I10.LT.N10) GO TO 370
      IF(POUT) GO TO 370
      C
      C *** COMPUTE DIFF, RIP, AND GAIN ***
      IF (OPTION,NE,2) NGB0
      CALL RIFDIF (I10,OPTION,IRES,N10,TIN,MIN,MAX,STEP,JDIM,R,
      * DIFF,RIP,GAIN,NG,PLDT,GPLOT)
      IF (IPLT3,NE,1,OR,OPTION,EQ,2) GO TO 370
      IF (GPLOT) CALL PLNTG (NG,ABSC,XY,G,3,PARAM,K1,2)
      370 IF (IPLT1,EQ,1) CALL PLOTPD(I1,ABSC,XY,G,1,PARAM,K1,3)
      380 CONTINUE
      C
      C END UP DO LOOP FOR FAMILY OF PARAMETER
      C
      C IF(LVARY) CALL PGETLRES,1,NPHUD)
      IF (PRODT) GO TU 390
      IF (IPLT2,EG,1,OR,IPLT5,EG,1) CALL PLDT (N10,ABSC,XY,G,3,PARAM,
      * K1,1)
      * IF (IPLT3,EQ,1,AND,OPTION,EQ,2) CALL PLDTG (NG,ABSC,XY,G,3,PARAM,
      * K1,2)
      * IF (IPLT4,EG,1) CALL PLDTPD (N10,ABSC,XY,G,3,PAWAM,K1,3)
      390 IF (NVPLOT) CALL PLOTRV (I10,DELRL)
      GO TO 40
      9999 STOP
      C
      C FORMAT STATEMENTS
      C
      C 1001 FORMAT (6A1)
      1002 FORMAT (60A1)
      1003 FORMAT (* T ON LAMT MUST BE GIVEN FOR THE EQUATION YOU SPECIFIED*,*
      * // ENTIRE DATA CASE IS TERMINATED*)
      1004 FORMAT (* THE VARIABLE THAT IS TO BE USED*,*
      * FOR THE FAMILY OF PARAMETERS IS*,* J1X, * PAR*,*6A1)
      1005 FORMAT (* RV VERSUS R PLUT NOT TO BE PERFORMED FOR THIS CASE*,*,/
      * SINCE CALCULATIONS ARE FOR THE B PART OF EQUATION *,12)
      1006 FORMAT (* INCORRECT TYPE FOR EQUATION *,12,* TRY ANOTHER*)
      1007 FORMAT (1H ,#P10.3, #P12.7, #E18.7)
      1008 FORMAT (( 1H ,#P7.5, #P4.5, #P2(2X,F10.7), #P2(2X,F16.7))
      1048 FORMAT (* DO YOU WISH TO SPECIFY ANOTHER PARAMETER*,*,/
      ** ANSWER YES OR NO*)
      1029 FORMAT (* TYPE IN NEW PARAMETER (FOR PRODUCT OF*,*
      ** RELIABILITY*) AS HEFUE*)
      1030 FORMAT (* IMPROPER VALUE FOR K = K = *,E14.6,*,/
      ** K MUST SATISFY 0.LE.K.LE.INFINITY*,*,/
      ** CALCULATIONS ARE NOT PERFORMED FOR THIS K VALUE*)
      1032 FORMAT (1H ,#60A1)
      2006 FORMAT (( /6X,*LAMT*,3X,*REL PRODUCT*)
      2007 FORMAT (( /6X,*T*,4X,*REL PRODUCT*)
      2008 FORMAT (1X,F10.3,F12.7)
      3000 FORMAT (10X,*FOR DUAL MODE MODEL, INDEP. VARIABLE MUST BE TIME*)
      * 25X,*JOB ABURTED*)
      3001 FORMAT (10X,*FOR DUAL MODE MODEL, TIME MUST START AT 0.0*)
      * 25X,*JOB ABORTED*)
      3002 FORMAT (//43X,*DUAL MODE SYSTEM RELIABILITY IN MODE 1*/4X,
      * *TIME*,6X,*SYSTEM REL. *,B(5,13,4X))
      3003 FORMAT (1X,F10.3,F12.7)
      3004 FORMAT (//25X,*WARNING -*/10X,*02 GREATER THAN Q1 *)
      * AFU STAGE*,15, * RSZN FORCED TO TRUE*)
      3005 FORMAT (1M1,49X,*RUN*,15, * RELIABILITY RESULTS*/49X)
      * 50X,*-----*)
      3006 FORMAT (//49X,*STAGE*,13,* EQUATION NUMBER*,12*)
      3007 FORMAT (6X,*LAMT*,7X,*REL*,8X,*UNREL*,7X,*SIMREL*,9X,
      * *SIMGAIN*,9X,*SMHIF*)
      3008 FORMAT (8X,7X,BX,*REL1BX,*UNREL1BX,*SIMREL1BX,*MAINLOG)
      * MAINLOG

```

```

MAINLOG 146
MAINLOG 147
MAINLOG 148
CARE 369
CARE 370
CARE 371
BISECT 1
BISECT 2
BISECT 3
BISECT 4
BISECT 5
BISECT 6
BISECT 7
BISECT 8
BISECT 9
BISECT 10
BISECT 11
BISECT 12
BISECT 13
BISECT 14
BISECT 15
BISECT 16
BISECT 17
BISECT 18
BISECT 19
BISECT 20
BISECT 21
BISECT 22
BISECT 23
BISECT 24
BISECT 25
BISECT 26
BISECT 27
BISECT 28
BISECT 29
BISECT 30
BISECT 31
BISECT 32
BISECT 33
BISECT 34
BISECT 35
BISECT 36
BISECT 37
BISECT 38
BISECT 39
BISECT 40
BISECT 41
BISECT 42
BISECT 43
BISECT 44
BISECT 45
BISECT 46
BISECT 47
BISECT 48
BISECT 49
BISECT 50
BISECT 51
BISECT 52
BISECT 53
BISECT 54
BISECT 55
BISECT 56
BISECT 57
BISECT 58
BISECT 59
BISECT 60

      *SIMGAIN*,YX,*SIMWIRE*)
1009 FORMAT(2X,*ELAMT*,EX,*EMUT*,QX,*REL*,BX,*UNREL*,QX,
      *SIMGAIN*,10X,*SIMRIF*)
```

C

```

END
SUBROUTINE BISECT( NEQ,BCOMP,S,N,K,Q,C,RY,Z,W,P,FIRST,LAMT,R)
INTEGER NEQ,3,N,Z,W,ITER,ITMAX
LOGICAL BCUMP,FIRST
```

C

```

REAL K,LAMT,INF
```

C ****

C THIS SUBROUTINE COMPUTES *
C LAMT FOR GIVEN RELIABILITY *
C USING REGULA FALSI METHOD *
C ****

C

```

DATA TWO/2.0/, INF/1.0E35/, TOL/1.0E-4/, ITMAX/40/
ITER=1
IF (R) 5,10,30
5  WRITE (6,1005)
WRITE (6,1004)
RETURN
10 IF (FIRST) GO TO 20
LAMT=INF
RETURN
20 WRITE (6,1001)
WRITE (6,1004)
RETURN
30 IF (R=1.0E0) 60,50,40
40 WRITE (6,1002)
WRITE (6,1004)
RETURN
50 LAMT=0.
RETURN
60 LAMT=10.0
70 RL=EXP(-LAMT)
IF(K .EQ. 0.0) K=1.0
R=RL*(1.0/K)
C   OBTAIN RELIABILITY FOR UPPER BOUND FOR LAMT
CALL RELEQS (NEQ,RCOMP,RL,RS,S,N,K,Q,C,RY,Z,W,P,LAMT,REL)
C
DIF=REL-R
IF ( ABS(DIF).LT.TOL) RETURN
IF (UIF) 80,90,100
```

C

```

C   UPPER BOUND IS ATTAINED FOR LAMT
80 X2=LAMT
Y2=DIF
GO TU 105
C
90 RETURN
C
100 LAMT=TWO*LAMT
GO TU 70
C
C   LOWER BOUND FOR LAMT IS 0.000
105 LAMT=0.0
X1=LAMT
C
R=EXP(-LAMT)
C   OBTAIN RELIABILITY FOR LOWER BOUND FOR LAMT
CALL RELEQS (NEQ,RCOMP,RL,RS,S,N,K,Q,C,RY,Z,W,P,LAMT,REL)
C
```

```

YIELREL=H
C   INTERPOLATE FOR NEW VALUE OF LAMT BY REGULA FALSI METHOD
C   110 LAMT=(X1*Y2-X2*Y1)/(Y2-Y1)
      RL=EXP(-LAMT)
      IF (.NOT.BCOMP) RSLBL**=(1.0E0/K)
C   OBTAIN RELIABILITY FOR NEW LAMT
      CALL RELEOS (NEO,RCOMP,RL,R,S,N,K,Q,C,RV,Z,W,P,LAMT,REL)
      DIF=REL-R
C   CONVERGENCE TEST
      IF ( ABS(DIF).LE.TOL) RETURN
C   ITHM=ITER+1
C   TEST FOR MAX NUMBER OF ITERATIONS EXCEEDED
      IF (ITER.LE.ITMAX) GO TO 120
      WRITE(6,1003)
      RETURN
C   120 IF (DIF*Y2) 130,130,140
      130 X1=X2
      Y1=Y2
      X2=LAMT
      Y2=DIF
      GO TO 110
      140 X2=LAMT
      Y2=DIF
      GO TO 110
C   1001 FORMAT(* REFERENCE POINT/R2 MUST BE GREATER THAN 0.0*)
      1002 FORMAT(* R1 OR R2 MUST BE LESS THAN OR EQUAL TO 1.0*)
      1003 FORMAT (* CONVERGENCE PROBLEM WHEN CALCULATING MAXIMUM MISSION*
     * TIME*)
      1004 FORMAT (* MAXIMUM MISSION TIME IS NOT CALCULATED FOR THIS CASE*)
      1005 FORMAT (* R1 OR R2 CAN NOT BE NEGATIVE*)
C   END
      SUBROUTINE EQUAL (BCOMP,MU,S,N,K,Q,C,Z,W,P,NEG,I10,RLRV,DELRL)
      C   *****
      C   * THIS SUBROUTINE CALCULATES THE
      C   * LOCUS OF RV SUCH THAT THE SYSTEM
      C   * RELIABILITY EQUALS THE UNIT
      C   * RELIABILITY, R.
      C   *
      C   * *****
      C   REAL RLRV(1,2)
      C   REAL KMU
      C   INTEGER S,N,W,Z
      C   LOGICAL BCUMP
      C   DATA HVLAMT/1.0E0/
      C   DELRL=5.0E-3
      C   RVT=1.0
      C   RL1=1.0E-10
      C   J=1
      C   JT=1
      C   WRITE (6,1001)
      C   10 1+ (K**NE-0.0 ) H3RLBL*(1.0 /K)
      C   CALL RELEOS (NEO,BCOMP,RL,R,S,N,K,Q,C,RVT,1,1,P,RLVLMT,EXPR)
      C   RLRV(J,1)=RL*(1.0/(W*Z))/EXPR
      C   IF (J.T.LE.20) GO TO 110
      C   WRITE (6,1002) RLRV(J,1),RLRV(J,1),RLRV(J,110+1)
      C   JT=1
      C   *****
      C   EQUAL 1
      C   EQUAL 2
      C   EQUAL 3
      C   EQUAL 4
      C   EQUAL 5
      C   EQUAL 6
      C   EQUAL 7
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      C   CRUSH 1
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110 J=J+1
111 JT=JT+1
112 RL=RL+DELRL
113 IF (RL,LT.1.00000001 ) GO TO 20
114 RETURN
115
116 1001 FORMAT (//,SX,*EXP(-LAHT)*,7X,*RV*)
117 1002 FORMAT (SX,FB,5,SX,E14.5)
118 END
119
120 FUNCTION FFAC(K)
121 *****
122 C
123 C * THIS FUNCTION COMPUTES FACTORIALS. *
124 C
125 C ***** THIS FUNCTION GIVEN PARAMETER K WILL COMPUTE K FACTORIAL.
126 C TO USE THIS FUNCTION STATE FFAC(K).
127 C IF (K) 20,40,40
128 C
129 C DEFINE FACTORIAL OF A NEGATIVE NUMBER TO BE 1,000
130 C
131 20 FFAC=1.0
132 C
133 40 RETURN
134 C
135 40 IF (K=1) 60,60,70
136 C
137 60 FFAC=1.0
138 C
139 60 RETURN
140 C
141 70 IF (K=12) 75,75,85
142 C
143 75 IF ACSEK
144 C
145 L=K=1
146 C
147 K=K-1
148 C
149 IF AC=IFAC*KF
150 C
151 60 CONTINUE
152 C
153 FFAC=IFAC
154 C
155 RETURN
156 C
157 65 FFAC*K
158 C
159 L=L-1
160 C
161 DU 90 I=1,L
162 C
163 Y=1
164 C
165 FA=K-1
166 C
167 FFAC=FFAC+F
168 C
169 90 CONTINUE
170 C
171 RETURN
172 C
173 END
174
175 FUNCTION FNCK(NFACT,KFACT)
176 *****
177 C
178 C * THIS FUNCTION COMPUTES BINOMIAL COEFFICIENTS. *
179 C
180 C ***** THIS FUNCTION GIVEN TWO PARAMETERS N,K
181 C WILL COMPUTE NCK I.E. NFACT/(N-K)FACT * KFACT
182 C THIS IS EQUIV. TO N*(N-1)...*(K+1)/(N-K)FACT.
183 C TO USE THIS FUNCTION STATE FNCK(N,K).
184 C NMINK=FNCK*KFACT
185 C
186 C IF (KFACT) 20,30,60
187 C 60 IF (NMINK) 20,30,40
188 C 20 WRITE(6,100)
189 C 100 FORMAT (22H ILLEGAL COMBINATORIAL )
190 C
191 C GO TO 50
192 C
193 C 30 FNCK=1
194 C 30 GO TO 50
195 C
196 C 40 Y=KFACT+1
197 C 40 Z=1
198 C
199 C FNCK=1
200 C
201 C 10 IF (I>1,NMINK
202 C FNCK=FNCK*(Y/Z)
203 C 14 FNCK
204 C 15 FNCK
205 C 16 FNCK
206 C 17 FNCK
207 C 18 FNCK
208 C 19 FNCK
209 C 20 FNCK
210 C 21 FNCK
211 C 22 FNCK
212 C 23 FNCK

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L1#Z1+1.
10  CONTINUE
50  CONTINUE
RETURN
END
SUBROUTINE INTEGR (TIN,BCOMP,LAMBDA,MU,S,N,K,Q,C,RV,Z,W,P,NEQ,U,
     MTF,FOFX)
C
C ****
C   * THIS SUBROUTINE COMPUTES THE *
C   * MEAN TIME TO FAILURE = MTF *
C   * AND THE RELIABILITY AT MTF *
C   *
C ****
C
REAL K ,MTF
REAL LAMBDA,MU
INTEGER N,S,Z,W
LOGICAL TIN,BCOMP,TESTG
COMMON /OUTPT1/ OUTPT2,OUTPT3,OUTPT4,OUTPTS
COMMON /OUTPT/ OUTPT1,OUTPT2,OUTPT3,OUTPT4,OUTPTS
TESTG=.FALSE.
A=0.0
MSTAR=0.01
MIN=0.0001
MAX=10.0
ERMAX=1.0E-6
KEY=0
PMTFB=0.0
DdB
IF (B.NE.0.0 ) GO TU 3
C
C *** INPUT UPPER LIMIT OF INTEGRATION ***
C *** IF IT WAS NOT INPUTED IN SVAR ***
C
      WRITE (6,1000)
1 READ(S,1001) B1
2 IF (OUTPTS) WRITE (6,1005) B1
      DdB
C
C *** CALL ROMBERG INTEGRATOR ***
3 CALL RUMBD (A,D,X1,FUFX,MSTAR,MIN,MAX,ERMAX,MTF,K1,KEY)
5 X=X1
IF (TIN) X=LAMBDA*X1
HL= EXP(-X)
IF (K.NE.0.0 ) RS= EXP(-X/K)
CALL RELEQS (NEQ,BCOMP,RL,RS,S,N,K,Q,C,RV,Z,W,P,X,POPX)
IF (TESTG) GO TO 90
CALL ROM2D(A,D,X1,FDFX,MSTAR,MIN,MAX,ERMAX,MTF,K1,KEY)
IF (K1.EQ.1) GO TO 5
MTF=MTF+PMTF
REL=ABS(MTF-PMTF)/ MAX1(ABS(MTF),1.0)
IF (REL.LT.1.0E-8) GO TO 80
IF (U.GT.1.0E24) GO TO 80
PMTFB=MTF
AND
D=1.5E0*D
GO TU 3
60 IP (OUTPT4) WRITE (6,1002) MTF,D
X=LAMTF
TESTG=.TRUE.
GO TO 5
90 IP (OUTPT4) WRITE (6,1004) FOFX
RETURN
9999 STOP
C   * THE INTEGRATION UPPER LIMIT =B= WAS NOT INPUTTED INNE/ /
1000 FORMAT (A)

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63      *,*, NAMELIST VAMN. THE VALUE OF -B- IS EXPECTED AND MUST BE "", //
64      *   * LE = 1.0E24 AND .GT. 0.0*)
65
66 1001 FORMAT (F20.0)
67 1002 FORMAT (/* MEAN TIME TO FAILURE = MTF = *,E15.0,/,/
68      *  UPPER LIMIT FOR INTEGRATION = B = *,E15.0)
69 1004 FORMAT (* RELIABILITY AT MTF = *,E15.0)
70 1005 FORMAT (1H ,F20.5)
71
72      END
73
74      SUBROUTINE NEO2A (RL,RS,S,K,Q,RV,Z,W,P,LAINT,R,C)
75
76      C *****
77      C
78      C   * THIS SUBROUTINE COMPUTES THE
79      C   * RELIABILITY FOR EQUATION 2A
80      C
81      C *****
82
83      REAL K,LAINT
84      INTEGER I,S,L,W
85      SUM=0.0
86      IF (LAINT.NE.0.0 ) GO TO 5
87      R=RV*(W/Z)
88      RETURN
89
90      5 IF (S.NE.0) GO TO 7
91      R=((RL**((Q/W)))*RV)**(W/Z)
92      RETURN
93
94      7 DO 10 I=1,B
95      SUM=SUM+(C*(1.0-H*S**((1.0/W)))*I)/FFAC(I)*PROD(J,I=1,Q,K)
96      R=(RV*(HL**((Q/W)))*(1.0+SUM))*((W/Z))
97      RETURN
98
99      END
100     SUBROUTINE NEO2B (RL,LAINT,S,RV,Z,W,P,R,C,Q)
101
102     C *****
103     C
104     C   * THIS SUBROUTINE COMPUTES THE
105     C   * RELIABILITY FOR EQUATION 2B
106     C
107     C *****
108
109     REAL LAINT
110     INTEGER S,L,W
111     SUM=0.0
112     IF (LAINT.NE.0.0 ) GO TO 5
113     R=RV*(W/Z)
114     RETURN
115
116     5 IF (S.NE.0) GO TO 7
117     R=((RL**((Q/W)))*RV)**(W/Z)
118     RETURN
119
120     7 DO 10 I=1,B
121     SUM=SUM+(((LAINT+C*Q)/W)**I)/FFAC(I)
122     R=(RV* EXP((-(LAINT+Q)/W)*(1.0+SUM))**((W/Z)))
123     RETURN
124
125     END
126     SUBROUTINE NEO1A (HL,RS,S,N,K,RV,Z,W,P,LAINT,R)
127
128     C *****
129     C
130     C   * THIS SUBROUTINE COMPUTES THE
131     C   * RELIABILITY FOR EQUATION 1A
132     C
133     C *****
134
135     REAL LAINT,K,L,S
136     INTEGER S,RS,E,I,N,W,I2 ,S22
137     SUM=0.0

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      SUM1=0.
      SUM2=0.0
      SUM3=0.0
      S2=S-2
      IF (LAHT,NE.0.0) GO TO 3
      R=RV*(W-Z)
      RETURN
  3   ETAK$=ETA^K+S
      HAMRRL=(1.0/W)
      HMURR$=(1.0/W)
      IF (S=1) 5,20,50
      5   R=0.0
      NN=N+1
      DO 10 IX=1,NN
      10  R=R+FNC(K(ETA,I)*(1.0-HAM)*I*RLAM*(ETA=1))
      R=R*(R*RV)*(W-Z)
      RETURN
  20  NN=N+1
      DO 40 IX=1,NN
      21  IX=1
      SUM=0.0
      I=I+1
      DO 30 LX=1,II
      22  LX=1
      30  SUM=SUM+FNC(K(I,L)(I=1)*(1.0/(RMU*RLAM*EL))=1.0)/(K=1,0)
      40  SUM1=SUM + FNC(K(ETA,I))*SUM
      R=RLAM*(ETA*RMU)*(1.0*(ETA^K+1.0)*SUM)
      R=R*(R*RV)*(W-Z)
      RETURN
  50  NN=N+1
      DO 60 IX=1,NN
      51  IX=1
      I=I+1
      SUM1=0.0
      DO 70 LX=1,II
      52  LX=1
      SUM2=0.0
      K1$=K$+S
      S2=S2+1
      DO 60 JX=1,S22
      53  J=JX-1
      60  SUM2=SUM2+RCOMB(KL,8,J+1)*(1.0/RMU=1.0)**(J+1)
      70  SUM1=SUM1+FNC(K(LI)*(J+1)*(1.0/(RMU*RLAM*EL))=1.0=SUM)
      *  RCOMB(KL,S)
      80  SUM=SUM+FNC(K(ETA,I))*RCOMB(ETAK,S)*SUM
      92  S2=S2+1
      DO 90 JX=1,S22
      93  J=JX-1
      90  SUM3=SUM3+RCOMB(ETAK$,(J+1)*(1.0/RMU=1.0)**(J+1))
      R=RLAM**ETA*RMU*(1.0*SUM3+SUM)
      R=R*(R*RV)*(W-Z)
      RETURN
      END
      SUBROUTINE NE01B (RL,S,N,RV,Z,w,PLAMT,R)
      ****
      * THIS SUBROUTINE COMPUTES THE *
      * RELIABILITY FOR EQUATION 1B *
      ****
      REAL LAHT
      INTEGER S,N,Z,w,ETA,N2,S1 ,BS

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12 IF (LAM1.NE.0.0 ) GO TO 10
13 K=RV*(w*z)
14 RETURN
15
16 ETA=N2+1
17 RLAM=HL+(1.0/w)
18 S1=S-1
19 SUM1=0.0
20 SUM2=0.0
21 SUM3=0.0
22 SUM4=0.0
23 IF ( S1) 20,30,60
24 DO 25 I=1,N
25 SUM1=SUM1+((1.0 -RLAM)*I)*(RLAM*(ETA-I))*FNCK(ETA,I)
26 CONTINUE
27 R=RV*SUM1**(w+z)
28 RETURN
29 DO 50 I=1,N
30 SUM2=0.0
31 DO 40 J=1,I
32 40 SUM2=SUM2+FNCK(I,J)*(-1)**(I-J)*(1.0 /(RLAM+j)-1.0 )/J
33 50 SUM1=SUM1+FNCK(ETA,I)*SUM2
34 R=(RV*RLAM)*ETA*(1.0 +ETA*SUM1)**(w+z)
35 * +ETA*SUM1))**(w+z)
36 RETURN
37 DO 90 I=1,N
38 SUM2=0.0
39 DO 80 J=1,I
40 SUM1=0.0
41 DO 70 L=1,S1
42 70 SUM1=SUM1+RLAM*TAL/(FFAC(L)*J**S-L)
43 80 SUM2=SUM2+FNCK(I,J)*(-1)**(I-J)*(1.0 /(RLAM+j)-1.0 )/(J+z)
44 * -SUM1)
45 90 SUM3=SUM3+FNCK(ETA,I)*SUM2
46 SS=SS+1
47 DO 100 IX=1,SS
48 100 SUM4=SUM4+(ETA*PLAMT)**I/FFAC(I)
49 R=(RV*RLAM)*ETA*(SUM4*(ETA*LAHT)+S*(-1)**N*FNCK(N2,N)/FFAC(S)+*
50 * ETA**S*SUM4)**(w+z)
51 RETURN (* IMPROPER INPUT FOR S = S CANNOT BE LESS THAN 1*)
52 1001 FORMAT (* THIS SUBROUTINE COMPUTES THE *
53 * RELIABILITY FOR EQUATION 3 *
54 END
55 SUBROUTINE NEGS (RL,R9,S,K,Q,C,RV,Z,W,P,BCOMP,LAHT,R)
56 *****NEGS*****
57
58 * THIS SUBROUTINE COMPUTES THE *
59 * RELIABILITY FOR EQUATION 3 *
60 *****NEGS*****
61
62 REAL K,PLAMT
63 INTEGER I,S,Z,W,SS
64 LOGICAL BCUMP
65 IF (C.LT.1.0 .AND. C.GT.0.0 ) GO TO 5
66 WRITE (6,1000) (
67 10 TO 40
68 5 IF (LAM1.NE.0.0 ) GO TO 7
69 R=RV*(w+z)
70 SUM=0.0
71 39=S+1
72 DU 10 I=X=1,SS
73 RETURN
74

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10 SUM=SUM+FNCK(S,I)+C*I*((1.0-C)**(D-I))
11 IF (BCOMP) GO TO 20
12 CALL NEQ2A (HL,RJ,S,K,Q,RV,Z,W,P,LAHT,R)
13 GO TO 30
14 CALL NEQ2B (LAHT,S,RV,Z,W,P,R)
15 30. RS(BUM,R)=Z
16 40 RETURN
17 1000 FORMAT (* IMPROPER INPUT FOR C = C = **E15.8,/)
18 ** MUST HAVE 0.LT.C.LT.1*)
19 END
20 SUBROUTINE NEQ2A (RL,HS,S,K,RV,Z,W,P,LAHT,R)
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      Y1=R(K(1,1,10))
      Y2=R(K(J,1,10))
      Y3=R(K(1,J,10))
      Z1=Y1-2*X2+Y3
      Z2=2.0*STEP+Z1
      A=Z1/22
      Z3=(Y3-Y1)/(2.0*STEP)
      B=Z3-2.0*A*X2
      C=X2*B+Z2-B*X2
      D=C+A*B+C
      IF(DCR.LT.0.0.UR.DCR.GT.1.0) GO TO 100
      RETURN
100  WRITE(*,11)
      11 FORMAT(72DX,*ERRUR IN EQUATION 7 INTERPOLATION*)
      STOP.
      END.
      SUBROUTINE PARAH1 (R2,R1MIN,R1MAX,R1STEP,PLOTR2,R2OPT,II0,TMAX)
      ****
      * THIS SUBROUTINE COMPUTES THE *
      * RATIO OF MAX. MISSION TIMES *
      * (RATIF) FOR THE VARIOUS SYSTEMS *
      * PARAMETERS SPECIFIED. *
      ****
      DIMENSIONIUN PARAM(16,10)
      REAL COMRI(101,4),TMAX1(101),TMAX2(101),RATIF(101)
      REAL TMAX(101,15),XAXIS(101)
      REAL INF(4),INFI,NITY
      REAL ENC(20),AJ
      INTEGER PROD,PAR(6),NPRED,NEQ,N10,K1,II0,R2OPT
      LOGICAL PRODT,RESULT,PLOTR2,NOPLOT
      LOGICAL OUTPT1,OUTPT2,OUTPT3,OUTPT4,OUTPTS
      COMMON/GGRAPH/ NEQ,PROD,NPRED,PAR,ENC,AB,PRODT
      COMMON /PARM/ PARAM,N10,K1
      COMMON /OUTPT/ OUTPT1,OUTPT2,OUTPT3,OUTPT4,OUTPTS
      COMMON/CPLOT/COMRI
      EQUIVALENCE (COMRI(1,1),XAXIS(1)), (COMRI(1,2),TMAX1(1)),
      (COMRI(1,3),TMAX2(1)), (COMRI(1,4),RATIF(1))
      DATA INF/4MINF/,NITY/4MINITY/
      DATA ITEST1/1/
      DATA NPT/10/
      NPLOT=0
      NUPLOTS=TRUE.
      IF (R2OPT.EQ.1) GO TO 30
      IF (R2OPT.EQ.3) GO TO 10
      IR2=II0
      IR1=II0-1
      GO TO 60
      60  WRITE (6,1001) PAR
      100 READ(5,1002) IR1,IR2
      101 IF (OUTPT3) WRITE (6,1003) IR1,IR2
      102 IF (IR1.LE.II0.AND.IR2.LE.II0) GO TO 60
      WRITE (6,1004)
      STOP.
      30  IR1=0
      40  IR1=IR1+1
      41  IF (IR1.EQ.N10) GO TO 130
      42  IR2=IR1
      43  IR2=IR2+1
      44  IF (IR2.GT.N10) GO TO 40
      45  IF (OUTPT5) WRITE (6,1005) PAR,PARAM(IR1,K1),PAR,PARAM(IR2,K1),
      46  * NEQ,AB,R2
      47  R1=R1MIN
      48  PARAR1
      49  PARAR1
      50  PARAR1
      ****
      FINAL 6
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      J=J+1

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XAXIS(J,J,0)
IF (CR1.NE.0.0) GO TO 100
ENCODE(8,1006,TMX(1)) INF1,NITY
ENCODE(H,1005,TMX(3)) INF1,NITY
TMAX1(J)=TMAX(J,IR1)
TMAX2(J)=TMAX(J,IR2)
RATIF(J)=1.0
LU TU 110
100 ENCODE (14,1007,TMX(1)) TMAX(J,IR1)
ENCODE (14,1007,TMX(3)) TMAX(J,IR2)
TMAX1(J)=TMAX(J,IR1)
TMAX2(J)=TMAX(J,IR2)
IF ((TMAX(J,IR1).NE.0.0) GO TO 105
RATIF(J)=1.0
GO TU 110
105 RATIF(J)=TMAX(J,IR2)/TMAX(J,IR1)
110 IF (OUTPT5) *WRITE (6,1008) R1,(TMX(I),I=1,4),RATIF(J)
      R1B*W1STE P
      IF (R1.LE.HIMAX) GO TO 90
      IF (.NOT.PLOTR2) GO TO 116
      IF (NNT.LE.15) GO TO 114
      IF (NOPLUT) *WRITE (6,1009)
      NUPLOT=.FALSE.
      GO TU 118
114 NPLT*NPLT+1
      CALL PLOT(J,2)
116 IF (R2OPT.EQ.1) GO TU 50
130 IF (PLOTR2) *WRITE (6,1014) NPLT,
      RETURN
1001 FORMAT (* IF MAXIMUM MISSION TIME IS WANTED FOR PARAMETER *,6A1,/,PARA1
      * INPUT T1 IN COLUMNS 1=2 AND T2 IN COLUMNS 3=4*,/,PARA1
      * OTHERWISE INPUT NO IN COLUMNS 1=2*)
1002 FORMAT (2I2)
1003 FORMAT (1H ,2I2)
1004 FORMAT(*1 OR T2 HAS NOT BEEN CALCULATED YET - TRY AGAIN*)
1005 FORMAT(*// MAXIMUM MISSION TIME FOR *,6A1,* ,G14.7,/,PARA1
      * AND *,6A1,* = *,G14.7,* FOLLOWS FOR EQUATION *,I2,A6,/,PARA1
      * 15X,*REFERENCE R2 = *,F7.5,* /4X,*R1*,9X,*TMAX1*,/
      * 20X,*TMAX2*,18X,*RATIF*)
1006 FORMAT(2A4)
1007 FORMAT(E14.7)
1008 FURMATE(1H ,F7.5 2(4X,2A10),3X,E14.7)
1009 FORMAT (* A MAXIMUM OF 15 PLOTS HAS BEEN GENERATED FOR MAXIMUM*,/,PARA1
      * MISSION TIME CALCULATIONS - NO MORE PLOTS TO BE GENERATED*,/,PARA1
      * FOR THESE CALCULATIONS*)
1014 FURMATE(/42X,* TMAX1(A),TMAX2(B),RATIF(C) VS R1(XAIS)* /
      *40X,I2,* MAXIMUM MISSION TIME PLOT(S) FOR VARYING *,/40X,*
      * PARAMETER VALUEZ COMPLETED*)
END
SUBROUTINE PLOTRV(110,DELRL)
*****C
*****C
*****C   THIS SUBROUTINE PLOTS THE
*****C   LOCUS OF RV SUCH THAT THE
*****C   SYSTEM RELIABILITY EQUALS
*****C   THE UNIT RELIABILITY, R.
*****C
*****C COMMON /CHAFF/XAXIS(1),YAXIS(1,1),PSYMBL(16)
*****C NPTPS1.0 /DELRL
*****C CALLPLOTIN110=1,NPTP+1,50,XAXIS,YAXIS,PSYMBL,16,210,F.)
*****C CALL ROWPLT
*****C      WRITE (6,1000)
*****C RETURN
*****C 1000 FORMAT(/40X,* RV VS R PLUT COMPLETED*)
END

```

```

C PFUNCTION KLUMB (LCOMB,RCOMB)
C *****
C      * THIS FUNCTION COMPUTES THE *
C      * GENERALISED BINOMIAL *
C      * COEFFICIENTS (THOSE NOT *
C      * NECESSARILY HAVING INTEGER *
C      * VALUES).
C *****
C      INTEGER BCUM
C      PROTE1.0
C      TCOMT=TCUM
C      INT=TCUM-BCUM
C      IF (INT) 10,30,30
C      10 WRITE (6,1000)
C      CALL EXIT
C      30 DO 40 I=1,BCUM
C      PROT=PROT+TCUMT
C      40 TCOMT=TCOMT-1.0
C      RCOMB=PROT/FFAC(RCOMB)
C      RETURN
C 1000 FFORMAT (* ERROR IN COMBINATORIAL - CHECK INPUT*,/,,
C      * PROGRAM IS TERMINATED*)
C      END
C
C      FUNCTION PROD (LIM1,LIM2,Q,K)
C *****
C      * THIS FUNCTION CALCULATES *
C      * SPECIAL PRODUCT FACTORS *
C      * FOR THE COMPUTATION OF *
C      * RELIABILITY EQUATIONS.
C *****
C      REAL K
C      PROD=1.0
C      DO 10 J1=LIM1,LIM2
C      10 PROD=(J1+Q*K)*PROD
C      RETURN
C      END
C
C      FUNCTION PROD1 (LIM1,LIM2,Q,K,DEN)
C *****
C      * THIS FUNCTION CALCULATES *
C      * SPECIAL PRODUCT FACTORS *
C      * FOR THE COMPUTATION OF *
C      * RELIABILITY EQUATIONS.
C *****
C      REAL K
C      PROD1=1.0
C      DO 10 J1=LIM1,LIM2
C      10 PROD1=PROD1*(Q*K+J1)/(DEN+J1)
C      RETURN
C      END
C
C      SUBROUTINE PLOTR (KC,ABSC,XY,G,PLOT,PARAM,K1,IPLT)
C *****
C      * THIS SUBROUTINE IS A DRIVER *
C      * FOR THE PLOT ROUTINE = PLOTN *
C *****
C      REAL MTF(16),FUFX(16),PARAM(16,10)
C      REAL MIN,MAX
C      REAL PDT(121),SIMPPX(121)

```

```

1      DIMENSION XY(1:4),XNAME1(2),XNAME2,XNAME3(1),XNAME4(2),
2      XNAME(2),YNAME(2)
3      REAL DIFF(1,1),RIF(1,1),GAIN(1,1),ADSGC(1,1),
4      GC(1,1),FDUM(1),R121,10)
5      INTEGER IDUM(1),PLUT
6      LOGICAL TINY,XHANGE,LUG
7      COMMON /PLUTIN/ TIN,MIN,MAX,STEP,DIFF,RIF,GAIN,MIF,FOPX,
8      *PUT,SIMPX,XMIN,XMAX,YMIN,YMAX,XHANGE,IA,IAA,IB,IBB,
9      *IC,ICC,IPLT1,IPLT2,IPLT3,IPLT4,IPLTS
10     COMMON /DUM/ IDUM,PDUM,R
11     COMMON /GRAFF/DUM(2),PSYMBL(16)
12     DATA JDIM/121/
13     DATA XNAME1(1),XNAME1(2),XNAME2,XNAME3(1),XNAME4(2),XNAME4(1),
14     *XNAME4(2),XNAME5,XNAME6,XNAME7,YNAME1,YNAME2,YNAME3,
15     *YNAME4,YNAME5,YNAME6,YNAME7,YNAME8,YNAME9,
16     *YNAME10,YNAME11,YNAME12,YNAME13,YNAME14,YNAME15,YNAME16,
17     *YNAME17,YNAME18,BMISSN,7M TIME,T,10MNORMAL,6MSIMPLEX,
18     *10MRELIABILITY,5MLG10,3MCT,6M(CLWT),10HEXP(*LAMT),9MPARAMETER,PLOT,
19     *10M,UN,4MDIFF,3MRIF,4MGAIN,10MGAIN,10MPRODUCT OP,3MHTF,6MAT MTF/
20     DU 10 I=1,2
21     10 XNAME(I)=YNAME(I)I=1,16
22     NPLT=0
23     NPTP=INT((MAX-MIN)/STEP)+1
24     IPLOTZ1
25     IPLOTZ2
26     IAATIAA
27     IHT=10b
28     ICCT=ICC
29     IF (IPLT2.NE.1) IPLT=2
30     GU 10 (30,40,50).IPLOT
31     PLOT
32     PLOT
33     PLOT
34     PLOT
35     PLOT
36     PLOT
37     PLOT
38     PLOT
39     PLOT
40     PLOT
41     PLOT
42     PLOT
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63     PLOT
64     PLOT
65     PLOT
66     PLOT
67     PLOT
68     PLOT
69     PLOT
70     PLOT
71     PLOT
72     PLOT
73     PLOT
74     PLOT
75     PLOT
76     PLOT
77     PLOT
78     PLOT

C      *** SET UP SIMREL CURVE FOR REL. PLOTS WMFN x-AXIS IS EXP(-LAMT)
C      KCEXP=KC+1
C      DN 38 J$1,JDIM
C      $B G(J,KCEXP)=SIMPX(J),
C      YNAME(1)=XNAME3(2),
C      YNAME(2)=10H(EWA,FOB,.
C      GO TO 170
C      40 IF (IPLT5.NE.1) GO TO 510
C
C      *** SET UP SIMREL CURVE FOR UNRELIABILITY PLOT ***
C      DU 45 I=1,KC
C      DO 45 J=1,JDIM
C      45 G(J,I)=1.0-H(J,I)
C      YNAME(1)=YNAME2
C      YNAME(2)=XNAME3(2)
C      GO TO 170
C      50 WRITE (6,1016) NPLT
C      RETURN
C
C      ****
C      * ENTRY FOR DIFF, MIF, *
C      * AND GAIN PLOTS *
C      *
C      ****
C
C      ENTRY PLUTG
C      KCEXP=KC+1
C      NPTP=INT((MAX-MIN)/STEP)+1
C      IAATIAA
C      IBB=10B
C      ICCT=ICC
C      NPLT=0

```

```

IPLU1=1
70 GO TU (80,90,100,110),IPLOT
C   *** SET UP INFORMATION FOR DIFFERENCE PLUT ***
C
80 DO 85 I=1,KC
81   DU 85 J=1,JDIM
82     DO 85 J=1,JDIM
83       G(J,I)=DIF(J,I)
84         YNAME(1)=SM
85           YNAME(2)=YNAME3
86             YNAME(2)=YNAME3
87               GU TU 170
88
C   *** SET UP INFORMATION FOR RELATIVE IMPROVEMENT FACTOR PLOT ***
C
90 DO 95 I=1,KC
91   DU 95 J=1,JDIM
92     G(J,I)=RIF(J,I)
93       YNAME(1)=H
94         YNAME(2)=YNAME4
95           GU TU 170
96
C   *** SET UP INFORMATION FOR GAIN PLOT ***
C
100 DU 105 I=1,KC
101   DU 105 J=1,JDIM
102     G(J,I)=GAIN(J,I)
103       YNAME(1)=H
104         YNAME(2)=YNAME5
105           GU TU 170
106             NPLT
107               RETURN
108
C   **** ENTRY FOR MTF, RELIABILITY AT MTF,
C   * AND PRODUCT OF RELIABILITIES PLOTS *
C
110 *****

ENTRY PLUTPD
KCEXP=KC+1
IAAT=IAA
IBBT=IBB
ICCT=ICC
NPLT=0
IPLOTE1
IT (PLOT,NE,J) IPLOTE3
120 CONTINUE
GU TU (150,140,150,160),IPLOT
C
C   *** SET UP INFORMATION FOR MEAN TIME TO FAILURE PLOT ***
C
130 DO 135 I=1,KC
131   G(I,I)=MTF(I)
132     YNAME(1)=H
133       YNAME(2)=YNAME7
134         GU TU 500
135
C   *** SET UP INFORMATION FOR RELIABILITY AT MTF PLOT ***
C
140 DU 145 I=1,KC
141   ABSC(1,1)=MTF(1)
142     G(I,I)=FU(X(I))
143       YNAME(1)=NAME1(2)
144         YNAME(2)=NAME8
145           GU TU 300
146             IF (IPLT1,NE,1) GO TU 510
C
C   *** SET UP INFORMATION FOR PRODUCT OF RELIABILITIES PLOT ***
C
155 DU 155 J=1,JDIM
156   G(J,I)=PDT(J)

```

```

NPTP= INIT(MAXMIN)/SYE*+1          145
PLOTR 145
PLOTR 146
PLOTR 147
PLOTR 148
PLOTR 149
PLOTR 150
PLOTR 151
PLOTR 152
PLOTR 153
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PLOTR 210

      IF (IAA.NE.1) GO TO 210
C
C     *** SET UP INFORMATION FOR PLOTS WITH ***
C     *** ABSCISSA T OR LOG(T) = BASE 10 ***
C     XNAME(1)=XNAME1(1)
C     XNAME(2)=XNAME1(2)
C     LOG=.FALSE.
C     GO TO 200
C     XNAME1(1)=XNAME4(1)
C     XNAME1(2)=XNAME4(2)
C
C     200 CALL PLUTN(KC,NPTP,50,XY,G,PSYMBL,16,121,LOG)
C
C     *** PRINT DATA BELOW PLOT ***
C     WRITE(6,205) (YNAME(KL),KL=1,2), (XNAME(KL),KL=1,2)
C     205 FORMAT(//40X,2A10,2X,*VS*,2X,2A10)
C     CALL R0PLT
C     NPLTNPLT+1
C
C     210 IF (IAA.NE.1) GO TO 220
C     IAA=0
C     LOG=.TRUE.
C     GO TO 190
C
C     220 CONTINUE
C     IF (IBB.NE.1) GO TO 250
C
C     *** SET UP INFORMATION FOR PLOTS WITH ***
C     *** ABSCISSA LAMT (OR LOG(LAMT)) = BASE 10 ***
C     XNAME(1)=XNAME2
C     XNAME(2)=XNAME1(2)
C     LOG=.FALSE.
C     GO TO 240
C
C     250 XNAME(1)=XNAME4(1)
C     XNAME(2)=XNAME5
C
C     240 CALL PLUTN(KC,NPTP,50,XY(1,2),G,PSYMBL,16,121,LOG)
C
C     *** PRINT DATA BELOW PLOT ***
C     WRITE(6,205) (YNAME(KL),KL=1,2), (XNAME(KL),KL=1,2)
C     CALL R0PLT
C     NPLTNPLT+1
C
C     250 IF (IBB.NE.1) GO TO 260
C     IBB=0
C     LOG=.TRUE.
C     GO TO 230
C
C     260 CONTINUE
C     IF (IC.NE.1) GO TO 290
C
C     *** SET UP INFORMATION FOR PLOTS WITH ***
C     *** ABSCISSA EXP(-LAMBDA*T) OR ***
C     *** LOG(EXP(-LAMBDA*T)) = BASE 10 ***
C     XNAME(1)=XNAME3(1)
C     XNAME(2)=XNAME3(2)
C     LOG=.FALSE.
C     GO TO 280
C
C     270 XNAME(1)=XNAME4(1)
C     XNAME(2)=XNAME5
C
C     280 CALL PLUTN(KC,NPTP,50,XY(1,3),G,PSYMBL,16,121,LOG)
C
C     *** PRINT DATA BELOW PLOT ***

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```

211 WRITE(6,205) (YNAME(KL),KL=1,2), (XNAME(KL),KL=1,2)
212 CALL RUMPLT
213 NPLT=NPLT+1
214 LOG=.TRUE.
215 290 IF (ICC,NE,0) GO TO 310
216 ICC=0
217 GO TO 270
218 300 XNAME(2)=XNAME(1)
219 XNAME(1)=XNAME(2)
220 DU 305 1=1,KC
221 305 ABC(1,1)=PAHAM(1,K1)
222 CALL PLOTN(1,KC,50,XY,E,PSYMBL,16,121,LOG)
223 WRITE(6,205) (YNAME(KL),KL=1,2), (XNAME(KL),KL=1,2)
224 CALL RUMPLT
225 NPLT=NPLT+1
226 310 IPLOTNPLT+1
227 IAA=IAAT
228 1BB=IBBT
229 ICC=ICCT
230 1016 FORMAT(//40X,13,* PLOT(S) COMPLETED*)
231 END
232 SUBROUTINE PLOTN(NPP,IBIRTH)
233
234 * THIS SUBROUTINE PLOTS THE
235 * MAX. MISSION TIME FUNCTIONS*
236 * TMAX, SIMTMAX, SIMTIF AND *
237 * HATIF.
238 *
239 ***** ***** ***** ***** ***** ***** ***** ***** *****
240
241 DIMENSION PSYMBL(3)
242 COMMON/PPLOT/XAXIS(101),YAXIS(101,3)
243 COMMON/CPLOT/XAXISC(101),YAXISC(101,3)
244 COMMON /GWAFF/DUM(2),PSYMBL
245 IF(IBIRTH .EQ. 1)
246 1CALL PLOTN(3,NPP,50 ,XAXIS,YAXIS,PSYMBL,3 ,101 ,F)
247 IF(IBIRTH .EQ. 2) CALL PLOTN(3,NPP,50 ,XAXISC,YAXISC,PSYMBL,3,101 ,F)
248 2F.)
249 CALL RUMPLT
250 RETURN
251 END
252 SUBROUTINE PLOTN(NPLT,NBIN,NLIN,XAXIS,YAXIS,PSYMBL,MAXPLT,
253 ILUG)
254 DIMENSION XAXIS(MAXPLT),PSYMBL(MAXPLT),YAXIS(MAXPLT)
255 COMMON/PLTAR/NUM,PS(10),ZLINE,BLANK,DUM(3),NHI,UMB,RESTY
256 LOGICAL LGUN
257 COMMON /UN/LOGN
258 DATA ZLINE/10H-----/
259 LOGN=LOG
260 IF(.NOT.LOGN) GO TO 91
261 IF (NPLT .GT. 0) GO TO 8
262 NPLT=NPLT
263 DO 90 KIP=1,NPLT
264 DO 90 LIP=1,NBIN
265 YAXIS(LIP,KIP)=ALOG10(YAXIS(LIP,KIP))
266 90 CONTINUE
267 8 CONTINUE
268 NMIS=(NBIN*9)/10
269 YMINS=YMAX
270 DO 2 J=1,NPLT
271 DO 2 I=1,NBIN
272 YMINS=YMAX(YMAX,YAXIS(I,J))
273 YMINS=YMIN(YMIN,YAXIS(I,J))
274
```

```

2 YMINBMIN((YMIN,YAXIS(I,J)))
3 YSPAN=YMAX-YMIN
4 YMXX=YMXX
5 YMXY=YMXX
6 IF ((YMIN.GT.0.0)) GO TO 10
7 IF ((YMAX.GT.0.0).AND.((YMIN.LT.0.0))) GO TO 11
8 YMXX=YMIN
9 YMXY=YMIN
10 YMXX=YMXX
11 YMXY=YMXX/2.
12 DO 12 J=1,NPLT
13 DO 12 I=1,NBIN
14 YAXIS(I,J)=YAXIS(I,J)+YMXX
15 YMXX=YMXX/2.
16 GO TO 10
17
18 CONTINUE
19 NLINES=ABS(NLIN)
20 DY=AMAX1(YSPAN,AYMX)/FLDAT(NLINE8)
21 RESTY=YMXX-YMXY
22 YMXX=EDIM(YMXX,0.0)
23 YMXY=YMXX
24 PRINT 105
25 IF (IGROS.EQ.0) GO TU 60
26 NBIN=100
27 GO TO 61
28 60 NBINNBIN=NGROS+100
29 61 NHIN=NBIN+9)/10
30 ICOR=100*(NGROS-IGROS)
31 DO 62 J=1,NPLT
32 DO 62 I=1,NBIN
33 YAXIS(I,J)=YAXIS(I+1,CUR,J)
34 DO 63 I=1,NBIN
35 XAXIS(I)=XAXIS(I+ICOR)
36 LFLGE=0
37 DO 20 K=1,NLINES
38 IF ((YMXX.GT.0.0).OR.((LFLG,NE.0))) GO TO 23
39 LFLG=1
40 DO 25 I=1,NHI
41 PS(I)=ZLINE
42 PRINT 101,(PS(I),I=1,NHI)
43 23 DO 21 I=1,NHI
44 PS(I)=BLANK
45 DO 22 J=1,NPLT
46 DO 22 I=1,NBIN
47 YISAXIS(I,J)
48 IF ((YMXX.LT.YI).OR.((YMXX>YI).GT.DY)) GO TO 22
49 I1=I+9)/10
50 I2=I-(I1+1)*10
51 CALL MOVC(1,PSYMBL(J),I2,PS(I1))
52 CONTINUE
53 CONVREDUC(YMXX+RESTY)
54 PRINT 102,CONT,(PS(I),I=1,NHI)
55 PRINT 107
56 YMXX=YMXX+DY
57 CONVREDUC(YMXX+RESTY)
58 DO 30 I=1,NHI
59 PS(I)=ZLINE
60 PRINT 102,CONT,(PS(I),I=1,NHI)
61 PLOT ZLINE,NH1,NH2,NH3,NH4,NH5,NH6,NH7,NH8,NH9,NH10,NH11,NH12,NH13,NH14,NH15,NH16,NH17,NH18,NH19,NH20,NH21,NH22,NH23,NH24,NH25,NH26,NH27,NH28,NH29,NH30,NH31,NH32,NH33,NH34,NH35,NH36,NH37,NH38,NH39,NH40,NH41,NH42,NH43,NH44,NH45,NH46,NH47,NH48,NH49,NH50,NH51,NH52,NH53,NH54,NH55,NH56,NH57,NH58,NH59,NH60,NH61,NH62,NH63,NH64,NH65,NH66,NH67,NH68,NH69,NH70,NH71,NH72,NH73,NH74,NH75,NH76,NH77,NH78,NH79,NH80,NH81,NH82,NH83,NH84,NH85,NH86,NH87,NH88,NH89,NH90

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91 PRINT 10/
DO 40 I=1,NBIN
11=(I+9)/10
12=I-((I-1)*10
40 CALL MOVC(I1,NUM,I2,PS(I1))
PRINT 107
CONT'DUM(j)
PRINT 106,CONT,(PS(I),I=1,NHI)
DO 45 I=1,NBIN
11=(I+9)/10
12=I-((I-1)*10
45 CALL MUVC(I2,NUM,I2,PS(I1))
CONT'UMB
PRINT 106,CONT,(PS(I),I=1,NHI)
IF (NLIN.LT.0) GO TO 70
PRINT 104
CALL WRNR(XAXIS(1),NBIN)
DO 50 J=1,NPLT
PRINT 103,PSYMBL(J)
DO 55 I=1,NBIN
55 YAXIS(I,J)=REDUCE(YAXIS(I,J)+RESTY)
50 CALL WRNR(YAXIS(1,J),NBIN)
70 IF (IGRUS.EQ.0) GO TO 100
IGRUS=IGRUS-1
GO TO 19
GO RETURN
00 FORMAT(1H+,10X,10A10)
01 FORMAT(1H+,10X,10A10)
02 FORMAT(1H+,F12.3,7X,10A10)
03 FORMAT(1H0,4CHANNELS FOR MISTOGRAM=3X,A1,3X,
A *FOLLOWING*)
04 FORMAT(*OCHANNEL VALUES FOR X AXIS*/)
05 FORMAT(1H1)
06 FORMAT(10X,A5,5X,10A10)
07 FORMAT(1H )
END
SUBROUTINE WHNR(X,N)
DIMENSION X(1)
DIMENSION IX(100)
COMMON/PLTRW/NUM,KX(10),MINUS,MESSG(4),NHI,NUMB,RE3TY
DATA NUM/10H0123456789/ ,NUMB/4HNUMB/
DATA MESAG/1M ,4HCONT*,3M OF .4HCHAN/,1D01/1H /
DATA INF/10HRRRRRRRRRR/ ,IZERO/10HZZZZZZZ/
XMAX=ABS(X(1))
DO 10 I=2,N
10 XMAX=XMAX1(XMAX,ABS(X(I)))
IF (XMAX.LT.1.E-6) GO TO 150
IF (XMAX.GE.1.E0) GO TO 160
X1=SALOG10(XMAX)
NLIN=6
IPNT=(X1+A9*(X1))/2. +1.
NPWR=NLIN-IPNT
DU S I=1,NHI
5 KX(I)=MESSAL(I)
DU 11 I=1,N
IF ((X(I).GE.0.0) GO TO 11
11=(I+9)/10
12=I-((I-1)*10
CALL MOVC(I,MINUS,I2,KX(I1))
CONTINUE
MES1=MTSAG(1)
MES2=MES1
PRINT 1010,MES1,MES2,(KX(I),I=1,NHI)
DU 20 I=1,N
20 IX(I)=ABS(X(I))*10.*NPWR+.5
21 K9EQ
DU 22 I=1,N
DU 23 I=1,N

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22 K98K9+KK1
   IF (KS,NR,0,UR,NPWR,EQ,0) GO TO 25
   NPWHENPWR1
   NLIN=NLIN+1
   DO 23 I=1,N
23 IX(I)=IX(I)/10
   GO TU 21
25 CONTINUE
   MPNTNPWR,J
   NPWHENLINE,J
   LIN10=10*NLIN
   DO 50 J=1,NLIN
   LTNEN=10*NLINNR
   NLINLTEN=10
   MES1=MESS1(1)
   MESS2=MESS1(1)
   DN 30 I=1,N
   IX1=IX(I)
   KX1=IX1/LTN
   I1=(I+9)/10
   I2=(I-1)/10
   IF (KX1,G1,0,OK,IPNT,LE,J) GO TO 45
   CALL MOVC1,MESSAG(1),12,KX(I1))
   GO TU 30
35 IND=KX1+1*(IX1/NTEN)*10
   CALL MOVC(IND,NUM,12,KX(I1))
   50 CONTINUE
   JPNT=J-HPNT
   IF (JPNT,61,J) GO TO 51
   MESS1=MESSAG(JPNT+1)
51 14 (J.EQ.IPNT) MESS2=IDUT
   PRINT 1010,MESS1,MESS2,(KX(I),I=1,NHI)
   50 NPWHENPWR,J
   IF (NLIN,GE,3) GO TO 100
   DO 65 J=NLIN,2
   DU 67 I=1,NHI
   67 KX(I)=MESSAG(I)
   MESS1=MESSAG(J+2)
   MESS2=MESSAG(I)
65 PRINT 1010,MESS1,MESS2,(KX(I),I=1,NHI)
100 RETURN
150 DU 151 I=1,NHI
151 KX(I)=IZHKQ
   GO TU 170
160 DO 161 I=1,NHI
161 KX(I)=INF
170 MESS1=MESSAG(2)
   MESS2=MESSAG(1)
   PRINT 1010,MESS1,MESS2,(KX(I),I=1,NHI)
   GO TU 100
1010 FORMAT(0X,A5,4X,A1,10A10)
   END

   SUBROUTINE MUVC(L1,W1,L2,W2)
   DIMENSION MASK(10)
   DATA IBLNK/10H /
   DATA MASK/77000000000000000000000000000000B,
   1000070000000000000000000000000000000000000000B,
   200000000700000000000000000000000000000000000000B,
   300000000000000000000000000000000000000000000000B,
   400000000000000000000000000000000000000000000000B/
   1DATA=AND(MASK(L1),W1)
   IF ((L2,GT,L1) ICNT=6*(L2-L1)*6
   IF ((L2,LE,1) ICNT=6*(L1-L2)
   W2=AND(=MASK(L2),W2)
   W2=OR(W2,1SHIFT(IDATA,ICNT))

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      RETURN
      END
      FUNCTION REDUC(X)
      LOGICAL LOGN
      COMMON /FUN/LOGN
      REDUC=X
      IF(LOGN) REDUC=(10.)**X
      RETURN
      END
      SUBROUTINE ROMBD(A,B,X2,POP,X,HSTAR,HMIN,HMAX,ERMAX,ANS,K,KEY)
      MOVEC
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      REDUC
      REDUC
      REDUC
      REDUC
      REDUC
      REDUC
      REDUC
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      ROMBD 2 3
      ROMBD 3 4
      ROMBD 4 5
      ROMBD 5 6
      ROMBD 6 7
      ROMBD 7 8
      ROMBD 8 9
      ROMBD 9 10
      ROMBD 10 11
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      ROMBD 56 57
      C
      THE DOCUMENTATION OF THIS SUBROUTINE IS ENTITLED
      ROMBERG QUADRATURE SUBROUTINES FOR SINGLE AND MULTIPLE INTEGRALS
      SECTION 314 TECH. MEMO NO. 221, JET PROPULSION LAB.
      1 JULY, 1969
      BY W. BUNTON, M. DIETHLEM, K. HAIGLER
      C
      C CURRENT STEP SIZE
      C NAB=0, H .GT. HMIN, =1, THEN H =LE. HMIN
      C NFG=0 MAY DOUBLE STEP, =0,1 CANT DOUBLE AFTER PREVIOUS CUT
      C K=1, INTEGRATE FROM A TO B, =2, FINISHED INTEGRATION
      C I = COUNTER ON 1 TH FUNCTIONAL EVALUATION
      C X2= INDEPENDENT VARIABLE
      C L=1, TAKE 16 OR 17 FUNCTIONAL EVALUATIONS
      C LL=2, TAKE ONLY 8 FUNCTIONAL EVALUATIONS
      C X1 = FIRST X VALUE OF EACH SUBINTERVAL
      C KEY= FLAG ON THE DIAGNOSTIC PRINT
      C
      C DIMENSION Y(17),T(5,5)
      C FOFX HAS BEEN DIMENSIONED TO OBTAIN PROPER EXECUTION ON THE UNIVACROMD
      C 1108. IT IS NOT NECESSARY FOR THE USER TO DIMENSION FOFX IN HIS
      C CALLING PROGRAM
      C INTEGER FINISH
      C IF(A.GE.B.OR.HMIN.GT.HSTAR.OR.HMIN.LE.0..OR.HMAX.LT.HMIN.OR.ERMAX,ROMBD
      C *LE.0..OR.HSTAR.GT.HMAX)GO TO 200
      C
      C INITIALIZE STARTING VALUES
      C
      C ANS = 0.
      C NAB = 0
      C NFG = 0
      C X1 = A
      C H= HSTAR
      C K = 1
      C I = 0
      C X2 = X1
      C LL=1
      C
      FINSH = 0
      IF(X1+16.*H.LT.B)GO TO 10
      H=(B-A)/16.
      FINSH=1
      10 RETURN
      ENTRY ROMBD
      C
      C STORE FUNCTIONAL EVALUATIONS IN Y ARRAY
      C
      IF( LL.GT.1 ) GO TO 140
      I = 1 +
      Y(I)=FOFX
      IF(I.EQ.17) GO TO 20
      X2 = X2 + H
      IF(I.EQ.16.AND.FINISH.EQ.1)X2=H
      RETURN
      C
      C CALCULATE T VALUES

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ROMBD 123

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20 TEMP= .5*(Y(1)+Y(17))
T(1,1)=2*TEMP+16.*H
TEMP=TEMP+Y(9)
T(1,2)= -TEMP+.8.*H
TEMP=TEMP+Y(5)+Y(13)
T(1,3)= TEMP+.4.*H
TEMP=TEMP+Y(5)+Y(15)+Y(7)+Y(11)
T(1,4)= TEMP+.2.*H
TEMP=TEMP+Y(2)+Y(16)+Y(4)+Y(14)+Y(6)+Y(12)+Y(8)+Y(10)
T(1,5)= TEMP+.H
DO 30 I=2,5
LUP= 6.-I
DO 30 J=1,LUP
T(1,J)=T(1-1,J+1)-(T(1-1,J)-T(1-1,J+1))/(4.*H*(I-1) -1.)
30 CONTINUE
IF( ABS(T(5,1)) + ABS(ANS) .EQ. 0.) GO TO 110
C TEST D.1, RELATIVE ERROR OVER INTERVAL H
C
IF( ABS(T(5,1)) .EQ. 0.) GO TU 40
DENOM= T(5,1)
IF( ABS(T(5,1)-T(4,2))/DENOM ) .LE. ERMAX) GO TO 50
IF( ABS(T(5,1)-T(4,2)).LE. ERMAX)GO TO 50
C TEST D.2, RELATIVE ERROR OVER INTERVAL (A,X1)
40 IF(CANB.EQ.0.) GO TO 120
DENOM= ANS
IF( ABS((T(5,1)-T(4,2))/DENOM).GT.ERMAX.AND. ABS((T(5,1)-T(4,2)).GT.ERMAX
*.ERMAX)GO TO 120
C ALL TESTS PASSED, ADD VALUE OF SUBINTERVAL INTO SUM
C
50 ANSB= ANS+T(5,1)
60 IF(FINISH.EQ.1)GO TO 180
X=X1+16.*H
C TEST ON WHETHER TO DOUBLE H OR NOT TO
C WHEN NFGE 0, CAN DOUBLE ANYTIME
IF(NFGE) 90,70,70
70 IF( ABS((T(5,1)-T(4,1))/DENOM).GT.ERMAX.AND. ABS((T(5,1)-T(4,1)).GT.ERMAX
*.ERMAX) GO TO 100
C STEP SIZE H CAN NOW BE DOUBLED
C
80 H= 2.*H
NABED
IF( H.GT. HMAX ) H=HMAX
90 NFGEO
100 IF(X1+16.*H.LT.H)GO TO 95
H=(X1)/16.
FINISH=1
IF(H)>180,180,95
95 CONTINUE
Y(1)= Y(17)
X2= X1 + H
I= 1
GO TU 10
C TRYING TO FIND THE FUNCTION
110 X1= X1 +16.*H
IF(FINISH.EQ.1)GO TU 180
GO TU 100
C CUT STEP SIZE IN HALF
120 H= H*.5

```

```

NRGSPZI
IF(M.GT.MMIN) GU TO 130
IF(NAB.EQ.1) GU TO 160
C MMIN HAS BEEN REACHED
C C
NAB=1
MMIN
X2 = X1 + "H"
I = 1
GO TO 10
C IN H CUT, SAVE VALUABLE INFO
C
130 Y(17)= Y(9)
Y(15)= Y(8)
Y(13)= Y(7)
Y(11)= Y(6)
Y(9)= Y(5)
Y(7)= Y(4)
Y(5)= Y(3)
Y(3)= Y(2)
I=0
LL = 2
X2 = X1 +"H"
FINISH=0
RETURN
C NOW PICK UP ONLY THOSE FUNCTIONAL EVALUATIONS NECESSARY
C
140 IN 1*2
Y(17)=FOPX
IF( I .GE. 16) GU TO 150
X2= X2 +2."H"
RETURN
150 LL=1
GU TU 20
C BOTH TEST D.1 AND D.2 HAVE FAILED, ACCEPT ANSWER
C AND PROCEED WITH INTEGRATION
C
160 M$ MMIN
IF(KEY.NE.7) WRITE(6,170) X1,X2
170 FORMAT(16H IN INTERVAL X= E18.8,7H TO X= E18.8,5H RELATIVE ERROR
1CANNOT BE REACHED WITH MINIMUM STEP SIZE )
GO TO 50
160 K = 2
RETURN
200 WRITE(6,201)A,B,MSTAR,MMIN,MMAX,ERMAX
201 FORMAT(10X,36HEMORR RUMBD,CHECK CALLING PARAMETERS /10X,3MA ",",
"E15.8,5X,3MB =",E15.8,5X,BMSTART =",E15.8,5X,6HHMIN =",E15.8,10X
",6HHMAX =",E15.8,5X,7HERRMAX =",E15.8)
STOP
END
SUBROUTINE RIFDIF (IT,OPTION,IRES,N7,TIN,MIN,MAX,STEP,JDIM,R,
* P0IFF,PRIF,Pgain,NG,Lplot,Gplot)
C ****
C * THIS SUBROUTINE COMPUTES THE *
C * DIFFERENCE = DIFF, RELATIVE *
C * IMPROVEMENT = FACTOR = RIF, AND *
C * GAIN BETWEEN TWO VALUES OF *
C * THE FAMILY OF PARAMETERS *
C ****
C
RIFDIF 1
RIFDIF 2
RIFDIF 3
RIFDIF 4
RIFDIF 5
RIFDIF 6
RIFDIF 7
RIFDIF 8
RIFDIF 9
RIFDIF 10
RIFDIF 11
RIFDIF 12

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      15
      16      DIMENSION PARAM(16,10)
      17      REAL PDIFF(1,1),PHIF(1,1),PGAIN(1,1),R(121,1),RF(2)
      18      REAL ENC(20),AB,DIFF,RIF,GAIN,INFI,NITY
      19      REAL MIN,MAX
      20      INTEGER PROD(10),PAR(6),OPTION,NPROD
      21      LOGICAL PRODT
      22      LOGICAL OUTPT1,OUTPT2,OUTPT3,OUTPT4,OUTPTS
      23      COMMON/GHARH/ NEG,PROD,PAR,ENC,AB,PRODT
      24      COMMON /PARM/ PARAM,N10,K1
      25      COMMON /OUTP/ OUTPT1,OUTPT2,OUTPT3,OUTPT4,OUTPTS
      26      DATA INFI/4MINFI/,NITY/4MNITY/
      27      GPOINT=.FALSE.
      28      IF (OPTION.EQ.1) GO TO 30
      29      IF (OPTION.NE.2) GO TO 10
      30      IR2=17
      31      IR1=17-1
      32      NG=NG+1
      33      GU TU 60
      34      WRITE (6,1000) PAR
      35      HEAD (5,1001)
      36      IR1,IR2
      37      IF (OUTPT3) WRITE (6,1009) IR1,IR2
      38      NG=NG+1
      39      IF (IR1.LE.IR2.AND.IR2.LE.IR1) GO TU 60
      40      NG=NG+1
      41      IF (IR1.EQ.N7) GO TO 130
      42      IR1=IR1+1
      43      IF (IR1.GT.N7) GO TO 130
      44      NG=NG+1
      45      IR2=IR1
      46      IR2=IR2+1
      47      IP (IR2,GT,N7) GO TO 40
      48      IF (LTIN) GU TO 70
      49      IF (OUTPT2) WRITE (6,1004) PAR,PARAM(IR1,K1),PAR,PARAM(IR2,K1),
      50      * NEG,AB
      51      GU TU 60
      52      IF (OUTPT2) WRITE (6,1005) PAR,PARAM(IR1,K1),PAR,PARAM(IR2,K1),
      53      * NEG,AB
      54      CTAMIN
      55      RIFDF
      56      RIFDF
      57      RIFDF
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      71      RIFDF
      72      RIFDF
      73      RIFDF
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      78      RIFDF
      79
      80      * * * SET UP ARRAYS FOR DIFF, RIF, AND GAIN PLOTS * *
      81
      82      PDIFF(J,NG)=DIFF
      83      PRIF(J,NG)=RIF
      84      IF (LRIF) GO TO 94
      85
      86      * * * INSTEAD OF PLOTTING POINT WITH VALUE OF 1.0E35
      87      * * * FOR RIF, PLOT 3.0 TIMES THE VALUE OF THE NEXT POINT
      88      * * * TO THE RIGHT FOR THAT VALUE
      89      * * * PHIF(J-1,NG)= 3.0*PRIF(J,NG)
      90
      91      ENCODE(14,1013,RF(1)) RIF
      92      GAINR(J,IR2)=R(J,IR1)
      93      HIF=((1.0-RCU(IR1))/((1.0-H(J,IR2)))
      94      IF (H(J,IR2).NE.1.0) GU TO 91
      95      ENCODE(8,1012,RF(1)) INFI,NITY
      96      RIF=1.0E35
      97      GO TU 910
      98
      99      DIFFR(J,IR2)=R(J,IR1)
      100     GAINR(J,IR2)/R(J,IR1)
      101     IF (OUTPT2) WRITE (6,1006) CT,DIFF,(RF(J)),J=1,2),GAIN
      102     IF (OPTION.EQ.0.AND.LPLOT) GO TO 92
      103     IF (IR2.NE.(IR1+1).OR..NOT.LPLOT) GO TO 96
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      60 TU 110
      C 60 IF (BCOMP) GO TO 70
      C
      C   COMPUTE RELIABILITY FOR EQUATION 4A
      C   CALL NEQ4A (RL,HS,S,K,RV,Z,W,P,LAMT,RDP)
      C   GO TU 110

      C   COMPUTE RELIABILITY FOR EQUATION 5
      C   70 CALL NEQ5 (RL,S,RV,Z,W,P,LAMT,RDP)
      C   GO TU 110

      C   COMPUTE RELIABILITY FOR EQUATION 6
      C   80 CALL NEQ6 (RL,RV,Z,W,P,LAMT,RDP)
      C   GO TU 110

      C   COMPUTE RELIABILITY FOR EQUATION 7
      C   100 CALL NEQ7 (RL,RS,S,N,K,Q,C,RV,Z,W,P,BCOMP,LAMT,RDP)
      C   110 RETURN
      C
      C
      C   COMPUTE RELIABILITY FOR EQUATION 7
      C   100 CALL NEQ7 (RL,RS,S,N,K,Q,C,RV,Z,W,P,BCOMP,LAMT,RDP)
      C   110 RETURN
      C
      C
      C   SUBROUTINE ROWPLT
      C   *****
      C   * THIS SUBROUTINE LABELS *
      C   * THE PLOTS GENERATED. *
      C   *****
      C
      C   REAL ENC(20)
      C   INTEGER NEU,PRUD(10),NPROD,PARR(6)
      C   LOGICAL PRODT
      C   COMMON/GPROD/NPROD,NPROD,PAR,ENC,AB,PRODT
      C   COMMON /PARM/ PARM,NICK1
      C   DIMENSION PARM(16,10)
      C
      C   IF (IPRODT) GU TO 10
      C   WRITE(6,1001) NEU
      C   WRITE(6,1002) PARH,(PARAM(I,K1)),I=1,N10
      C   GO TU 20
      C   10 WRITE(6,1006) (PROD(I),I=1,NPROD)
      C   20 WRITE(6,1003)
      C   WRITE(6,1004)
      C   WRITE(6,1005) (ENC(I),I=1,20)
      C   RETURN
      C
      C   FORMAT STATEMENTS
      C
      C   1001 FORMAT(//6DX, * PLOT FOR EQUATION *,I2)
      C   1002 FORMAT((20X,*FAMILY OF PARAMETERS IS *,6A1,* ,*,5(G13.8,2X),/,/
      C   * (40X,6(G13.8,2X)))
      C   1003 FORMAT((20X,*(*N1 MEANS NOT INPUTED OR DEFAULT VALUE USED*)*)
      C   1004 FORMAT(3IX,*LAMBDA*,9X,*MU*,11X,*SX*,5X,*AN*,6X,*K*,12X,*Q*,/
      C   * 12X,*C*,11X,*RV*,12X,*Z*,5X,*W*,6X,*P*,11X,*M17*)
      C   1005 FORMAT(1H,*10*(2A6,1X))
      C   1006 FORMAT (67X,*PLOT FOR EQUATIONS *,10(I2,2X))
      C
      C
      C   END
      C
      C   SUBROUTINE SIMPR1 (TINACOMP,LAMBDA,S,N,K,Q,C,RV,Z,W,P,NEQ,
      C   * R2,RIMIN,RIMAX,RISTEP,PLOTH1,OPT1,I10,THMAX)
      C   *****
      C   * THIS SUBROUTINE COMPUTES THE MAX. MISSION *
      C   * TIME (TMAX) AND THE SIMPLEX MISSION TIME *
      C
      C
      C   SIMPRI
      C   SIMPRI
      C   SIMPRI
      C   SIMPRI
      C   SIMPRI
      C

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      * (SIMTMX) AND THE RATIO OF THESE (SIMTIF) *
      *****
      REAL SIMR1(101,15),XAXIS(101),SIMTMX(101),SIMTIF(101),TM(101)
      REAL TMX(101,15),TX(4),INFI,NITY
      REAL LAMBDA,K,LAMTR2,LAMTR1,INF
      INTEGER S,N,Z,W,NEQ
      LOGICAL TIN,BDCUMP,PLUTH1,FIRST,SEC,ZERO,OPTR1
      LOGICAL OUTPT1,OUTPT2,OUTPT3,OUTPT4,OUTPT5
      EQUIVALENCE (SIMR1(1,1),XAXIS(1)), (SIMR1(1,2),SIMTMX(1)),
      (SIMR1(1,3),SIMTIF(1)), (SIMR1(1,4),TM(1))
      COMMON /UUTPT/ OUTPT1,OUTPT2,OUTPT3,OUTPT4,OUTPT5
      COMMON /PPLUT/SIMR1
      DATA FIRST/.TRUE./, SEC/.FALSE./, INF/1.0E35/
      DATA INFI/4MINF1/NITY/4NITY/
      ZERO=.FALSE.
      IF (.NOT.(OPTR1.AND.OUTPT5)) GO TO 20
      IF (TIN) GU TO 10
      WRITE (6,1001) R2
      GU TU 20
      10 WRITE (6,1002) R2
      20 CALL BISECT(NEQ,BCOMP,S,N,K,Q,C,RV,Z,W,P,FIRST,LAMTR2,R2)
      R1=R1MIN
      J=0
      40 J=J+1
      XAXIS(J)=K1
      CALL BISECT(NEW,BCOMP,S,N,K,Q,C,RV,Z,W,P,SEC,LAMTR1,R1)
      IF ((LAMTR1.NE.INF) .OR. (LAMTR1.EQ.0)) GU TO 50
      ENCODE(B,1005,TX(1)) INFI,NITY
      ENCODE(B,1005,TX(3)) INFI,NITY
      SIMTIF(J)=1.0
      ZERUS=.TRUE..
      JJBJ
      GO TU 84
      50 SIMTMX(J)=ALOG(R1)
      IF ((SIMTMX(J).GT.1.0E-6) .OR. (SIMTMX(J).LT.-6)) GO TU 60
      SIMTMX(J)=0.0
      THAX(J,I10)=0.0
      SIMTIF(J)=1.0
      SIMTIF(I10)=0
      GO TU 80
      60 THAX(J,I10)=LAMTR1-LAMTR2
      IF (.NOT.TIN) GO TU 70
      THAX(J,I10)=TMX(J,I10)/LAMBDAA
      SIMTMX(J)=SIMTMX(J)/LAMBDAA
      SIMTIF(J)=TMX(J,I10)/SIMTMX(J)
      70 TH(J)=TMX(J,I10)
      ENCODE( 14,100b,TX(1)) SIMTMX(J)
      ENCODE( 14,100b,TX(3)) THMAX(J,I10)
      TH(J)=TMX(J,I10)
      84 IF ((UPTH1.AND.OUTPT5)) WRITE (6,1003) R1,(TX(I),I=1,4),SIMTIF(J)
      R1=R1+R1STEP
      IF ((R1.LT.RIMAX)) GO TU 40
      IF (.NOT.ZERU) GU TO 88
      THAX(J,I10)=2.0*TMX(J,I10)
      SIMTMX(J)=2.0*SIMTMX(J,I10)
      TH(J)=TMX(J,I10)
      88 IF (.NOT.PLOTR1) GO TU 90
      CALL PLOTT(J,1)
      WRITE (6,1004)
      90 RETURN
      1001 FORMAT (//,6X,*MAXIMUM MISSION TIME*,UX,*REFERENCE R2 = *,F7.5,/,*
      4X,*R1*,9X,*SIMLAMTMX*,16X,*LAMTMX*,16X,*SIMTIF*) , SIMPRI
      1002 FORMAT (//,6X,*MAXIMUM MISSION TIME*,UX,*REFERENCE R2 = *,F7.5,/, SIMPRI
      4X,*R1*,8X,*SIMTMX*,17X,*TMAX*,17X,*SIMTIF*)
      1003 FORMAT (1H,,F7.52(UX,2A10),3X,E14.7) , SIMPRI
      1004 FORMAT (36X,*36X,*SIMLAMMAX(A),SIMTIF(B),LAMTMX(C) VS R1(XAXIS) PLNSIMPRI
      37 COMPLETED */

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DATA (IGENC(1),I=1,10)/10*0/, (IGENP(1),I=1,10)/10*0/
DATA (IF9C(1),I=1,8)/8*0/, (FRACT(1),I=1,8)/8*0*0/
NAMELIST /VART,LAMT,ELMT,MUT,MIN,STEP,B,OPTION
NAMELIST /VARI/ PROD
NAMELIST /OPTION/OUTPT1,OUTPT2,OUTPT3,OUTPT4,OUTPT5, PRODT,NEQ,
* DEBUG,INPUT,STOUT,COVINT,LSTCH,COPRC,DEPCHNG,
* LPLT,RVLPT,OPT1,UPTR1,PLUTR2,IND,XYRANGE
NAMELIST /DEFAULT/Q1DEF,Q2DEF,LAMDEF,MUDEF,GMPDEF,CDEF,
* CTRDEF,PRCDEF,RVDEF,PDEF,NDEF,SDEF,MDEF,ZDEF
NAMELIST /COVAL/COVINT,IGENC,IGENP,IFSC,PRAC
IN0=0
NPT10
T0=0
ELAMT=0.0
MIN=0.0
NPROD=1
NUMS0
DMFLG=.F.
DEBUG=.F.
INPUTS=.T.
STGOUT=.F.
COVINT=.F.
LSTCH=.F.
COPRC=.F.
DEPCHNG=.F.
STEP=1.0
B=0.0
OPTIONS=0
TINA=.FALSE.
HUTIN=.FALSE.
ELATIN=.FALSE.
PRODT=.FALSE.
XYRANGE=.FALSE.
LPLT=.FALSE.
RVLPT=.FALSE.
OPT1=.FALSE.
OPT2=.FALSE.
OPT3=.FALSE.
OPT4=.FALSE.
PLOTR1=.FALSE.
PLOTR2=.FALSE.
OUTPT1=.FALSE.
OUTPT2=.FALSE.
OUTPT3=.FALSE.
OUTPT4=.FALSE.
OUTPT5=.FALSE.
IA=0
IAA=0
IBB=0
ICB=0
ICC=0
IPLT1=0
IPLT2=0
IPLT3=0
IPLT4=0
IPLT5=0
DO 20 IA=1,10
HUT(1)=0.0
PROD(I)=0
20 PROD(I)=0
C READ THE REQUESTED OPTIONS
C READ(S,OPTION)
PRINTED ANSWERS TO QUESTIONS OPTION
IF(OUTPT5) WRITE(6,1037) OUTPT3
IF(IND .GT. 0) WRITE(6,OPTION)
PRODUCT OF RELIABILITY OPTION
READIN 90
READIN 91
READIN 92
READIN 93
READIN 94
READIN 95
READIN 96
READIN 97
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READIN 195
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READIN 197
READIN 198
READIN 199
READIN 200

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      IF (OUTPT1) WRITE(6,1001) PROD
      IF (,NOT,PROD) GO TO 120
C     READ IN THE EQUATION NUMBERS TO BE
C     USED IN THE PRODUCT OF RELIABILITIES
      READ(S,VAR1)
      IF (OUTPT3) WRITE (6,VAR1)

C     COUNT THE NUMBER OF EQUATIONS INVOLVED IN THE PRODUCT
      NPROD=NPT
      NPT=NPT+1
      DO 80 I=1,NPT
      IF (PROD(NPT1-I).NE.0) GO TO 90
      NPROD=NPROD+1
      80 CONTINUE

C     90 DO 100 I=1,NPROD
      IF (PROD(I).LT.1.0R,PROD(I).GT.7) GO TO 110
      IF (PROD(I).NE.7) GO TO 100
      DMFLG=0
      IF ((I=NUN).GT.1) GO TO 110
      NUN=I
      100 CONTINUE
      IF (NUN.LE.1) GO TO 121
      110 WRITE(6,1022)
      WRITE(6,1005) (PROD(I),I=1,NPROD)
      WRITE(6,1006)
      STOP
      C     WRITE THE RELIABILITY EQUATION NUMBER TO BE USED
      120 IF (OUTPT1) WRITE(6,1039) NEG
      IF (NEG.GT.7.0R, NEG.LT.1) GO TO 990
      DMFLG=0
      IF (DMFLG) NUN=1
      PROD(1)=NEG
      121 READ(S,VAR)
      IF ( INO .GT. 0) WRITE(6,VAR)

C     READ IN THE INPUT VARIABLES FOR THE RELIABILITY EQUATIONS
      C     PACK APPLICABILITY FIELD OF EACH PCW ELEMENT,
      C     THEN INITIALIZE DEFAULT VALUES.
      C
      DO 150 J=1,NPROD
      DO 150 I=1,22
      MTMP=MANDHBS9,ISHIFT(PCW(I),PROD(J))
      150 PCW(I)=OR(PCW(I),ISHIFT(MTMP,41-J))
      Q1DEF=0
      Q2DEF=0
      LAMDEF=1.0E+0
      MUDEF=1.0E+6
      GMDEF=1.0E+0
      PDEF=1.0E+0
      CDDEF=1.0
      CTDEF=1.0
      PRCDL=1.0
      AVDEF=1.0
      PDEF=0.5
      NDDEF=3
      SDEF=0
      MDEF=1
      ZDEF=1

C     READ NEW DEFAULT VALUES IF REQUESTED
      C
      IF (DEFCNG) READ(S,DEFAULT)

```

```

C READ INVARIANT COVERAGE DATA IF REQUESTED
C COVERAGE CALCULATION FLAGS AND LINKAGE DATA
C IF(COVCRC) HEAD(5,COVCAL)
C TEST TU SEE IF T, LAHT, OR ELAMT WAS INPUTED
C IF(T .NE. 0.0) GO TO 190
C IF (ELAMT.NE.0.0 ) GO TO 200
C IF (ELAMT.LE.1.0 ) GO TO 180
C ELAMT=1.0
C WRITE (6,1032)
C
C DEFAULT VALUE FOR ELAMT IS 1.000
C 180 IF (ELAMT.EQ.0.0 ) ELAMT=1.0
C ELATIN=.TRUE.
C GO TU 200
C
C 190 TIN=.TRUE.
C
C ARE 2-D RELIABILITY PLOTS TO BE PERFORMED
C 200 IF (OUTPT3) WRITE(6,1013) LPLOT
C IF (.NOT.LPLOT) GO TO 280
C
C 2-D PLOT OPTION
C WRITE (6,1014)
C READ(5,1017) IPLT1,IPLT2,IPLT3,IPLT4,IPLT5
C IF (OUTPT3) WRITE (6,1040) IPLT1,IPLT2,IPLT3,IPLT4,IPLT5
C IF (.NOT.PHOUT) IPLT1=0
C WRITE (6,1016)
C HEAD(5,1017) IA,IAA,IB,IBB,IC,ICC
C IF (OUTPT3) WRITE (6,1040) IA,IAA,IB,IBB,IC,ICC
C IF (TIN) GO TO 240
C IF (IA.EQ.0) WRITE (6,1018)
C IF (IAA.EQ.1) WRITE (6,1019)
C IA=0
C IAA=0
C
C X-AXIS RANGE OPTION
C 240 IF (.NOT.XYRANGE) GO TO 280
C WRITE (6,1020)
C READ(5,1021) XMIN,XMAX
C IF (OUTPT3) WRITE (6,1041) XMIN,XMAX
C
C Y-AXIS RANGE OPTION
C WRITE (6,1015)
C READ(5,1021) YMIN,YMAX
C IF (OUTPT3) WRITE (6,1041) YMIN,YMAX
C
C 280 IF (PRODT) GO TO 430
C
C RV VERSUS R PLOT OPTION
C IF (OUTPT3) WRITE(6,1027) RPLOT
C IF (ELATIN) GO TO 430
C
C MAXIMUM MISSION TIME OPTIONS IF ELAMT WAS NOT INPUTED
C IF (OUTPT3) WRITE(6,1046) O PTR1
C IF (.NOT. O PTR1) GO TO 370
C IF (OUTPT3) WRITE(6,1047) PL PTR1
C 370 IF (PRODT) GO TO 410
C MAXIMUM MISSION TIME OPTION 2
C IF (OUTPT3) WRITE(6,1048) O PTR2
C IF (.NOT. O PTR2) GO TO 410
C IF (OUTPT3) WRITE(6,1049)
C READ(5,1008) R2OPT
C IF (OUTPT3) WRITE(6,1109) R2OPT
C IF (OUTPT3) WRITE(6,1050) PL PTR2
C
C FINAL 9
C FINAL 10
C FINAL 11
C MAINLOG 95
C READIN 128
C READIN 129
C READIN 130
C READIN 131
C READIN 132
C READIN 133
C READIN 134
C READIN 135
C READIN 136
C READIN 137
C READIN 138
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C READIN 182
C READIN 183
C READIN 184
C READIN 185
C READIN 186
C READIN 187
C READIN 188

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410 IF (.NU1.LUPTRI.UR.UPIW2) GU TU 450
IF (OUTPT3) WRITE(6,1051)
READIN 190
READIN 191
READIN 192
READIN 193
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READIN 254

C
C   OUTPUT OPTIONS
C   450 IF (.NOT. OUTPT3) RETURN
      WRITE(6,1034) OUTPT1
      WRITE(6,1036) OUTPT2
      WRITE(6,1045) OUTPT4
      WRITE(6,1052) OUTPT5

C   RETURN
      590 WRITE(6,1022)
      STOP

C   FORMAT STATEMENTS

C   1001 FORMAT (* DO YOU WISH TO FORM A COMPLEX EQUATION WHICH IS*,/,
* THE PRODUCT OF THE PRIMARY EQUATIONS,* ,30X,*PRODTS *,L2)
      READIN 200
      READIN 201
      READIN 202
      READIN 203
      READIN 204
      READIN 205
      READIN 206
      READIN 207
      READIN 208
      READIN 209
      READIN 210
      READIN 211
      READIN 212
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      READIN 247
      READIN 248
      READIN 249
      READIN 250
      READIN 251
      READIN 252
      READIN 253
      READIN 254

      1002 FORMAT (0B0A1)
      1005 FORMAT (* INPUT VARIABLES FOR EQUATIONS *,10(12,2X),/
* WHICH ARE INVOLVED IN THE PRODUCT OF RELIABILITIES*,)
      1006 FORMAT (* TYPE IN THE EQUATION NUMBERS INVOLVED IN THE PRODUCT*,/,READIN
* USE VAR1 AS THE NAMELIST NAME*,/
* EXAMPLE FOR THE PRODUCT OF THE RELIABILITIES OF EQUATIONS 1, 2,READIN
* AND 3*,/, TYPE*,/,/
* SVARI PRODP12,SS*,/,,
* NOTE* NAMELIST INPUT IGNORES COLUMN 1*)
      1007 FORMAT (* TYPE IN COLUMN 1 THE NUMBER OF THE RELIABILITY EQUATION*,READIN
* /* TO BE USED = 1 THRU 7*,/,)
      1008 FORMAT (11)
      1013 FORMAT (* DO YOU WISH TO HAVE 2-D RELIABILITY PLOTS* *22X,
* LPOTS *,L2;
      1014 FORMAT (* INPUT A 1 IN THE COLUMN SPECIFIED BELOW IF YOU WISH*,/,
* THE CORRESPONDING PLOT OPTION. OTHERWISE INPUT 0*,/,,
* NOTE* WHEN PERFORMING PRODUCT OF RELIABILITIES, NO OTHER*,/,,
* PLOT OPTION BESIDES PRODUCT OF RELIABILITIES MAY BE*,,
* SPECIF ID*,/,,
* COLUMN 1 - PLOTS PRODUCT OF RELIABILITIES*,/,
* COLUMN 2 - PLOTS RELIABILITY*,/,
* COLUMN 3 - PLOTS DIFF, RIF, AND GAIN*,/,
* COLUMN 4 - PLOTS MTF AND RELIABILITY AT MTF*,/,,
* COLUMN 5 - PLOTS UNRELIABILITY*)
      1015 FORMAT (* IF YOU WISH TO PLOT A CERTAIN RANGE OF Y-AXIS VALUES*,/,READIN
* FOR THE 2-D PLOTS, ENTER LEFT-END POINT IN COLUMNS 1-8 WIDTH*,/READIN
* FORMAT F8.0 AND RIGHT-END POINT IN COLUMNS 9-16 WITH FORMAT*,/READIN
* F8.0 *)
      1016 FORMAT (* FOR ABSCISSA, INPUT 1 IN COLUMN 1 IF ABSCISSA IS LOG(T) - BASE 10,*,/,,
* 1 IN COLUMN 2 IF ABSCISSA IS LOG(T) - BASE 10,*,/,,
* 1 IN COLUMN 3 IF ABSCISSA IS LAMT*,/,,
* 1 IN COLUMN 4 IF ABSCISSA IS LOG(LAMT) - BASE 10,*,/,,
* 1 IN COLUMN 5 IF ABSCISSA IS EXP(-LAMDA(T)),*,/,,
* 1 IN COLUMN 6 IF ABSCISSA IS LOG(ZEXP(-LAMT)) - BASE 10,*) )
      1017 FORMAT (611)
      1018 FORMAT (* WARNING ABSCISSA CAN NOT BE T = NO PLOT FOR ABSCISSA T*)READIN
      1019 FORMAT (* WARNING ABSCISSA CAN NOT BE LOG(T) = BASE 10 - NO PLOT*,READIN
* /* FOR ABSCISSA LOG(T) = BASE 10*)
      1020 FORMAT (* IF YOU WISH TO PLOT A CERTAIN RANGE OF X-AXIS VALUES*,/,READIN
* FOR THE 2-D PLOTS, ENTER LEFT-END POINT IN COLUMNS 1-8 WIDTH*,/READIN
* FORMAT F8.0 AND RIGHT-END POINT IN COLUMNS 9-16 WIDTH WITH FORMAT*,/READIN

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49 READIN2
50 READIN2
51 READIN2
52 READIN2
53 READIN2
54 READIN2
55 READIN2
56 READIN2
57 READIN2
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97 READIN2
98 READIN2
99 READIN2
100 READIN2
101 READIN2
102 READIN2
103 READIN2

C REQUEST FOR NAMELIST DATA
C
C 5 READ(S,DATA)
C
C REQUEST FOR NAMELIST PARVEC
C
C 10 READ(S,PARVEC)
C GO TU 1

C REQUEST FOR ITERATION ON PARAMETER 'NUM'.
C VARIATION DATA IS READ VIA NAMELIST VARY.
C
C 20 IRESNUM
C IF(IRES,LT,20) GO TU 22
C Lvary="F"
C GO TO 999
C
C 22 LVARY=IRES,GT,0
C N10=1
C IF(L,NUT,LVARY) GO TU 1
C RLFLG=PCM(IRES)
C ISUBBAND(M9KSUB,RLFLG)
C IF(RLFLG,LT,0) UVALERLDFS(IISUB)
C IF(RLFLG,GT,0) UVALINTDFS(IISUB)
C DU 24 J=1,PRBD
C DO 24 I=2,16
C 24 PARAM(C1,J)=UVAL
C DO 26 J=1,NPRBD
C 26 GO TU(101,102,103,104,105,106,107,108,109,110,
C * 111,112,113,114,115,116,117,118,119),IRES
C
C 101 VAL=Q1(JJ)
C 102 GO TU 26
C 102 VAL=Q2(JJ)
C 102 GO TU 26
C 103 VAL=N(JJ)
C 103 GO TU 26
C 104 VAL=S(JJ)
C 104 GO TU 26
C 105 VAL=W(JJ)
C 105 GO TU 26
C 106 VAL=Z(JJ)
C 106 GO TU 26
C 107 VAL=LAM(JJ)
C 107 GO TU 26
C 108 VAL=M(JJ)
C 108 GO TU 26
C 109 VAL=GMP(JJ)
C 109 GO TU 26
C 110 VAL=CL(JJ)
C 110 GO TU 26
C 111 VAL=CD(JJ)
C 111 GO TU 26

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      GU TU 26
112 VALC2(J)
      GU TU 26
113 VALCD2(J)
114 VALCTR(J)
      GO TU 26
115 VALCDTR(J)
      GO TU 26
116 VALPHC1(J)
      GO TU 26
117 VALPRC2(J)
      GO TU 26
118 VALRV(J)
      GO TU 26
119 VALSP(J)
26 PARAM(I,J)=VAL
      READ(S,VAHY)
      DO 28 I=1,6
      DO 28 J=1,NPRUD
      IF (PARAM(I,J).EQ.DVAL) GO TU 28
      N10$1
      &8 CONTINUE
      GO TU 1
C   CONTROL CARD CONTAINS FUNCTION NUMBER SELECTION
C   DATA (C CARD),
C
30 IPR#0
      IF(IP#0.EQ.1MD) IPR#1
      IF(IP#0.EQ.1MH) IPR#2
      IF(IP#0.EQ.1ME) IPR#3
      IF(IP#0.EQ.1MT) IPR#4
      IF(IP#0.EQ.0) GO TO 999
      IF(FCARD) GO TU 52
      IF(NUM.GT.NEXT(IPR)) GO TO 999
      NUM$AVNUM
      IF(FCARD) GO TO 62
51 MDF#MD.GT.#
      IF(IET.EQ.0.AND.MD.NE.0) GO TO 999
      IET#IET.GT.#
      IF(IISU.EQ.0) GO TO 999
      IF(IISU.GT.0) GO TO 32
      ISU#ISU
      ISU#ISU
      GO TU 34
52 ISU#ISU
      ISU#ISU
      34 IF(MKN.EQ.0) GO TO 999
      IF(MKN.GT.20) GO TO 36
      MKN#MKN
      MKN#MKN
      GO TU 38
36 MKN#1
      MKN#2=20
38 DU 49 MDT=1,3
      IF(MDF.UR.(MDT.EQ.(MD+1))) GO TU 40
      GU TU 49
40 DU 48 IETT#1,2
      IF(IETF.UH.(IETT.EQ.IETT)) GU TU 41
      GO TU 48
41 IF(MDT.EQ.1.AND.IETT.GT.1) GO TU 48
      INDEX#2*IETT#MDT#3
      IF(MDT.EQ.1) INDEX#=5
      DU 47 ISU#ISU,ISU2
      MKN#MKN1,MKN#2
      DO 47

```

```

60 TU(43,44,45,46),IPK
43 CALL INPUT(NDET(MKN,ISU),INDFX,NUMSAV)
GO TO 47
44 CALL INPUT(NISO(MKN,ISU),INDEX,NUMSAV)
GO TO 47
45 CALL INPUT(NEP(MKN,ISU),INDEX,NUMSAV)
GO TO 47
46 CALL INPUT(NTLR(MKN,ISU),INDEX,NUMSAV)
47 CONTINUE
48 CONTINUE
49 CONTINUE
GU TO 1

C   CONTROL CARD IS FIRST OF TWO E CARDS, DATA,
C   EXCEPT FOR FUNCTION NUMBER, IS SAME AS ON
C   C AND F CARDS.

C   ECARD=.T.
GO TO 30
52 NUMSAV=NEXT(IPK)
NEXT(IPR)=NUMSAV-1
GO TO 31

C   ENTER THE MECHANISM DEFINITION LOOP, WHICH
C   USES THE SPECIAL INPUT FORMAT BELOW. (IN CARD ONLY)
C   55 READ(S,1510,ISU,MKN,((LINE(I,J),J=1,4),I=1,5),
15 FORMAT(A,9X,215,203))
IF(CID,NE,1M) GO TN 1
IF((ISU,LT,1.0R.ISU,GT,8)) GO TO 999
IF((MKN,LT,1.0R.MKN,GT,20)) GO TO 999
UD 57 1B1,5
DO 56 J=1,4
IF((LINE(I,J).LE,0)) LINE(I,J)=0
56 CONTINUE
CALL INPUT(NDET(MKN,ISU),I,LINE(1,1))
CALL INPUT(NISO(MKN,ISU),I,LINE(1,2))
CALL INPUT(NEP(MKN,ISU),I,LINE(1,3))
57 CALL INPUT(NTLR(MKN,ISU),I,LINE(1,4))
GO TO 55

C   CONTROL CARD CONTAINS FUNCTION SPECIFICATION DATA
C   (P CARD)
C   60 FCARD=.T.
61 GO TO 30
62 FCARD=.F.
65 ECARD=.F.
66 CALL SPECIT(DET,NUMSAV,IGFT,ISCH,IREP,INTF,COEF,
*     TDEL,P1,P2,P3,TDUR)
67 CALL SPECIT(IFSO,NUMSAV,IGFT,0,0,INTF,COEF,
*     TDEL,P1,P2,P3,TDUR)
68 CALL SPECIT(FEPR,NUMSAV,IGFT,0,0,INTF,COEF,
*     0,0,P1,P2,P3,TDUR)
69 CALL SPECIT(FFTR,NUMSAV,IGFT,0,0,INTF,COEF,
*     0,0,P1,P2,P3,TDUR)
GO TO 1

C   NORMALIZE RATE FUNCTIONS AND CHECK ALL DEFINED
C   FUNCTIONS FOR REASONABLENESS
C   70 DO 270 IPRT=1,4

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NAME=NPHULL(PH)
NMAX=NEXT(LPH)
200 DO 200  NUM=1,NMAX
   GO TO (210,220,230,240),IPR
210 CODE=FDET(1,NUM)
CODES=FDET(2,NUM)
IF (IGET(CODES,4).EQ.0) GO TU 250
IF (IGET(CODES,1).EQ.0) GO TU 250
TDUR=FDET(1,NUM)
TESTSFINTEG(FDET,NUM,TDUR)
IF (TEST.GT.0.0) GO TO 212
WRITE(6,71)NUM,NUM
71 FORMAT(//OUX,*RANGE ERROR IN *,A10,* FUNCTION NUMBER*,I4,
      3      * FUNCTION DISABLED*)
CALL IPUT(CODES,4,0)
FDET(1,NUM)=CODES
GO TO 250
212 FDET(4,NUM)=FDET(4,NUM)/TEST
      GO TU 250
220 CODE=FIISU(2,NUM)
CODES=FIISU(1,NUM)
IF (IGET(CODES,4).EQ.0) GO TU 250
IF (IGET(CODES,1).EQ.0) GO TU 250
TDUR=FIISU(7,NUM)
TESTSFINTEG(FISO,NUM,TDUR)
IF (TEST.GT.0.0) GO TU 222
WRITE(6,71)NUM,NUM
CALL IPUT(CODES,4,0)
FISO(1,NUM)=CODES
GO TO 250
222 FIISU(4,NUM)=FIISU(4,NUM)/TEST
      GO TU 250
230 CUEF=FEPH(2,NUM)
CODES=FEPH(1,NUM)
IF (IGET(CODES,4).EQ.0) GO TU 250
IF (IGET(CODES,1).GT.0) GO TU 232
WRITE(6,73)NUM,NUM
73 FORMAT(//OUX,*IMPULSE NOT ALLOWED FOR REC. FUNCTIONS = *,
      $      A10,* FUNCTION NUMBER*,I4,* DISABLED*)
DTATDUR/10.0
TFLG=.T.
DO 235 ITPI=1,11
IT=ITP1-1
T=ITDT
TEST=FEVAL(FEPR,NUM,T)
IF (TEST.LT.0.0.OR.TEST.GT.1.0001) TFLG=.F.
235 CONTINUE
IF (TFLG) GO TU 250
WRITE(6,71)NUM,NUM
237 CALL IPUT(CODES,4,0)
FEPH(1,NUM)=CODES
GO TU 250
240 COEF=FTLR(2,NUM)
CODE=FTLH(1,NUM)
IF (IGET(CODES,4).EQ.0) GO TU 250
IF (IGET(CODES,1).GT.0) GO TU 242
WRITE(6,73)NUM,NUM
GO TU 247
DO 245 ITPI=1,11
TFLG=.T.
DO 245 ITPI=1,11
IT=ITP1-1
TEST=FEVAL(FTLR,NUM,T)

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      IF (TEST.LT.0.0.UH.TEST.GT.1.00001) TFLG=.F.
245  CONTINUE
1  IF (TFLG) GO TO 250
    WRITE(6,71)NUM,NUM
247  CALL IPUT(CODES,4,0)
    FTLR(1,NUM)=CODES
250  IF(COEFF.GE.0.0.AND.COEFF.LE.1.0) GO TO 260
      WRITE(6,72)NUM,NUM
      72 FORMAT(10X,*COEFFICIENT ERROR IN *,A10,* FUNCTION NUMBER*,i4,
      *     ,* FUNCTION DISABLEd*)
      CALL IPUT(CODE9,4,0)
      GU TO (251,252,253,254),IPR
251  FDET(1,NUM)=CODES
      GO TO 260
252  FSDG(1,NUM)=CODES
      GU TO 260
253  FPRC(1,NUM)=CODES
      GO TU 260
254  FTLH(1,NUM)=CODES
260  CONTINUE
270  WRITE(6,74)NUM
270  WRITE(6,74)NUM
274  FORMAT(10X,*NORMALIZATION COMPLETE FOR *,A10,* FUNCTIONS*)
      GO TO 1
C
C          DISPLAY THE COVERAGE DATA BASE, EXCLUSIVE
C          OF FUNCTION SPECIFICATIONS
C
60  WRITE(6,300)(STAW,I=1,20)
300  FORMAT(1M1,55X,*COVERAGE DATA BASE//55X,20A1//)
      WRITE(6,301)
301  FORMAT(46X,* FAULT SUBCLASS LINKAGE AND PARAMETERS **/*
      *FAULT*,*FAULT*,*LINKED*,*6X,*FRACTION OF*,*5X,
      *PROB.,*UF FAULT*,*5X,*TIME FOR FAULT*/28X,*SUBCLASS*
      *5X,*ATU STAGE*,*5X,*FAULT RATE*,*6X,*DET. IN SPARE3*,*
      *5X,*DET. IN SPARE4*/)
      DO 310 181,8
1  IF(IFSC(I).GE.0.AND.IFSC(I).LE.10) GO TO 310
1  IFSC(I)=0
1  FRAC(I)=0
1  WRITE(6,302)I,IFSC(I),FRAC(I),PFDS(I),TFDS(I)
302  FORMAT(28X,14.0X,14.9X,F8.6,10X,F8.6,9X,P12.6)
      WRITE(6,308)MINUR
308  FORMAT(*38X,*MINOR CYCLE DURATION (FOR SCHEDULED*,
      * DETECTORS) *,F12.6)
      WRITE(6,305)
305  FORMAT(145X,* D/I/R MECHANISM DEFINITIONS **,9X,
      * (X MEANS FUNCTION UNDEFINED)*/*58X,*FAULT TYPE/MODE*/
      *17X,*SUBCLASS MECHANISM*,*8X,*PERM/1*,*9X,*PERM/2*,*9X,
      *TRANS/1*,*8X,*TRANS/2*,*9X,*PERM0*/44X,*D I E T*,*
      *D I E T D I E T D I E T D I E T /)
      DU 350 19U=1,8
1  IF(IFSC(19U).EQ.0) GU TO 350
      DU 350  MEC=1,20
      MFLG=.T.
      DO 320 INDEX=1,5
        NUM=IGET(INDEX,MEC,ISU),INDEX
        IF(NUM.GT.0) MFLG=.F.
320  CONTINUE
      IF(MFLG) GO TO 350
      BFLG=.F.
      DO 330 INDEX=1,5
        DO 330 1PRA1,4
        FUNBAD(INDEX,IPR)=8
        GU TO (321,322,323,324),IPR
321  NUM=IGET(INDEX,MEC,ISU),INDEX
        IF(NUM.EQ.0) GO TO 325
      READIN2 278
      READIN2 279
      READIN2 280
      READIN2 281
      READIN2 282
      READIN2 283
      READIN2 284
      READIN2 285
      READIN2 286
      READIN2 287
      READIN2 288
      READIN2 289
      READIN2 290
      READIN2 291
      READIN2 292
      READIN2 293
      READIN2 294
      READIN2 295
      READIN2 296
      READIN2 297
      READIN2 298
      READIN2 299
      READIN2 300
      FINAL 46
      FINAL 47
      FINAL 48
      FINAL 49
      READIN2 301
      READIN2 302
      READIN2 303
      READIN2 304
      READIN2 305
      READIN2 306
      READIN2 307
      READIN2 308
      READIN2 309
      READIN2 310
      READIN2 311
      READIN2 312
      READIN2 313
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      READIN2 315
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      READIN2 337
      READIN2 338
      READIN2 339

```

```

        CUDGET(1,1,NUM)
        GO TO 325
322  NUMXIGET(NISO(MEC,ISU),INDEX)
        IF(NU.M,EQ.0) GO TO 325
        CODE3#P130(1,NU.M)
        GO TU 325
323  NUMXIGET(NBPR(MEC,ISU),INDEX)
        IF(NU.M,EQ.0) GO TU 325
        CODE3#FEP11,NUM)
        GU TO 325
324  NUMXIGET(NILR(MEC,ISU),INDEX)
        IF(NU.M,EQ.0) GO TO 325
        CODE3#FTL1(1,NU.M)
        LINE(INDEX,IPR)NUM
        IF((LINE(INDEX,1),EQ.0) GO TU 330
        IF(NU.M,EQ.0) GO TO 327
326  IF(CIGET(CODES,4),GT.0) GU TU 330
327  FUNBAD(INDEX,IPR)*X
        BFLG=.T.
330  CONTINUE
        WRITE(6,304)ISU,MEC,((LINE(I,J),J=1,4),I=1,5)
304  F0RMAT(10X,212.5X,5(3X,413))
        IF(BFLG) WRITE(6,305)((FUNBAD(I,J),J=1,4),I=1,5)
305  F0RMAT(39X,5(3X,4A3))
350  CONTINUE
        GU TU 1
C      DISPLAY RELEVANT SPECIFICATIONS FOR ALL DEFINED
C      FUNCTIONS IN THE COVERAGE DATA BASE
C
C      90 WRITE(6,400)(STAR,1,34)
400  F0RMAT(1H1,48X,*COVERAGE FUNCTION SPECIFICATIONS*/48X,34A1/)
        WRITE(6,401)
        WRITE(6,401)
401  F0RMAT(/59X,* DETECTION *//14X,*FUNCTION IGFT INTF ISCH *,
        * IREP COEF*,7X,*TDEL*,9X,*P1*,10X,*P2*,10X,*P3*,9X,
        * TDUH,*15X,*NUMBER*)/
        DO 420 NUM=1,200
        CODE8#FDET(1,NUM)
        IF(CIGET(CODES,4),EQ.0) GO TO 420
        IGFT#IGET(CODES,1)
        ISCH#IGET(CODES,2)
        IREP#IGET(CODES,3)
        INTF#IGET(CODES,5)
        WRITE(6,400)NUM,IGFT,INTF,ISCH,IREP,(#DET(1,NUM),I=2,7)
406  F0RMAT(1IX,216,316,F11.6,5E12.4)
420  CONTINUE
        WRITE(6,402)
        F0RMAT(/59X,* ISOLATION */14X,*FUNCTION IGFT INTF
        * 15X,*NUMBER*)/
        DO 430 NUM=1,50
        CODE9#P130(1,NUM)
        IF(CIGET(CODES,4),EQ.0) GO TU 430
        IGFT#IGET(CODES,1)
        INTF#IGET(CODES,5)
        WRITE(6,407)NUM,IGFT,INTF,(FISO(I,NUM),I=2,7)
407  F0RMAT(1IX,216,16,F11.6,5E12.4)
430  CONTINUE
        WRITE(6,403)
403  F0RMAT(/51X,* FAULT PROPAGATION RECOVERY */
        WRITE(6,405)
405  F0RMAT(14X,*FUNCTION IGFT INTF COEF*,8X,*P1*,10X,*P2*,10X,
        * P3*,9X,*TDUR*/15X,*NUMBER*/)
        DO 440 NUM=1,25
        CODE8#FEP1(1,NUM)
        IF(CIGET(CODES,4),EQ.0) GO TU 440

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107 IGET(I CODES,1)
110 INTF=IGET(I CODES,5)
111 WRITE(6,408)NUM,IGFT,INTF,FEPH(2,NUM),
112 *(FEPH(1,NUM),I=4,7)
113 FORMAT(11X,21B,16,F11.6,4E12.4)
114 CONTINUE
115 WRITE(6,404)
116 FORMAT('/*55X,* TIME LOST RECOVERY */')
117 WRITE(6,405)
118 DO 450 NUM=1,25
119   CODESS=FLW(1,NUM)
120   IF(IGET(I CODES,4),EQ,0.0) GO TO 450
121   IGET=IGET(I CODES,1)
122   INTF=IGET(I CODES,5)
123   INTF=IGET(I CODES,5)
124   WRITE(6,408)NUM,IGFT,INTF,FLTR(2,NUM),
125 *(FLW(1,NUM),I=4,7)
126 450 CONTINUE
127 GO TO 1
128 RETURN
129 * WRITE(6,99)ID,IP,NUM,IGFT,INTF,ISCH,IREP,COEF,
130 * TDEL,P1,P2,P3,TUH
131 * FORMAT('/*30X,*$SSSS ERROR ON CONTROL CARD $SSSS*/'
132 * 2A3,214,211,14,615,8)
133 * IF(DEBUG) GU TO 1
134 1000 STOP
C
C          ENTRY FOR RELIABILITY MODEL DATA BASE DISPLAY.
C          APPLICABLE PARAMETERS ONLY ARE PRINTED
C
C          ENTRY RITERS
C
135 WRITE(6,500)NRS,(STAR,1B1,2B)
136 500 FORMAT(1M1,51X,*DATA BASE FOR RUN=SET*/55X,17/
137 * 51X,23A1/*5X,*PARA*/5X,*METER*,49X,*STAGE/EQUATION NUMBER*/)
138 WRITE(6,501)((1,SLASH,PROD(I)),I=1,NPROD)
139 501 FORMAT(/6X,10(1I0,A1,I1))
140 CALL TRANSFR(Q1,1)
141 CALL TRANSFR(Q2,2)
142 CALL TRANSFR(N,3)
143 CALL TRANSFR(S,4)
144 CALL TRANSFR(W,5)
145 CALL TRANSFR(Z,B)
146 CALL TRANSFR(LLA,B)
147 CALL TRANSFR(MU,B)
148 CALL TRANSFR(GM,B)
149 CALL TRANSFR(C1,I0)
150 CALL TRANSFR(CD,I1)
151 CALL TRANSFR(C2,I2)
152 CALL TRANSFR(CD2,I3)
153 CALL TRANSFR(P,19)
154 CALL TRANSFR(CCR,14)
155 CALL TRANSFR(CDA,15)
156 CALL TRANSFR(PRC,16)
157 CALL TRANSFR(PRC2,17)
158 CALL TRANSFR(RV,18)
159 NAMBAVNAMES(S,NEB)
160 WRITE(6,502)NABAV
161 *NOT.LVARY) GO TO 510
162 RLPLG=PCW(IRES)
163 PCW(IRES)=OR(RLFLG,MB59)
164 NAMBAVNAMES(S,NEB)
165 WRITE(6,502)NABAV
166 FORMAT('/*5X,*ITER*/,15X,*PARAMETER TO BE VARIED = *,AS/
167 5X,*ATION*)')
168 502 DO 520 I=1,N10
169   ENCODE((10,503,NAMES(IRES)))I
170 503 FORMAT(15/5X)
171 DO 510 J=1,NPROD
172   OUT(J)=PARAM(I,J)
173 510

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520 CALL TRANSFR(OUT,IRES)
PCW(IRES)=DMLG
NAME(IRES)=NMSAV
530 IF(.,NOT.DMLG) RETURN
      WRITE(6,504)NUN,SLM2,SLM3,CBSF,RBN
504 FORMAT(//49X*DUAL MODE SYSTEM PARAMETERS//40X,
* NUMBER OF STAGES*,18/40X,*CHANNEL FAILURE RATE *,F12.8/
* 40X,*SYSTEM FAILURE RATE *,F13.8/40X,*CHANNEL FAILURE COV. *,LS//)
* F12.8/40X,*REALLOCATION SWITCH *,LS//)
      RETURN
END
SUBROUTINE TRANSFR(X,I)
C
C   USING APPLICABILITY FIELD OF PCW ELEMENT FOR EACH
C   PARAMETER, TRANSFR PRINTS THE PARAMETER NAME
C   AND VALUES FOR EACH STAGE IN WHICH IT IS USED
C
C
DIMENSION X(10),K(10),R(10)
EQUIVALENCE (K,R)
DATA B/10H
COMMON /GRAPH/M1JK(11),N
COMMON /DEF9/P(22),M(22)
INTEGER P
LOGICAL F1,F2
DO 5 J=1,N
  R(J)=X(J)
  F1=.F.
  IF((P(I))30,200,8
  A DO 20 J=1,N
    IF((ISHIFT(P(I),J+19))9,200,10
  9 F1=.T.
    ENCODE(10,11,R(U))K(J)
  11 FORMAT(16,UX)
  11 GO TO 20
  10 R(J)=B
  20 CONTINUE
  - IF(F1) GO TO 100
  - RETURN
  30 F2=.F.
  DO 40 J=1,N
    IF((ISHIFT(P(I),J+19))5,200,40
  45 F1=.T.
    IF(R(J).EQ.0.0) GO TO 40
    IF(R(I)).LT.0.001.OR.R(J).GT.0.999) F2=.T.
  40 CONTINUE
  IF(F1) GU TO 45
  RETURN
  45 DO 70 J=1,N
    IF((ISHIFT(P(I),J+19))47,200,60
  47 IF(F2) GU TO 50
    ENCODE(10,12,R(U))R(J)
  12 FORMAT(F10.8)
  50 GO TO 70
  50 ENCODE(10,13,R(U))R(J)
  13 FORMAT(E10.4)
  50 GO TO 70
  60 R(J)=B
  70 CONTINUE
  100 WRITE(6,14)R(I),(R(U),J=1,N)
  14 FORMAT(5X,A5,10I2X,A10)
  RETURN
  200 WRITE(6,201)
  201 FORMAT(//10X,*ERROR IN TRANSFR*)
  201 STOP
END
SUBROUTINE COVGEN(NRS,NPROD)
COVGEN

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      0  LTMPS0,0
      1  DU 27 J=1,8
      2  IF (JFSC(J), NE,1) GO TO 27
      3  CTMP=CTMP+FRAC(J)*COVERAGE(1,0,1,1)
      4  CONTINUE
      5  IF ((CTR(1),GT,0,0) CDTK(1)=CTMP/CTR(1)
      6  PFLG=(IGENP(1),LT,0),OR,(IGENP(1),GT,0,AND,NRS,EQ,1)
      7  IF ((NOT,(PFLG,OR,PRC(1)),LT,0,0)) GU TO 35
      8  IF ((ISWIFT(PCW(16),119))31,200,35
      9  PRC(1)=0,0
     10  DO 32 J=1,8
     11  IF ((JFSC(J),NE,1) GO TO 52
     12  PRC(1)=PRC(1)+FRAC(J)*COVERAGE(J,1,2,0)
     13  CONTINUE
     14  IF ((IP8C(J),NE,1) IF ((PFLG,OR,PRC2(1),LT,0,0)) 60 TO 40
     15  IF ((ISWIFT(PCW(17),119))36,200,40
     16  PRC2(1)=0,0
     17  DO 37 J=1,8
     18  IF ((IP8C(J),NE,1) GO TO 57
     19  PRC2(1)=PRC2(1)+FRAC(J)*COVERAGE(J,2,2,0)
     20  CONTINUE
     21  RETURN
     22  CONTINUE
     23  RETURN
     24  FORMAT(/10X,*ERROR IN COVGEN*)
     25  STOP
     26  END
     27  SUBROUTINE PGET(IR,I,NPROD)
     28
     29  C   TRANSFER A ROW OF ARRAY PARAM TO THE BASE-RUN
     30  C   VECTOR OF THE PARAMETER OF INTEREST
     31  COMMON /PARA1/QQ(10,2),IJK(10),N(10),KS(10)
     32  COMMON /PARAZ/XAM(10),XMU(10)
     33  COMMON /PARA3/RV(10),KZ(10),KW(10),P(10)
     34  COMMON /PARAV/CC(10,2),CCD(10,2),CTR(10),CDTR(10)
     35  COMMON /PARAS/XYZ(10,2),GMP(10),PPRC(10,2)
     36  COMMON /PARM/PARM(16,10)
     37  DO 20 J=1,NPROD
     38  VAL=PARAM(I,J)
     39  GU TU (1,2,3,4,5,6,7,8,9,10,11,12,13,14,15,16,17,18,19),IK
     40  1  QQ(J,1)=VAL
     41  2  QQ(J,2)=VAL
     42  GU TU 20
     43  3  N(J)=VAL
     44  GU TU 20
     45  4  KS(J)=VAL
     46  GU TU 20
     47  5  KW(J)=VAL
     48  GU TU 20
     49  6  KZ(J)=VAL
     50  GU TU 20
     51  7  XLM(X,J)=VAL
     52  GU TU 20
     53  8  XMU(J)=VAL
     54  GU TU 20
     55  9  GMP(J)=VAL
     56  GU TU 20
     57  10  CC(J,1)=VAL
     58  GU TU 20
     59  11  CCO(J,1)=VAL
     60  GU TU 20
     61  12  CC(J,2)=VAL
     62  GU TU 20
     63  13  CCO(J,2)=VAL
     64
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      60 TU 20
      61 CTR(J)IVAL
      62 GD TU 20
      63 CDTR(J)IVAL
      64 GU TU 20
      65 PPRC(J,1)IVAL
      66 GO TO 20
      67 GO TO 20
      68 PPRC(J,2)IVAL
      69 GO TO 20
      70 RV(J)IVAL
      71 GO TO 20
      72 PC(J)IVAL
      73 CONTINUE
      74 RETURN
      75 END

      SUBROUTINE DCR(J,UNITR,RELH1,RSYS)
      C
      C COMPUTE THE DUAL-MODE SYSTEM RELIABILITY, RSYS,
      C FOR THE JTH TIME STEP. ALSO RETURN VALUES FOR
      C SYSTEM AND INDIVIDUAL STAGE RELIABILITIES
      C ASSUMING MODE 1 OPERATION
      C
      C NOTE THAT DUE TO THE USE OF STRUCTURED NUMERICAL
      C INTEGRATIONS IN SUBPROGRAMS DCT2 AND DCT, DCR MAY
      C NOT BE CALLED FOR AN ARBITRARY VALUE OF CLTIME.
      C
      DIMENSION UNITR(8)
      COMMON /DRIVE/T,XYZ(2),NUN
      COMMON /PARA1/YXZ(20),IJK(20),NS(10)
      COMMON /PARA2/ZYX(40),SLM2,SLM3
      RSYS =1.0
      IF(J.EQ.1) GO TO 100
      DO 10 IX=1,NUN
      UNITR(IX)=DCRU(IX,1,NS(IX),T)
      10 RSYS=RSYS*UNITR(IX)
      RSYS=RSYS*EXP(-SLM2*T)
      ESLM3=EXP(-SLM3*T)
      RELH1=RSYS*ESLM3
      DO 20 IX=1,NUN
      20 RSYS=RSYS*DCT(IX,J)
      RSYS=RSYS*DCT2(J)
      RSYS=RSYS*ESLM3
      99 RETURN
      100 RELH1=RSYS
      101 DO 110 IX=1,NUN
      110 UNITR(IX)=RSYS
      111 GO TO 99
      END

      FUNCTION DCT2(J)
      C
      C FOR THE JTH TIME STEP, COMPUTE THE PROBABILITY
      C THAT THE DUAL MODE SYSTEM WILL HAVE SURVIVED
      C AND HAVE DEGRADED DUE TO A CATEGORY 2 SWITCH FAILURE
      C
      COMMON /DRIVE/T,STEP,HSTEP,NUN
      COMMON /PARA2/YXZ(40),SLM2
      COMMON /PARA4/ZYX(60),CCSF
      JN=2*J-1
      DC2=0.0
      DO 50 IT=1,JN
      TAU=HSTEP*(IT-1)
      PART =1.0
      DO 10 IX=1,NUN
      PART=PART*DCS(IX,T,TAU)
      10 PART=PART*EXP(-SLM2*T)
      IF(IT.GT.1) GO TO 10
      50 END
      
```

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40 DCT=DCT*PART
50 GO TO 50
50 IF(IT.EQ.JN) GO TO 20
50 IF(IT.EQ.2*(IT/2)) GO TO 40
50 DCT=DCT*2.0*PART
50 GO TO 50
50 CONTINUE
50 DCT2=BLH2*CCSF*M8TFP*DCT2/3.0
50 RETURN
END
FUNCTION DCT(IUN,J)
C
C   FOR TIME JTH TIME STEP, COMPUTE THE PROBABILITY
C   THAT THE DUAL MODE SYSTEM WILL HAVE SURVIVED
C   AND HAVE DEGRADED DUE TO A FAILURE IN STAGE IUN
C
COMMON /PARA1/XYZ(20),IDQ(10)
COMMON /PARA2/ZYX(40),SLH2
LOGICAL RSGN
JN=2+J-1
DCT=0.0
IF(IDG(IUN).LE.0) RETURN
LR=0
IF(RSGN) LR=IDG(IUN)=1
DO 50 IT=1,JN
TAU=MSTEP*(IT-1)
PART=DCR(IUN,2,LR,TAU)*DCH(IUN,TAU)
DO 10 JUN=1,NUN
IF(JUN.EQ.IUN) GO TO 10
PART=PART*DCS(IUN,T,TAU)
10 CONTINUE
PART=PART*EXP(-BLH2*TAU)
IF(IT.GT.1) GO TO 30
20 DCT=DCT+PART
GO TO 50
50 IF(IT.EQ.JN) GO TO 20
50 IF(IT.EQ.2*(IT/2)) GO TO 40
50 DCT=DCT*2.0*PART
50 GO TO 50
50 CONTINUE
50 DCT=MSTEP*DCT/5.0
50 RETURN
END
FUNCTION DCS(IUN,T,TAU)
C
C   COMPUTE THE CONDITIONAL PROBABILITY THAT STAGE IUN
C   OF THE DUAL MODE SYSTEM CAN SURVIVE IN MODE 2
C   FROM TAU TO T GIVEN THAT DEGRADING OCCURRED
C   AT TIME TAU
C
COMMON /PARA1/XYZ(4),RSGN
COMMON /PARA2/ZYX(10),IDQ(10),IJK(10),S(10)
COMMON /PARA2/ZYX(10),MU(10),YZX(10),BCOMPS(10)
INTEGER SPUM
REAL MU,HUXT
LOGICAL BCOMPS,RSGN
DCS=0.0
NSP=JUN
NSP1=NS+1
DO 50 LDPI=1,NSP1
LDLDP1=1
NSL=NS-LD
IF(.NOT.BCOMPS(IUN)) GO TU 40
50

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15      JP=NSL
16      IF (RSGN)   JP=JP+IDG(IUN)
17      PROD=DCG(IUN,1,L0,TAU)*DCR(IUN,2,JP,T-TAU)
18      GU TO 50
19
20      NSLP1=NSL+1
21      DO 50 JDP1=1,NSLP1
22      JD=JDP1+1
23      PROD=FNCK(NSL,JD)
24      MUX=TAU*MUC(IUN)
25      PROD=PROD*EXP(-JD*MUX)
26      ONEMX=1.0-EXP(-MUX)
27      PW=NSL-JD
28      IF (ONEMX.LE.0.0.AND.PW.LE.0) GU TO 45
29      PROD=PROD*ONEMX*PW
30      PROD=PROD*DCG(IUN,1,L0,TAU)
31      JP=JD
32      IF (RSGN)   JP=JP+IDG(IUN)
33      PROD=PROD*DCR(IUN,2,JP,T-TAU)
34      DC9=DC8*PROD
35      RETURN
36      END
37      FUNCTION DCH(IUN,TAU)
38
39      COMPUTE THE PROBABILITY DENSITY OF A DEGENERATIVE
40      FAILURE IN STAGE IUN OF THE DUAL MODE SYSTEM BY
41      TIME T
42
43      COMMON /PARA1/Q0(10,2),IJK(20),S(10)
44      COMMON /PARA2/LAM(10),MU(10),K(10),BCOMPS(10)
45      COMMON /PARA3/XYZ(40),CTR(10),CDTR(10)
46
47      INTEGER S
48      REAL LAM,K,MU
49      LOGICAL BCOMPS
50      NS8(IUN)
51      IF (BCOMPS(IUN)) GU TO 60
52      DCH=0.0
53      NSP1=N8+1
54      DU 50 IDP1=1,NSP1
55      ID=IDP1+1
56      PROD=DCG(IUN,1/NS-ID,TAU)*CTR(IUN)
57      IF (ID.EQ.0) GU TO 50
58      PART=CDTR(IUN)*(1.0-EXP(-MU(IUN)*TAU))
59      DU 25 11-ID
60      25  PRD=PROD*PART
61      25  DCH=DCH+PROD
62      25  DCH=LAM(IUN)*Q0(IUN,1)*DCH
63      25  RETURN
64      60  DCH=DCG(IUN,1,NS,TAU)*CTR(IUN)
65      GU TO 55
66
67      END
68      FUNCTION DCR(IUN,MD,L,TAU)
69
70      COMPUTE THE PROBABILITY OF USING AT MOST L SPARE
71      LRU'S IN STAGE IUN OF THE DUAL MODE SYSTEM
72      (OPERATING IN MODE MD) BY TIME TAU
73
74      DCRU=0.0
75      IF (L.LT.0) RETURN
76      LP1=L+1
77      DO 50 IDP1=1,LP1
78      ID=IDP1+1
79      DCRU=DCRU+DCG(IUN,MD,1D,TAU)
80      RETURN
81
82      END
83      FUNCTION DCG(IUN,MD,I,T)
84
85      COMPUTE THE PROBABILITY DENSITY OF USING AT MOST L SPARE
86      LRU'S IN STAGE IUN OF THE DUAL MODE SYSTEM
87      (OPERATING IN MODE MD) BY TIME TAU
88
89      DCRU=0.0
90      POSTPCH 5
91      DCRU=DCRU+DCG(IUN,MD,1D,TAU)
92      POSTPCH 6
93      DCRU=DCRU+DCG(IUN,MD,2D,TAU)
94      POSTPCH 7
95      DCRU=DCRU+DCG(IUN,MD,3D,TAU)
96      POSTPCH 8
97      DCRU=DCRU+DCG(IUN,MD,4D,TAU)
98      POSTPCH 9
99      DCRU=DCRU+DCG(IUN,MD,5D,TAU)
100     POSTPCH 10
101     DCRU=DCRU+DCG(IUN,MD,6D,TAU)
102     POSTPCH 11
103     DCRU=DCRU+DCG(IUN,MD,7D,TAU)
104     POSTPCH 12
105     DCRU=DCRU+DCG(IUN,MD,8D,TAU)
106     POSTPCH 13
107     DCRU=DCRU+DCG(IUN,MD,9D,TAU)
108     POSTPCH 14
109     DCRU=DCRU+DCG(IUN,MD,10D,TAU)
110     POSTPCH 15
111     DCRU=DCRU+DCG(IUN,MD,11D,TAU)
112     POSTPCH 16
113     DCRU=DCRU+DCG(IUN,MD,12D,TAU)
114     POSTPCH 17
115     DCRU=DCRU+DCG(IUN,MD,13D,TAU)
116     POSTPCH 18
117     DCRU=DCRU+DCG(IUN,MD,14D,TAU)
118     POSTPCH 19
119     DCRU=DCRU+DCG(IUN,MD,15D,TAU)
120     POSTPCH 20
121     DCRU=DCRU+DCG(IUN,MD,16D,TAU)
122     POSTPCH 21
123     DCRU=DCRU+DCG(IUN,MD,17D,TAU)
124     POSTPCH 22
125     DCRU=DCRU+DCG(IUN,MD,18D,TAU)
126     POSTPCH 23
127     DCRU=DCRU+DCG(IUN,MD,19D,TAU)
128     POSTPCH 24
129     DCRU=DCRU+DCG(IUN,MD,20D,TAU)
130     POSTPCH 25
131     DCRU=DCRU+DCG(IUN,MD,21D,TAU)
132     POSTPCH 26
133     DCRU=DCRU+DCG(IUN,MD,22D,TAU)
134     POSTPCH 27
135     DCRU=DCRU+DCG(IUN,MD,23D,TAU)
136     POSTPCH 28
137     DCRU=DCRU+DCG(IUN,MD,24D,TAU)
138     POSTPCH 29
139     DCRU=DCRU+DCG(IUN,MD,25D,TAU)
140     POSTPCH 30
141     DCRU=DCRU+DCG(IUN,MD,26D,TAU)
142     POSTPCH 31
143     DCRU=DCRU+DCG(IUN,MD,27D,TAU)
144     POSTPCH 32
145     DCRU=DCRU+DCG(IUN,MD,28D,TAU)
146     POSTPCH 33
147     DCRU=DCRU+DCG(IUN,MD,29D,TAU)
148     POSTPCH 34
149     DCRU=DCRU+DCG(IUN,MD,30D,TAU)
150     POSTPCH 35
151     DCRU=DCRU+DCG(IUN,MD,31D,TAU)
152     POSTPCH 36
153     DCRU=DCRU+DCG(IUN,MD,32D,TAU)
154     POSTPCH 37
155     DCRU=DCRU+DCG(IUN,MD,33D,TAU)
156     POSTPCH 38
157     DCRU=DCRU+DCG(IUN,MD,34D,TAU)
158     POSTPCH 39
159     DCRU=DCRU+DCG(IUN,MD,35D,TAU)
160     POSTPCH 40
161     DCRU=DCRU+DCG(IUN,MD,36D,TAU)
162     POSTPCH 41
163     DCRU=DCRU+DCG(IUN,MD,37D,TAU)
164     POSTPCH 42
165     DCRU=DCRU+DCG(IUN,MD,38D,TAU)
166     POSTPCH 43
167     DCRU=DCRU+DCG(IUN,MD,39D,TAU)
168     POSTPCH 44
169     DCRU=DCRU+DCG(IUN,MD,40D,TAU)
170     POSTPCH 45
171     DCRU=DCRU+DCG(IUN,MD,41D,TAU)
172     POSTPCH 46
173     DCRU=DCRU+DCG(IUN,MD,42D,TAU)
174     POSTPCH 47
175     DCRU=DCRU+DCG(IUN,MD,43D,TAU)
176     POSTPCH 48
177     DCRU=DCRU+DCG(IUN,MD,44D,TAU)
178     POSTPCH 49
179     DCRU=DCRU+DCG(IUN,MD,45D,TAU)
180     POSTPCH 50
181     DCRU=DCRU+DCG(IUN,MD,46D,TAU)
182     POSTPCH 51
183     DCRU=DCRU+DCG(IUN,MD,47D,TAU)
184     POSTPCH 52
185     DCRU=DCRU+DCG(IUN,MD,48D,TAU)
186     POSTPCH 53
187     DCRU=DCRU+DCG(IUN,MD,49D,TAU)
188     POSTPCH 54
189     DCRU=DCRU+DCG(IUN,MD,50D,TAU)
190     POSTPCH 55
191     DCRU=DCRU+DCG(IUN,MD,51D,TAU)
192     POSTPCH 56
193     DCRU=DCRU+DCG(IUN,MD,52D,TAU)
194     POSTPCH 57
195     DCRU=DCRU+DCG(IUN,MD,53D,TAU)
196     POSTPCH 58
197     DCRU=DCRU+DCG(IUN,MD,54D,TAU)
198     POSTPCH 59
199     DCRU=DCRU+DCG(IUN,MD,55D,TAU)
200     POSTPCH 60
201     DCRU=DCRU+DCG(IUN,MD,56D,TAU)
202     POSTPCH 61
203     DCRU=DCRU+DCG(IUN,MD,57D,TAU)
204     POSTPCH 62
205     DCRU=DCRU+DCG(IUN,MD,58D,TAU)
206     POSTPCH 63
207     DCRU=DCRU+DCG(IUN,MD,59D,TAU)
208     POSTPCH 64
209     DCRU=DCRU+DCG(IUN,MD,60D,TAU)
210     POSTPCH 65
211     DCRU=DCRU+DCG(IUN,MD,61D,TAU)
212     POSTPCH 66
213     DCRU=DCRU+DCG(IUN,MD,62D,TAU)
214     POSTPCH 67
215     DCRU=DCRU+DCG(IUN,MD,63D,TAU)
216     POSTPCH 68
217     DCRU=DCRU+DCG(IUN,MD,64D,TAU)
218     POSTPCH 69
219     DCRU=DCRU+DCG(IUN,MD,65D,TAU)
220     POSTPCH 70
221     DCRU=DCRU+DCG(IUN,MD,66D,TAU)
222     POSTPCH 71
223     DCRU=DCRU+DCG(IUN,MD,67D,TAU)
224     POSTPCH 72
225     DCRU=DCRU+DCG(IUN,MD,68D,TAU)
226     POSTPCH 73
227     DCRU=DCRU+DCG(IUN,MD,69D,TAU)
228     POSTPCH 74
229     DCRU=DCRU+DCG(IUN,MD,70D,TAU)
230     POSTPCH 75
231     DCRU=DCRU+DCG(IUN,MD,71D,TAU)
232     POSTPCH 76
233     DCRU=DCRU+DCG(IUN,MD,72D,TAU)
234     POSTPCH 77
235     DCRU=DCRU+DCG(IUN,MD,73D,TAU)
236     POSTPCH 78
237     DCRU=DCRU+DCG(IUN,MD,74D,TAU)
238     POSTPCH 79
239     DCRU=DCRU+DCG(IUN,MD,75D,TAU)
240     POSTPCH 80
241     DCRU=DCRU+DCG(IUN,MD,76D,TAU)
242     POSTPCH 81
243     DCRU=DCRU+DCG(IUN,MD,77D,TAU)
244     POSTPCH 82
245     DCRU=DCRU+DCG(IUN,MD,78D,TAU)
246     POSTPCH 83
247     DCRU=DCRU+DCG(IUN,MD,79D,TAU)
248     POSTPCH 84
249     DCRU=DCRU+DCG(IUN,MD,80D,TAU)
250     POSTPCH 85
251     DCRU=DCRU+DCG(IUN,MD,81D,TAU)
252     POSTPCH 86
253     DCRU=DCRU+DCG(IUN,MD,82D,TAU)
254     POSTPCH 87
255     DCRU=DCRU+DCG(IUN,MD,83D,TAU)
256     POSTPCH 88
257     DCRU=DCRU+DCG(IUN,MD,84D,TAU)
258     POSTPCH 89
259     DCRU=DCRU+DCG(IUN,MD,85D,TAU)
260     POSTPCH 90
261     DCRU=DCRU+DCG(IUN,MD,86D,TAU)
262     POSTPCH 91
263     DCRU=DCRU+DCG(IUN,MD,87D,TAU)
264     POSTPCH 92
265     DCRU=DCRU+DCG(IUN,MD,88D,TAU)
266     POSTPCH 93
267     DCRU=DCRU+DCG(IUN,MD,89D,TAU)
268     POSTPCH 94
269     DCRU=DCRU+DCG(IUN,MD,90D,TAU)
270     POSTPCH 95
271     DCRU=DCRU+DCG(IUN,MD,91D,TAU)
272     POSTPCH 96
273     DCRU=DCRU+DCG(IUN,MD,92D,TAU)
274     POSTPCH 97
275     DCRU=DCRU+DCG(IUN,MD,93D,TAU)
276     POSTPCH 98
277     DCRU=DCRU+DCG(IUN,MD,94D,TAU)
278     POSTPCH 99
279     DCRU=DCRU+DCG(IUN,MD,95D,TAU)
280     POSTPCH 100
281     DCRU=DCRU+DCG(IUN,MD,96D,TAU)
282     POSTPCH 101
283     DCRU=DCRU+DCG(IUN,MD,97D,TAU)
284     POSTPCH 102
285     DCRU=DCRU+DCG(IUN,MD,98D,TAU)
286     POSTPCH 103
287     DCRU=DCRU+DCG(IUN,MD,99D,TAU)
288     POSTPCH 104
289     DCRU=DCRU+DCG(IUN,MD,100D,TAU)
290     POSTPCH 105
291     DCRU=DCRU+DCG(IUN,MD,101D,TAU)
292     POSTPCH 106
293     DCRU=DCRU+DCG(IUN,MD,102D,TAU)
294     POSTPCH 107
295     DCRU=DCRU+DCG(IUN,MD,103D,TAU)
296     POSTPCH 108
297     DCRU=DCRU+DCG(IUN,MD,104D,TAU)
298     POSTPCH 109
299     DCRU=DCRU+DCG(IUN,MD,105D,TAU)
300     POSTPCH 110
301     DCRU=DCRU+DCG(IUN,MD,106D,TAU)
302     POSTPCH 111
303     DCRU=DCRU+DCG(IUN,MD,107D,TAU)
304     POSTPCH 112
305     DCRU=DCRU+DCG(IUN,MD,108D,TAU)
306     POSTPCH 113
307     DCRU=DCRU+DCG(IUN,MD,109D,TAU)
308     POSTPCH 114
309     DCRU=DCRU+DCG(IUN,MD,110D,TAU)
310     POSTPCH 115
311     DCRU=DCRU+DCG(IUN,MD,111D,TAU)
312     POSTPCH 116
313     DCRU=DCRU+DCG(IUN,MD,112D,TAU)
314     POSTPCH 117
315     DCRU=DCRU+DCG(IUN,MD,113D,TAU)
316     POSTPCH 118
317     DCRU=DCRU+DCG(IUN,MD,114D,TAU)
318     POSTPCH 119
319     DCRU=DCRU+DCG(IUN,MD,115D,TAU)
320     POSTPCH 120
321     DCRU=DCRU+DCG(IUN,MD,116D,TAU)
322     POSTPCH 123
323     DCRU=DCRU+DCG(IUN,MD,117D,TAU)
324     POSTPCH 125
325     DCRU=DCRU+DCG(IUN,MD,118D,TAU)
326     POSTPCH 127
327     DCRU=DCRU+DCG(IUN,MD,119D,TAU)
328     POSTPCH 129
329     DCRU=DCRU+DCG(IUN,MD,120D,TAU)
330     POSTPCH 131
331     DCRU=DCRU+DCG(IUN,MD,121D,TAU)
332     POSTPCH 133
333     DCRU=DCRU+DCG(IUN,MD,122D,TAU)
334     POSTPCH 135
335     DCRU=DCRU+DCG(IUN,MD,123D,TAU)
336     POSTPCH 137
337     DCRU=DCRU+DCG(IUN,MD,124D,TAU)
338     POSTPCH 139
339     DCRU=DCRU+DCG(IUN,MD,125D,TAU)
340     POSTPCH 141
341     DCRU=DCRU+DCG(IUN,MD,126D,TAU)
342     POSTPCH 143
343     DCRU=DCRU+DCG(IUN,MD,127D,TAU)
344     POSTPCH 145
345     DCRU=DCRU+DCG(IUN,MD,128D,TAU)
346     POSTPCH 147
347     DCRU=DCRU+DCG(IUN,MD,129D,TAU)
348     POSTPCH 149
349     DCRU=DCRU+DCG(IUN,MD,130D,TAU)
350     POSTPCH 151
351     DCRU=DCRU+DCG(IUN,MD,131D,TAU)
352     POSTPCH 153
353     DCRU=DCRU+DCG(IUN,MD,132D,TAU)
354     POSTPCH 155
355     DCRU=DCRU+DCG(IUN,MD,133D,TAU)
356     POSTPCH 157
357     DCRU=DCRU+DCG(IUN,MD,134D,TAU)
358     POSTPCH 159
359     DCRU=DCRU+DCG(IUN,MD,135D,TAU)
360     POSTPCH 161
361     DCRU=DCRU+DCG(IUN,MD,136D,TAU)
362     POSTPCH 163
363     DCRU=DCRU+DCG(IUN,MD,137D,TAU)
364     POSTPCH 165
365     DCRU=DCRU+DCG(IUN,MD,138D,TAU)
366     POSTPCH 167
367     DCRU=DCRU+DCG(IUN,MD,139D,TAU)
368     POSTPCH 169
369     DCRU=DCRU+DCG(IUN,MD,140D,TAU)
370     POSTPCH 171
371     DCRU=DCRU+DCG(IUN,MD,141D,TAU)
372     POSTPCH 173
373     DCRU=DCRU+DCG(IUN,MD,142D,TAU)
374     POSTPCH 175
375     DCRU=DCRU+DCG(IUN,MD,143D,TAU)
376     POSTPCH 177
377     DCRU=DCRU+DCG(IUN,MD,144D,TAU)
378     POSTPCH 179
379     DCRU=DCRU+DCG(IUN,MD,145D,TAU)
380     POSTPCH 181
381     DCRU=DCRU+DCG(IUN,MD,146D,TAU)
382     POSTPCH 183
383     DCRU=DCRU+DCG(IUN,MD,147D,TAU)
384     POSTPCH 185
385     DCRU=DCRU+DCG(IUN,MD,148D,TAU)
386     POSTPCH 187
387     DCRU=DCRU+DCG(IUN,MD,149D,TAU)
388     POSTPCH 189
389     DCRU=DCRU+DCG(IUN,MD,150D,TAU)
390     POSTPCH 191
391     DCRU=DCRU+DCG(IUN,MD,152D,TAU)
392     POSTPCH 193
393     DCRU=DCRU+DCG(IUN,MD,154D,TAU)
394     POSTPCH 195
395     DCRU=DCRU+DCG(IUN,MD,156D,TAU)
396     POSTPCH 197
397     DCRU=DCRU+DCG(IUN,MD,158D,TAU)
398     POSTPCH 199
399     DCRU=DCRU+DCG(IUN,MD,160D,TAU)
400     POSTPCH 201
401     DCRU=DCRU+DCG(IUN,MD,162D,TAU)
402     POSTPCH 203
403     DCRU=DCRU+DCG(IUN,MD,164D,TAU)
404     POSTPCH 205
405     DCRU=DCRU+DCG(IUN,MD,166D,TAU)
406     POSTPCH 207
407     DCRU=DCRU+DCG(IUN,MD,168D,TAU)
408     POSTPCH 209
409     DCRU=DCRU+DCG(IUN,MD,170D,TAU)
410     POSTPCH 211
411     DCRU=DCRU+DCG(IUN,MD,172D,TAU)
412     POSTPCH 213
413     DCRU=DCRU+DCG(IUN,MD,174D,TAU)
414     POSTPCH 215
415     DCRU=DCRU+DCG(IUN,MD,176D,TAU)
416     POSTPCH 217
417     DCRU=DCRU+DCG(IUN,MD,178D,TAU)
418     POSTPCH 219
419     DCRU=DCRU+DCG(IUN,MD,180D,TAU)
420     POSTPCH 221
421     DCRU=DCRU+DCG(IUN,MD,182D,TAU)
422     POSTPCH 223
423     DCRU=DCRU+DCG(IUN,MD,184D,TAU)
424     POSTPCH 225
425     DCRU=DCRU+DCG(IUN,MD,186D,TAU)
426     POSTPCH 227
427     DCRU=DCRU+DCG(IUN,MD,188D,TAU)
428     POSTPCH 229
429     DCRU=DCRU+DCG(IUN,MD,190D,TAU)
430     POSTPCH 231
431     DCRU=DCRU+DCG(IUN,MD,192D,TAU)
432     POSTPCH 233
433     DCRU=DCRU+DCG(IUN,MD,194D,TAU)
434     POSTPCH 235
435     DCRU=DCRU+DCG(IUN,MD,196D,TAU)
436     POSTPCH 237
437     DCRU=DCRU+DCG(IUN,MD,198D,TAU)
438     POSTPCH 239
439     DCRU=DCRU+DCG(IUN,MD,200D,TAU)
440     POSTPCH 241
441     DCRU=DCRU+DCG(IUN,MD,202D,TAU)
442     POSTPCH 243
443     DCRU=DCRU+DCG(IUN,MD,204D,TAU)
444     POSTPCH 245
445     DCRU=DCRU+DCG(IUN,MD,206D,TAU)
446     POSTPCH 247
447     DCRU=DCRU+DCG(IUN,MD,208D,TAU)
448     POSTPCH 249
449     DCRU=DCRU+DCG(IUN,MD,210D,TAU)
450     POSTPCH 251
451     DCRU=DCRU+DCG(IUN,MD,212D,TAU)
452     POSTPCH 253
453     DCRU=DCRU+DCG(IUN,MD,214D,TAU)
454     POSTPCH 255
455     DCRU=DCRU+DCG(IUN,MD,216D,TAU)
456     POSTPCH 257
457     DCRU=DCRU+DCG(IUN,MD,218D,TAU)
458     POSTPCH 259
459     DCRU=DCRU+DCG(IUN,MD,220D,TAU)
460     POSTPCH 261
461     DCRU=DCRU+DCG(IUN,MD,222D,TAU)
462     POSTPCH 263
463     DCRU=DCRU+DCG(IUN,MD,224D,TAU)
464     POSTPCH 265
465     DCRU=DCRU+DCG(IUN,MD,226D,TAU)
466     POSTPCH 267
467     DCRU=DCRU+DCG(IUN,MD,228D,TAU)
468     POSTPCH 269
469     DCRU=DCRU+DCG(IUN,MD,230D,TAU)
470     POSTPCH 271
471     DCRU=DCRU+DCG(IUN,MD,232D,TAU)
472     POSTPCH 273
473     DCRU=DCRU+DCG(IUN,MD,234D,TAU)
474     POSTPCH 275
475     DCRU=DCRU+DCG(IUN,MD,236D,TAU)
476     POSTPCH 277
477     DCRU=DCRU+DCG(IUN,MD,238D,TAU)
478     POSTPCH 279
479     DCRU=DCRU+DCG(IUN,MD,240D,TAU)
480     POSTPCH 281
481     DCRU=DCRU+DCG(IUN,MD,242D,TAU)
482     POSTPCH 283
483     DCRU=DCRU+DCG(IUN,MD,244D,TAU)
484     POSTPCH 285
485     DCRU=DCRU+DCG(IUN,MD,246D,TAU)
486     POSTPCH 287
487     DCRU=DCRU+DCG(IUN,MD,248D,TAU)
488     POSTPCH 289
489     DCRU=DCRU+DCG(IUN,MD,250D,TAU)
490     POSTPCH 291
491     DCRU=DCRU+DCG(IUN,MD,252D,TAU)
492     POSTPCH 293
493     DCRU=DCRU+DCG(IUN,MD,254D,TAU)
494     POSTPCH 295
495     DCRU=DCRU+DCG(IUN,MD,256D,TAU)
496     POSTPCH 297
497     DCRU=DCRU+DCG(IUN,MD,258D,TAU)
498     POSTPCH 299
499     DCRU=DCRU+DCG(IUN,MD,260D,TAU)
500     POSTPCH 301
501     DCRU=DCRU+DCG(IUN,MD,262D,TAU)
502     POSTPCH 303
503     DCRU=DCRU+DCG(IUN,MD,264D,TAU)
504     POSTPCH 305
505     DCRU=DCRU+DCG(IUN,MD,266D,TAU)
506     POSTPCH 307
507     DCRU=DCRU+DCG(IUN,MD,268D,TAU)
508     POSTPCH 309
509     DCRU=DCRU+DCG(IUN,MD,270D,TAU)
510     POSTPCH 311
511     DCRU=DCRU+DCG(IUN,MD,272D,TAU)
512     POSTPCH 313
513     DCRU=DCRU+DCG(IUN,MD,274D,TAU)
514     POSTPCH 315
515     DCRU=DCRU+DCG(IUN,MD,276D,TAU)
516     POSTPCH 317
517     DCRU=DCRU+DCG(IUN,MD,278D,TAU)
518     POSTPCH 319
519     DCRU=DCRU+DCG(IUN,MD,280D,TAU)
520     POSTPCH 321
521     DCRU=DCRU+DCG(IUN,MD,282D,TAU)
522     POSTPCH 323
523     DCRU=DCRU+DCG(IUN,MD,284D,TAU)
524     POSTPCH 325
525     DCRU=DCRU+DCG(IUN,MD,286D,TAU)
526     POSTPCH 327
527     DCRU=DCRU+DCG(IUN,MD,288D,TAU)
528     POSTPCH 329
529     DCRU=DCRU+DCG(IUN,MD,290D,TAU)
530     POSTPCH 331
531     DCRU=DCRU+DCG(IUN,MD,292D,TAU)
532     POSTPCH 333
533     DCRU=DCRU+DCG(IUN,MD,294D,TAU)
534     POSTPCH 335
535     DCRU=DCRU+DCG(IUN,MD,296D,TAU)
536     POSTPCH 337
537     DCRU=DCRU+DCG(IUN,MD,298D,TAU)
538     POSTPCH 339
539     DCRU=DCRU+DCG(IUN,MD,300D,TAU)
540     POSTPCH 341
541     DCRU=DCRU+DCG(IUN,MD,302D,TAU)
542     POSTPCH 343
543     DCRU=DCRU+DCG(IUN,MD,304D,TAU)
544     POSTPCH 345
545     DCRU=DCRU+DCG(IUN,MD,306D,TAU)
546     POSTPCH 347
547     DCRU=DCRU+DCG(IUN,MD,308D,TAU)
548     POSTPCH 349
549     DCRU=DCRU+DCG(IUN,MD,310D,TAU)
550     POSTPCH 351
551     DCRU=DCRU+DCG(IUN,MD,312D,TAU)
552     POSTPCH 353
553     DCRU=DCRU+DCG(IUN,MD,314D,TAU)
554     POSTPCH 355
555     DCRU=DCRU+DCG(IUN,MD,316D,TAU)
556     POSTPCH 357
557     DCRU=DCRU+DCG(IUN,MD,318D,TAU)
558     POSTPCH 359
559     DCRU=DCRU+DCG(IUN,MD,320D,TAU)
560     POSTPCH 361
561     DCRU=DCRU+DCG(IUN,MD,322D,TAU)
562     POSTPCH 363
563     DCRU=DCRU+DCG(IUN,MD,324D,TAU)
564     POSTPCH 365
565     DCRU=DCRU+DCG(IUN,MD,326D,TAU)
566     POSTPCH 367
567     DCRU=DCRU+DCG(IUN,MD,328D,TAU)
568     POSTPCH 369
569     DCRU=DCRU+DCG(IUN,MD,330D,TAU)
570     POSTPCH 371
571     DCRU=DCRU+DCG(IUN,MD,332D,TAU)
572     POSTPCH 373
573     DCRU=DCRU+DCG(IUN,MD,334D,TAU)
574     POSTPCH 375
575     DCRU=DCRU+DCG(IUN,MD,336D,TAU)
576     POSTPCH 377
577     DCRU=DCRU+DCG(IUN,MD,338D,TAU)
578     POSTPCH 379
579     DCRU=DCRU+DCG(IUN,MD,340D,TAU)
580     POSTPCH 381
581     DCRU=DCRU+DCG(IUN,MD,342D,TAU)
582     POSTPCH 383
583     DCRU=DCRU+DCG(IUN,MD,344D,TAU)
584     POSTPCH 385
585     DCRU=DCRU+DCG(IUN,MD,346D,TAU)
586     POSTPCH 387
587     DCRU=DCRU+DCG(IUN,MD,348D,TAU)
588     POSTPCH 389
589     DCRU=DCRU+DCG(IUN,MD,350D,TAU)
590     POSTPCH 391
591     DCRU=DCRU+DCG(IUN,MD,352D,TAU)
592     POSTPCH 393
593     DCRU=DCRU+DCG(IUN,MD,354D,TAU)
594     POSTPCH 395
595     DCRU=DCRU+DCG(IUN,MD,356D,TAU)
596     POSTPCH 397
597     DCRU=DCRU+DCG(IUN,MD,358D,TAU)
598     POSTPCH 399
599     DCRU=DCRU+DCG(IUN,MD,360D,TAU)
600     POSTPCH 401
601     DCRU=DCRU+DCG(IUN,MD,362D,TAU)
602     POSTPCH 403
603     DCRU=DCRU+DCG(IUN,MD,364D,TAU)
604     POSTPCH 405
605     DCRU=DCRU+DCG(IUN,MD,366D,TAU)
606     POSTPCH 407
607     DCRU=DCRU+DCG(IUN,MD,368D,TAU)
608     POSTPCH 409
609     DCRU=DCRU+DCG(IUN,MD,370D,TAU)
610     POSTPCH 411
611     DCRU=DCRU+DCG(IUN,MD,372D,TAU)
612     POSTPCH 413
613     DCRU=DCRU+DCG(IUN,MD,374D,TAU)
614     POSTPCH 415
615     DCRU=DCRU+DCG(IUN,MD,376D,TAU)
616     POSTPCH 417
617     DCRU=DCRU+DCG(IUN,MD,378D,TAU)
618     POSTPCH 419
619     DCRU=DCRU+DCG(IUN,MD,380D,TAU)
620     POSTPCH 421
621     DCRU=DCRU+DCG(IUN,MD,382D,TAU)
622     POSTPCH 423
623     DCRU=DCRU+DCG(IUN,MD,384D,TAU)
624     POSTPCH 425
625     DCRU=DCRU+DCG(IUN,MD,386D,TAU)
626     POSTPCH 427
627     DCRU=DCRU+DCG(IUN,MD,388D,TAU)
628     POSTPCH 429
629     DCRU=DCRU+DCG(IUN,MD,390D,TAU)
630     POSTPCH 431
631     DCRU=DCRU+DCG(IUN,MD,392D,TAU)
632     POSTPCH 433
633     DCRU=DCRU+DCG(IUN,MD,394D,TAU)
634     POSTPCH 435
635     DCRU=DCRU+DCG(IUN,MD,396D,TAU)
636     POSTPCH 437
637     DCRU=DCRU+DCG(IUN,MD,398D,TAU)
638     POSTPCH 439
639     DCRU=DCRU+DCG(IUN,MD,400D,TAU)
640     POSTPCH 441
641     DCRU=DCRU+DCG(IUN,MD,402D,TAU)
642     POSTPCH 443
643     DCRU=DCRU+DCG(IUN,MD,404D,TAU)
644     POSTPCH 445
645     DCRU=DCRU+DCG(IUN,MD,406D,TAU)
646     POSTPCH 447
647     DCRU=DCRU+DCG(IUN,MD,408D,TAU)
648     POST
```

```

C LUMP UP THE PROBABILITY OF USING EXACTLY I SPARE
C LRUs IN STAGE IUN OF THE DUAL MODE SYSTEM
C (OPERATING IN MODE MD) BY TIME T
C
COMMON /PARA1/DQ(10,2)
COMMON /PARA2/LAM(10),MU(10),K(10),BCOMPS(10)
COMMON /PARA4/CC(10,2),CCD(10,2)
COMMON /PARAS/GGM(10,2)
REAL LAM,K,MU
LOGICAL BCUMPS
DATA(IUN,MD)
DCG=1.0
IF(BCOMPS(IUN)) GO TO 30
IF(I.LE.0) GU TO 20
PART=CC(IUN,MD)*(I-EXP(-MU(IUN)*T))
DO 10 1D=1,1
10 DCG=DCG*PART
20 DCG=DCG+DCUMB(K(IUN)*Q*CC(IUN,MD)/CCD(IUN,MD)*(I=1),1)
25 DCG=DCG*EXP(-GGM(IUN,MD)*T)
DCG=DCG*PART
30 IF(I.LE.0) GO TO 25
PART=Q*CC(IUN,MD)*LAM(IUN)*T
DO 40 1D=1,1
40 DCG=DCG*PART/IU
GU TO 25
END
FUNCTION DCOMB(TOP,C)
DCOMB=1.0
DCOMB=DCOMB*TOP
RETURN
C
C DCOMB RETURN THE BINOMIAL COEFFICIENT OF THE
C EXPRESSION (TOP C K)
C
COMMON /PARA1/DQ(10,2)
COMMON /PARA2/LAM(10),MU(10),K(10),BCOMPS(10)
COMMON /PARA4/CC(10,2),CCD(10,2)
COMMON /PARAS/GGM(10,2)
REAL LAM,K,MU
LOGICAL BCUMPS
DATA(IUN,MD)
DCG=1.0
IF(K.LE.0) GO TO 99
DO 30 1D=1,K
30 COM=COM*(TOP-I+1)
99 COM=COM/FACT(K)
99 DCOMB=COM
RETURN
END
C
C COMPUTE THE COVERAGE PROVIDED BY UP TO 20 D/I/R/
C MECHANISMS COMPETING FOR THE DETECTION AND ISOLATION
C OF, AND THE RECOVERY FROM FAULTS OF SUBCLASS ISSU,
C WHEN JS SPARE LRUs MUST BE CHECKED OUT AS PART
C OF THE RECOVERY PROCESS
C
C MECHANISM CHARACTERISTICS WILL DEPEND ON SYSTEM
C OPERATIONAL MODE (MD) AND FAULT TYPE (IET)
C
FUNCTION COVERAGE(ISSU,MD,IET,JS)
DIMENSION PDIRAR(20)
COMMON /CVB0/COVINT
COMMON /CVB1/NDET(20,8),NISO(20,8),NEPH(20,8),NTLR(20,8)
COMMON /CVB2/FDET(7,200),FISO(7,50),FPR(7,25),TLR(7,25)
1 /CVB3/NDSAV(20),NISAV(20),NR1SAV(20),NR2SAV(20)
2 /CVB7/ICMAR(20),PDETAR(20),IREPAR(20),PERIAR(20),TDELAR(20)
3 /CVB4/P1,P2,P3,TDUR,IGFT
4 /CVB5/PFD(6),TFDS(8)
5 /CVB5/PFD(6),TFDS(8) /CVB6/LCM,TMINOR,FACTOR
6 /CVB8/GPFLG,GPAK(20,10) /CVB9/N
LOGICAL IMPG,IMPH,FOUT,FIN,GPFLG,COVINT
NIGN+1
INDEX=2*IET+MD=2
IF(MD.EQ.0) INDEX=5
FAILFAC=PFD9(ISSU)*JS
LCM=1

```

```

C      PHEPROCESSING LOOP!
C      DETERMINES THE CHARACTERISTIC CODE FOR EACH DETECTOR
C      (0 IS USED FOR ANY MECHANISM WHICH IS NOT PROPERLY
C      DEFINED) AND LOCALIZES OTHER PARAMETERS
C
C      DO 1  I=1,20
C      NERRS=0
C      ICMAR(1)=0
C      NUM=IGET(INDET(1,ISU),INDEX)
C      IF(NUM.EQ.0) GO TO 1
C      NDSAV(1)=NUM
C      CODES=DET(1,NUM)
C      IF(IGET(CODES,4).EQ.0) NERRS=NERRS+1
C      KCFTRIGET(CODES,1)
C      KSCHIGET(CODES,2)
C      KREPGET(CODES,3)
C      IF(KSCHEQ.1.AND.KREP.EQ.0) NERRS=NERRS+1
C      IREPAR(1)=KREP
C      PERIAR(2)=TMINORKEP
C      PDETAR(1)=PDET(2,NUM)
C      TDELAR(1)=PDET(3,NUM)
C      PDIHAR(1)=PDETAR(1)
C      NUM=IGET(NISU(1,ISU),INDEX)
C      IF(NUM.GT.0) GO TO 310
C      QU TO 320
C      NERRS=NERRS+1
C
310  NISAV(1)=NUM
C      CODES=SO(1,NUM)
C      IF(IGET(CODES,4).EQ.0) NERRS=NERRS+1
C      PDIRAR(1)=PDIRAR(1)+1
C      NUM=IGET(NEPRI(1,ISU),INDEX)
C      IF(NUM.GT.0) GO TO 330
C      NERRS=NERRS+1
C      GO TO 340
C
330  NRISAV(1)=NUM
C      CODES=FEPR(1,NUM)
C      IF(IGET(CODES,1).EQ.0.OR.IGET(CODES,4).EQ.0) NERRS=NERRS+1
C      PDIRAR(1)=PDIRAR(1)+1
C      NUM=IGET(INTLR(1,ISU),INDEX)
C      IF(NUM.GT.0) GO TO 350
C      NERRS=NERRS+1
C      GO TO 160
C
350  NR2SAV(1)=NUM
C      CODES=FTLH(1,NUM)
C      IF(IGET(CODES,1).EQ.0.OR.IGET(CODES,4).EQ.0) NERRS=NERRS+1
C      PDIHAR(1)=PDIRAR(1)+1
C      FTLR(2,NUM)
C      IF(PDIHAR(1).LE.0) NERRS=NERRS+1
C      IF(NERRS.EQ.0) GO TO 201
C      WRITE(6,11)NERRS,I18U,MD,IELT
C      11 FORMAT(17*ERROR(S) IN COV, MECH,*,*)
C      11 * WHEN ISU **,12,*, MD **,12,*, IELT **,12)
C      GO TO 1
C
201  IF(KSCHEQ.1) GU TO 210
C      IF(KREP.GT.1LCM) GC TU 205
C      IF(1LCM.GT.KREP) C TU 206
C      GU TO 210
C
205  IASKREP
C      IBALCP
C      GU TU 207
C
206  IASLCM
C      IBALKREP
C
207  M2=4
C      M1=16
C
208  MMEM2=MMEM1
C      MMEM2/MMEM1
C
C      FINAL 12
C      FINAL 13
C      FINAL 14
C      FINAL 15
C      FINAL 16
C      FINAL 17
C      COVERAGE 17
C      COVERAGE 18
C      COVERAGE 19
C      COVERAGE 20
C      COVERAGE 21
C      COVERAGE 22
C      COVERAGE 23
C      COVERAGE 24
C      COVERAGE 25
C      COVERAGE 26
C      COVERAGE 27
C      COVERAGE 28
C      COVERAGE 29
C      COVERAGE 30
C      COVERAGE 31
C      COVERAGE 32
C      COVERAGE 33
C      COVERAGE 34
C      COVERAGE 35
C      COVERAGE 36
C      COVERAGE 37
C      COVERAGE 38
C      COVERAGE 39
C      COVERAGE 40
C      COVERAGE 41
C      COVERAGE 42
C      COVERAGE 43
C      COVERAGE 44
C      COVERAGE 45
C      COVERAGE 46
C      COVERAGE 47
C      COVERAGE 48
C      COVERAGE 49
C      COVERAGE 50
C      COVERAGE 51
C      COVERAGE 52
C      COVERAGE 53
C      COVERAGE 54
C      COVERAGE 55
C      COVERAGE 56
C      COVERAGE 57
C      COVERAGE 58
C      COVERAGE 59
C      COVERAGE 60
C      COVERAGE 61
C      COVERAGE 62
C      COVERAGE 63
C      COVERAGE 64
C      COVERAGE 65
C      COVERAGE 66
C      COVERAGE 67
C      COVERAGE 68
C      COVERAGE 69
C      COVERAGE 70
C      COVERAGE 71
C      COVERAGE 72
C      COVERAGE 73
C      COVERAGE 74
C      COVERAGE 75
C      COVERAGE 76

```

```

// COVERAGE
COVERAGE 78
COVERAGE 79
COVERAGE 80
COVERAGE 81
COVERAGE 82
COVERAGE 83
COVERAGE 84
COVERAGE 85
COVERAGE 86
COVERAGE 87
COVERAGE 88
COVERAGE 89
COVERAGE 90
POSTPC 91
POSTPC 92
POSTPC 93
POSTPC 94
POSTPC 95
POSTPC 96
POSTPC 97
POSTPC 98
POSTPC 99
POSTPC 100
POSTPC 101
POSTPC 102
POSTPC 103
POSTPC 104
POSTPC 105
POSTPC 106
POSTPC 107
POSTPC 108
POSTPC 109
POSTPC 110
POSTPC 111
POSTPC 112
POSTPC 113
POSTPC 114
POSTPC 115
POSTPC 116
POSTPC 117
POSTPC 118
POSTPC 119
POSTPC 120
POSTPC 121
POSTPC 122
POSTPC 123
POSTPC 124
POSTPC 125
POSTPC 126
POSTPC 127

// GU TO 204
IF(MU.EQ.0.) GU TO 204
M2=1
M2=M1
GU TO 208
LCM$IA=1B/M1
ICHAR(1)=2*KSCW+1
IF(KGFT.GT.0) ICHAR(1)=ICHAR(1)+1
1 CONTINUE
FACTR=1.0/(LLM*TWINW)
COVERAGE 0.0
IF(COVINT) WRITE(6,12)ISU,MD,IET,JS
12 FORMAT(1/10X,*COVERAGE CONTRIBUTIONS,* ISU **,I2,* MD **,I2,
      * IET **,I2,* JS **,I2/15X,*MECHANISM CONTRIBUTION*)
SDEL=JS*TDS(13U)
GPFLG=F.
GPFLG=F.

C EVALUATE SCHEDULED DETECTORS FIRST, WITH GPFLG=F.
C TIME GPAR ARRAY CONTAINS N+1 SAMPLES OF THE G-PRIME
C FUNCTIONS FOR THESE DETECTORS. ON THE SECOND
C PASS, GPFLG=T., THE GPAR ARRAY CONTAINS THE CUMULATIVE
C INTEGRALS OF ITS FORMER CONTENTS, AND UNSCHEDULED
C DETECTORS ARE EVALUATED.

C
DO 101 IJK=1,2
IF(GPFLG) GO TO 6
DO 5 IS1=20
ICH=ICHAR(1)
IF(ICH.LT.3) GU TO 5
IF(ICH.GT.3) GU TO 4
CALL CGP3(I)
GO TO 5
4 CALL CGP4(I)
5 CONTINUE
GO TU 9
6 DO 8 I=1,20
IF(ICHAR(1).LT.3) GU TO 8
DT=PERIAH(I)/N
A=GPAR(I,1)
GPARI(I,1)=0.0
B=GPAR(I,2)
GPARI(1,2)=DT*(A+B)/2.0
AREA=0.0
DO 7 IT=2,N
CGPARI(I,IT+1)
GPARI(I,IT+1)=AREA+DT*(A+B+C)/3.0
A=B
B=C
7 AREA=GPARI(I,IT)
8 CONTINUE

C COMPUTE COVERAGE CONTRIBUTIONS FOR EACH PROPERLY
C DEFINED MECHANISM, USING A DOUBLE SIMPSON INTEGRAL.
C IMPULSE FUNCTIONS ARE TREATED SPECIALLY IN THE
C INTEGRATION ALGORITHM.
C
9 DO 100 I=1,20
ICH=ICHAR(1)
IF(ICH.EQ.0) GO TO 100
IF(ICH.LE.4.AND.GPFLG) GO TO 100
IF(ICH.LE.4.AND..NOT.GPFLG) GO TO 100
NWNDSAV(I)
NX=NISAV(I)
NY=NIRSAV(I)
NZ=NRRSAV(I)
IMPGZCM,BW,I
IMPGET(FISOC(N),N=1,I),NG,I

```

```

1 IF(IMP>) GO TO 10
2 IF(LICH,Lt.2) TGFIN=TDELAR(I)*FDLT(7,NW)
3 IF(LICH,GE,3) TGFIN=PERIAR(I)
4 TRIFIN=EPRT(7,NY)
5 OUT=AMIN((TGFIN,TRIFIN)
6 OUT=0.0
7 IF(LICH,LE,2) WOUT=TDELAR(I)
8 OUT=(UPUT+WDUT)/N
9 POUT=P.
10 SOUT=0.0
11 HDEL=FISO(3,NX)
12 THFIN=HDEL+FISO(7,NX)
13 TR2FIN=FTLR(7,NZ)
14
C   BEGIN OUTER INTEGRAL
15
C   DO 70 IOUTP1=1,NP1
16   IOUT=IOUTP1-1
17   TAUD=OUT*IOUT+BDUT
18   GO TO (21,22,23,23),JCH
21   JAU=TDELAR(I)
22   VOUT=CYG1(I,TAU)
23   GO TO 25
24   VOUT=CYG2(I,TAU)
25   GO TO 25
26   VOUT=CYG5(I,TAU)
27   VOUT=VOUT*FEVAL(FEPR,NY,TAU)
28   IF(IMP>) GO TO 30
29   UPIN=AMIN((THFIN+3DEL),(TR2FIN+TAU))
30   BIN=HDEL+SDEL
31   DIN=(UPIN-BIN)/N
32   FIN=.F.
33   BIN=0.0
34
C   BEGIN INNER INTEGRAL
35
C   DO 50 LINP1=1,NP1
36   LIN=LINP1-1
37   IF(IMP>) GO TO 35
38   TAUP=DN+LIN*BIN
39   VIN=FEVAL(FISO,NX,TAUP+BIN)
40   GO TO 40
41   TAUP=FISO(J,NX)+SDEL
42   VIN=1.0
43   VIN=VIN*FEVAL(FTLR,NZ,TAU+TAUP)
44   IF(IMP>) GO TO 55
45   IF((IN,EQ,0).OR.(IN,EU,N)) GO TO 45
46   IF(FIN) GO TO 42
47   BIN=SIN*2.0*VIN
48   GO TO 50
49   SIN=SIN+VIN
50   FIN=.NOT.FIN
51   ANSIN=DN*SIN/J,0
52   GO TO 60
53   ANSIN=VIN
54   VOUT=VOUT+ANSIN
55   IF(IMP>) GO TO 75
56   IF(IOUT,EQ,0,OR,IOUT,NE,1) GO TO 65
57   FIN=.NOT.FIN
58   GO TO 70
59   SOUT=SOUT+4.0*VOUT
60   GO TO 70
61   SOUT=SOUT+VOUT
62
C   END OF PROGRAM

```



```

50      GU TU 50
47      SUM=SUM+PDETAR(K)*CVGPI(K,T)
50      CONTINUE
        CVG1=ANS*PROD*(1.0-SUM)
        RETURN
      END

      FUNCTION CVG2(I,T)
C
C      COMPUTE TIME VALUE OF THE G FUNCTION FOR
C      UNSCHEDULED FINITE DETECTOR I, TIME T.
C      (THE COMPETITIVE RATE OF DETECTION)
C
C      COMMON /CVB3/NDSAV(20) /CVB7/ICHAR(20),PDETAR(20),XYZ(40),
1      TDELTAR(20) /CVB2/FDET(7,1)
        PROD=1.0
        SUM=0.0
        DO 10   K=1,20
          IF(K.EQ.1) GO TO 10
          ICHAR=ICHAR(K)
          IF(ICH.EQ.0) GO TO 5
          IF(ICH.GT.3) GO TO 5
          IF(ICH.EQ.0) GO TO 10
          PROD=PROD*(1.0-PDETAR(K)*FINTEG(FDET,NDSAV(K),T*TDELTAR(K)))
          GO TO 10
5      SUM=SUM+PDETAR(K)*CVGPI(K,T)
10     CONTINUE
        CVG2=PROD*(1.0-SUM)*FEVAL(FDET,NDSAV(I),T*TDELTAR(I))
        RETURN
      END

      FUNCTION CVG3(I,T)
C
C      COMPUTE THE VALUE OF THE G FUNCTION FOR
C      SCHEDULED DETECTOR I, TIME T.
C      (THE COMPETITIVE RATE OF DETECTION)
C
C      COMMON /CVB3/NDSAV(20) /CVB7/ICHAR(20),PDETAR(20),XYZ(20),
1      PERIAH(20),TDFLAR(20) /CVB2/FDET(7,1)
        CVG3=0.0
        IF(T.LT.0.0.UR,T.GT.PERIAH(I)) GO TO 20
        PROD=1.0
        DO 10   K=1,20
          ICHAR=ICHAR(K)
          IF(ICH.GT.2.0K.ICH.EQ.0) GO TO 10
          PROD=PROD*(1.0-PDETAR(K)*FINTEG(FDET,NDSAV(K),T*TDELTAR(K)))
          GO TO 10
10     CONTINUE
        CVG3=PROD*CVGPI(I,T)
20     RETURN
      END

      SUBROUTINE CVGP3(I)
C
C      COMPUTE AND SAVE NO.1 SAMPLES OF THE G-PRIME FUNCTION
C      FOR SCHEDULED IMPULSE DETECTOR I, OVER ITS PERIOD.
C      (DATE OF DETECTION IN COMPETITION WITH OTHER
C      SCHEDULED DETECTORS)
C
C      COMMON /CVB3/NDSAV(20) /CVB6/LCM,TMINW,FACTOR /CVB7/ICHAR(20),
1      PDETAR(20),TREPAR(20),PERIAR(20),TDELTAR(20) /CVB8/GPPFL6,
2      GPW(20,101) /CVB9/N /CVB2/FDET(7,1)
3      /CVB10/TJLFLG
        LOGICAL TJLFLG
        LIM=LCM/TREPAR(1)
        DTSPERIAR(I)=N
        NP1=N+1
        DO 30   IT=ITP1+1,NP1
30      IT=ITP1+1
        TAUADT=IT
        SUM=0.0

```

```

98
99
CVG 100
CVG 101
CVG 102
CVG 103
CVG 104
CVG 105
CVG 106
CVG 107
CVG 108
CVG 109
CVG 110
CVG 111
CVG 112
FINAL 22
FINAL 23
FINAL 24
FINAL 25
FINAL 26
FINAL 27
CVG 113
CVG 114
CVG 115
CVG 116
CVG 117
POSTPCH 4
POSTPCH 5
POSTPCH 6
CVG 118
CVG 119
CVG 120
CVG 121
CVG 122
CVG 123
CVG 124
CVG 125
CVG 126
CVG 127
CVG 128
CVG 129
CVG 130
CVG 131
CVG 132
CVG 133
POSTPCH 7
POSTPCH 8
CVG 135
CVG 136
CVG 137
CVG 138
CVG 139
CVG 140
CVG 141
CVG 142
CVG 143
CVG 144
CVG 145
CVG 146
CVG 147
CVG 148
CVG 149
CVG 150
CVG 151
CVG 152
CVG 153

```

```

98
99
C
C COMPUTE AND SAVE N+1 SAMPLES OF THE G-PRIME FUNCTION
C FOR SCHEDULED FINITE DETECTOR I, OVER ITS PERIOD.
C RATE OF DETECTION IN COMPETITION WITH OTHER
C SCHEDULED DETECTORS)
C
C COMMON /CVB6/ND8AV(20) /CVB6/LCM,TWINDR,FACTOR /CVB7/ICHAR(20),
1 PDETAR(20),IREPAH(20),PERIAR(20),TDELAR(20) /CVB8/GPFLG,
2 GPAR(20,101) /CVB9/N /CVB2/FDET(7,1)
3 /CVB10/TJLFLG
LOGICAL FLUP,TJLFLG,TPLG
NP1=N+1
NUMENDSAV(I)
TDLRFD(7,NUM)
TFLG,F.
LIMBLIM/IREPAR(I)
DT*PERIAR(I)/N
DU 60 ITPI=1,NPI.
IT=1,ITPI=1
SUM=0.0
DE=0.0
TAU=0.0
IF(LT,EQ,0) GO TO 30
UPLIM=TAU
TFLG=TAU.GT.TDLR
IF(TFLG) UPLIM=TDLR
DE=UPLIM/N
DO 40 L=1,LIM
FLOP=F.
EUML=0.0
DO 30 ITPI=1,NPI
IT=1,ITPI=1
ETADE=IT
PROD=1.0
DO 10 J=1,20
IF((ICHAR(JJ).LT.3) GO TO 10
IF(J.EQ.1) GO TO 10
IF(LT,IE,EQ,1) TJLFLG=F.
TJL=CTJL(J,L,1)
PROD*PROD*(1.0*PDETAR(I)*(1.0-FINTEG(FDET,ND8AV(I),PERIAR(I))*
1 TDELAR(I)*ETA-TAU-TJL))
10 CONTINUE
PROD*PROD*FEVAL(FDET,ND8AV(I),ETA)
IF(LT,EQ,0,OR,IE,EQ,N) GO TO 20
IF(FLOP) GO TO 15
EUML=EUML+2.0*PROD
GO TO 30
15 EU4=EUML+4.0*PROD
GO TO 30
20 EUML=EUML+PHUD
30 FLOP=.NOT.FLUP

```

```

154 SUM=SUM+EUM
155 VAL=FACTOR*SUM*DL/3.0
156 IF(TFLG) GO TO 60
157 VALVAL=(1.0-FINTEG(FDET,NSAV(I),TAU))/PFRIAR(I)
158 GPARC(I,IT+1)=VAL
159 RETURN
160
161 FUNCTION CVTJL(J,L,I)
162
163 C C RETURN THE VALUE OF TJL FOR USE BY CVGP3 AND CVGP4
164
165 COMMON /CVB7/XYZ(60),PERIAR(20),TDELAR(20),
166 /CVB10/TJLFLG
167 LOGICAL TJLFLG
168 XNUM(TDLAR(I)+L*PERIAR(I)-TDELAR(J))/PERIAR(J)
169 NUM=XNU
170 YNU=NU
171 IF(XNU.EQ.YNU) GO TO 99
172 CTVL=PERIAR(J)+YNU*PERIAR(J)-(L-1)*PERIAR(I)
173 IF(CTVL.LT.TDELAR(I)) CTVL=-PERIAR(J)
174
175 10 RETURN
176 99 IF(TJLFLG) GO TO 10
177 WRITE(6,11) J,T
178 FORMAT(5X,*ERROR IN CVTJL = 2 DETECTORS (*,12,1H,,13,
179 * SCHEDULED SIMULTANEOUSLY*)
180 TJLFLG*,T)
181 GU TU 10
182 END
183 FUNCTION CVGP1(I,T)
184
185 C C INTERPOLATE THE SAMPLE G-PRIME OR INTEGRAL G-PRIME
186 VALUES SAVED IN ARRAY GPAR
187
188 COMMON /CVB7/XYZ(60),PERIAR(20)
189 /CVB8/GPFLG,GPAR(20,101)/CVB9/N
190 IF(T.LT.0.0) GO TO 101
191 PERIAR(I)
192 IF(T.LT.PER) GO TO 1
193 CVGPIE=0.0
194 IF(GPFLG.UH.T.EQ.PER) CVGPIE=GPAR(I,N+1)
195 GU TU 100
196 1 DTAPER/N
197 IDST/DT
198 IT=ID+1
199 X=T-DT*ID
200 A=GPAR(I,IT)
201 B=GPAR(I,IT+1)
202 CVGPI=A+(B-A)/DT
203
204 100 RETURN
205 101 WRITE(6,11)
206 11 FORMAT(5X,*ERROR IN CVGPI = NEGATIVE TIME ARGUMENT*)
207 STOP
208 END
209 SUBROUTINE SPECIT(FLIST,NUM,IGFT,ISCH,IREP,INTF,COEF,TDEL,
210 IGT,TDUR)
211
212 C C SAVE THE SPECIFICATIONS FOR ONE DETECTION, ISOLATION
213 OR RECOVERY (1 OF 2) FUNKTION IN THE DATA BASE
214
215 P1,P2,P3,TDUR
216 DIMENSION FLIST(7,1)
217 CALL INPUT(CODES,1,IGFT)
218 CALL INPUT(CODES,2,ISCH)
219 CALL INPUT(CODES,3,IREP)
220 CALL INPUT(CODES,4,1)
221 CALL INPUT(CODES,5,INTF)
222
223 C C

```

```

FLIST(2,NUM)=TDEL
FLIST(4,NUM)=P1
FLIST(5,NUM)=P2
FLIST(6,NUM)=P3
FLIST(7,NUM)=TDUR
RETURN
END
FUNCTION FEVAL(FLIST,NUM,T)
C
C   EVALUATE DEFLECTION, ISOLATION, OR RECOVERY (1 OF 2)
C   FUNCTION 'NUM' AT TIME 'T'. THE FUNCTION EVALUATES
C   TO 0.0 OUTSIDE THE RANGE 0.0, TDUR.
C
C   DIMENSION FLIST(7,1)
COMMON/CVB4/P,P2,P3,TDUR,IGFT
CODES=FLIST(1,NUM)
IGFT=IGFT(CODES,1)
TDUR=FLIST(7,NUM)
IF(IGFT.GT.0.AND.T.GE.0.0.AND.T.LE.TDUR) GO TO 10
ANS=0.0
GO TO 100
10 P1=FLIST(4,NUM)
P2=FLIST(5,NUM)
P3=FLIST(6,NUM)
ENTRY EVAL
GO TO (21,22,23,24,25,26),IGFT
21 ANSPNP1(T)
GO TO 100
22 ANSFN2(T)
GO TO 100
23 ANSFN3(T)
GO TO 100
24 ANSFN4(T)
GO TO 100
25 ANSFN5(T)
GO TO 100
26 ANSFN6(T)
100 FEVAL=ANS
RETURN
END
FUNCTION FINTEG(FLIST,NUM,T)
C
C   EVALUATE THE INTEGRAL OF DEFLECTION, ISOLATION, OR
C   RECOVERY (1 OF 2) FUNCTION 'NUM' AT TIME 'T'.
C   IF THE INTEGRAL MODEL IS NOT DEFINED, AN NO1
C   POINT SIMPSUN INTEGRAL IS PERFORMED USING FEVAL.
C
C   DIMENSION FLIST(7,1)
LOGICAL IFLUP
COMMON/CVB4/P1,P2,P3,TDUR,IGFT
DATA N/20/
NPI=N+1
TDUR=FLIST(7,NUM)
IF(T.GE.0.0) GO TO 5
ANS=0.0
GO TO 100
5 IF(T.LE.TDUR) GO TO 10
6 ANS=1.0
GO TO 100
10 CODES=FLIST(1,NUM)
IGFT=IGFT(CODES,1)
IF(IGFT.EQ.0) GO TO 6
PI1=FLIST(4,NUM)
P2=FLIST(5,NUM)
PI3=FLIST(6,NUM)

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19      INT=ISHIFT(ICODE,5)
20      IF((INTF.GT.0)) GO TO 50
21
22      START OF SIMPSON INTEGRAL
23
24      DELET/N
25      IFLOPA=.F.
26      SUMS0=0
27      DO 30   IPI1=1,NPI1
28      IF(IPI1=1)
29      TAURDEL=1
30      VALSTVAL(0,0,TAU)
31      IF((I.EQ.0.OR.I.EQ.N)) GO TO 20
32      IF((IPLDOP)) GU TO 15
33      SUM=SUM+2.0*VAL
34      GO TO 30
35      YUM=SUM+4.0*VAL
36      GO TO 30
37      SUM=SUM+VAL
38      IF(LFLUP=.NOT.IFLUP
39      ANS=DEL*SUM/3.0
40      GO TO 100
41      GO TO (51,52,53,54,55,56),IGFT
42      51  ANS=FN1(T)
43      GO TU 100
44      52  ANS=FN2(T)
45      GO TU 100
46      53  ANS=FN3(T)
47      GO TU 100
48      54  ANS=FN4(T)
49      GO TO 100
50      55  ANS=FN5(T)
51      GO TU 100
52      56  ANS=FN6(T)
53      GO TU 100
54      FINTEGSANS
55      RETURN
56      END
57      FUNCTION IGET(IWORD,INDEX)
58
59      RETURN THE VALUE OF THE INDEX=TH 12 BIT FIELD
60      OF IWORD, AS A RIGHT JUSTIFIED INTEGER
61
62      DIMENSION MASK(5)
63      DATA MASK/777000000000000B,000077700000000000B,
64      1000000077700000000B,0000000000077700000B,00000000000000007777B/GETPUT
65      ITP=AND(IWORD,MASK(INDEX))
66      IGET=ISHIFT(ITP,12*INDEX)
67      RETURN
68      END
69      SUBROUTINE IPUT(IWORD,INDEX,ICODE)
70
71      PACK THE HIGHMOS 12 BITS OF ICODE INTO THE
72      INDEX=TH 12 BIT FIELD OF IWORD
73
74      DIMENSION MASK(5)
75      DATA MASK/0000777777777777B,777700000777777777B,
76      177777770007777777B,77777777770007777B,7777777777770000B/GETPUT
77      ITP=ISHIFT(ICODE,12*(5*INDEX))
78      IMODUS=AND(IWORD,MASK(INDEX))
79      IWORD=OR(IWORD,ITP)
80      RETURN
81      END
82      IDENT ISHIFT
83      ENTRY ISHIFT
84      PS
85      ISHIFT

```

